

# Hyperbolic Graph Convolutional Neural Networks

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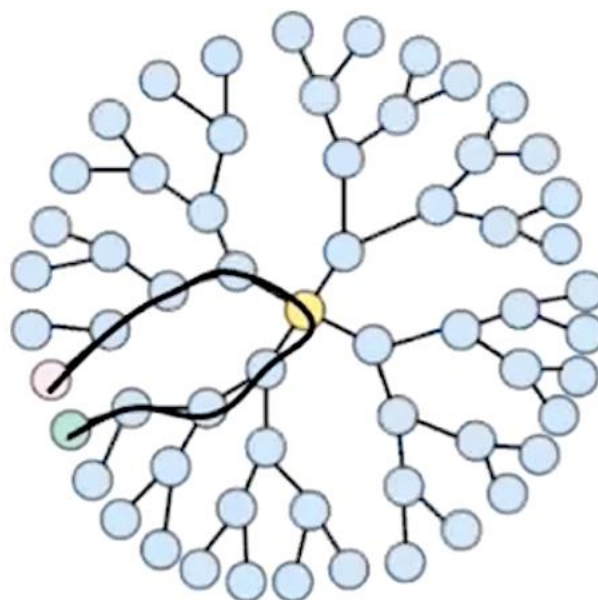
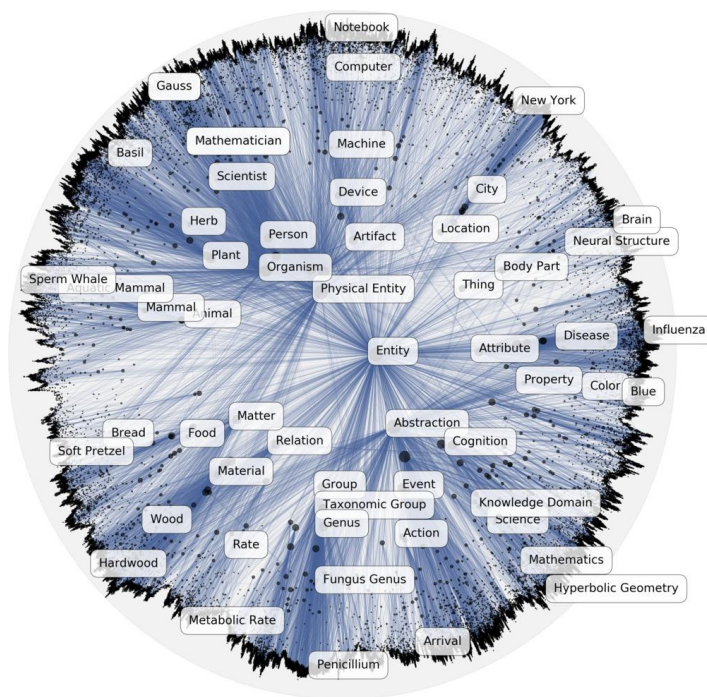
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# 为什么用双曲空间嵌入

- 对于具备“层级结构”的数据而言，传统的欧式嵌入会导致隐向量失真：



Socar

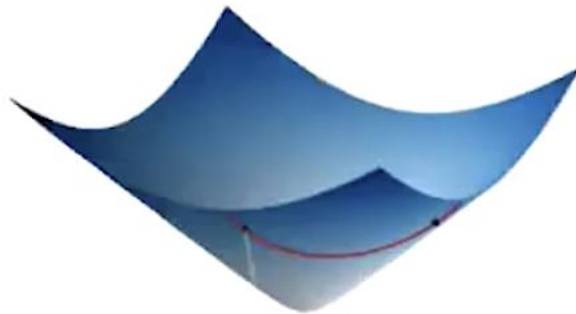
### 解决方案：引入曲率

$$k = \frac{1}{\text{曲率半径}}$$

# 双曲空间/双曲面模型

- 双曲空间：一个n维双曲空间就是一个高斯曲率处处为常数的流形。数学家认为这种形状拥有负常曲率(constant negative curvature), 而球形拥有正常曲率(constant positive curve)。

