

Differential ideals and homomorphisms of Lie groups

Supporting material of the talk

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1 Left invariant forms

Proposition 1.1. *Left invariant forms are smooth.*

Proof. Let $\omega \in \Omega_{l\text{inv}}^p(G)$. It suffices to check that for $X_1, \dots, X_p \in \mathfrak{X}(G)$, $\omega(X_1, \dots, X_p)$ is smooth. This is equivalent to

$$\begin{aligned} \omega(X_1, \dots, X_p)(\sigma) &= \omega|_{\sigma}(X_1|_{\sigma}, \dots, X_p|_{\sigma}) \\ &= (l_{\sigma^{-1}}^* \omega)|_{\sigma}(X_1|_{\sigma}, \dots, X_p|_{\sigma}) \\ &= \omega|_e(d_{\sigma} l_{\sigma^{-1}} X_1|_{\sigma}, \dots, d_{\sigma} l_{\sigma^{-1}} X_p|_{\sigma}) \end{aligned} \quad (1)$$

for all $\sigma \in G$. Let $\tilde{\omega}$ be a smooth form such that $\tilde{\omega}|_e = \omega|_e$. Then for $\varphi : G \times G \rightarrow G$, $(a, b) \mapsto ab$, $\varphi^* \tilde{\omega}$ is smooth. Also $(0, X_i)$ is a smooth vector field on $G \times G$, and $i : G \rightarrow G \times G$, $\tau \mapsto (\tau^{-1}, \tau)$ is smooth. Therefore, $\varphi^* \tilde{\omega}((0, X_1), \dots, (0, X_p))(i(\sigma))$ is smooth with respect to σ . But,

$$\begin{aligned} &\varphi^* \tilde{\omega}((0, X_1), \dots, (0, X_r))(i(\sigma)) \\ &= \varphi^* \tilde{\omega}|_{(\sigma^{-1}, \sigma)}((0, X_1)|_{(\sigma^{-1}, \sigma)}, \dots, (0, X_r)|_{(\sigma^{-1}, \sigma)}) \\ &= \tilde{\omega}|_e(d\varphi(0, X_1)|_{(\sigma^{-1}, \sigma)}, \dots, d\varphi(0, X_r)|_{(\sigma^{-1}, \sigma)}) . \end{aligned} \quad (2)$$

Furthermore,

$$d\varphi(0, X_i)|_{(a, b)}(f) = (0, X_i)|_{(a, b)}(f \circ \varphi) = X_i|_b(f \circ l_a) = dl_a X_i|_b(f). \quad (3)$$

Therefore

$$\begin{aligned} &\tilde{\omega}|_e(d\varphi(0, X_1)|_{(\sigma^{-1}, \sigma)}, \dots, d\varphi(0, X_r)|_{(\sigma^{-1}, \sigma)}) \\ &= \tilde{\omega}|_e(dl_{\sigma^{-1}} X_i|_{\sigma}, \dots, dl_{\sigma^{-1}} X_r|_{\sigma}), \end{aligned} \quad (4)$$

and the result follows with equation (1). \square

2 Lie derivative

Proposition 2.1. *Let $X \in \mathfrak{X}(M)$ a smooth vector field on a differentiable manifold M . For each $m \in M$ there exists $a(m), b(m) \in \mathbb{R} \cup \{\pm\infty\}$, and a smooth curve*

$$\gamma_m : (a(m), b(m)) \rightarrow M \quad (5)$$

with

- (a) $0 \in (a(m), b(m))$ and $\gamma_m(0) = m$.
- (b) γ_m is an integral curve of X .
- (c) If $\mu : (c, d) \rightarrow M$ is a smooth curve satisfying conditions (a) and (b), then $(c, d) \subset (a(m), b(m))$ and $\mu = \gamma_m|_{(c, d)}$.

