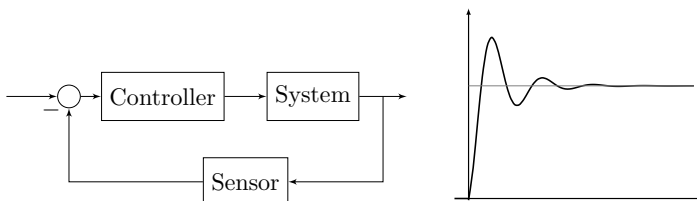
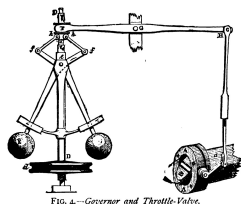


# ECE 380 Analog Control Systems

## Spring 2024



Without control systems there could be no manufacturing, no vehicles, no computers, no regulated environment—in short, no technology.

J. Doyle, B. Francis, A. Tannenbaum  
*Feedback Control Theory (1990)*

All modern control algorithms for engineering systems are implemented in software.

K. J. Åström, R. Murray  
*Feedback Systems (2020)*

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<b>Time and place</b>	Lectures	Tuesday, Wednesday 8:30-9:50, E7 5353
	Tutorials	Friday 8:30-9:50, E7 5353
	Office hours	Monday 14:00-16:00, E5 4006

<b>Website</b>	<a href="https://learn.uwaterloo.ca/">learn.uwaterloo.ca/</a>
	<a href="https://piazza.com/uwaterloo.ca/summer2024/ece380sec001">https://piazza.com/uwaterloo.ca/summer2024/ece380sec001</a>
	<a href="https://www.gnotomista.com/teaching.html">https://www.gnotomista.com/teaching.html</a>

### Description

This course will introduce students to the mathematical modeling of systems and to the analysis and design of feedback control systems. The course will be divided into four modules, corresponding to the following topics:

- Mathematical models of systems
- Linear system theory
- Analysis of feedback control systems
- Controller synthesis

Each topic will be presented during lectures and reinforced via homeworks. Moreover, throughout the term, a project will walk the students through the implementation of a controller for an autonomous mobile robot, which will be demonstrated on a real robotic platform in the UWaterloo Robohub.

**Prerequisites** ECE 207 or MATH 213

## Reading

The course textbook is:

(DB) Richard C. Dorf, Robert H. Bishop, *Modern Control Systems*, 13th edition, Pearson, 2016

Other useful resources are:

(AM) K. J. Åström, R. Murray, *Feedback Systems. An Introduction for Scientists and Engineers*, 2nd edition, Princeton University Press, 2021 [https://fbswiki.org/wiki/index.php/Main\\_Page](https://fbswiki.org/wiki/index.php/Main_Page)

(N) Norman S. Nise, *Control Systems Engineering*, 8th edition, John Wiley & Sons, 2019

## Deliverables and grading

- Homeworks (5%)
  - Handled via Crowdmark
- Lab (20%)
  - Carried out in groups
- Project (5%)
  - Handled via LEARN
  - Carried out in groups (same groups of the lab)
  - More details in the project description on the course website
- Exams (70%)
  - 1 midterm, 1 final
  - Total worth  $\max\{30\% \text{ midterm} + 40\% \text{ final}, 70\% \text{ final}\}$

## Policy on academic integrity

**Academic integrity** To maintain a culture of academic integrity, members of the University of Waterloo are expected to promote honesty, trust, fairness, respect and responsibility. A student is expected to know what constitutes academic integrity, to avoid committing academic offences, and to take responsibility for their actions. A student who is unsure whether an action constitutes an offence, or who needs help in learning how to avoid offences (e.g., plagiarism, cheating) or about “rules” for group work/collaboration should seek guidance from course instructor, academic advisor, or Graduate Associate Dean. When misconduct has been found to have occurred, disciplinary penalties will be imposed under Policy 71 - Student Discipline. For information on categories of offenses and types of penalties, students should refer to Policy 71 - Student Discipline, <https://uwaterloo.ca/secretariat/policies-procedures-guidelines/policy-71>.

**Grievance** A student who believes that a decision affecting some aspect of their University life has been unfair or unreasonable may have grounds for initiating a grievance. Read Policy 70 - Student Petitions and Grievances, Section 4, <https://uwaterloo.ca/secretariat/policies-procedures-guidelines/policy-70>.

**Discipline** A student is expected to know what constitutes academic integrity (<https://uwaterloo.ca/academic-integrity>) to

avoid committing an academic offence, and to take responsibility for his/her actions. A student who is unsure whether an action constitutes an offence, or who needs help in learning how to avoid offences (e.g., plagiarism, cheating) or about “rules” for group work/collaboration should seek guidance from the course instructor, academic advisor, or the undergraduate Associate Dean.

**Appeals** A student may appeal the finding and/or penalty in a decision made under Policy 70 - Student Petitions and Grievances (other than regarding a petition) or Policy 71 - Student Discipline if a ground for an appeal can be established. Read Policy 72 - Student Appeals, <https://uwaterloo.ca/secretariat/policies-procedures-guidelines/policy-72>.

**Note for students with disabilities** The Office for persons with Disabilities (OPD), located in Needles Hall, Room 1132, collaborates with all academic departments to arrange appropriate accommodations for students with disabilities without compromising the academic integrity of the curriculum. If you require academic accommodations to lessen the impact of your disability, please register with the OPD at the beginning of each academic term.

**Academic Integrity Office (UW)** <https://uwaterloo.ca/academic-integrity/>.

## Schedule

Date	Subject	Reading	Deliverable due
	<b>MATHEMATICAL MODELS OF SYSTEMS</b>		
May 7	Introduction to control systems	1 (DB)	
May 8	Examples of control systems	1 (DB)	
May 14	From differential equations to state space	2, 3 (DB)	
May 15	Linearization	2 (DB)	
May 21	Transfer function	2 (DB)	
May 22	Examples of transfer functions	2 (DB)	
May 28	Frequency response	8 (DB)	
May 29	Bode plots	8 (DB)	
Jun 4	Examples of bode plots	8 (DB)	
	<b>LINEAR SYSTEM THEORY</b>		
Jun 5	System stability	3, 6 (DB)	
Jun 11	Performance	5 (DB)	
Jun 12	First and second order systems	5 (DB)	
<b>Jun 17-21</b>	<b>Midterm week — no class</b>		
<b>Jun 20</b>	<b>Midterm exam, 13:30-14:45, E7 4043/4053/4433/5353</b>		
Jun 25	Lower-order approximations and system identification	5 (DB)	
	<b>ANALYSIS OF FEEDBACK CONTROL SYSTEMS</b>		
Jun 26	Stability of interconnected systems	2, 4 (DB)	
Jul 2	Routh-Hurwitz criterion	6 (DB)	
Jul 3	Nyquist and Bode criteria	9 (DB)	
	<b>CONTROLLER SYNTHESIS</b>		
Jul 9	Loop shaping	7, 10 (DB)	
Jul 10	Lead-lag compensators	10 (DB)	
Jul 16	PID controller	7 (DB)	
Jul 17	Root locus	7 (DB)	
Jul 23	Examples of control design		
Jul 24	Back to state space	11 (DB)	
Jul 30	Pole placement	11 (DB)	
	<b>TBD</b>	<b>Final exam</b>	