

Repast HPC
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Contents

1	Repast HPC: A High-Performance Agent-Based Modeling Platform	1
1.1	What is Repast HPC?	1
2	Deprecated List	3
3	Hierarchical Index	5
3.1	Class Hierarchy	5
4	Class Index	9
4.1	Class List	9
5	Class Documentation	15
5.1	repast::AbstractExporter Class Reference	15
5.1.1	Detailed Description	16
5.1.2	Member Function Documentation	16
5.1.2.1	incorporateAgentExporterInfo	16
5.2	repast::AbstractImporter Class Reference	17
5.2.1	Detailed Description	17
5.2.2	Member Function Documentation	17
5.2.2.1	registerOutgoingRequests	17
5.3	repast::AbstractImporterExporter Class Reference	18
5.3.1	Detailed Description	19
5.3.2	Member Function Documentation	19
5.3.2.1	exchangeAgentStatusUpdates	19
5.3.2.2	version	19
5.4	repast::Agent Class Reference	19
5.4.1	Detailed Description	19
5.4.2	Member Function Documentation	20
5.4.2.1	getId	20
5.4.2.2	getId	20
5.5	repast::AgentExporterData Class Reference	20
5.5.1	Detailed Description	20
5.5.2	Member Function Documentation	21

5.5.2.1	selectSet	21
5.6	repast::AgentFromGridPoint< T, GPType > Struct Template Reference	21
5.6.1	Detailed Description	21
5.7	repast::AgentHashId< AgentType > Struct Template Reference	21
5.7.1	Detailed Description	22
5.8	repast::AgentId Class Reference	22
5.8.1	Detailed Description	22
5.8.2	Constructor & Destructor Documentation	23
5.8.2.1	AgentId	23
5.8.3	Member Function Documentation	23
5.8.3.1	agentType	23
5.8.3.2	currentRank	23
5.8.3.3	currentRank	23
5.8.3.4	hashcode	23
5.8.3.5	id	24
5.8.3.6	startingRank	24
5.9	repast::AgentRequest Class Reference	24
5.9.1	Detailed Description	25
5.9.2	Constructor & Destructor Documentation	25
5.9.2.1	AgentRequest	25
5.9.2.2	AgentRequest	26
5.9.3	Member Function Documentation	26
5.9.3.1	addAll	26
5.9.3.2	addAllCancellations	26
5.9.3.3	addAllRequests	26
5.9.3.4	addCancellation	26
5.9.3.5	addRequest	26
5.9.3.6	cancellations	27
5.9.3.7	contains	27
5.9.3.8	containsInCancellations	27
5.9.3.9	containsInRequests	27
5.9.3.10	remove	27
5.9.3.11	removeCancellation	28
5.9.3.12	removeRequest	28
5.9.3.13	requestCount	28
5.9.3.14	requestCountCancellations	28
5.9.3.15	requestCountRequested	29
5.9.3.16	requestedAgents	29
5.9.3.17	sourceProcess	29
5.9.3.18	targetProcess	29

5.9.3.19	targets	29
5.9.3.20	targetsOfCancellations	29
5.9.3.21	targetsOfRequests	29
5.10	repast::AgentStateFilter< T > Struct Template Reference	30
5.10.1	Detailed Description	30
5.11	repast::AgentStatus Class Reference	30
5.11.1	Detailed Description	31
5.11.2	Constructor & Destructor Documentation	31
5.11.2.1	AgentStatus	31
5.11.2.2	AgentStatus	31
5.11.3	Member Function Documentation	31
5.11.3.1	getId	31
5.11.3.2	getNewId	32
5.11.3.3	getOldId	32
5.11.3.4	getStatus	32
5.12	Appender Class Reference	32
5.13	AppenderBuilder Class Reference	33
5.14	repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType > Class Template Reference	33
5.14.1	Detailed Description	35
5.14.2	Constructor & Destructor Documentation	35
5.14.2.1	BaseGrid	35
5.14.3	Member Function Documentation	36
5.14.3.1	begin	36
5.14.3.2	contains	36
5.14.3.3	dimensions	36
5.14.3.4	end	36
5.14.3.5	getAgentsToPush	37
5.14.3.6	getDisplacement	37
5.14.3.7	getDistance	37
5.14.3.8	getDistanceSq	37
5.14.3.9	getLocation	38
5.14.3.10	getLocation	38
5.14.3.11	getObjectAt	38
5.14.3.12	getObjectsAt	39
5.14.3.13	isPeriodic	39
5.14.3.14	moveByDisplacement	39
5.14.3.15	moveTo	39
5.14.3.16	moveTo	40
5.14.3.17	moveTo	40
5.14.3.18	moveTo	40

5.14.3.19 size	41
5.14.3.20 transform	41
5.14.3.21 translate	41
5.15 repast::BaseValueLayer Class Reference	42
5.15.1 Detailed Description	42
5.15.2 Member Function Documentation	42
5.15.2.1 name	42
5.16 repast::Borders Class Reference	42
5.16.1 Detailed Description	43
5.17 repast::CartTopology Class Reference	43
5.17.1 Detailed Description	44
5.18 repast::CellContents< AgentContent, GPType > Class Template Reference	44
5.18.1 Detailed Description	44
5.19 CerrAppender Class Reference	44
5.20 ConfigLexer Class Reference	45
5.21 repast::Context< T > Class Template Reference	45
5.21.1 Detailed Description	48
5.21.2 Member Function Documentation	48
5.21.2.1 addAgent	48
5.21.2.2 addProjection	49
5.21.2.3 addValueLayer	49
5.21.2.4 begin	49
5.21.2.5 byTypeBegin	49
5.21.2.6 byTypeEnd	49
5.21.2.7 byTypeFilteredBegin	50
5.21.2.8 byTypeFilteredEnd	50
5.21.2.9 end	51
5.21.2.10 filteredBegin	51
5.21.2.11 filteredEnd	51
5.21.2.12 getAgent	52
5.21.2.13 getContinuousValueLayer	53
5.21.2.14 getDiscreteValueLayer	53
5.21.2.15 getProjection	53
5.21.2.16 getProjectionInfo	54
5.21.2.17 getRandomAgents	54
5.21.2.18 removeAgent	55
5.21.2.19 selectAgents	55
5.21.2.20 selectAgents	55
5.21.2.21 selectAgents	55
5.21.2.22 selectAgents	56

5.21.2.23 selectAgents	56
5.21.2.24 selectAgents	56
5.21.2.25 selectAgents	57
5.21.2.26 selectAgents	57
5.21.2.27 selectAgents	57
5.21.2.28 selectAgents	59
5.21.2.29 selectAgents	59
5.21.2.30 selectAgents	60
5.21.2.31 selectAgents	60
5.21.2.32 selectAgents	61
5.21.2.33 selectAgents	61
5.21.2.34 selectAgents	62
5.21.2.35 setProjectionInfo	62
5.22 repast::ContinuousValueLayer< ValueType, Borders > Class Template Reference	62
5.22.1 Detailed Description	63
5.22.2 Constructor & Destructor Documentation	63
5.22.2.1 ContinuousValueLayer	63
5.22.3 Member Function Documentation	63
5.22.3.1 get	64
5.22.3.2 set	64
5.23 CoutAppender Class Reference	64
5.24 repast::data_type_traits< T > Struct Template Reference	64
5.24.1 Detailed Description	65
5.25 repast::data_type_traits< double > Struct Template Reference	65
5.25.1 Detailed Description	65
5.26 repast::data_type_traits< int > Struct Template Reference	65
5.26.1 Detailed Description	65
5.27 repast::DataSet Class Reference	66
5.27.1 Detailed Description	66
5.28 repast::DefaultNumberGenerator< T > Class Template Reference	66
5.28.1 Detailed Description	67
5.29 repast::DenseMatrix< T > Class Template Reference	67
5.29.1 Detailed Description	67
5.30 repast::DirectedVertex< V, E > Class Template Reference	67
5.30.1 Detailed Description	68
5.30.2 Member Function Documentation	68
5.30.2.1 addEdge	68
5.30.2.2 adjacent	69
5.30.2.3 edges	69
5.30.2.4 findEdge	69

5.30.2.5	inDegree	69
5.30.2.6	outDegree	70
5.30.2.7	predecessors	70
5.30.2.8	removeEdge	70
5.30.2.9	successors	70
5.31	repast::DiscreteValueLayer< ValueType, Borders > Class Template Reference	70
5.31.1	Detailed Description	71
5.31.2	Constructor & Destructor Documentation	71
5.31.2.1	DiscreteValueLayer	71
5.31.3	Member Function Documentation	71
5.31.3.1	get	72
5.31.3.2	set	72
5.32	repast::DoubleVariable Class Reference	72
5.32.1	Detailed Description	73
5.32.2	Member Function Documentation	73
5.32.2.1	insert	73
5.32.2.2	insert	73
5.32.2.3	write	73
5.33	repast::EdgeExporter< E > Class Template Reference	73
5.33.1	Detailed Description	74
5.33.2	Member Function Documentation	74
5.33.2.1	gatherReceivers	74
5.33.2.2	sendExportRequests	75
5.33.3	Friends And Related Function Documentation	75
5.33.3.1	createComplementaryEdges	75
5.34	repast::EventCompare Class Reference	75
5.34.1	Detailed Description	76
5.35	repast::Exporter_LIST Class Reference	76
5.35.1	Detailed Description	76
5.36	repast::Exporter_SET Class Reference	76
5.36.1	Detailed Description	77
5.37	repast::ExportRequest Class Reference	77
5.37.1	Detailed Description	77
5.38	repast::ExtractPtrs< T > Struct Template Reference	78
5.38.1	Detailed Description	78
5.39	repast::Functor Class Reference	78
5.39.1	Detailed Description	78
5.40	repast::Graph< V, E, Ec, EcM > Class Template Reference	79
5.40.1	Detailed Description	81
5.40.2	Constructor & Destructor Documentation	81

5.40.2.1	Graph	81
5.40.3	Member Function Documentation	81
5.40.3.1	addEdge	81
5.40.3.2	addEdge	82
5.40.3.3	adjacent	82
5.40.3.4	edgeCount	82
5.40.3.5	findEdge	82
5.40.3.6	getAgentStatusExchangePartners	83
5.40.3.7	getAgentsToPush	83
5.40.3.8	getInfoExchangePartners	83
5.40.3.9	inDegree	83
5.40.3.10	keepsAgentsOnSyncProj	83
5.40.3.11	outDegree	84
5.40.3.12	predecessors	84
5.40.3.13	removeEdge	84
5.40.3.14	removeEdge	84
5.40.3.15	sendsSecondaryAgentsOnStatusExchange	84
5.40.3.16	successors	85
5.40.3.17	vertexCount	85
5.40.3.18	verticesBegin	85
5.40.3.19	verticesEnd	85
5.41	repast::Grid< T, GPType > Class Template Reference	86
5.41.1	Detailed Description	87
5.41.2	Constructor & Destructor Documentation	87
5.41.2.1	Grid	87
5.41.3	Member Function Documentation	87
5.41.3.1	contains	87
5.41.3.2	dimensions	88
5.41.3.3	getAgentStatusExchangePartners	88
5.41.3.4	getAgentsToPush	88
5.41.3.5	getDisplacement	89
5.41.3.6	getDistance	89
5.41.3.7	getDistanceSq	89
5.41.3.8	getInfoExchangePartners	89
5.41.3.9	getLocation	90
5.41.3.10	getLocation	90
5.41.3.11	getObjectAt	90
5.41.3.12	getObjectsAt	91
5.41.3.13	getRequiredAgents	91
5.41.3.14	isPeriodic	91