Proof. See [Warner, 1.48]. \square

Proposition 2.2. *Let $X \in \mathfrak{X}(M)$, $t \in \mathbb{R}$ and $\mathfrak{D}_t \equiv \{m \in M | t \in (a(m), b(m))\}$. Then $X_t : \mathfrak{D}_t \rightarrow \mathfrak{D}_{-t}, m \mapsto \gamma_m(t)$ is a diffeomorphism with inverse X_{-t} . Furthermore:*

- (a) *For each $m \in M$, there exist an open neighborhood V of m and $\epsilon > 0$, such that the map*

$$(-\epsilon, \epsilon) \times V \rightarrow M, (t, p) \mapsto X_t(p) \quad (6)$$

is $C^\infty((-\epsilon, \epsilon) \times V, M)$.

- (b) \mathfrak{D}_t is open for each $t \in \mathbb{R}$.
- (c) $\cup_{t>0} \mathfrak{D}_t = M$.
- (d) *Let $s, t \in \mathbb{R}$. Then the domain of $X_s \circ X_t$ is contained but generally not equal to \mathfrak{D}_{s+t} . However, the domain of $X_s \circ X_t$ is \mathfrak{D}_{s+t} in the case in which s and t both have the same sing. Moreover, on the domain of $X_s \circ X_t$ we have*

$$X_s \circ X_t = X_{s+t}. \quad (7)$$

Proof. See [Warner, 1.48]. \square

Definition 2.1. Let $X \in \mathfrak{X}(M)$ a smooth vector field on M with transformation X_t , let $Y \in \mathfrak{X}(M)$ another smooth vector field on M and let $m \in M$. The Lie derivative of Y with respect to X at m is defined by

$$(\mathcal{L}_X Y)|_m = \lim_{t \rightarrow 0} \frac{d_m X_{-t}(Y|_{X_t(m)}) - Y|_m}{t} = \frac{d}{dt} \Big|_{t=0} \left(d_m X_{-t}(Y|_{X_t(m)}) \right). \quad (8)$$

In a similar way we define the Lie derivative of a differential form $\omega \in \Omega^*(M)$ with respect to X at m by

$$(\mathcal{L}_X \omega)|_m = \lim_{t \rightarrow 0} \frac{(X_t^* \omega)|_m - \omega|_m}{t} = \frac{d}{dt} \Big|_{t=0} (X_t^* \omega)|_m. \quad (9)$$

Remark. The Lie derivative L_X can be extended to arbitrary tensor fields in the obvious way. See [Warner, 2.24].

Proposition 2.3. $L_X f = X(f)$ whenever $f \in C^\infty(M)$ and $X \in \mathfrak{X}(M)$.

Proof. Let $m \in M$, $f \in C^\infty(M) = \Omega^0(M)$ and $X \in \mathfrak{X}(M)$. Then

$$\begin{aligned} (L_X f)|_m &= \frac{d}{dt} \Big|_{t=0} (X_t^* f)|_m = \frac{d}{dt} \Big|_{t=0} (f \circ X_t)|_m \\ &= \frac{d}{dt} \Big|_{t=0} (f \circ \gamma_m(t)) = X|_m(f). \end{aligned} \quad (10)$$

□

Proposition 2.4. Let $X, Y \in \mathfrak{X}(M)$. Then

$$L_X Y = [X, Y]. \quad (11)$$

Proof. Let $X, Y \in \mathfrak{X}(M)$ with transformations X_t and Y_t respectively. We need to show that $(L_X Y)(f) = [X, Y](f)$ for each $f \in C^\infty(M)$. Let $m \in M$. Then

$$\begin{aligned} (L_X Y)|_m(f) &= \frac{d}{dt} \Big|_{t=0} \left(d_m X_{-t} (Y|_{X_t(m)})(f) \right) \\ &= \frac{d}{dt} \Big|_{t=0} \left(Y|_{X_t(m)} (f \circ X_{-t})|_m \right). \end{aligned} \quad (12)$$