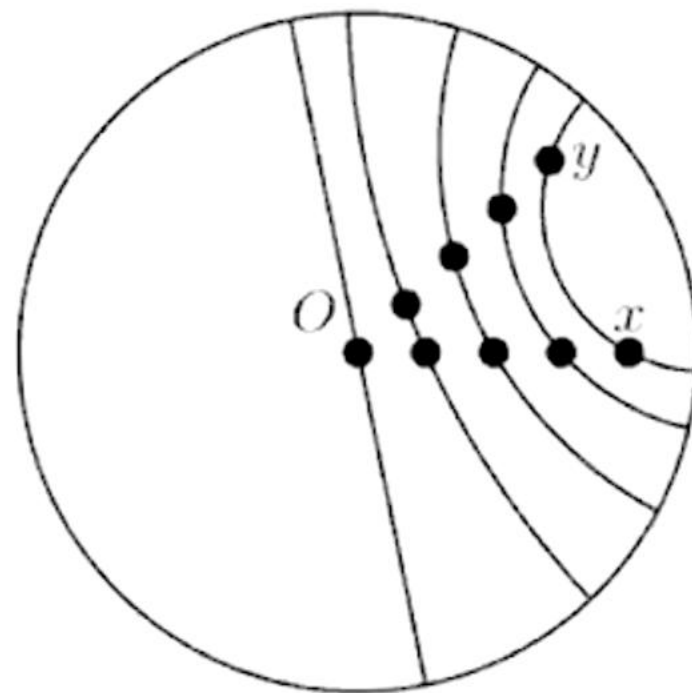
双曲面模型



庞加莱圆盘



$$x^2 - y^2 - z^2 = 1$$



# 度规

- 在每一点处对空间距离的定义

- 欧式空间中的度规:  $dr^2 = dx^2 + dy^2 \rightarrow \begin{pmatrix} dx \\ dy \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} dx & dy \end{pmatrix}$   
度规张量