5.41.3.15 keepsAgentsOnSyncProj	91
5.41.3.16 moveByDisplacement	92
5.41.3.17 moveByVector	92
5.41.3.18 moveTo	93
5.41.3.19 sendsSecondaryAgentsOnStatusExchange	93
5.41.3.20 transform	93
5.41.3.21 translate	94
5.42 repast::Grid2DQuery< T > Class Template Reference	94
5.42.1 Detailed Description	95
5.42.2 Member Function Documentation	95
5.42.2.1 query	95
5.43 repast::GridBufferSyncher< T, GPType > Class Template Reference	95
5.43.1 Detailed Description	95
5.44 repast::GridDimensions Class Reference	96
5.44.1 Detailed Description	96
5.45 repast::GridMovePacket< PtType > Struct Template Reference	96
5.45.1 Detailed Description	97
5.46 repast::GridMovePackets< PtType > Class Template Reference	97
5.46.1 Detailed Description	97
5.47 repast::GridPointHolder< T, GPType > Struct Template Reference	97
5.47.1 Detailed Description	98
5.48 repast::HashGridPoint< T > Struct Template Reference	98
5.48.1 Detailed Description	98
5.49 repast::HashId Struct Reference	98
5.49.1 Detailed Description	98
5.50 repast::HashVertex< V, E > Struct Template Reference	99
5.50.1 Detailed Description	99
5.51 repast::Importer_COUNT Class Reference	99
5.51.1 Detailed Description	100
5.51.2 Member Function Documentation	100
5.51.2.1 registerOutgoingRequests	100
5.52 repast::Importer_LIST Class Reference	100
5.52.1 Detailed Description	101
5.52.2 Member Function Documentation	101
5.52.2.1 registerOutgoingRequests	101
5.53 repast::Importer_MAP_int Class Reference	101
5.53.1 Detailed Description	102
5.53.2 Member Function Documentation	102
5.53.2.1 registerOutgoingRequests	102
5.54 repast::Importer_SET Class Reference	102

5.54.1 Detailed Description	103
5.54.2 Member Function Documentation	103
5.54.2.1 registerOutgoingRequests	103
5.55 repast::ImporterExporter_BY_SET Class Reference	103
5.55.1 Detailed Description	104
5.55.2 Member Function Documentation	104
5.55.2.1 version	104
5.56 repast::ImporterExporter_COUNT_LIST Class Reference	105
5.56.1 Detailed Description	105
5.56.2 Member Function Documentation	105
5.56.2.1 version	105
5.57 repast::ImporterExporter_COUNT_SET Class Reference	105
5.57.1 Detailed Description	106
5.57.2 Member Function Documentation	106
5.57.2.1 version	106
5.58 repast::ImporterExporter_LIST Class Reference	106
5.58.1 Detailed Description	107
5.58.2 Member Function Documentation	107
5.58.2.1 version	107
5.59 repast::ImporterExporter_MAP_int Class Reference	107
5.59.1 Detailed Description	108
5.59.2 Member Function Documentation	108
5.59.2.1 version	108
5.60 repast::ImporterExporter_SET Class Reference	108
5.60.1 Detailed Description	108
5.60.2 Member Function Documentation	108
5.60.2.1 version	109
5.61 repast::IntVariable Class Reference	109
5.61.1 Detailed Description	109
5.61.2 Member Function Documentation	109
5.61.2.1 insert	109
5.61.2.2 insert	110
5.61.2.3 write	111
5.62 repast::IsAgentType< T > Struct Template Reference	111
5.62.1 Detailed Description	111
5.63 repast::IsLocalAgent< T > Struct Template Reference	111
5.63.1 Detailed Description	112
5.64 repast::IsNotType< T > Struct Template Reference	112
5.64.1 Detailed Description	112
5.65 repast::ItemReceipt< E > Class Template Reference	112

5.65.1 Detailed Description	113
5.66 repast::KEBuilder< V, E, Ec, EcM > Class Template Reference	113
5.66.1 Detailed Description	113
5.66.2 Member Function Documentation	113
5.66.2.1 build	113
5.67 repast::KeyGetter Struct Reference	114
5.67.1 Detailed Description	114
5.68 Log4CL Class Reference	114
5.69 Log4CLConfigurator Class Reference	115
5.70 Logger Class Reference	115
5.71 repast::Matrix< T > Class Template Reference	115
5.71.1 Detailed Description	116
5.71.2 Constructor & Destructor Documentation	116
5.71.2.1 Matrix	116
5.71.3 Member Function Documentation	116
5.71.3.1 shape	116
5.72 repast::MethodFunctor< T > Class Template Reference	117
5.72.1 Detailed Description	117
5.73 repast::Moore2DGridQuery< T > Class Template Reference	117
5.73.1 Detailed Description	118
5.73.2 Member Function Documentation	118
5.73.2.1 query	118
5.74 repast::MultipleOccupancy< T, GPType > Class Template Reference	118
5.74.1 Detailed Description	119
5.74.2 Member Function Documentation	119
5.74.2.1 get	119
5.74.2.2 getAll	119
5.74.2.3 put	119
5.74.2.4 remove	119
5.75 repast::NCDataSet Class Reference	120
5.75.1 Detailed Description	120
5.76 repast::NCDataSetBuilder Class Reference	120
5.76.1 Detailed Description	121
5.76.2 Constructor & Destructor Documentation	121
5.76.2.1 NCDataSetBuilder	121
5.76.3 Member Function Documentation	121
5.76.3.1 addDataSource	121
5.76.3.2 createDataSet	121
5.77 repast::NCDataSource Class Reference	122
5.77.1 Detailed Description	122

5.78	repast::NCReducibleDataSource< Op, T > Class Template Reference	122
5.78.1	Detailed Description	123
5.79	repast::NcTypeTrait< T > Struct Template Reference	123
5.79.1	Detailed Description	123
5.80	repast::NcTypeTrait< double > Struct Template Reference	123
5.80.1	Detailed Description	123
5.81	repast::NcTypeTrait< int > Struct Template Reference	124
5.81.1	Detailed Description	124
5.82	repast::Neighbor Class Reference	124
5.82.1	Detailed Description	124
5.83	repast::Neighbors Class Reference	124
5.83.1	Detailed Description	125
5.83.2	Member Function Documentation	125
5.83.2.1	findNeighbor	125
5.83.2.2	findNeighbor	125
5.83.2.3	neighbor	125
5.84	repast::NodeGetter< V, E > Struct Template Reference	126
5.84.1	Detailed Description	126
5.85	repast::NumberGenerator Class Reference	126
5.85.1	Detailed Description	127
5.86	repast::OneTimeEvent Class Reference	127
5.86.1	Detailed Description	127
5.87	repast::Point< T > Class Template Reference	127
5.87.1	Detailed Description	128
5.87.2	Constructor & Destructor Documentation	129
5.87.2.1	Point	129
5.87.2.2	Point	129
5.87.2.3	Point	129
5.87.2.4	Point	129
5.87.3	Member Function Documentation	129
5.87.3.1	add	129
5.87.3.2	begin	129
5.87.3.3	coords	130
5.87.3.4	copy	130
5.87.3.5	dimensionCount	130
5.87.3.6	end	130
5.87.3.7	getCoordinate	130
5.87.3.8	getX	131
5.87.3.9	getY	131
5.87.3.10	getZ	131

5.87.3.11 operator[]	131
5.87.3.12 operator[]	131
5.88 repast::Problem Class Reference	132
5.88.1 Detailed Description	132
5.89 repast::Projection< T > Class Template Reference	132
5.89.1 Detailed Description	134
5.89.2 Constructor & Destructor Documentation	134
5.89.2.1 Projection	134
5.89.3 Member Function Documentation	134
5.89.3.1 addFilterVal	134
5.89.3.2 agentCanBeAdded	134
5.89.3.3 getAgentStatusExchangePartners	134
5.89.3.4 getAgentsToPush	135
5.89.3.5 getInfoExchangePartners	135
5.89.3.6 getRequiredAgents	135
5.89.3.7 keepsAgentsOnSyncProj	135
5.89.3.8 removeFilterVal	136
5.89.3.9 sendsSecondaryAgentsOnStatusExchange	136
5.90 repast::ProjectionInfoPacket Class Reference	136
5.90.1 Detailed Description	137
5.91 repast::Properties Class Reference	137
5.91.1 Detailed Description	138
5.91.2 Constructor & Destructor Documentation	138
5.91.2.1 Properties	138
5.91.2.2 Properties	139
5.91.2.3 Properties	139
5.91.3 Member Function Documentation	139
5.91.3.1 contains	139
5.91.3.2 getProperty	139
5.91.3.3 keys_begin	139
5.91.3.4 keys_end	140
5.91.3.5 log	140
5.91.3.6 processCommandLineArguments	140
5.91.3.7 putProperty	140
5.91.3.8 putProperty	140
5.91.3.9 readFile	141
5.91.3.10 size	141
5.91.3.11 writeToSVFile	141
5.91.3.12 writeToSVFile	141
5.92 repast::Random Class Reference	141

5.92.1 Detailed Description	142
5.92.2 Member Function Documentation	142
5.92.2.1 createCauchyGenerator	142
5.92.2.2 createExponentialGenerator	143
5.92.2.3 createNormalGenerator	143
5.92.2.4 createTriangleGenerator	143
5.92.2.5 createUniDoubleGenerator	143
5.92.2.6 createUniIntGenerator	144
5.92.2.7 engine	144
5.92.2.8 getGenerator	144
5.92.2.9 initialize	144
5.92.2.10 nextDouble	144
5.92.2.11 putGenerator	144
5.92.2.12 seed	145
5.93 repast::RandomAccess< I > Class Template Reference	145
5.93.1 Detailed Description	145
5.93.2 Constructor & Destructor Documentation	146
5.93.2.1 RandomAccess	146
5.93.3 Member Function Documentation	146
5.93.3.1 get	146
5.94 repast::ReducibleDataSource< Op, T > Class Template Reference	146
5.94.1 Detailed Description	147
5.95 repast::RepastEdge< V > Class Template Reference	147
5.95.1 Detailed Description	148
5.95.2 Constructor & Destructor Documentation	149
5.95.2.1 RepastEdge	149
5.95.2.2 RepastEdge	149
5.95.2.3 RepastEdge	149
5.95.2.4 RepastEdge	149
5.95.3 Member Function Documentation	149
5.95.3.1 source	149
5.95.3.2 target	150
5.95.3.3 weight	150
5.96 repast::RepastEdgeContent< V > Struct Template Reference	150
5.96.1 Detailed Description	150
5.97 repast::RepastEdgeContentManager< V > Class Template Reference	151
5.97.1 Detailed Description	151
5.98 repast::RepastEvent Class Reference	151
5.98.1 Detailed Description	151
5.99 repast::RepastProcess Class Reference	152

5.99.1 Detailed Description	153
5.99.2 Member Function Documentation	153
5.99.2.1 addExportedAgent	153
5.99.2.2 addImportedAgent	153
5.99.2.3 agentRemoved	153
5.99.2.4 done	153
5.99.2.5 getScheduleRunner	154
5.99.2.6 init	154
5.99.2.7 instance	154
5.99.2.8 moveAgent	154
5.99.2.9 rank	154
5.99.2.10 requestAgents	154
5.99.2.11 synchronizeAgentStates	156
5.99.2.12 synchronizeAgentStatus	156
5.100repast::RepeatingEvent Class Reference	156
5.100.1 Detailed Description	157
5.101repast::Request_Packet< Content > Class Template Reference	157
5.101.1 Detailed Description	158
5.102RollingFileAppender Class Reference	158
5.103repast::Schedule Class Reference	158
5.103.1 Detailed Description	159
5.103.2 Member Function Documentation	159
5.103.2.1 getCurrentTick	159
5.103.2.2 getNextTick	159
5.103.2.3 schedule_event	159
5.103.2.4 schedule_event	159
5.104repast::ScheduledEvent Class Reference	160
5.104.1 Detailed Description	160
5.105repast::ScheduleRunner Class Reference	161
5.105.1 Detailed Description	161
5.105.2 Member Function Documentation	161
5.105.2.1 currentTick	161
5.105.2.2 schedule	162
5.105.2.3 scheduleEndEvent	162
5.105.2.4 scheduleEvent	162
5.105.2.5 scheduleEvent	162
5.105.2.6 scheduleStop	162
5.106repast::SecondElement< T > Struct Template Reference	163
5.106.1 Detailed Description	163
5.107repast::SharedBaseGrid< T, GPTransformer, Adder, GPType > Class Template Reference	163