Define a real-valued function H on a neighborhood of $(0, 0)$ in \mathbb{R}^2 by setting

$$H(t, u) = f(X_{-t}(Y_u(X_t(m)))). \quad (13)$$

Then by proposition 2.3 and

$$Y|_{X_t(m)} ((f \circ X_{-t})|_m) = \frac{\partial}{\partial r_2} \Big|_{(t,0)} H(t, u), \quad (14)$$

equation (12) becomes

$$(L_X Y)|_m(f) = \frac{\partial^2 H}{\partial r_1 \partial r_2} \Big|_{(0,0)}. \quad (15)$$

To evaluate this derivative, we set

$$K(t, u, s) = f(X_s(Y_u(X_t(m)))). \quad (16)$$

Then $H(t, u) = K(t, u, -t)$. It follows from the chain rule that

$$\frac{\partial^2 H}{\partial r_1 \partial r_2} \Big|_{(0,0)} = \frac{\partial^2 K}{\partial r_1 \partial r_2} \Big|_{(0,0,0)} - \frac{\partial^2 K}{\partial r_3 \partial r_2} \Big|_{(0,0,0)}. \quad (17)$$

Now, $K(t, u, 0) = f(Y_u(X_t(m)))$. Hence

$$\frac{\partial K}{\partial r_2} \Big|_{(0,0,0)} = Y|_{X_t(m)}(f), \quad (18)$$

$$\frac{\partial^2 K}{\partial r_1 \partial r_2} \Big|_{(0,0,0)} = X|_m(Y|_m f). \quad (19)$$

Also $K(0, u, s) = f(X_s(Y_u(m)))$. Hence

$$\frac{\partial K}{\partial r_3} \Big|_{(0,0,0)} = X|_m f(Y_u(m)), \quad (20)$$

$$\frac{\partial^2 K}{\partial r_2 \partial r_3} \Big|_{(0,0,0)} = Y|_m(X|_m f). \quad (21)$$

The proposition now follows from equation (15), (17), (19) and (21). \square

Lemma 2.1. $L_X : \Omega^*(M) \rightarrow \Omega^*(M)$ is a derivation of degree 0 which commutes with d for every $X \in \mathfrak{X}(M)$.

Proof. Let $X \in \mathfrak{X}(M)$, $\omega \in \Omega^u(M)$ and $\eta \in \Omega^s(M)$. Then

$$\begin{aligned} L_X(\omega \wedge \eta) &= \frac{d}{dt} \Big|_{t=0} (X_t^* (\omega \wedge \eta)) = \frac{d}{dt} \Big|_{t=0} ((X_t^* \omega) \wedge (X_t^* \eta)) \\ &= \left(\frac{d}{dt} \Big|_{t=0} (X_t^* \omega) \right) \wedge (X_t^* \eta) \Big|_{t=0} \\ &\quad + (X_t^* \omega) \Big|_{t=0} \wedge \left(\frac{d}{dt} \Big|_{t=0} (X_t^* \eta) \right) \\ &= \left(\frac{d}{dt} \Big|_{t=0} (X_t^* \omega) \right) \wedge \eta + \omega \wedge \left(\frac{d}{dt} \Big|_{t=0} (X_t^* \eta) \right) \\ &= L_X(\omega) \wedge \eta + \omega \wedge L_X(\eta) \end{aligned} \quad (22)$$

That shows the first part of the lemma. Hence we need only show that $L_X \circ d = d \circ L_X$ for all functions $f \in C^\infty(M)$ and 1-forms df :

$$\begin{aligned} (L_X \circ d)(f) &= (L_X)(df) = \frac{d}{dt} \Big|_{t=0} (X_t^* df) = \frac{d}{dt} \Big|_{t=0} (d(X_t^* f)) \\ &= \frac{d}{dt} \Big|_{t=0} (d(f \circ X_t)) = \frac{d}{dt} \Big|_{t=0} \left(\sum_i \frac{\partial}{\partial x^i} (f \circ X_t) dx^i \right) \\ &= \sum_i \frac{\partial}{\partial x^i} \left(\frac{d}{dt} \Big|_{t=0} (f \circ X_t) dx^i \right) = \sum_i \frac{\partial}{\partial x^i} L_X(f) dx^i \\ &= d(L_X(f)) = (d \circ L_X)(f), \end{aligned} \quad (23)$$

$$(L_X \circ d)(df) = L_X(d^2 f) = 0 = d^2(L_X(f)) = d(L_X(df)) = (d \circ L_X)(df). \quad (24)$$