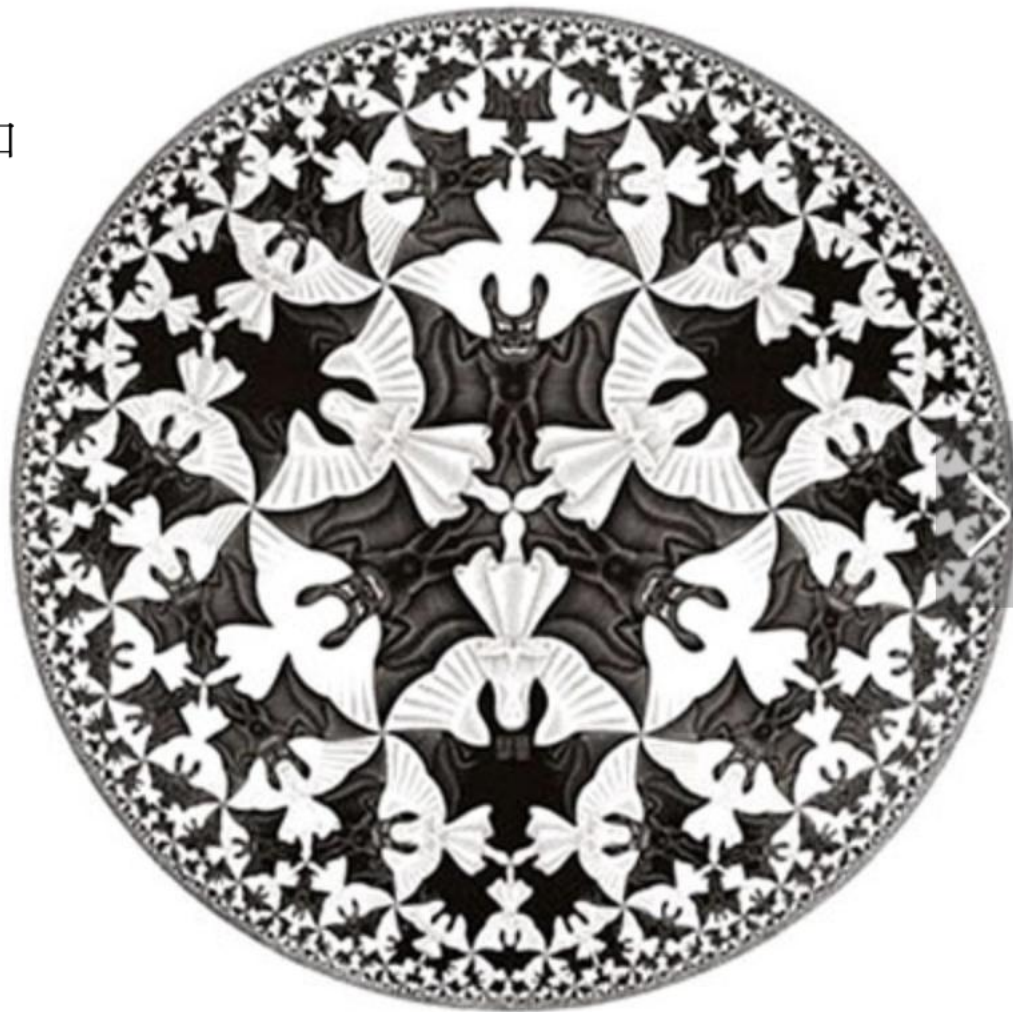
- 双曲空间中的度规:  $dr^2 = \frac{2dx^2}{1-x^2-y^2} + \frac{2dy^2}{1-x^2-y^2} \rightarrow$   
 $\begin{pmatrix} dx \\ dy \end{pmatrix} \begin{pmatrix} \frac{2}{1-x^2-y^2} & 0 \\ 0 & \frac{2}{1-x^2-y^2} \end{pmatrix} \begin{pmatrix} dx & dy \end{pmatrix}$   
度规张量

# 双曲空间及基于双曲空间的嵌入

双曲空间也有维度，其维度表示比欧式空间中同维度空间增加一维，与对应的庞加莱圆盘的维度相同。

正式的： $D^n = \{x \in R^n: ||x|| < 1\}$

双曲空间的距离： $d(u, v) = \operatorname{arcosh}(1 + \frac{2||u-v||^2}{(1-||u||^2)(1-||v||^2)})$



# 双曲空间下的神经网络运算

- (Hyperbolic Neural Network 2018,NIPS)

**Möbius addition.** The *Möbius addition* of  $x$  and  $y$  in  $\mathbb{D}_c^n$  is defined as

$$x \oplus_c y := \frac{(1 + 2c\langle x, y \rangle + c\|y\|^2)x + (1 - c\|x\|^2)y}{1 + 2c\langle x, y \rangle + c^2\|x\|^2\|y\|^2}. \quad (6)$$

In particular, when  $c = 0$ , one recovers the Euclidean addition of two vectors in  $\mathbb{R}^n$ . Note that without loss of generality, the case  $c > 0$  can be reduced to  $c = 1$ . Unless stated otherwise, we will use  $\oplus$  as  $\oplus_1$  to simplify notations. For general  $c > 0$ , this operation is not commutative nor associative. However, it satisfies  $x \oplus_c \mathbf{0} = \mathbf{0} \oplus_c x = \mathbf{0}$ . Moreover, for any  $x, y \in \mathbb{D}_c^n$ , we have  $(-x) \oplus_c x = x \oplus_c (-x) = \mathbf{0}$  and  $(-x) \oplus_c (x \oplus_c y) = y$  (left-cancellation law). The *Möbius subtraction* is then defined by the use of the following notation:  $x \ominus_c y := x \oplus_c (-y)$ . See [29, section 2.1] for a geometric interpretation of the Möbius addition.