5.107.1 Detailed Description	165
5.107.2 Constructor & Destructor Documentation	165
5.107.2.1 SharedBaseGrid	165
5.107.3 Member Function Documentation	165
5.107.3.1 bounds	165
5.107.3.2 dimensions	165
5.107.3.3 getAgentStatusExchangePartners	166
5.107.3.4 getAgentsToPush	166
5.107.3.5 getInfoExchangePartners	166
5.107.3.6 initSynchBuffer	166
5.107.3.7 moveTo	167
5.107.3.8 moveTo	167
5.107.3.9 synchMove	167
5.108repast::SharedContext< T > Class Template Reference	167
5.108.1 Detailed Description	171
5.108.2 Member Function Documentation	171
5.108.2.1 addProjection	171
5.108.2.2 begin	171
5.108.2.3 byTypeBegin	171
5.108.2.4 byTypeEnd	172
5.108.2.5 byTypeFilteredBegin	173
5.108.2.6 byTypeFilteredEnd	173
5.108.2.7 decrementProjRefCount	173
5.108.2.8 end	173
5.108.2.9 filteredBegin	174
5.108.2.10filteredEnd	174
5.108.2.11importedAgentRemoved	174
5.108.2.12ncrementProjRefCount	174
5.108.2.13keepsAgentsOnSyncProj	175
5.108.2.14ocalBegin	175
5.108.2.15ocalEnd	175
5.108.2.16removeAgent	175
5.108.2.17removeAgent	175
5.108.2.18selectAgents	175
5.108.2.19selectAgents	176
5.108.2.20selectAgents	176
5.108.2.21selectAgents	177
5.108.2.22selectAgents	177
5.108.2.23selectAgents	177
5.108.2.24selectAgents	178

5.108.2.25	selectAgents	178
5.108.2.26	selectAgents	179
5.108.2.27	selectAgents	179
5.108.2.28	selectAgents	180
5.108.2.29	selectAgents	180
5.108.2.30	selectAgents	181
5.108.2.31	selectAgents	181
5.108.2.32	selectAgents	182
5.108.2.33	selectAgents	182
5.109	repast::SharedContinuousSpace< T, GPTransformer, Adder > Class Template Reference	183
5.109.1	Detailed Description	184
5.109.2	Member Function Documentation	184
5.109.2.1	synchBuffer	184
5.110	repast::SharedDiscreteSpace< T, GPTransformer, Adder > Class Template Reference	185
5.110.1	Detailed Description	185
5.110.2	Member Function Documentation	186
5.110.2.1	getAgentsToPush	186
5.110.2.2	synchBuffer	186
5.111	repast::SharedNetwork< V, E, Ec, EcM > Class Template Reference	186
5.111.1	Detailed Description	187
5.111.2	Constructor & Destructor Documentation	188
5.111.2.1	SharedNetwork	188
5.111.3	Member Function Documentation	188
5.111.3.1	addEdge	188
5.111.3.2	addSender	188
5.111.3.3	isMaster	188
5.111.3.4	removeEdge	188
5.111.4	Friends And Related Function Documentation	189
5.111.4.1	createComplementaryEdges	189
5.111.4.2	synchEdges	189
5.112	repast::SharedSpaces< T > Struct Template Reference	190
5.112.1	Detailed Description	190
5.112.2	Member Typedef Documentation	190
5.112.2.1	SharedStrictContinuousSpace	190
5.112.2.2	SharedStrictDiscreteSpace	191
5.112.2.3	SharedWrappedContinuousSpace	191
5.112.2.4	SharedWrappedDiscreteSpace	191
5.113	repast::SimpleAdder< T > Class Template Reference	191
5.113.1	Detailed Description	191
5.114	repast::SingleOccupancy< T, GPType > Class Template Reference	191

5.114.1 Detailed Description	192
5.114.2 Member Function Documentation	192
5.114.2.1 get	192
5.114.2.2 getAll	192
5.114.2.3 put	192
5.114.2.4 remove	193
5.115repast::Spaces< T > Struct Template Reference	193
5.115.1 Detailed Description	194
5.116repast::SparseMatrix< T > Class Template Reference	194
5.116.1 Detailed Description	194
5.117repast::SpecializedProjectionInfoPacket< Datum > Class Template Reference	195
5.117.1 Detailed Description	195
5.118SRManager Class Reference	195
5.118.1 Detailed Description	196
5.118.2 Constructor & Destructor Documentation	196
5.118.2.1 SRManager	196
5.118.2.2 SRManager	196
5.118.3 Member Function Documentation	196
5.118.3.1 mark	196
5.118.3.2 retrieveSources	197
5.118.3.3 retrieveSources	197
5.118.3.4 setVal	197
5.119repast::StickyBorders Class Reference	197
5.119.1 Detailed Description	198
5.120repast::StrictBorders Class Reference	198
5.120.1 Detailed Description	198
5.121repast::SVDataSet Class Reference	199
5.121.1 Detailed Description	199
5.122repast::SVDataSetBuilder Class Reference	199
5.122.1 Detailed Description	200
5.122.2 Constructor & Destructor Documentation	200
5.122.2.1 SVDataSetBuilder	200
5.122.3 Member Function Documentation	200
5.122.3.1 addDataSource	200
5.122.3.2 createDataSet	200
5.123repast::SVDataSource Class Reference	201
5.123.1 Detailed Description	201
5.124repast::SyncStatus_Packet< Content > Class Template Reference	201
5.124.1 Detailed Description	202
5.124.2 Member Function Documentation	202

5.124.2.1 deleteExporterInfo	202
5.125repast::TDataSource< T > Class Template Reference	202
5.125.1 Detailed Description	203
5.125.2 Member Function Documentation	204
5.125.2.1 getData	204
5.126repast::Timer Class Reference	204
5.126.1 Detailed Description	204
5.126.2 Member Function Documentation	204
5.126.2.1 stop	204
5.127repast::UndirectedVertex< V, E > Class Template Reference	205
5.127.1 Detailed Description	205
5.127.2 Member Function Documentation	205
5.127.2.1 addEdge	205
5.127.2.2 adjacent	206
5.127.2.3 edges	206
5.127.2.4 findEdge	206
5.127.2.5 inDegree	206
5.127.2.6 outDegree	207
5.127.2.7 predecessors	207
5.127.2.8 removeEdge	207
5.127.2.9 successors	207
5.128repast::ValueLayer< ValueType, PointType > Class Template Reference	207
5.128.1 Detailed Description	208
5.128.2 Member Function Documentation	208
5.128.2.1 dimensions	208
5.128.2.2 get	209
5.128.2.3 operator[]	209
5.128.2.4 operator[]	209
5.128.2.5 set	209
5.128.2.6 shape	210
5.129repast::Variable Class Reference	210
5.129.1 Detailed Description	210
5.129.2 Member Function Documentation	210
5.129.2.1 insert	210
5.129.2.2 insert	211
5.129.2.3 write	211
5.130repast::Vertex< V, E > Class Template Reference	211
5.130.1 Detailed Description	212
5.130.2 Constructor & Destructor Documentation	213
5.130.2.1 Vertex	213

5.130.3 Member Function Documentation	214
5.130.3.1 addEdge	214
5.130.3.2 adjacent	214
5.130.3.3 edges	214
5.130.3.4 findEdge	214
5.130.3.5 inDegree	215
5.130.3.6 item	215
5.130.3.7 outDegree	215
5.130.3.8 predecessors	215
5.130.3.9 removeEdge	215
5.130.3.10 successors	216
5.131 repast::VN2DGridQuery< T > Class Template Reference	217
5.131.1 Detailed Description	217
5.131.2 Member Function Documentation	217
5.131.2.1 query	217
5.132 repast::WrapAroundBorders Class Reference	218
5.132.1 Detailed Description	218

Chapter 1

Repast HPC: A High-Performance Agent-Based Modeling Platform

By Argonne National Laboratory, 2009-2013

1.1 What is Repast HPC?

Repast HPC is an Agent-Based Modeling Platform in the spirit of Repast Symphony but designed for top-500 high-performance computing systems (supercomputers).

Chapter 2

Deprecated List

Class [repast::CellContents](#)< [AgentContent](#), [GPType](#) >

Replaced by ProjectionInfoPacket as of Version 2.0

Class [repast::EdgeExporter](#)< [E](#) >

As of Version 2.0 replaced by ProjectionInfoPacket

Class [repast::ExportRequest](#)

As of Version 2.0

Class [repast::GridBufferSyncher](#)< [T](#), [GPType](#) >

As of Version 2.0

Class [repast::ItemReceipt](#)< [E](#) >

As of Version 2.0 replaced by ProjectionInfoPacket objects.

Chapter 3

Hierarchical Index

3.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

repast::AbstractExporter	15
repast::Exporter_LIST	76
repast::Exporter_SET	76
repast::AbstractImporter	17
repast::Importer_COUNT	99
repast::Importer_LIST	100
repast::Importer_MAP_int	101
repast::Importer_SET	102
repast::AbstractImporterExporter	18
repast::ImporterExporter_BY_SET	103
repast::ImporterExporter_COUNT_LIST	105
repast::ImporterExporter_COUNT_SET	105
repast::ImporterExporter_LIST	106
repast::ImporterExporter_MAP_int	107
repast::ImporterExporter_SET	108
repast::Agent	19
repast::AgentExporterData	20
repast::AgentHashId< AgentType >	21
repast::AgentId	22
repast::AgentRequest	24
repast::AgentStateFilter< T >	30
repast::AgentStatus	30
Appender	32
CerrAppender	44
CoutAppender	64
RollingFileAppender	158
AppenderBuilder	33
repast::Borders	42
repast::StickyBorders	197
repast::StrictBorders	198
repast::CartTopology	43
repast::CellContents< AgentContent, GPType >	44
ConfigLexer	45
repast::Context< T >	45
repast::SharedContext< T >	167
repast::data_type_traits< T >	64

repast::data_type_traits< double >	65
repast::data_type_traits< int >	65
repast::DataSet	66
repast::NCDataSet	120
repast::SVDataSet	199
repast::EdgeExporter< E >	73
repast::EventCompare	75
repast::ExportRequest	77
repast::Functor	78
repast::MethodFunctor< T >	117
repast::Grid2DQuery< T >	94
repast::Moore2DGridQuery< T >	117
repast::VN2DGridQuery< T >	217
repast::GridBufferSyncher< T, GPType >	95
repast::GridDimensions	96
repast::GridMovePacket< PtType >	96
repast::GridMovePackets< PtType >	97
repast::GridMovePackets< double >	97
repast::GridMovePackets< GPType >	97
repast::GridMovePackets< int >	97
repast::GridPointHolder< T, GPType >	97
repast::HashGridPoint< T >	98
repast::HashId	98
repast::HashVertex< V, E >	99
repast::IsAgentType< T >	111
repast::IsLocalAgent< T >	111
repast::IsNotType< T >	112
repast::ItemReceipt< E >	112
repast::KEBuilder< V, E, Ec, EcM >	113
Log4CL	114
Log4CLConfigurator	115
Logger	115
repast::Matrix< T >	115
repast::DenseMatrix< T >	67
repast::SparseMatrix< T >	194
repast::Matrix< ValueType >	115
repast::MultipleOccupancy< T, GPType >	118
repast::MultipleOccupancy< T, double >	118
repast::MultipleOccupancy< T, int >	118
repast::NCDataSetBuilder	120
repast::NCDataSource	122
repast::NCReducibleDataSource< Op, T >	122
repast::NcTypeTrait< T >	123
repast::NcTypeTrait< double >	123
repast::NcTypeTrait< int >	124
repast::Neighbor	124
repast::Neighbors	124
noncopyable	
repast::Projection< V >	132
repast::Graph< V, E, Ec, EcM >	79
repast::SharedNetwork< V, E, Ec, EcM >	186
repast::BaseValueLayer	42
repast::ValueLayer< ValueType, PointType >	207
repast::ValueLayer< ValueType, double >	207
repast::ContinuousValueLayer< ValueType, Borders >	62
repast::ValueLayer< ValueType, int >	207

repat::DiscreteValueLayer< ValueType, Borders >	70
repat::Projection< T >	132
repat::Grid< T, double >	86
repat::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >	33
repat::SharedBaseGrid< T, GPTransformer, Adder, double >	163
repat::SharedContinuousSpace< T, GPTransformer, Adder >	183
repat::Grid< T, int >	86
repat::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >	33
repat::SharedBaseGrid< T, GPTransformer, Adder, int >	163
repat::SharedDiscreteSpace< T, GPTransformer, Adder >	185
repat::Grid< T, GPType >	86
repat::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >	33
repat::SharedBaseGrid< T, GPTransformer, Adder, GPType >	163
repat::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >	33
repat::RepatProcess	152
repat::ScheduleRunner	161
repat::NumberGenerator	126
repat::DefaultNumberGenerator< T >	66
repat::Point< T >	127
repat::Point< double >	127
repat::Point< GPType >	127
repat::Point< int >	127
repat::Point< PtType >	127
repat::Problem	132
repat::ProjectionInfoPacket	136
repat::SpecializedProjectionInfoPacket< Datum >	195
repat::Properties	137
repat::Random	141
repat::RandomAccess< I >	145
repat::RepatEdge< V >	147
repat::RepatEdgeContent< V >	150
repat::RepatEdgeContentManager< V >	151
repat::RepatEvent	151
repat::Request_Packet< Content >	157
repat::Schedule	158
repat::ScheduledEvent	160
repat::OneTimeEvent	127
repat::RepeatingEvent	156
repat::SharedSpaces< T >	190
repat::SimpleAdder< T >	191
repat::SingleOccupancy< T, GPType >	191
repat::Spaces< T >	193
SRManager	195
repat::SVDataSetBuilder	199
repat::SVDataSource	201
repat::ReducibleDataSource< Op, T >	146
repat::SyncStatus_Packet< Content >	201
repat::TDataSource< T >	202
repat::Timer	204
unary_function	
repat::AgentFromGridPoint< T, GPType >	21
repat::ExtractPtrs< T >	78
repat::KeyGetter	114
repat::NodeGetter< V, E >	126
repat::SecondElement< T >	163
repat::Variable	210

repast::DoubleVariable	72
repast::IntVariable	109
repast::Vertex< V, E >	211
repast::DirectedVertex< V, E >	67
repast::UndirectedVertex< V, E >	205
repast::WrapAroundBorders	218