\square

Lemma 2.2. *Every derivation D of $\Omega^*(M)$ of degree 0, which commutes with the exterior derivativ d , is equal to the Lie derivation L_X of a smooth vector field $X \in \mathfrak{X}(M)$ on M .*

Proof. Let D be a derivation of $\Omega^*(M)$ of degree 0, which commutes with d . Then D is a derivation of $C^\infty(M) = \Omega^0(M)$. Hence, there exist $X \in \mathfrak{X}(M)$ with $D(f) = X(f) = L_X(f)$ for all $f \in C^\infty(M)$. Let $D' = D - L_X$ and $\sum_i f_i dx^i \in \Omega^1(M)$. Then

$$\begin{aligned} D' \left(\sum_i f_i dx^i \right) &= \sum_i D' (f_i dx^i) = \sum_i D' (f_i) dx^i + f_i D' (dx^i) \\ &= \sum_i (D(f_i) - L_X(f_i)) dx^i + f_i d(D(x^i) - L_X(x^i)) \\ &= \sum_i (X(f_i) - L_X(f_i)) dx^i + f_i d(X(x^i) - L_X(x^i)) = 0. \end{aligned} \quad (25)$$

□

Proposition 2.5. *Let $X \in \mathfrak{X}(M)$. Then*

$$L_X = d \circ i_X + i_X \circ d. \quad (26)$$

Proof. Let $X \in \mathfrak{X}(M)$. $d \circ i_X + i_X \circ d$ is a derivation of degree 0, which commutes with d . With lemma 2.2, there exists $Y \in \mathfrak{X}(M)$ with

$$d \circ i_X + i_X \circ d = L_Y. \quad (27)$$

Let $f \in C^\infty(M)$. Then

$$Y(f) = (d \circ i_X + i_X \circ d)(f) = i_X \circ df = df(X) = X(f), \quad (28)$$

and therefore $X = Y$. □

Lemma 2.3. *Let $\omega \in \Omega^p(M)$ and $Y_0, \dots, Y_p \in \mathfrak{X}(M)$. Then*

$$\begin{aligned} L_{Y_0}(\omega(Y_1, \dots, Y_p)) &= (L_{Y_0}\omega)(Y_1, \dots, Y_p) \\ &+ \sum_{i=1}^p \omega(Y_1, \dots, Y_{i-1}, L_{Y_0}Y_i, Y_{i+1}, \dots, Y_p). \end{aligned} \quad (29)$$

Proof. Let $Y_0, \dots, Y_p \in \mathfrak{X}(M)$. Since the equation 29 is linear with respect to ω , it is enough to consider the case $\omega = g dx^{i_1} \wedge \dots \wedge dx^{i_p} \in \Omega^p(M)$. Then

$$\begin{aligned} L_{Y_0}(\omega(Y_1, \dots, Y_p)) &= Y_0 \left(g \det(Y_1(x^{i_j}), \dots, Y_p(x^{i_j}))_{1 \leq j \leq p} \right) \\ &= Y_0(g) \det(Y_1(x^{i_j}), \dots, Y_p(x^{i_j}))_{1 \leq j \leq p} \\ &+ g Y_0 \left(\det(Y_1(x^{i_j}), \dots, Y_p(x^{i_j}))_{1 \leq j \leq p} \right) \end{aligned} \quad (30)$$

$$\begin{aligned}
L_{Y_0}(\omega)(Y_1, \dots, Y_p) &= Y_0(g) \det(Y_1(x^{i_j}), \dots, Y_p(x^{i_j}))_{1 \leq j \leq p} \\
&+ \sum_{k=1}^p g \det(Y_1(x^{i_j}), \dots, Y_k(Y_0(x^{i_j})), \dots, Y_p(x^{i_j}))_{1 \leq j \leq p}
\end{aligned} \tag{31}$$

$$\begin{aligned}
&\omega(Y_1, \dots, L_{Y_0} Y_k, \dots, Y_p) \\
&= g \det(Y_1(x^{i_j}), \dots, Y_0(Y_k(x^{i_j})), \dots, Y_p(x^{i_j}))_{1 \leq j \leq p} \\
&- g \det(Y_1(x^{i_j}), \dots, Y_k(Y_0(x^{i_j})), \dots, Y_p(x^{i_j}))_{1 \leq j \leq p}
\end{aligned} \tag{32}$$