其中,  $c = \frac{1}{r^2}$

# 双曲空间下的神经网络运算

- (Hyperbolic Neural Network 2018,NIPS)

**Möbius scalar multiplication.** For  $c > 0$ , the *Möbius scalar multiplication* of  $x \in \mathbb{D}_c^n \setminus \{\mathbf{0}\}$  by  $r \in \mathbb{R}$  is defined as

$$r \otimes_c x := (1/\sqrt{c}) \tanh(r \tanh^{-1}(\sqrt{c}\|x\|)) \frac{x}{\|x\|}, \quad (7)$$

and  $r \otimes_c \mathbf{0} := \mathbf{0}$ . Note that similarly as for the Möbius addition, one recovers the Euclidean scalar multiplication when  $c$  goes to zero:  $\lim_{c \rightarrow 0} r \otimes_c x = rx$ . This operation satisfies desirable properties such as  $n \otimes_c x = x \oplus_c \cdots \oplus_c x$  ( $n$  additions),  $(r + r') \otimes_c x = r \otimes_c x \oplus_c r' \otimes_c x$  (scalar distributivity<sup>3</sup>),  $(rr') \otimes_c x = r \otimes_c (r' \otimes_c x)$  (scalar associativity) and  $|r| \otimes_c x / \|r \otimes_c x\| = x / \|x\|$  (scaling property).

其中,  $c = \frac{1}{r^2}$



# 双曲空间下的神经网络运算

- (Hyperbolic Neural Network 2018,NIPS)

**Distance.** If one defines the generalized hyperbolic metric tensor  $g^c$  as the metric conformal to the Euclidean one, with conformal factor  $\lambda_x^c := 2/(1 - c\|x\|^2)$ , then the induced distance function on  $(\mathbb{D}_c^n, g^c)$  is given by<sup>4</sup>

$$d_c(x, y) = (2/\sqrt{c}) \tanh^{-1} (\sqrt{c} \| -x \oplus_c y \|) . \quad (8)$$

Again, observe that  $\lim_{c \rightarrow 0} d_c(x, y) = 2\|x - y\|$ , *i.e.* we recover Euclidean geometry in the limit<sup>5</sup>. Moreover, for  $c = 1$  we recover  $d_{\mathbb{D}}$  of Eq. (4).

其中,  $c = \frac{1}{r^2}$



# 双曲空间下的神经网络运算

- (Hyperbolic Neural Network 2018,NIPS)

**Parallel transport.** Finally, we connect parallel transport (from  $T_0\mathbb{D}_c^n$ ) to gyrovector spaces with the following theorem, which we prove in appendix B.