Chapter 4

Class Index

4.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

repast::AbstractExporter	Responsible for keeping a list of the agents that have been requested by other processes for which data is to be sent when agents' states are synchronized, and for packaging and sending that data during synchronization	15
repast::AbstractImporter	This class manages importing agent information; primarily this means constructing the appropriate mpi receives when agent information is to be exchanged	17
repast::AbstractImporterExporter	Wraps and Importer and an Exporter so that both use commensurate semantics and all imports and exports are balanced	18
repast::Agent	Interface for agent classes	19
repast::AgentExporterData	Data structure for exporter data that is to be sent to other processes when the agents being exported are moved	20
repast::AgentFromGridPoint< T, GPType >	Unary function used in the transform_iterator that allows context iterators to return the agent maps values	21
repast::AgentHashId< AgentType >	Operator() implementation that returns the hashcode of an agent via its AgentId	21
repast::AgentId	Agent identity information	22
repast::AgentRequest	Encapsulates a request made by one process for agents in another	24
repast::AgentStateFilter< T >	Used in a filter iterator to filter on local or non-local agents only	30
repast::AgentStatus	Encapsulates the status (moved or removed) of agent in order to synchronize that status across processes	30
Appender	32
AppenderBuilder	33
repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >	Base grid implementation, implementing elements common to both Grids and ContinuousSpaces	33
repast::BaseValueLayer	Base implementation of a ValueLayer	42
repast::Borders	Base class for representations of border semantics (e.g	42

repat::CartTopology	Allows retrieval of the position of this process within the MPI Cartesian Topology into which it is placed	43
repat::CellContents< AgentContent, GPType >	<i>DEPRECATED</i> Encapsulates the contents of a grid / space location so that it can be sent between processes	44
CerrAppender	44
ConfigLexer	45
repat::Context< T >	Collection of agents of type T with set semantics	45
repat::ContinuousValueLayer< ValueType, Borders >	Continuous value layer whose location coordinates are double	62
CoutAppender	64
repat::data_type_traits< T >	Base class for specialized int and double type classes	64
repat::data_type_traits< double >	Double data types for SVDDataSource objects	65
repat::data_type_traits< int >	Int data types for SVDDataSource objects	65
repat::DataSet	Interface for recording and writing data	66
repat::DefaultNumberGenerator< T >	Adapts the templated boost::variate_generator to the NumberGenerator interface	66
repat::DenseMatrix< T >	A dense matrix implementation that stores each cell individually	67
repat::DirectedVertex< V, E >	Used internally by repast graphs / networks to encapsulate the vertices of a directed graph	67
repat::DiscreteValueLayer< ValueType, Borders >	Creates ValueLayer whose location coordinates are ints	70
repat::DoubleVariable	Used in SVDDataSet to manage double data	72
repat::EdgeExporter< E >	<i>DEPRECATED</i> Handles exporting edges created locally between one or more non-local agents	73
repat::EventCompare	Compares ScheduledEvents based on their tick times	75
repat::Exporter_LIST	Maintains a list of agents being exported for each receiving process	76
repat::Exporter_SET	Maintains a set of agents being exported for each receiving process	76
repat::ExportRequest	<i>DEPRECATED</i> Used to send a request for agent information from another process	77
repat::ExtractPtrs< T >	Unary function that allows retrieving the occupants of locations	78
repat::Functor	Functor interface	78
repat::Graph< V, E, Ec, EcM >	Graph / Network implementation where agents are vertices in the graph	79
repat::Grid< T, GPType >	Abstract interface for Grids and ContinuousSpaces	86
repat::Grid2DQuery< T >	Base class for neighborhood queries on discrete Grids	94
repat::GridBufferSyncher< T, GPType >	<i>DEPRECATED</i> Helper class that provides support for synchronizing a grid / space buffer	95
repat::GridDimensions	Basic structure for specifying grid dimenions	96
repat::GridMovePacket< PtType >	Encapsulates info about an agent moving off the grid: the rank it moved to, its grid location, and the agent id	96

repastr::GridMovePackets< PtType >	
A collection of GridMovePacket objects, kept in a map per destination process	97
repastr::GridPointHolder< T, GPType >	
Encapsulates a grid point and what is held in it	97
repastr::HashGridPoint< T >	
Class that allows retrieval of hash value for Point objects	98
repastr::HashId	
Operator() implementation that returns the hashcode of an AgentId	98
repastr::HashVertex< V, E >	
Hashes a Vertex using the hashcode of the AgentId that the vertex contains	99
repastr::Importer_COUNT	
Importer that maintains a simple count of the agents being sent from each sending process	99
repastr::Importer_LIST	
Importer that maintains a list of the agents being sent from each sending process	100
repastr::Importer_MAP_int	
Importer that maintains a map of agents being sent from each sending process and a count of the number of times that agent was requested	101
repastr::Importer_SET	
Importer that maintains a set of agents being sent from each sending process	102
repastr::ImporterExporter_BY_SET	
Implementation of the AbstractImporterExporter class that wraps a collection of AbstractImporterExporter objects that can be referenced by name	103
repastr::ImporterExporter_COUNT_LIST	
An implementation of AbstractImporterExporter that uses an importer of type 'Importer_COUNT' and an exporter of type 'Exporter_LIST'	105
repastr::ImporterExporter_COUNT_SET	
An implementation of AbstractImporterExporter that uses an importer of type 'Importer_COUNT' and an exporter of type 'Exporter_SET'	105
repastr::ImporterExporter_LIST	
An implementation of AbstractImporterExporter that uses an importer of type 'Importer_LIST' and an exporter of type 'Exporter_LIST'	106
repastr::ImporterExporter_MAP_int	
An implementation of AbstractImporterExporter that uses an importer of type 'Importer_MAP_int' and an exporter of type 'Exporter_LIST'	107
repastr::ImporterExporter_SET	
An implementation of AbstractImporterExporter that uses an importer of type 'Importer_SET' and an exporter of type 'Exporter_LIST'	108
repastr::IntVariable	
Used in SVDDataSet to manage integer data	109
repastr::IsAgentType< T >	
Struct that allows filtering by Agent Type	111
repastr::IsLocalAgent< T >	
Used in a filter iterator to filter on local agents only	111
repastr::IsNotType< T >	
Struct that allows filtering by !(Agent Type)	112
repastr::ItemReceipt< E >	
<i>DEPRECATED</i> Receipt for edges Class used to receive edges being sent	112
repastr::KEBuilder< V, E, Ec, EcM >	
Builds KE type networks	113
repastr::KeyGetter	
Unary function used in a transform_iterator that allows the map iterator to return the keys	114
Log4CL	114
Log4CLConfigurator	115
Logger	115
repastr::Matrix< T >	
Base class for matrix implementations	115
repastr::MethodFunctor< T >	
Adapts a no-arg method call on an object instance to a Functor interface	117

repast::Moore2DGridQuery< T >	Neighborhood query that gathers neighbors in a Moore (N, S, E, W, NE, etc.) neighborhood . . .	117
repast::MultipleOccupancy< T, GPType >	Multiple Occupancy cell accessor for accessing the occupants of locations in a Grid	118
repast::NCDataSet	Provides data recording and writing into a single file in NetCDF format	120
repast::NCDataSetBuilder	Used to build NCDataSets to record data in NetCDF format	120
repast::NCDataSource	Data source used internally by NCDataSets	122
repast::NCReducibleDataSource< Op, T >	Source of data and a reduction operation	122
repast::NcTypeTrait< T >	Base class for specialized int and double NcType classes	123
repast::NcTypeTrait< double >	Used for converting to NetCDF Data, double type	123
repast::NcTypeTrait< int >	Used for converting to NetCDF Data, int type	124
repast::Neighbor	Contains the rank and boundaries of a semantically adjacent process (that is, a process that manages the space that is adjacent to the simulation space managed by this process)	124
repast::Neighbors	Provides lookup of grid topology process neighbors given a point in the pan process grid . . .	124
repast::NodeGetter< V, E >	Unary function used in the transform_iterator that allows an iterator over the vertex map to return the node	126
repast::NumberGenerator	Number generator interface	126
repast::OneTimeEvent	ScheduledEvent that will only execute only once	127
repast::Point< T >	A N-dimensional Point representation	127
repast::Problem	Helper class for calculating outcomes based on a set of probabilities that sum to 1	132
repast::Projection< T >	Abstract base class for all Projections	132
repast::ProjectionInfoPacket	Serializable packet that can contain projection information regardless of the type of projection (network or spatial)	136
repast::Properties	Map type object that contains key, value(string) properties	137
repast::Random	Methods for working with random distributions, draws etc	141
repast::RandomAccess< I >	Given an iterator and a number of elements, creates a data structure that allows efficient access to those elements	145
repast::ReducibleDataSource< Op, T >	Source of data and a reduction operation	146
repast::RepastEdge< V >	Default graph / network edge implementation	147
repast::RepastEdgeContent< V >	Serializable; also, does not include agent content, only agent IDs	150
repast::RepastEdgeContentManager< V >	Class for creating RepastEdges from RepastEdgeContent , and vice versa	151
repast::RepastEvent	General class linking a function pointer to a specific tick	151

repast::RepastProcess	Encapsulates the process in which repast is running and manages interprocess communication etc	152
repast::RepeatingEvent	ScheduledEvent that executes repeatedly	156
repast::Request_Packet< Content >	Contains information sent as agents are exchanged, either in response to requests or agent movement	157
RollingFileAppender		158
repast::Schedule	The simulation schedule queue	158
repast::ScheduledEvent	The object that is placed (scheduled) in the priority queue for execution	160
repast::ScheduleRunner	Runs the Schedule by popping events off of the Schedule and executing them; also provides methods for scheduling events	161
repast::SecondElement< T >	Unary function used in the transform_iterator that allows context iterators to return the agent maps values	163
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >	Grid / Space implementation specialized for the distributed context	163
repast::SharedContext< T >	Context implementation specialized for the parallel distributed simulation	167
repast::SharedContinuousSpace< T, GPTransformer, Adder >	Continuous space SharedBaseGrid implementation	183
repast::SharedDiscreteSpace< T, GPTransformer, Adder >	Discrete matrix-like SharedBaseGrid implementation	185
repast::SharedNetwork< V, E, Ec, EcM >	Network implementation that can be shared across processes	186
repast::SharedSpaces< T >	Struct within which multiple kinds of shared space are typedef-ed	190
repast::SimpleAdder< T >	Basic class for adding elements to grids	191
repast::SingleOccupancy< T, GPType >	Single Occupancy cell accessor for accessing the occupants of locations in a Grid	191
repast::Spaces< T >	Struct within which multiple kinds of space are typedef-ed	193
repast::SparseMatrix< T >	A sparse matrix implementation that stores values in a map	194
repast::SpecializedProjectionInfoPacket< Datum >	Serializable packet that can contain projection information of a specific kind using the template parameter	195
SRManager	Coordinates send and receive between processes by notifying processes to expect a send from X other processes	195
repast::StickyBorders	Implements sticky border semantics: translates out side of the border are clamped to the border coordinates	197
repast::StrictBorders	Implements strict grid border semantics: anything outside the dimensions is out of bounds	198
repast::SVDataSet	Encapsulates data recording to a single plain text file, separating the recorded values using a specified separator value	199
repast::SVDataSetBuilder	Used to build SVDataSets to record data in plain text tabular format	199
repast::SVDataSource	Data source for data to be written into separated-value data sets	201

repast::SyncStatus_Packet< Content >	
Class that contains information sent in conjunction with synchronizing agent status (agents moving or being removed from the simulation)	201
repast::TDataSource< T >	
Interface for class that act as datasoures for DataSets	202
repast::Timer	
Simple timing class	204
repast::UndirectedVertex< V, E >	
A vertex in an undirected network	205
repast::ValueLayer< ValueType, PointType >	
A collection that stores values at point locations	207
repast::Variable	
Used in SVDataSet to manage and store the data	210
repast::Vertex< V, E >	
Used internally by repast graphs / networks to encapsulate Vertices	211
repast::VN2DGridQuery< T >	
Neighborhood query that gathers neighbors in a Von Neumann (N, S, E, W) neighborhood	217
repast::WrapAroundBorders	
Implements periodic wrap around style border semantics	218