The lemma follows by combining equation (30), (31) and (32). \square

Proposition 2.6. *Let $\omega \in \Omega^p(M)$ and $Y_0, \dots, Y_p \in \mathfrak{X}(M)$. Then*

$$\begin{aligned}
d\omega(Y_0, \dots, Y_p) &= \sum_{i=0}^p (-1)^i \cdot Y_i \cdot \omega(Y_0, \dots, \hat{Y}_i, \dots, Y_p) \\
&+ \sum_{i < j} (-1)^{i+j} \cdot \omega([Y_i, Y_j], Y_0, \dots, \hat{Y}_i, \hat{Y}_j, \dots, Y_p).
\end{aligned} \tag{33}$$

Proof. We will proof this proposition by induction on p . For the case $p = 1$, we have from lemma 2.3

$$L_{Y_0}(\omega(Y_1)) = (L_{Y_0}\omega)(Y_1) + \omega([Y_0, Y_1]). \tag{34}$$

Applying lemma 2.3 and proposition 2.5 to (34), one obtains

$$\begin{aligned}
Y_0\omega(Y_1) &= ((i_{Y_0} \circ d + d \circ i_{Y_0})(\omega))(Y_1) + \omega([Y_0, Y_1]) \\
&= d\omega(Y_0, Y_1) + Y_1(\omega(Y_1)) + \omega([Y_0, Y_1]),
\end{aligned} \tag{35}$$

which is result (33) for the case $p = 1$. Now assume that (33) holds for $p - 1$. Then (33) is obtained for p by again starting with 2.3 and applying 2.5 and the induction hypothesis. \square

3 Differential ideals

Definition 3.1. Let \mathcal{D} be a p -dimensional smooth distribution on M .

A q -form ω is said to annihilate \mathcal{D} if for each $m \in M$ and $v_1, \dots, v_q \in \mathcal{D}(m)$

$$\omega|_m(v_1, \dots, v_q) = 0. \quad (36)$$

A form $\omega \in \Omega^*(M)$ is said to annihilate \mathcal{D} if each of the homogenous parts of ω annihilates \mathcal{D} . We let

$$\mathcal{I}(\mathcal{D}) = \{\omega \in \Omega^*(M) \mid \omega \text{ annihilates } \mathcal{D}\}. \quad (37)$$

Definition 3.2. A collection $\omega_1, \dots, \omega_n$ of 1-forms on M is called independent if they form an independent set in T_m^*M for each $m \in M$.

Proposition 3.1. Let \mathcal{D} be a smooth p -dimensional distribution on M . $\mathcal{I}(\mathcal{D})$ is an ideal in $\Omega^*(M)$.

Proof. The proposition follows from the definition of $\mathcal{I}(\mathcal{D})$ and the definition of multiplication in $\Omega^*(M)$. \square

Lemma 3.1. Let \mathcal{D} be a smooth p -dimensional distribution on M . $\mathcal{I}(\mathcal{D})$ is locally generated by $d - p$ independent 1-forms.

That is, to each $m \in M$ there corresponds a neighborhood U of m and a set of independent 1-forms $\omega_1, \dots, \omega_{d-p}$ on U such that:

- (i) If $\omega \in \mathcal{I}(\mathcal{D})$, then $\omega|_U$ belongs to the ideal in $\Omega^*(U)$ generated by $\omega_1, \dots, \omega_{d-p}$.
- (ii) If $\omega \in \Omega^*(M)$, and if there is a cover of M by sets U (as above) such that for each U in the cover, $\omega|_U$ belongs to the ideal generated by $\omega_1, \dots, \omega_{d-p}$, then $\omega \in \mathcal{I}(\mathcal{D})$.