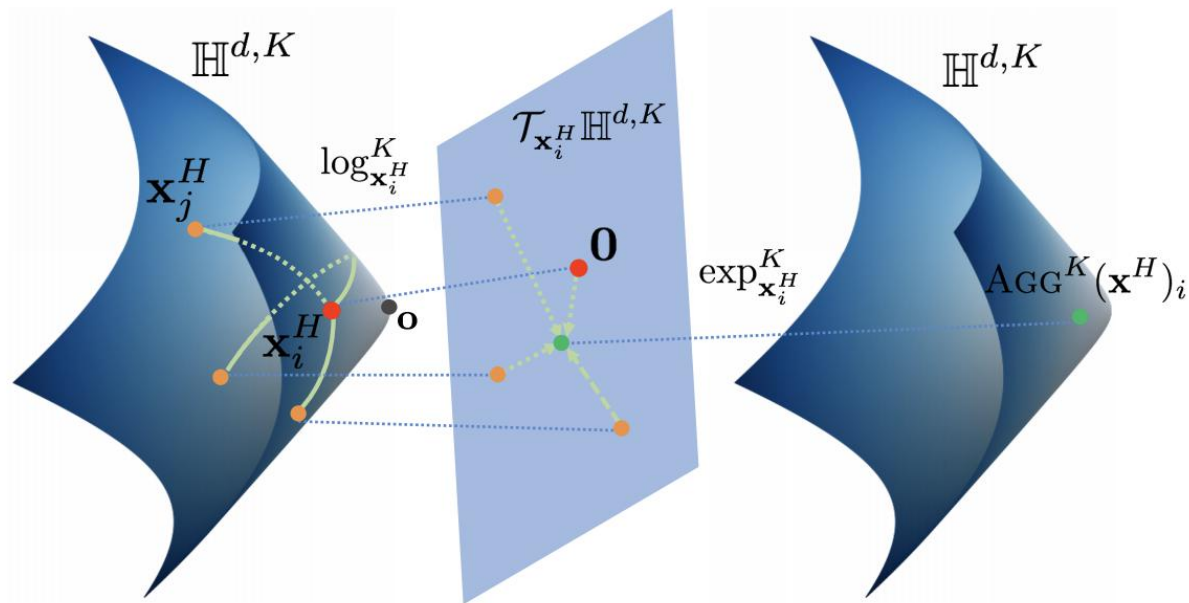
**Theorem 4.** *In the manifold  $(\mathbb{D}_c^n, g^c)$ , the parallel transport w.r.t. the Levi-Civita connection of a vector  $v \in T_0\mathbb{D}_c^n$  to another tangent space  $T_x\mathbb{D}_c^n$  is given by the following isometry:*

$$P_{0 \rightarrow x}^c(v) = \log_x^c(x \oplus_c \exp_0^c(v)) = \frac{\lambda_0^c}{\lambda_x^c} v. \quad (16)$$

其中,  $c = \frac{1}{r^2}$

# 双曲空间与欧式空间的转换

- log映射:  $H^n \rightarrow R^n$
- exp映射:  $R^n \rightarrow H^n$



**Definition 3.2** (Möbius version). For  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ , we define the *Möbius version of  $f$*  as the map from  $\mathbb{D}_c^n$  to  $\mathbb{D}_c^m$  by:

$$f^{\otimes c}(x) := \exp_0^c(f(\log_0^c(x))), \quad (26)$$

where  $\exp_0^c : T_{\mathbf{0}_m} \mathbb{D}_c^m \rightarrow \mathbb{D}_c^m$  and  $\log_0^c : \mathbb{D}_c^n \rightarrow T_{\mathbf{0}_n} \mathbb{D}_c^n$ .

# HGCN

- 结合图卷积和双曲嵌入，在双曲面模型上做GCN,在结合聚合上做GAT。曲率可训练。

- N维度双曲面  $x^2 - y^2 - z^2 = 1 \rightarrow x_0^2 - (x_1^2 + \dots + x_n^2) = 1$

内积定义  $\langle \mathbf{x}, \mathbf{y} \rangle_{\mathcal{L}} := -x_0 y_0 + x_1 y_1 + \dots + x_d y_d$ .

双曲面上的距离  $d_{\mathcal{L}}^K(\mathbf{x}, \mathbf{y}) = \sqrt{K} \operatorname{arcosh}(-\langle \mathbf{x}, \mathbf{y} \rangle_{\mathcal{L}} / K)$ .

双曲面上的映射

$$\exp_{\mathbf{x}}^K(\mathbf{v}) = \cosh\left(\frac{\|\mathbf{v}\|_{\mathcal{L}}}{\sqrt{K}}\right)\mathbf{x} + \sqrt{K} \sinh\left(\frac{\|\mathbf{v}\|_{\mathcal{L}}}{\sqrt{K}}\right) \frac{\mathbf{v}}{\|\mathbf{v}\|_{\mathcal{L}}}, \quad \log_{\mathbf{x}}^K(\mathbf{y}) = d_{\mathcal{L}}^K(\mathbf{x}, \mathbf{y}) \frac{\mathbf{y} + \frac{1}{K} \langle \mathbf{x}, \mathbf{y} \rangle_{\mathcal{L}} \mathbf{x}}{\|\mathbf{y} + \frac{1}{K} \langle \mathbf{x}, \mathbf{y} \rangle_{\mathcal{L}} \mathbf{x}\|_{\mathcal{L}}}.$$