Chapter 5

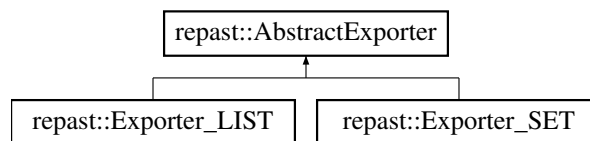
Class Documentation

5.1 repast::AbstractExporter Class Reference

Responsible for keeping a list of the agents that have been requested by other processes for which data is to be sent when agents' states are synchronized, and for packaging and sending that data during synchronization.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::AbstractExporter:



Public Types

- typedef std::map< int, std::set< [AgentStatus](#) > > **StatusMap**

Public Member Functions

- virtual void [registerIncomingRequests](#) (std::vector< [AgentRequest](#) > &requests)=0
Makes a record of the data receives (in the form of a vector of AgentRequests) so that the agents' data can be sent to the requesting processes.
- virtual void [incorporateAgentExporterInfo](#) (std::map< int, [AgentRequest](#) * > info)
The set of information received here comprises the information that some other process was using to export information about agents that are now being moved to this process.
- virtual void [agentRemoved](#) (const [AgentId](#) &id)
1) Removes the agent export information from this process 2) Updates the outgoing status change buffer to include the status change for this agent to all procs to which this agent was being exported (except if one of these was the proc to which the agent is now moving; this is omitted)
- virtual void [agentMoved](#) (const [AgentId](#) &id, int process)
1) Removes the agent export information from this process 2) Places a copy of the agent export information into the outgoing buffer 3) Updates the outgoing status change buffer to include the status change for this agent to all procs to which this agent was being exported (except if one of these was the proc to which the agent is now moving; this is omitted)
- virtual const std::set< int > & [getProcessesExportedTo](#) ()
Gets the list of processes this exporter is sending information to.

- `AgentExporterInfo * getAgentExportInfo (int destProc)`
Gets the export information that has been placed into the 'outgoing agent export information' buffer because agents that were being exported are being sent to a new process, for the specified process.
- `const StatusMap * getOutgoingStatusChanges ()`
Gets the set of status changes for the exported agents.
- `void clearAgentExportInfo ()`
Clears the outgoing agent export information buffer; should be called after the information is sent.
- `void clearStatusMap ()`
Clears the outgoing status information buffer; should be called after the information is sent.
- `virtual const std::map< int, AgentRequest > & getAgentsToExport ()`
Gets the list of agents being exported by this exported, as a map by ints representing the processes to which information will be sent.
- **`AbstractExporter`** (`StatusMap *outgoingStatusMap`, `AgentExporterData *outgoingAgentExporterInfo`)
- `virtual std::string getReport ()=0`
Gets a printable report of the state of this object.
- `virtual void clear ()`
- `virtual void clearExportToSpecificProc (int rank)`

Protected Attributes

- `StatusMap * outgoingStatusChanges`
- `AgentExporterData * outgoingAgentExporterInformation`
- `std::set< int > processesExportedTo`
- `std::map< int, AgentRequest > exportedMap`

5.1.1 Detailed Description

Responsible for keeping a list of the agents that have been requested by other processes for which data is to be sent when agents' states are synchronized, and for packaging and sending that data during synchronization.

It is also responsible for exchanging this 'export' information when any of the agents that it is exporting are being moved to other processes; when an agent moves, its new home process must be able to assume the same export duties that its original process was performing.

5.1.2 Member Function Documentation

5.1.2.1 `void AbstractExporter::incorporateAgentExporterInfo (std::map< int, AgentRequest * > info) [virtual]`

The set of information received here comprises the information that some other process was using to export information about agents that are now being moved to this process.

This method takes that information and incorporates it into this exporter, so that this exporter can now export the agents' information to the processes that have requested it.

The documentation for this class was generated from the following files:

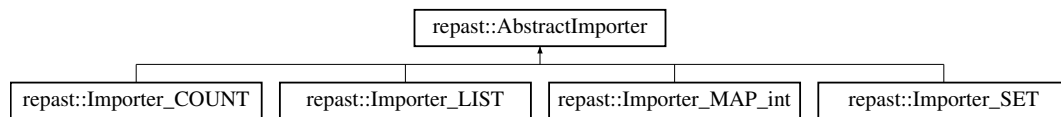
- `repast_hpc/AgentImporterExporter.h`
- `repast_hpc/AgentImporterExporter.cpp`

5.2 repast::AbstractImporter Class Reference

This class manages importing agent information; primarily this means constructing the appropriate mpi receives when agent information is to be exchanged.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::AbstractImporter:



Public Member Functions

- virtual const std::set< int > & [getExportingProcesses](#) ()
Gets a const reference to the set of ints representing the processes that are sending this process agent information.
- virtual void [registerOutgoingRequests](#) ([AgentRequest](#) &req)=0
Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.
- virtual void [importedAgentsRemoved](#) (const [AgentId](#) &id)=0
Notifies this importer that the agent that it (presumably) has been importing has been removed from the simulation on its home process, and the information for that agent will no longer be sent.
- virtual void [importedAgentsMoved](#) (const [AgentId](#) &id, int newProcess)=0
Notifies this importer that the agent that it (presumably) has been importing from another process has been moved; its information will now be received from its new home process (unless the agent was moved to this process)
- void [importedAgentsNowLocal](#) (const [AgentId](#) &id)
Some semantic sugar; operationally this is the same as 'importedAgentsRemoved'.
- virtual std::string [getReport](#) ()=0
Get a printable indication of the data in this object.
- virtual void [getSetOfAgentsBeingImported](#) (std::set< [AgentId](#) > &set)=0
- virtual void [clear](#) ()

Protected Attributes

- std::set< int > [exportingProcesses](#)

5.2.1 Detailed Description

This class manages importing agent information; primarily this means constructing the appropriate mpi receives when agent information is to be exchanged.

However, this class can also define specific semantics that can apply to agent requests- what to do in the case that an agent is requested twice, for example.

5.2.2 Member Function Documentation

5.2.2.1 virtual void repast::AbstractImporter::registerOutgoingRequests ([AgentRequest](#) & req) [pure virtual]

Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.

The record must at a minimum indicate which other processes are sending agent information, but may include other information, such as how many times a particular agent has been requested.

Implemented in [repast::Importer_MAP_int](#), [repast::Importer_SET](#), [repast::Importer_LIST](#), and [repast::Importer_COUNT](#).

The documentation for this class was generated from the following files:

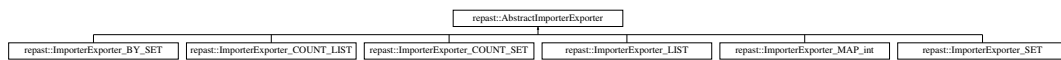
- [repast_hpc/AgentImporterExporter.h](#)
- [repast_hpc/AgentImporterExporter.cpp](#)

5.3 repast::AbstractImporterExporter Class Reference

Wraps and Importer and an Exporter so that both use commensurate semantics and all imports and exports are balanced.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::AbstractImporterExporter:



Public Member Functions

- **AbstractImporterExporter** ([AbstractImporter](#) *i, [AbstractExporter](#) *e)
- virtual const std::set< int > & **getExportingProcesses** ()
- virtual void **registerOutgoingRequests** ([AgentRequest](#) &req)
- virtual void **importedAgentsRemoved** (const [AgentId](#) &id)
- virtual void **importedAgentsMoved** (const [AgentId](#) &id, int newProcess)
- virtual void **importedAgentsNowLocal** (const [AgentId](#) &id)
- virtual void **getSetOfAgentsBeingImported** (std::set< [AgentId](#) > &set)
- virtual const
AbstractExporter::StatusMap * **getOutgoingStatusChanges** ()
- virtual const std::set< int > & **getProcessesExportedTo** ()
- virtual void **registerIncomingRequests** (std::vector< [AgentRequest](#) > &requests)
- virtual void **agentRemoved** (const [AgentId](#) &id)
- virtual void **agentMoved** (const [AgentId](#) &id, int process)
- virtual void **incorporateAgentExporterInfo** (std::map< int, [AgentRequest](#) * > info)
- virtual void **clearStatusMap** ()
- virtual [AgentExporterInfo](#) * **getAgentExportInfo** (int destProc)
- virtual void **clearAgentExportInfo** ()
- virtual const std::map< int,
[AgentRequest](#) > & **getAgentsToExport** ()
- virtual void **exchangeAgentStatusUpdates** (boost::mpi::communicator world, std::vector< std::vector< [Agent-Status](#) > * > &statusUpdates)
Exchanges the contents of the 'statusMap' with the destination processes, updating the status (moved or removed) for all agents being exported.
- virtual std::string **version** ()=0
Returns the version of this [AbstractImporterExporter](#).
- virtual std::string **getReport** ()
Gets a printable report of the state of this object.
- virtual void **clear** ()
- virtual void **clearExporter** ()
- virtual void **clearExportToSpecificProc** (int rank)

Protected Attributes

- [AbstractImporter](#) * **importer**
- [AbstractExporter](#) * **exporter**

5.3.1 Detailed Description

Wraps and Importer and an Exporter so that both use commensurate semantics and all imports and exports are balanced.

Most methods are pass-through to the underlying importer or exporter.

5.3.2 Member Function Documentation

5.3.2.1 `void AbstractImporterExporter::exchangeAgentStatusUpdates (boost::mpi::communicator world, std::vector< std::vector< AgentStatus > * > & statusUpdates) [virtual]`

Exchanges the contents of the 'statusMap' with the destination processes, updating the status (moved or removed) for all agents being exported.

Returns this information in the statusUpdates vector.

5.3.2.2 `virtual std::string repast::AbstractImporterExporter::version () [pure virtual]`

Returns the version of this [AbstractImporterExporter](#).

The version is a string that indicates the semantic version of the importer and the exporter (e.g. "COUNT_LIST")

Implemented in [repast::ImporterExporter_BY_SET](#), [repast::ImporterExporter_MAP_int](#), [repast::ImporterExporter_SET](#), [repast::ImporterExporter_LIST](#), [repast::ImporterExporter_COUNT_SET](#), and [repast::ImporterExporter_COUNT_LIST](#).

The documentation for this class was generated from the following files:

- [repast_hpc/AgentImporterExporter.h](#)
- [repast_hpc/AgentImporterExporter.cpp](#)

5.4 repast::Agent Class Reference

Interface for agent classes.

```
#include <AgentId.h>
```

Public Member Functions

- virtual [AgentId](#) & [getid](#) ()=0
Gets the [AgentId](#) for this [Agent](#).
- virtual const [AgentId](#) & [getid](#) () const =0
Gets the [AgentId](#) for this [Agent](#).

5.4.1 Detailed Description

Interface for agent classes.

5.4.2 Member Function Documentation

5.4.2.1 virtual AgentId& repast::Agent::getId () [pure virtual]

Gets the [AgentId](#) for this [Agent](#).

Returns

the [AgentId](#) for this [Agent](#).

5.4.2.2 virtual const AgentId& repast::Agent::getId () const [pure virtual]

Gets the [AgentId](#) for this [Agent](#).

Returns

the [AgentId](#) for this [Agent](#).