Proof. Let $m \in M$. Since \mathcal{D} is smooth and p -dimensional, there exist smooth vector fields X_{d-p+1}, \dots, X_d defined and spanning \mathcal{D} at each point of a neighborhood of m . This collection can be completed to a collection X_1, \dots, X_d of smooth vector fields forming a basis of $T_m M$ for each n in a neighborhood U of m . Let $\omega_1, \dots, \omega_d$ be the dual 1-forms; that is,

$$\omega_i(X_j)(n) = \delta_{ij} \quad (38)$$

for each n in U . Then $\omega_1, \dots, \omega_{d-p}$ are the desired 1-forms on U . They are independent smooth 1-forms on U . If $\omega \in \mathcal{I}(\mathcal{D})$, $\omega|_U = \sum a_\Phi \omega_{i_1} \wedge \dots \wedge \omega_{i_r}$, where Φ runs over nonempty subsets $\{i_1, \dots, i_r\} \subset \{1, \dots, d\}$, and where the a_Φ must be identically zero unless $\{i_1, \dots, i_r\} \cap \{1, \dots, d-p\} = \emptyset$. Thus $\omega|_U$ belongs to the ideal in $\Omega^*(U)$ generated by $\omega_1, \dots, \omega_{d-p}$, then clearly $\omega \in \mathcal{I}(\mathcal{D})$. This proves the lemma. \square

Lemma 3.2. If $\mathcal{I} \subset \Omega^*(M)$ is an ideal locally generated by $d - p$ independent 1-forms, then there exists a unique smooth distribution \mathcal{D} of dimension p on M for which $\mathcal{I} = \mathcal{I}(\mathcal{D})$.

Proof. Let $m \in M$, and let the independent 1-forms $\omega_1, \dots, \omega_{d-p}$ generate \mathcal{I} on a neighborhood U . Define $\mathcal{D}(m)$ to be the subspace of T_m^*M whose annihilator is the subspace of T_m^*M spanned by the collection $\{\omega_i(m) \mid i \in \{1, \dots, d-p\}\}$. It follows that \mathcal{D} is a smooth p -dimensional distribution on M and that $\mathcal{I} = \mathcal{I}(\mathcal{D})$. Uniqueness of \mathcal{D} follows from the fact that $\mathcal{D} \neq \mathcal{D}_1$ implies $\mathcal{I}(\mathcal{D}) \neq \mathcal{I}(\mathcal{D}_1)$. \square

Definition 3.3. An ideal $\mathcal{I} \subset \Omega^*(M)$ is called a differential ideal if it is closed under exterior differentiation d ; that is,

$$d(\mathcal{I}) \subset \mathcal{I}. \quad (39)$$

Lemma 3.3. A smooth distribution \mathcal{D} on M is involutive if and only if the ideal $\mathcal{I}(\mathcal{D})$ is a differential ideal.

Proof. Let ω be a q -form in $\mathcal{I}(\mathcal{D})$, and let X_0, \dots, X_q be smooth vector fields lying in \mathcal{D} . Then proposition 2.6 together with the involutiveness of \mathcal{D} implies $d\omega(X_0, \dots, X_q) \equiv 0$. Hence $d\omega \in \mathcal{I}(\mathcal{D})$, and $\mathcal{I}(\mathcal{D})$ is a differential ideal. Conversely, suppose that $\mathcal{I}(\mathcal{D})$ is a differential ideal. Let Y_0 and Y_1 be vector fields lying in \mathcal{D} , and let $m \in M$. By proposition 3.1, there are independent 1-forms $\omega_1, \dots, \omega_{d-p}$ generating $\mathcal{I}(\mathcal{D})$ on a neighborhood U of m . Extend these forms to M by multiplying by a $C^\infty(M)$ function which is 1 on a neighborhood of m and has support in U . We shall denote the extended forms similarly by $\omega_1, \dots, \omega_{d-p}$. By 2.6,