# 算法框架

- 输入（欧式空间转化为双曲空间）

$$\mathbf{x}^{0,H} = \exp_{\mathbf{o}}^K((0, \mathbf{x}^{0,E})) = \left( \sqrt{K} \cosh\left(\frac{\|\mathbf{x}^{0,E}\|_2}{\sqrt{K}}\right), \sqrt{K} \sinh\left(\frac{\|\mathbf{x}^{0,E}\|_2}{\sqrt{K}}\right) \frac{\mathbf{x}^{0,E}}{\|\mathbf{x}^{0,E}\|_2} \right).$$

- 线性变换

$$W \otimes^K \mathbf{x}^H := \exp_{\mathbf{o}}^K(W \log_{\mathbf{o}}^K(\mathbf{x}^H)),$$

$$\mathbf{x}^H \oplus^K \mathbf{b} := \exp_{\mathbf{x}^H}^K(P_{\mathbf{o} \rightarrow \mathbf{x}^H}^K(\mathbf{b})).$$

# 算法框架

- 节点聚合

$$w_{ij} = \text{SOFTMAX}_{j \in \mathcal{N}(i)}(\text{MLP}(\log_{\mathbf{o}}^K(\mathbf{x}_i^H) || \log_{\mathbf{o}}^K(\mathbf{x}_j^H)))$$
$$\text{AGG}^K(\mathbf{x}^H)_i = \exp_{\mathbf{x}_i^H}^K \left( \sum_{j \in \mathcal{N}(i)} w_{ij} \log_{\mathbf{x}_i^H}^K(\mathbf{x}_j^H) \right).$$

- 非线性激活

$$\sigma^{\otimes^{K_{\ell-1}, K_{\ell}}}(\mathbf{x}^H) = \exp_{\mathbf{o}}^{K_{\ell}}(\sigma(\log_{\mathbf{o}}^{K_{\ell-1}}(\mathbf{x}^H))).$$

- 解码

$$p((i, j) \in \mathcal{E} | \mathbf{x}_i^{L, H}, \mathbf{x}_j^{L, H}) = \left[ e^{(d_{\mathcal{L}}^{K_L}(\mathbf{x}_i^{L, H}, \mathbf{x}_j^{L, H})^2 - r)/t} + 1 \right]^{-1},$$