The documentation for this class was generated from the following file:

- repast_hpc/AgentId.h

5.5 repast::AgentExporterData Class Reference

Data structure for exporter data that is to be sent to other processes when the agents being exported are moved.

```
#include <AgentImporterExporter.h>
```

Public Member Functions

- void [addData](#) (const [AgentId](#) &id, const int destProc, const int sourceProc, const int numberOfCopies=1)
Adds an agent ID to this list of data that is being exported to a specific processor (destProc), so that the agent's information will be exported to another processor (sourceProc).
- AgentExporterInfo * [dataForProc](#) (int destProc)
Gets the packaged set of information to be sent to a specific processor.
- void [clear](#) ()
Clears this data structure.
- void [removeAllDataForAgent](#) ([AgentId](#) &id)
Remove all the data for a specific agent; useful when the agent is removed.
- void [selectSet](#) (std::string setName)
Specifies that add and retrieve actions are to be performed on the subset of data identified by the given set name.

5.5.1 Detailed Description

Data structure for exporter data that is to be sent to other processes when the agents being exported are moved.

Note that the internal data structure is protected; classes can use this data without knowing its actual internal structure.

5.5.2 Member Function Documentation

5.5.2.1 void AgentExporterData::selectSet (std::string setName)

Specifies that add and retrieve actions are to be performed on the subset of data identified by the given set name.

(Does not affect 'clear' or 'removeAllDataForAgent')

The documentation for this class was generated from the following files:

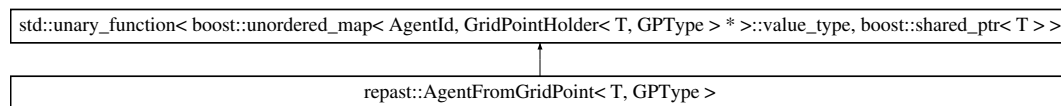
- repast_hpc/AgentImporterExporter.h
- repast_hpc/AgentImporterExporter.cpp

5.6 repast::AgentFromGridPoint< T, GPType > Struct Template Reference

Unary function used in the transform_iterator that allows context iterators to return the agent maps values.

```
#include <BaseGrid.h>
```

Inheritance diagram for repast::AgentFromGridPoint< T, GPType >:



Public Member Functions

- boost::shared_ptr< T > **operator()** (const typename boost::unordered_map< [AgentId](#), [GridPointHolder](#)< T, GPType > * >::value_type &value) const

5.6.1 Detailed Description

```
template<typename T, typename GPType>struct repast::AgentFromGridPoint< T, GPType >
```

Unary function used in the transform_iterator that allows context iterators to return the agent maps values.

The documentation for this struct was generated from the following file:

- repast_hpc/BaseGrid.h

5.7 repast::AgentHashId< AgentType > Struct Template Reference

operator() implementation that returns the hashcode of an agent via its [AgentId](#).

```
#include <AgentId.h>
```

Public Member Functions

- std::size_t **operator()** (const AgentType *agent) const

5.7.1 Detailed Description

`template<typename AgentType>struct repast::AgentHashId< AgentType >`

`operator()` implementation that returns the hashcode of an agent via its [AgentId](#).

The documentation for this struct was generated from the following file:

- `repast_hpc/AgentId.h`

5.8 repast::AgentId Class Reference

[Agent](#) identity information.

```
#include <AgentId.h>
```

Public Member Functions

- [AgentId](#) ()
No-arg constructor necessary for serialization.
- [AgentId](#) (int `id`, int `startProc`, int `agentType`, int `currentProc`=-1)
Creates an [AgentId](#).
- int `id` () const
Gets the id component of this [AgentId](#).
- int `startingRank` () const
Gets the starting rank component of this [AgentId](#).
- int `agentType` () const
Gets the agent type component of this [AgentId](#).
- int `currentRank` () const
Gets the current process rank of this [AgentId](#).
- void `currentRank` (int `val`)
Sets the current process rank of this [AgentId](#).
- std::size_t `hashcode` () const
Gets the hashcode for this [AgentId](#).

Friends

- class `boost::serialization::access`
- std::ostream & `operator<<` (std::ostream &`os`, const [AgentId](#) &`id`)
Writes the agent id to the ostream.
- bool `operator==` (const [AgentId](#) &`one`, const [AgentId](#) &`two`)
Equality operator.
- bool `operator<` (const [AgentId](#) &`one`, const [AgentId](#) &`two`)
A comparison operator for use with std::set.

5.8.1 Detailed Description

[Agent](#) identity information.

An [Agent](#) ID consists of four values: 1) a numerical identifier; 2) the process on which the agent was created; 3) a numerical identifier that indicates the agent's type (in simulation semantic terms, not a software object type); and 4) the process on which the agent is a local agent. Each agent should be uniquely identified by an [AgentId](#) using the first three of the four values, which should be immutable. The fourth value can change throughout the simulation.

5.8.2 Constructor & Destructor Documentation

5.8.2.1 repast::AgentId::AgentId (int *id*, int *startProc*, int *agentType*, int *currentProc* = -1)

Creates an [AgentId](#).

The combination of the first three parameters should uniquely identify the agent.

Parameters

<i>id</i>	the agent's id
<i>startProc</i>	the rank of the agent's starting process
<i>agentType</i>	the agent's type (user defined)
<i>currentProc</i>	the rank where the agent is a local agent

5.8.3 Member Function Documentation

5.8.3.1 int repast::AgentId::agentType () const [inline]

Gets the agent type component of this [AgentId](#).

Returns

the agent type component of this [AgentId](#).

5.8.3.2 int repast::AgentId::currentRank () const [inline]

Gets the current process rank of this [AgentId](#).

The current rank identifies which process the agent with this [AgentId](#) is currently on.

Returns

the current process rank of this [AgentId](#).

5.8.3.3 void repast::AgentId::currentRank (int *val*) [inline]

Sets the current process rank of this [AgentId](#).

The current rank identifies which process the agent with this [AgentId](#) is currently on.

Parameters

<i>val</i>	the current process rank
------------	--------------------------

5.8.3.4 std::size_t repast::AgentId::hashCode () const [inline]

Gets the hashcode for this [AgentId](#).

Returns

the hashcode for this [AgentId](#).

5.8.3.5 `int repast::AgentId::id () const [inline]`

Gets the id component of this [AgentId](#).

Returns

the id component of this [AgentId](#).

5.8.3.6 `int repast::AgentId::startingRank () const [inline]`

Gets the starting rank component of this [AgentId](#).

Returns

the starting rank component of this [AgentId](#).

The documentation for this class was generated from the following files:

- `repast_hpc/AgentId.h`
- `repast_hpc/AgentId.cpp`

5.9 repast::AgentRequest Class Reference

Encapsulates a request made by one process for agents in another.

```
#include <AgentRequest.h>
```

Public Member Functions

- [AgentRequest](#) (int [sourceProcess](#))
Creates an [AgentRequest](#) that comes from the specified process.
- [AgentRequest](#) (int [sourceProcess](#), int [targetProcess](#))
Creates an [AgentRequest](#) made from the source process to the target process.
- void [addAll](#) (const [AgentRequest](#) &req)
Adds all the agent ids (both requests and cancellations) in req to this [AgentRequest](#).
- void [addAllRequests](#) (const [AgentRequest](#) &req)
Adds all the agent ids in req to this request, including only the ids that are requests and not those that are cancellations.
- void [addAllCancellations](#) (const [AgentRequest](#) &req)
Adds all the agent ids in req to this request, including only the ids that are cancellations and not those that are requests.
- const std::vector< [AgentId](#) > & [requestedAgents](#) () const
Gets a reference to the vector of requested agents.
- const std::vector< [AgentId](#) > & [cancellations](#) () const
Gets a reference to the vector of cancellations.
- bool [remove](#) (const [AgentId](#) &id, bool removeAllInstances=true)
Removes the specified id from the lists of requested agents, including both requests and cancellations.
- bool [removeRequest](#) (const [AgentId](#) &id, bool removeAllInstances=true)
Removes the specified id from the list of agent requests; does not affect the list of cancellations.
- bool [removeCancellation](#) (const [AgentId](#) &id, bool removeAllInstances=true)
Removes the specified id from the list of agent request cancellations; does not affect the list of requests.
- void [targets](#) (std::set< int > &targets)

- Puts the targets of all the requests into the set.*
- void [targetsOfRequests](#) (std::set< int > &targets)
 - Puts the targets of all the requests into the set, including only the requests and not the cancellations.*
- void [targetsOfCancellations](#) (std::set< int > &targets)
 - Puts the targets of all the requests into the set, including only the requests and not the cancellations.*
- void [addRequest](#) (const [AgentId](#) &id)
 - Adds the specified agent to the collection agents being requested.*
- void [addCancellation](#) (const [AgentId](#) &id)
 - Adds the specified agent to the collection of agents for which a previous request is being cancelled.*
- int [requestCount](#) () const
 - Gets the number agents requested.*
- int [requestCountRequested](#) () const
 - Gets the number of agents requested, counting only the requests and not the cancellations.*
- int [requestCountCancellations](#) () const
 - Gets the number of agents requested, counting only the cancellations and not the requests.*
- bool [contains](#) (const [AgentId](#) &id)
 - Returns true if this [AgentRequest](#) contains a request for the specified id (either a request or a cancellation), otherwise false.*
- bool [containsInRequests](#) (const [AgentId](#) &id)
 - Returns true if the list of requests contains the specified id (the list of cancellations is ignored)*
- bool [containsInCancellations](#) (const [AgentId](#) &id)
 - Returns true if the list of cancellations contains the specified id (the list of requests is ignored)*
- int [sourceProcess](#) () const
 - Gets the source process of these requests, that is, the process making the request.*
- int [targetProcess](#) () const
 - If the requested agent ids are all on the same process then target process will identify that process.*

Friends

- class **boost::serialization::access**
- class **Importer_LIST**
- class **Importer_SET**
- class **Importer_MAP_int**
- std::ostream & [operator<<](#) (std::ostream &os, const [AgentRequest](#) &request)
 - Prints the specified [AgentRequest](#) to the specified ostream.*

5.9.1 Detailed Description

Encapsulates a request made by one process for agents in another.

Includes a list of requests and a list that represents cancellations of previous requests.

5.9.2 Constructor & Destructor Documentation

5.9.2.1 repast::AgentRequest::AgentRequest (int sourceProcess)

Creates an [AgentRequest](#) that comes from the specified process.

Parameters

<i>sourceProcess</i>	the rank of the process making the request
----------------------	--

5.9.2.2 `repast::AgentRequest::AgentRequest (int sourceProcess, int targetProcess)`

Creates an [AgentRequest](#) made from the source process to the target process.

This can be used when all the requested agents reside on the same process (i.e. the target process).

Parameters

<i>sourceProcess</i>	the rank of the source process
<i>targetProcess</i>	the rank of the target process

5.9.3 Member Function Documentation

5.9.3.1 `void repast::AgentRequest::addAll (const AgentRequest & req)`

Adds all the agent ids (both requests and cancellations) in *req* to this [AgentRequest](#).

Parameters

<i>req</i>	the AgentRequest to add all the agent ids from
------------	--

5.9.3.2 `void repast::AgentRequest::addAllCancellations (const AgentRequest & req)`

Adds all the agent ids in *req* to this request, including only the ids that are cancellations and not those that are requests.

Parameters

<i>req</i>	the AgentRequest to add all the agent ids from
------------	--

5.9.3.3 `void repast::AgentRequest::addAllRequests (const AgentRequest & req)`

Adds all the agent ids in *req* to this request, including only the ids that are requests and not those that are cancellations.

Parameters

<i>req</i>	the AgentRequest to add all the agent ids from
------------	--

5.9.3.4 `void repast::AgentRequest::addCancellation (const AgentId & id)`

Adds the specified agent to the collection of agents for which a previous request is being cancelled.

Parameters

<i>id</i>	the AgentId of the agent for which the request is being cancelled
-----------	---

5.9.3.5 `void repast::AgentRequest::addRequest (const AgentId & id)`

Adds the specified agent to the collection agents being requested.

Parameters

<i>id</i>	the requested agent
-----------	---------------------

5.9.3.6 `const std::vector<AgentId>& repast::AgentRequest::cancellations () const` `[inline]`

Gets a reference to the vector of cancellations.

Returns

a reference to the vector of AgentIds representing cancellations.