$$\omega([Y_0, Y_1]) = -d\omega_i(Y_0, Y_1) + Y_0 \omega_i(Y_1) - Y_1 \omega_i(Y_0) \quad (40)$$

for $i \in \{1, \dots, d-p\}$. The right-hand side of (40) is identically zero on M since $\mathcal{I}(\mathcal{D})$ is a differential ideal and since $\omega_i \in \mathcal{I}(\mathcal{D})$. Thus $\omega_i([Y_0, Y_1])(m) = 0$ for $i \in \{1, \dots, d-p\}$. Now $\mathcal{D}(m)$ is the subspace of T_m^*M whose annihilator is the subspace of T_m^*M spanned by the collection $\{\omega_i(m) \mid i \in \{1, \dots, d-p\}\}$. Thus $[Y_0, Y_1](m) \in \mathcal{D}(m)$, and \mathcal{D} is involutive. \square

Definition 3.4. A submanifold (N, ψ) of M is an integral manifold of an ideal $\mathcal{I} \subset \Omega^*(M)$ if for every $\omega \in \mathcal{I}$, $\psi^* \omega \equiv 0$. A connected integral manifold of an ideal \mathcal{I} is maximal if its image is not a proper subset of the image of any other connected integral manifold of the ideal.

Theorem 3.1. Let $\mathcal{I} \subset \Omega^*(M)$ be a differential ideal locally generated by $d-p$ independent 1-forms. Let $m \in M$. Then there exists a unique maximal, connected, integral manifold of \mathcal{I} through m , and this integral manifold has dimension p .

Proof. Let $\mathcal{I} \subset \Omega^*(M)$ be a differential ideal locally generated by $d-p$ independent 1-forms. By lemma 3.2, there exists a unique smooth distribution \mathcal{D} of dimension p on M for which $\mathcal{I} = \mathcal{I}(\mathcal{D})$. Hence, by lemma 3.3, the distribution \mathcal{D} is involutive. Let $m \in M$. By theorem [Warner, 1.64] there exist a unique maximal connected integral manifold (N, ψ) of \mathcal{D} passing through m . Then

$$d\psi(T_n N) = \mathcal{D}(\psi(n)) \quad \text{for each } n \in N. \quad (41)$$

This implies

$$0 = \omega(d_n \psi(v)) = (\psi^* \omega)|_n(v) \quad (42)$$

for every $n \in N$, $\omega \in \mathcal{I} = \mathcal{I}(\mathcal{D})$ and $v \in T_n N$. Therefore, (N, ψ) is a unique maximal, connected, integral manifold of \mathcal{I} through m with dimension p . \square

Proposition 3.2. *Let N^c and M^d be differentiable manifolds, and let π_1 and π_2 be the canonical projections of $N \times M$ onto N and M respectively. Suppose that there exists a basis $\{w_i \in \Omega^1(M) \mid i \in \{1, \dots, d\}\}$ for the 1-forms on M .*

(a) *If $f : N \rightarrow M$ is $C^\infty(M, N)$, then the graph of f is an integral manifold of the ideal of forms on $N \times M$ generated by*

$$\{\pi_1^* f^* \omega_i - \pi_2^* \omega_i \mid i \in \{1, \dots, d\}\}. \quad (43)$$

(b) *If $\{\alpha_i \in \Omega^1(M) \mid i \in \{1, \dots, d\}\}$ are 1-forms on N , and if the ideal of forms on $N \times M$ generated by*

$$\{\pi_1^* \alpha_i - \pi_2^* \omega_i \mid i \in \{1, \dots, d\}\} \quad (44)$$

is a differential ideal, then given $n_0 \in N$ and $m_0 \in M$ there exists a neighborhood U of n_0 and a $C^\infty(U, M)$ map $f : U \rightarrow M$ such that $f(n_0) = m_0$ and such that

$$f^* \omega_i = \alpha_i|_U \quad (45)$$

for all $i \in \{1, \dots, d\}$. Moreover, if U is any connected open set containing n_0 for which there exist a $C^\infty(U, M)$ map $f : U \rightarrow M$ satisfying both $f(n_0) = m_0$ and equation (45), then there exists a unique such map on U .

