

MIT 18.06 Final Exam, Fall 2018  
Johnson

Your name: \_\_\_\_\_

Recitation: \_\_\_\_\_

problem	score
1	/15
2	/15
3	/15
4	/15
5	/15
6	/15
7	/10
total	/100

**Problem 1 (5+10 points):**

The matrix  $A$  has the diagonalization  $A = X\Lambda X^{-1}$  with

$$X = \begin{pmatrix} 1 & 1 & -1 & 0 \\ & 1 & 2 & 1 \\ & & 1 & 0 \\ & & & 1 \end{pmatrix}, \Lambda = \begin{pmatrix} 1 & & & \\ & 2 & & \\ & & -2 & \\ & & & -1 \end{pmatrix}.$$

- (a) Give a basis for the nullspace  $N(M)$  of the matrix  $M = A^4 - 2A^2 - 8I$ .  
(Hint: not much calculation required!)

- (b) Write down the solution  $x(t)$  to the ODE  $\frac{dx}{dt} = Ax$  for  $x(0) = \begin{pmatrix} 2 \\ 3 \\ 1 \\ -1 \end{pmatrix}$ .

Your final answer should contain no matrix exponentials or matrix inverses, just a sum of vectors (whose components you give explicitly as numbers) multiplied by given scalar coefficients (that may depend on  $t$ ).

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**Problem 2 (3+3+3+3+3 points):**

The real  $m \times n$  matrix  $A$  has a QR factorization  $A = QR$  of the form

$$Q = \begin{pmatrix} q_1 & q_2 & q_3 & q_4 & q_5 & q_6 \end{pmatrix}, R = \begin{pmatrix} 1 & -2 & 2 & 0 & 0 & 0 \\ & 2 & -3 & 0 & 0 & 0 \\ & & 1 & 0 & 0 & 0 \\ & & & 3 & 1 & -1 \\ & & & & 1 & 2 \\ & & & & & 1 \end{pmatrix}.$$

where  $q_1, \dots, q_6$  are six orthonormal vectors in  $\mathbb{R}^m$ .

- (a) Give as much true information as possible about  $m$ ,  $n$ , and the rank of  $A$ .
- (b) If  $a_5$  is the 5th column of  $A$ , write it in the basis  $q_1, \dots, q_6$ , i.e. write it as  $a_5 = c_1 q_1 + c_2 q_2 + \dots + c_6 q_6$ , by giving the numerical values of the coefficients  $c_1, \dots, c_6$ .
- (c) What is  $\|a_5\|$ ?
- (d) This pattern of zero entries in  $R$  means that columns ..... of  $A$  must be ..... to columns ..... of  $A$ .
- (e) If  $A$  is a square matrix, what is  $|\det A|$  (the absolute value of the determinant)?

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**Problem 3 (8+3+4 points):**

You are given the matrix

$$A = \begin{pmatrix} 1 & 2 & 1 & 0 \\ 2 & 5 & 1 & 1 \\ 0 & 1 & 1 & 3 \end{pmatrix}$$

- (a) Give bases for the four fundamental subspaces of  $A$ .
- (b) Which of  $Ax = b$  or  $A^T y = c$  will *not* have *unique* solutions for  $x$  or  $y$  (assuming a solution exists)?
- (c) Which of  $Ax = b$  or  $A^T y = c$  may *not have a solution*? For that equation, **give a right-hand side** ( $b$  or  $c$ ) for which a solution exists, and that has only *two nonzero* entries in the right-hand side.

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**Problem 4 (5+10 points):**

A vector  $\hat{x}$  minimizes  $\|Ax - b\|$  over all possible vectors  $x$ .

(a) If  $\hat{x} = 0$ , then  $b$  must be in which fundamental subspace of  $A$ ?

(b) If  $A = \begin{pmatrix} 1 & 2 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$  and  $b = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ , what is the minimum possible  $\|Ax - b\|$ ? Describe (with as much detail as you can) *all possible*  $\hat{x}$  that give this minimum.



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**Problem 5 (5+10 points):**

Suppose that  $A = A^T$  is a real-symmetric  $10 \times 10$  matrix whose eigenvalues are 11, 10, 9, 8, 7, 6, 5, 4, 3, 2. Corresponding eigenvectors of  $A$ , each normalized to have length  $\|x\| = 1$ , are (to three significant digits) the columns of the matrix:

$$X = \begin{pmatrix} -0.179 & 0.415 & -0.173 & 0.115 & -0.125 & 0.079 & -0.676 & -0.066 & 0.3 & -0.423 \\ -0.239 & -0.168 & -0.53 & -0.08 & 0.232 & -0.281 & -0.386 & -0.223 & -0.353 & 0.413 \\ -0.35 & 0.116 & -0.201 & -0.41 & 0.547 & 0.197 & 0.182 & 0.373 & 0.38 & 0.029 \\ -0.399 & -0.238 & -0.079 & -0.46 & -0.279 & -0.139 & 0.259 & -0.427 & -0.028 & -0.468 \\ -0.378 & -0.132 & 0.013 & 0.28 & -0.374 & -0.332 & 0.096 & 0.056 & 0.582 & 0.4 \\ -0.227 & 0.352 & 0.195 & 0.336 & 0.388 & 0.137 & 0.242 & -0.657 & 0.042 & 0.109 \\ -0.404 & 0.327 & 0.566 & -0.143 & 0.024 & -0.399 & -0.123 & 0.277 & -0.371 & 0.03 \\ -0.001 & 0.628 & -0.369 & -0.162 & -0.46 & 0.172 & 0.3 & 0.05 & -0.202 & 0.261 \\ -0.303 & -0.07 & -0.331 & 0.6 & 0.07 & -0.052 & 0.288 & 0.329 & -0.29 & -0.389 \\ -0.425 & -0.285 & 0.195 & 0.047 & -0.213 & 0.732 & -0.194 & 0.051 & -0.194 & 0.195 \end{pmatrix}.$$

(That is, the first column of  $X$  is an eigenvector for  $\lambda = 11$ , and so on.)

Consider the recurrence relation  $x_{n+1} - x_n = -\alpha Ax_n$  on vectors  $x_n \in \mathbb{R}^{10}$ , where  $\alpha > 0$  is some positive real number.

- (a) For what values of  $\alpha$  (if any) can the recurrence have solutions that *diverge* in magnitude as  $n \rightarrow \infty$ ?

- (b) For  $\alpha = 1$ , give a good approximation for the vector  $x_{100}$  given  $x_0 =$

$$\begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}.$$

You can leave your answer in the form of some vector times

some coefficient(s) without carrying out the multiplications, but give all the numbers in your coefficients and vectors to 3 significant digits.

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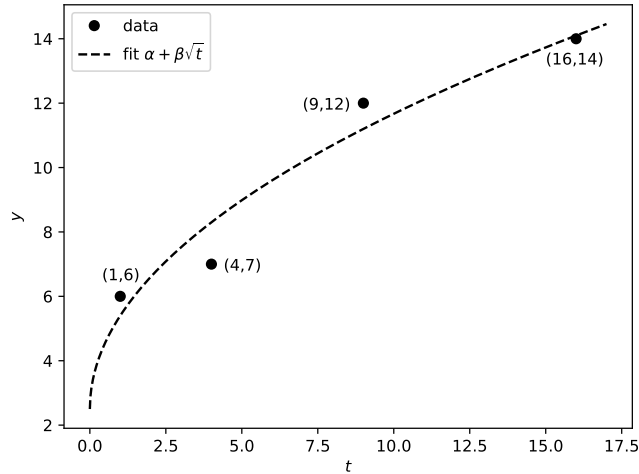


Figure 1: Fitting four data points  $(t_k, y_k)$  to  $y(t) = \alpha + \beta\sqrt{t}$

**Problem 6 (5+10 points):**

As shown in Fig. 1, you are trying to fit of a sequence of four data points  $(t_k, y_k) = (1, 6), (4, 7), (9, 12), (16, 14)$  to a function of the form  $y(t) = \alpha + \beta\sqrt{t}$  for unknown coefficients  $\alpha$  and  $\beta$ .

- (a) Write down a minimization problem of the form “minimize ..... over all possible  $\alpha, \beta$ ” that we could solve for a “best fit” curve (resembling the dashed line in Fig. 1) using 18.06 techniques. (Don’t solve it.)
- (b) Write down a  $2 \times 2$  system of equations of the form

$$\begin{pmatrix} \text{some} \\ \text{matrix} \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} \text{some} \\ \text{vector} \end{pmatrix}$$

whose solution gives the “best” fit coefficients  $\alpha$  and  $\beta$  for your minimization problem from part (a). You don’t need to solve it! You can leave the matrix and vector as a product of other matrices/vectors/transposes, but give the numerical values of each of the terms (no matrix inverses allowed).

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**Problem 7 (10 points):**

Suppose that you want to multiply each of the three matrices

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}, B = \begin{pmatrix} 1 & 1 \\ -1 & 0 \\ 0 & 1 \end{pmatrix}, C = \begin{pmatrix} 4 & 5 \end{pmatrix},$$

by each of the two vectors  $x, y \in \mathbb{R}^2$ . That is, you want to compute the *six* vectors  $x_A = Ax$ ,  $x_B = Bx$ ,  $x_C = Cx$ ,  $y_A = Ay$ ,  $y_B = By$ , and  $y_C = Cy$ . Write *all* of these products in the form of a *single* matrix-matrix multiplication:

$$\begin{pmatrix} \text{some matrix in terms of} \\ x_A, x_B, x_C, y_A, y_B, y_C \end{pmatrix} = \begin{pmatrix} \text{some matrix in terms of} \\ A, B, C \end{pmatrix} \begin{pmatrix} x & y \end{pmatrix}.$$

Note that the third matrix here is the  $2 \times 2$  matrix whose columns are  $x$  and  $y$ . That is, **give the sizes of the other two matrices and how their contents are arranged.**

[For example, a possible but wrong(!) answer for the second matrix would be the  $2 \times 6$  matrix  $\begin{pmatrix} A & B^T & C^T \end{pmatrix}$ .]

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