5.9.3.7 `bool repast::AgentRequest::contains (const AgentId & id)`

Returns true if this [AgentRequest](#) contains a request for the specified id (either a request or a cancellation), otherwise false.

Parameters

<i>id</i>	the id sought in the lists of requests and cancellations
-----------	--

Returns

true if either the list of requests or the list of cancellations contains the specified id

5.9.3.8 `bool repast::AgentRequest::containsInCancellations (const AgentId & id)`

Returns true if the list of cancellations contains the specified id (the list of requests is ignored)

Parameters

<i>id</i>	the AgentId sought
-----------	------------------------------------

Returns

true if the specified [AgentId](#) is in the list of cancellations

5.9.3.9 `bool repast::AgentRequest::containsInRequests (const AgentId & id)`

Returns true if the list of requests contains the specified id (the list of cancellations is ignored)

Parameters

<i>id</i>	the AgentId sought
-----------	------------------------------------

Returns

true if the specified [AgentId](#) is in the list of requests

5.9.3.10 `bool repast::AgentRequest::remove (const AgentId & id, bool removeAllInstances = true)`

Removes the specified id from the lists of requested agents, including both requests and cancellations.

Parameters

<i>id</i>	the AgentId to be removed
<i>removeAll-Instances</i>	if true (the default), all instances of the AgentId are removed; if false, only the first instance found is removed

Returns

true if the id was found (in either list) and removed, otherwise false.

5.9.3.11 `bool repast::AgentRequest::removeCancellation (const AgentId & id, bool removeAllInstances = true)`

Removes the specified id from the list of agent request cancellations; does not affect the list of requests.

Parameters

<i>id</i>	the AgentId to be removed
<i>removeAll-Instances</i>	if true (the default), all instances of the AgentId are removed; if false, only the first instance found is removed

Returns

true if the id was found in the list of cancellations and removed, otherwise false

5.9.3.12 `bool repast::AgentRequest::removeRequest (const AgentId & id, bool removeAllInstances = true)`

Removes the specified id from the list of agent requests; does not affect the list of cancellations.

Parameters

<i>id</i>	the AgentId to be removed
<i>removeAll-Instances</i>	if true (the default), all instances of the AgentId are removed; if false, only the first instance found is removed

Returns

true if the id was found in the list of requests and removed, otherwise false

5.9.3.13 `int repast::AgentRequest::requestCount () const [inline]`

Gets the number agents requested.

Includes both requests and cancellations; exactly equivalent to

[requestCountRequested\(\)](#) + [requestCountCancellations\(\)](#)

Returns

the number agents requested.

5.9.3.14 `int repast::AgentRequest::requestCountCancellations () const [inline]`

Gets the number of agents requested, counting only the cancellations and not the requests.

Returns

the number of agents requested (cancellations only)

5.9.3.15 `int repast::AgentRequest::requestCountRequested () const [inline]`

Gets the number of agents requested, counting only the requests and not the cancellations.

Returns

the number of agents requested (requests only)

5.9.3.16 `const std::vector<AgentId>& repast::AgentRequest::requestedAgents () const [inline]`

Gets a reference to the vector of requested agents.

Returns

a reference to the vector of requested agents.

5.9.3.17 `int repast::AgentRequest::sourceProcess () const [inline]`

Gets the source process of these requests, that is, the process making the request.

Returns

the process making the request

5.9.3.18 `int repast::AgentRequest::targetProcess () const [inline]`

If the requested agent ids are all on the same process then target process will identify that process.

Otherwise this will return -1.

5.9.3.19 `void repast::AgentRequest::targets (std::set< int > & targets)`

Puts the targets of all the requests into the set.

Includes both the requests and the cancellations.

Parameters

<i>targets</i>	set into which targets will be placed
----------------	---------------------------------------

5.9.3.20 `void repast::AgentRequest::targetsOfCancellations (std::set< int > & targets)`

Puts the targets of all the requests into the set, including only the requests and not the cancellations.

Parameters

<i>targets</i>	the set into which the targets will be placed
----------------	---

5.9.3.21 `void repast::AgentRequest::targetsOfRequests (std::set< int > & targets)`

Puts the targets of all the requests into the set, including only the requests and not the cancellations.

Parameters

<i>targets</i>	the set into which the targets will be placed
----------------	---

The documentation for this class was generated from the following files:

- repast_hpc/AgentRequest.h
- repast_hpc/AgentRequest.cpp

5.10 repast::AgentStateFilter< T > Struct Template Reference

Used in a filter iterator to filter on local or non-local agents only.

```
#include <SharedContext.h>
```

Public Member Functions

- **AgentStateFilter** (int rankInCommunicator)
- **AgentStateFilter** (bool localFlag, int rankInCommunicator)
- bool **operator()** (const boost::shared_ptr< T > &ptr)

Public Attributes

- int **rank**
- bool **local**

5.10.1 Detailed Description

```
template<typename T>struct repast::AgentStateFilter< T >
```

Used in a filter iterator to filter on local or non-local agents only.

The documentation for this struct was generated from the following file:

- repast_hpc/SharedContext.h

5.11 repast::AgentStatus Class Reference

Encapsulates the status (moved or removed) of agent in order to synchronize that status across processes.

```
#include <AgentStatus.h>
```

Public Types

- enum **Status** { **REMOVED**, **MOVED** }
Enum indicating the status of th agent.

Public Member Functions

- **AgentStatus** ()
No-arg constructor for serialization.
- **AgentStatus** (AgentId id)

- Creates an [AgentStatus](#) indicating the status for the specified agent.
- [AgentStatus](#) ([AgentId](#) old, [AgentId](#) newId)
 - Creates an [AgentStatus](#) indicating the status for the specified agent and the new id of that agent as result from the change in status.
- [Status](#) [getStatus](#) () const
 - Gets the status.
- const [AgentId](#) & [getId](#) () const
 - Gets the id of the agent that this is the status for.
- const [AgentId](#) & [getOldId](#) () const
 - Gets the old id of the agent that this is the status for, if this contains an old and updated [AgentId](#).
- const [AgentId](#) & [getNewId](#) () const
 - Gets the new updated id of the agent that this is the status for, if this contains an old and updated [AgentId](#).

Friends

- class **boost::serialization::access**
- bool [operator<](#) (const [AgentStatus](#) &one, const [AgentStatus](#) &two)
 - Comparison operator that can be used in sorts, etc.

5.11.1 Detailed Description

Encapsulates the status (moved or removed) of agent in order to synchronize that status across processes.

5.11.2 Constructor & Destructor Documentation

5.11.2.1 repast::AgentStatus::AgentStatus ([AgentId](#) id)

Creates an [AgentStatus](#) indicating the status for the specified agent.

Parameters

<i>id</i>	the id of the agent whose status this represents
-----------	--

5.11.2.2 repast::AgentStatus::AgentStatus ([AgentId](#) old, [AgentId](#) newId)

Creates an [AgentStatus](#) indicating the status for the specified agent and the new id of that agent as result from the change in status.

When an agent moves between processes its current rank may change and thus the current rank part of its id will change.

Parameters

<i>old</i>	the id of the agent whose status this represents
<i>newId</i>	the new id of the agent that results from its status change

5.11.3 Member Function Documentation

5.11.3.1 const [AgentId](#)& repast::AgentStatus::getId () const `[inline]`

Gets the id of the agent that this is the status for.

Returns

the id of the agent that this is the status for.

5.11.3.2 `const AgentId& repast::AgentStatus::getNewId () const [inline]`

Gets the new updated id of the agent that this is the status for, if this contains an old and updated [AgentId](#).

Returns

Gets the new id of the agent that this is the status for, if this contains an old and updated [AgentId](#).

5.11.3.3 `const AgentId& repast::AgentStatus::getOldId () const [inline]`

Gets the old id of the agent that this is the status for, if this contains an old and updated [AgentId](#).

Returns

Gets the old id of the agent that this is the status for, if this contains an old and updated [AgentId](#).

5.11.3.4 `Status repast::AgentStatus::getStatus () const [inline]`

Gets the status.

Returns

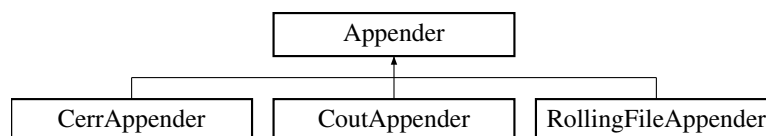
the status

The documentation for this class was generated from the following files:

- repast_hpc/AgentStatus.h
- repast_hpc/AgentStatus.cpp

5.12 Appender Class Reference

Inheritance diagram for Appender:

**Public Member Functions**

- **Appender** (const std::string name)
- virtual void **write** (const std::string &line)=0
- virtual void **close** ()
- const std::string & **name** () const

Protected Attributes

- `const std::string _name`

The documentation for this class was generated from the following files:

- `repast_hpc/logger.h`
- `repast_hpc/logger.cpp`

5.13 AppenderBuilder Class Reference

Public Member Functions

- **AppenderBuilder** (`const std::string name`)
- [Appender](#) * **build** ()

Public Attributes

- `std::string name`
- `std::string file_name`
- `long max_size`
- `int max_idx`

The documentation for this class was generated from the following files:

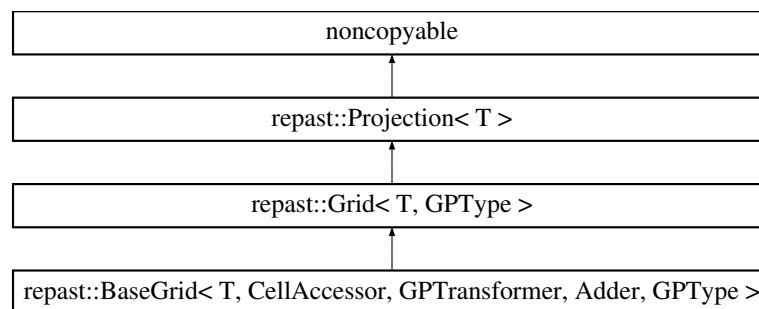
- `repast_hpc/logger.h`
- `repast_hpc/logger.cpp`

5.14 `repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >` Class Template Reference

Base grid implementation, implementing elements common to both Grids and ContinuousSpaces.

```
#include <BaseGrid.h>
```

Inheritance diagram for `repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >`:



Public Types

- typedef
`boost::transform_iterator
< AgentFromGridPoint< T,
GPType >, LocationMapConstIter > const_iterator`

A const iterator over `shared_ptr<T>`.

Public Member Functions

- `BaseGrid` (std::string name, GridDimensions dimensions)
Creates a `BaseGrid` with the specified name and dimensions.
- virtual bool contains (const AgentId &id)
Gets whether or not this grid contains the agent with the specified id.
- virtual bool getLocation (const T *agent, std::vector< GPTYPE > &pt) const
Gets the location of this agent and puts it in the specified vector.
- virtual bool getLocation (const AgentId &id, std::vector< GPTYPE > &out) const
Gets the location of this agent and puts it in the specified vectors.
- virtual T * getObjectAt (const Point< GPTYPE > &pt) const
Gets the first object found at the specified point, or NULL if there is no such object.
- virtual void getObjectsAt (const Point< GPTYPE > &pt, std::vector< T * > &out) const
Gets all the objects found at the specified point.
- virtual bool moveTo (const T *agent, const std::vector< GPTYPE > &newLocation)
Moves the specified agent to the specified location.
- virtual bool moveTo (const T *agent, const Point< GPTYPE > &newLocation)
Moves the specified agent to the specified location.
- virtual bool moveTo (const AgentId &id, const std::vector< GPTYPE > &newLocation)
Moves the specified agent to the specified location.
- virtual bool moveTo (const AgentId &id, const Point< GPTYPE > &pt)
Moves the specified agent to the specified point.
- virtual std::pair< bool, Point
< GPTYPE > > moveByDisplacement (const T *agent, const std::vector< GPTYPE > &displacement)
Moves the specified object from its current location by the specified amount.
- virtual std::pair< bool, Point
< GPTYPE > > moveByVector (const T *agent, double distance, const std::vector< double > &anglesInRadians)
doc inherited from Grid
- virtual const_iterator begin () const
Gets an iterator over the agents in this `BaseGrid` starting with the first agent.
- virtual const_iterator end () const
Gets the end of an iterator over the agents in this `BaseGrid`.
- virtual size_t size () const
Gets the number of agents in this `BaseGrid`.
- virtual double getDistance (const Point< GPTYPE > &pt1, const Point< GPTYPE > &pt2) const
Gets the distance between the two grid points.
- virtual double getDistanceSq (const Point< GPTYPE > &pt1, const Point< GPTYPE > &pt2) const
Gets the square of the distance between the two grid points.
- virtual void getDisplacement (const Point< GPTYPE > &pt1, const Point< GPTYPE > &pt2, std::vector< GPTYPE > &out) const
Gets vector difference between point 1 and point 2, putting the result in out.
- virtual const GridDimensions dimensions () const
Gets the dimensions of this `Grid`.
- virtual void translate (const Point< GPTYPE > &location, const Point< GPTYPE > &displacement, std::vector< GPTYPE > &out) const
Translates the specified location by the specified displacement put the result in out.
- virtual void transform (const std::vector< GPTYPE > &location, std::vector< GPTYPE > &out) const
Transforms the specified location using the properties (e.g.