Proof. Part (a): For each i , we define a form μ_i on $N \times M$ by setting

$$\mu_i = \pi_1^* f^* \omega_i - \pi_2^* \omega_i. \quad (46)$$

Let \mathcal{I} the ideal in $\Omega^*(N \times M)$ generated by the μ_i . Now the graph of f is the submanifold (N, g) of $N \times M$ where

$$g(n) = (n, f(n)). \quad (47)$$

We claim that the graph is an integral manifold of the ideal \mathcal{I} . For this, it suffices to show that $g^* \mu_i = 0$ for each i . Now, $\pi_1 \circ g = \text{id}$, and $\pi_2 \circ g = f$, and thus it follows that

$$g^* \mu_i = (\pi_1 \circ g)^* f^* \omega_i - (\pi_2 \circ g)^* \omega_i = f^* \omega_i - f^* \omega_i = 0. \quad (48)$$

Part (b): Let us define forms μ_i on $N \times M$ by setting

$$\mu_i = \pi_1^* \alpha_i - \pi_2^* \omega_i, \quad (49)$$

and we let \mathcal{I} the ideal in $\Omega^*(N \times M)$ which they generate. Let $(n_0, m_0) \in N \times M$. Then since \mathcal{I} is locally generated by d independent 1-forms, the Frobenius theorem 3.1 guarantees that there is a maximal, connected, integral manifold I of \mathcal{I} of dimension c through (n_0, m_0) . Let $q \in I$ and $v \in T_p I$ with $d|_p \pi_1(v) = 0$. Then since $\mu_i = 0$, it follows from equation (49) that $\omega_i(d|_p(v)) = 0$ for $i \in \{1, \dots, d\}$; and this implies that $d|_p \pi_2(v) = 0$ and therefore $v = 0$. Hence $d|_p \pi_1|_{I_q}$ is one-to-one. Thus $\pi_1|_I : I \rightarrow N$ is locally a diffeomorphism. So there exist neighborhoods V of (n_0, m_0) in I and U of n_0 such that $\pi_1|_V : V \rightarrow U$ is a diffeomorphism. We define $f : U \rightarrow M$ by setting

$$f = \pi_2 \circ (\pi_1|_V)^{-1}. \quad (50)$$

Then $f(n_0) = m_0$ and the graph of f is an open submanifold of I . Moreover,

$$\begin{aligned} 0 &= \mu_i(d|_q(\pi_1|_V)^{-1}(v)) \\ &= \alpha_i(v) - \omega_i(d|_{(\pi_1|_V)^{-1}(q)} \pi_2 \circ d|_q(\pi_1|_V)^{-1}(v)) \\ &= \alpha_i(v) - f^* \omega_i(v), \end{aligned} \quad (51)$$

which shows $f^* \omega_i = \alpha_i$. If U is a connected open neighborhood of n_0 in N for which there exist such f , then there is a unique such map on U . For let \tilde{f} be any other such map. Let (U, \tilde{g}) and (U, g) be the graphs of \tilde{f} and f over U respectively. Thus

$$\tilde{g}(n) = (n, \tilde{f}(n)) \quad \text{and} \quad g(n) = (n, f(n)) \quad (52)$$

for $n \in U$. By (a), not only is (U, g) an integral manifold of \mathcal{I} through (n_0, m_0) , but so is (U, \tilde{g}) . Now, the subset of U on which g and \tilde{g} agree is non-empty since it contains n_0 , and is closed by continuity, and is moreover open. Then it follows from the uniqueness of integral manifolds that there exist sufficiently small neighborhoods W and \tilde{W} of n so that

$$g(W) = g(\tilde{W}). \quad (53)$$

It follows from equation (52) that $W = \tilde{W}$. Hence, since U is connected, $g = \tilde{g}$ on U , which implies that $f = \tilde{f}$ on U . This proves uniqueness. \square