	Dataset Hyperbolicity $\delta$	DISEASE $\delta = 0$		DISEASE-M $\delta = 0$		HUMAN PPI $\delta = 1$		AIRPORT $\delta = 1$		PUBMED $\delta = 3.5$		CORA $\delta = 11$	
	Method	LP	NC	LP	NC	LP	NC	LP	NC	LP	NC	LP	NC
Shallow	EUC	$59.8 \pm 2.0$	$32.5 \pm 1.1$	-	-	-	-	$92.0 \pm 0.0$	$60.9 \pm 3.4$	$83.3 \pm 0.1$	$48.2 \pm 0.7$	$82.5 \pm 0.3$	$23.8 \pm 0.7$
	HYP [29]	$63.5 \pm 0.6$	$45.5 \pm 3.3$	-	-	-	-	$94.5 \pm 0.0$	$70.2 \pm 0.1$	$87.5 \pm 0.1$	$68.5 \pm 0.3$	$87.6 \pm 0.2$	$22.0 \pm 1.5$
	EUC-MIXED	$49.6 \pm 1.1$	$35.2 \pm 3.4$	-	-	-	-	$91.5 \pm 0.1$	$68.3 \pm 2.3$	$86.0 \pm 1.3$	$63.0 \pm 0.3$	$84.4 \pm 0.2$	$46.1 \pm 0.4$
	HYP-MIXED	$55.1 \pm 1.3$	$56.9 \pm 1.5$	-	-	-	-	$93.3 \pm 0.0$	$69.6 \pm 0.1$	$83.8 \pm 0.3$	$73.9 \pm 0.2$	$85.6 \pm 0.5$	$45.9 \pm 0.3$
NN	MLP	$72.6 \pm 0.6$	$28.8 \pm 2.5$	$55.3 \pm 0.5$	$55.9 \pm 0.3$	$67.8 \pm 0.2$	$55.3 \pm 0.4$	$89.8 \pm 0.5$	$68.6 \pm 0.6$	$84.1 \pm 0.9$	$72.4 \pm 0.2$	$83.1 \pm 0.5$	$51.5 \pm 1.0$
	HNN[10]	$75.1 \pm 0.3$	$41.0 \pm 1.8$	$60.9 \pm 0.4$	$56.2 \pm 0.3$	$72.9 \pm 0.3$	$59.3 \pm 0.4$	$90.8 \pm 0.2$	$80.5 \pm 0.5$	$94.9 \pm 0.1$	$69.8 \pm 0.4$	$89.0 \pm 0.1$	$54.6 \pm 0.4$
GNN	GCN[21]	$64.7 \pm 0.5$	$69.7 \pm 0.4$	$66.0 \pm 0.8$	$59.4 \pm 3.4$	$77.0 \pm 0.5$	$69.7 \pm 0.3$	$89.3 \pm 0.4$	$81.4 \pm 0.6$	$91.1 \pm 0.5$	$78.1 \pm 0.2$	$90.4 \pm 0.2$	$81.3 \pm 0.3$
	GAT [41]	$69.8 \pm 0.3$	$70.4 \pm 0.4$	$69.5 \pm 0.4$	$62.5 \pm 0.7$	$76.8 \pm 0.4$	$70.5 \pm 0.4$	$90.5 \pm 0.3$	$81.5 \pm 0.3$	$91.2 \pm 0.1$	$79.0 \pm 0.3$	<b><math>93.7 \pm 0.1</math></b>	<b><math>83.0 \pm 0.7</math></b>
	SAGE [15]	$65.9 \pm 0.3$	$69.1 \pm 0.6$	$67.4 \pm 0.5$	$61.3 \pm 0.4$	$78.1 \pm 0.6$	$69.1 \pm 0.3$	$90.4 \pm 0.5$	$82.1 \pm 0.5$	$86.2 \pm 1.0$	$77.4 \pm 2.2$	$85.5 \pm 0.6$	$77.9 \pm 2.4$
	SGC [44]	$65.1 \pm 0.2$	$69.5 \pm 0.2$	$66.2 \pm 0.2$	$60.5 \pm 0.3$	$76.1 \pm 0.2$	$71.3 \pm 0.1$	$89.8 \pm 0.3$	$80.6 \pm 0.1$	$94.1 \pm 0.0$	$78.9 \pm 0.0$	$91.5 \pm 0.1$	$81.0 \pm 0.1$
Ours	HGCN	<b><math>90.8 \pm 0.3</math></b>	<b><math>74.5 \pm 0.9</math></b>	<b><math>78.1 \pm 0.4</math></b>	<b><math>72.2 \pm 0.5</math></b>	<b><math>84.5 \pm 0.4</math></b>	<b><math>74.6 \pm 0.3</math></b>	<b><math>96.4 \pm 0.1</math></b>	<b><math>90.6 \pm 0.2</math></b>	<b><math>96.3 \pm 0.0</math></b>	<b><math>80.3 \pm 0.3</math></b>	$92.9 \pm 0.1$	$79.9 \pm 0.2$
	(%) ERR RED	-63.1%	-13.8%	-28.2%	-25.9%	-29.2%	-11.5%	-60.9%	-47.5%	-27.5%	-6.2%	+12.7%	+18.2%