- virtual bool `isPeriodic` () const
Gets whether or not this grid is periodic (i.e.
- virtual `ProjectionInfoPacket` * `getProjectionInfo` (`AgentId` id, bool secondaryInfo=false, std::set< `AgentId` > *secondaryIds=0, int destProc=-1)
- virtual void `updateProjectionInfo` (`ProjectionInfoPacket` *pip, `Context`< T > *context)
- virtual void `getAgentsToPush` (std::set< `AgentId` > &agentsToTest, std::map< int, std::set< `AgentId` > > &agentsToPush)
Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Protected Types

- typedef `AgentLocationMap::iterator` **LocationMapIter**
- typedef `AgentLocationMap::const_iterator` **LocationMapConstIter**

Protected Member Functions

- virtual bool `addAgent` (boost::shared_ptr< T > agent)
- virtual void `removeAgent` (T *agent)
- `LocationMapConstIter` `locationsBegin` () const
- `LocationMapConstIter` `locationsEnd` () const
- T * `get` (const `AgentId` &id)

Protected Attributes

- GPTransformer **gpTransformer**
- Adder **adder**

5.14.1 Detailed Description

template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>class repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >

Base grid implementation, implementing elements common to both Grids and ContinuousSpaces.

Standard grid and space types that provide defaults for the various template parameters can be found in Space in Space.h

Template Parameters

<i>T</i>	the type of objects contained by this <code>BaseGrid</code> (generally the type of agents)
<i>CellAccessor</i>	implements the actual storage for the grid.
<i>GPTransformer</i>	transforms cell points according to the topology (e.g. periodic) of the <code>BaseGrid</code> .
<i>Adder</i>	determines how objects are added to the grid from its associated context.
<i>GPType</i>	the coordinate type of the grid point locations; this must be an int or a double.

5.14.2 Constructor & Destructor Documentation

5.14.2.1 template<typename T , typename CellAccessor , typename GPTransformer , typename Adder , typename GPType > repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::BaseGrid (std::string *name*, GridDimensions *dimensions*)

Creates a `BaseGrid` with the specified name and dimensions.

Parameters

<i>name</i>	the name of the BaseGrid
<i>dimensions</i>	the dimensions of the BaseGrid

5.14.3 Member Function Documentation

5.14.3.1 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
virtual const_iterator repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::begin () const
[inline], [virtual]`

Gets an iterator over the agents in this [BaseGrid](#) starting with the first agent.

The iterator dereferences into `shared_ptr<T>`. The actual agent can be accessed by dereferenceing the iter: `(*iter)->getId()` for example.

Returns

an iterator over the agents in this [BaseGrid](#) starting with the first agent.

5.14.3.2 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType >
bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::contains (const AgentId & id)
[virtual]`

Gets whether or not this grid contains the agent with the specified id.

Parameters

<i>id</i>	the id of the agent to check
-----------	------------------------------

Returns

true if the grid contains the agent, otherwise false.

Implements [repast::Grid< T, GPType >](#).

5.14.3.3 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType> virtual
const GridDimensions repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::dimensions ()
const [inline], [virtual]`

Gets the dimensions of this [Grid](#).

Returns

the dimensions of this [Grid](#).

Implements [repast::Grid< T, GPType >](#).

Reimplemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), and [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#).

5.14.3.4 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
virtual const_iterator repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::end () const
[inline], [virtual]`

Gets the end of an iterator over the agents in this [BaseGrid](#).

Returns

the end of an iterator over the agents in this [BaseGrid](#).

```
5.14.3.5  template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
          virtual void repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getAgentsToPush ( std::set<
          AgentId > & agentsToTest, std::map< int, std::set< AgentId > > & agentsToPush ) [inline],
          [virtual]
```

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Implements [repast::Grid< T, GPType >](#).

Reimplemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), and [repast::SharedDiscreteSpace< T, GPTransformer, Adder >](#).

```
5.14.3.6  template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
          void repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getDisplacement ( const Point<
          GPType > & pt1, const Point< GPType > & pt2, std::vector< GPType > & out ) const [virtual]
```

Gets vector difference between point 1 and point 2, putting the result in out.

Parameters

	<i>p1</i>	the first point
	<i>p2</i>	the second point
out	<i>the</i>	vector where the difference will be put

Implements [repast::Grid< T, GPType >](#).

```
5.14.3.7  template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
          double repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getDistance ( const Point<
          GPType > & pt1, const Point< GPType > & pt2 ) const [virtual]
```

Gets the distance between the two grid points.

Parameters

<i>p1</i>	the first point
<i>p2</i>	the second point

Returns

the distance between pt1 and pt2.

Implements [repast::Grid< T, GPType >](#).

```
5.14.3.8  template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
          double repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getDistanceSq ( const Point<
          GPType > & pt1, const Point< GPType > & pt2 ) const [virtual]
```

Gets the square of the distance between the two grid points.

Parameters

<i>p1</i>	the first point
<i>p2</i>	the second point

Returns

the square of the distance between pt1 and pt2.

Implements [repast::Grid< T, GPType >](#).

```
5.14.3.9  template<typename T, typename CellAccessor , typename GPTransformer , typename Adder , typename GPType>
          bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getLocation ( const T * agent,
          std::vector< GPType > & out ) const    [virtual]
```

Gets the location of this agent and puts it in the specified vector.

The x coordinate will be the first value, the y the second and so on.

Parameters

	<i>agent</i>	the agent whose location we want to get
<i>out</i>	<i>the</i>	vector where the agents location will be put

Returns

true if the location was successfully found, otherwise false.

Implements [repast::Grid< T, GPType >](#).

```
5.14.3.10 template<typename T, typename CellAccessor , typename GPTransformer , typename Adder , typename GPType>
          bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getLocation ( const AgentId & id,
          std::vector< GPType > & out ) const    [virtual]
```

Gets the location of this agent and puts it in the specified vectors.

The x coordinate will be the first value, the y the second and so on.

Parameters

	<i>id</i>	the id of the agent whose location we want to get
<i>out</i>	<i>out</i>	the agent's location will be put into this vector

Returns

true if the location was successfully found, otherwise false.

Implements [repast::Grid< T, GPType >](#).

```
5.14.3.11 template<typename T , typename CellAccessor , typename GPTransformer , typename Adder , typename GPType> T
          * repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getObjectAt ( const Point< GPType >
          & pt ) const    [virtual]
```

Gets the first object found at the specified point, or NULL if there is no such object.

Returns

the first object found at the specified point, or NULL if there is no such object.

Implements [repast::Grid< T, GPType >](#).

5.14.3.12 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
void repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getObjectsAt (const Point<
GPType > & pt, std::vector< T * > & out) const [virtual]`

Gets all the objects found at the specified point.

The found objects will be put into the out parameter.

Parameters

	<i>pt</i>	the point to get all the objects at
out	<i>out</i>	the vector into which the found objects will be put

Implements [repast::Grid< T, GPType >](#).

5.14.3.13 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
virtual bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::isPeriodic () const
[inline], [virtual]`

Gets whether or not this grid is periodic (i.e.

toroidal).

Returns

true if this [Grid](#) is periodic, otherwise false.

Implements [repast::Grid< T, GPType >](#).

5.14.3.14 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
std::pair< bool, Point< GPType > > repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType
>::moveByDisplacement (const T * agent, const std::vector< GPType > & displacement) [virtual]`

Moves the specified object from its current location by the specified amount.

For example `moveByDisplacement(object, 3, -2, 1)` will move the object by 3 along the x-axis, -2 along the y and 1 along the z. The displacement argument can be less than the number of dimensions in the space in which case the remaining argument will be set to 0. For example, `moveByDisplacement(object, 3)` will move the object 3 along the x-axis and 0 along the y and z axes, assuming a 3D grid.

Parameters

<i>agent</i>	the object to move
<i>displacement</i>	the amount to move the object

Returns

a pair containing a bool that indicates whether the move was a success or not, and the point where the agent was moved to.

Implements [repast::Grid< T, GPType >](#).

5.14.3.15 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::moveTo (const T * agent, const
std::vector< GPType > & newLocation) [virtual]`

Moves the specified agent to the specified location.

Returns true if the move was successful otherwise false. The agent must be already added to the context associated with this space, otherwise this throws an `out_of_range` exception if the new location out of bounds.

Parameters

<i>agent</i>	the agent to move
<i>newLocation</i>	the location to move to

Returns

true if the move was successful, otherwise false

5.14.3.16 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::moveTo (const T * agent, const
Point< GPType > & newLocation) [virtual]`

Moves the specified agent to the specified location.

Returns true if the move was successful otherwise false. The agent must be already added to the context associated with this space, otherwise this throws an `out_of_range` exception if the new location out of bounds.

Parameters

<i>agent</i>	the agent to move
<i>newLocation</i>	the location to move to

Returns

true if the move was successful, otherwise false

5.14.3.17 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::moveTo (const AgentId & id, const
std::vector< GPType > & newLocation) [virtual]`

Moves the specified agent to the specified location.

Returns true if the move was successful otherwise false. The agent must be already added to the context associated with this space, otherwise this throws an `out_of_range` exception if the new location out of bounds.

Parameters

<i>id</i>	the id of the agent to move
<i>newLocation</i>	the location to move to

Returns

true if the move was successful, otherwise false

Reimplemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), and [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#).

5.14.3.18 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::moveTo (const AgentId & id, const
Point< GPType > & pt) [virtual]`

Moves the specified agent to the specified point.

Parameters

<i>id</i>	the id of the agent to move
<i>pt</i>	where to move the agent to

Returns

true if the move was successful, otherwise false

Implements [repast::Grid< T, GPType >](#).

Reimplemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), and [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#).

5.14.3.19 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
virtual size_t repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::size () const
[inline],[virtual]`

Gets the number of agents in this [BaseGrid](#).

Returns

the number of agents in this [BaseGrid](#).

5.14.3.20 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
virtual void repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::transform (const
std::vector< GPType > & location, std::vector< GPType > & out) const [inline],[virtual]`

Transforms the specified location using the properties (e.g. toroidal) of this space.

Parameters

	<i>location</i>	the location to transform
<i>out</i>	<i>out</i>	the vector where the result of the transform will be put

Implements [repast::Grid< T, GPType >](#).

5.14.3.21 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
virtual void repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::translate (const Point<
GPType > & location, const Point< GPType > & displacement, std::vector< GPType > & out) const
[inline],[virtual]`

Translates the specified location by the specified displacement put the result in out.

Parameters

	<i>location</i>	the initial location
	<i>displacement</i>	the amount to translate the location by
<i>out</i>	<i>out</i>	the vector where the result of the translation is put

Implements [repast::Grid< T, GPType >](#).

The documentation for this class was generated from the following file:

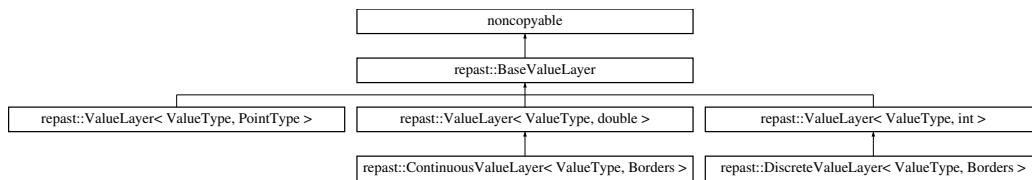
- `repast_hpc/BaseGrid.h`

5.15 repast::BaseValueLayer Class Reference

Base implementation of a [ValueLayer](#).

```
#include <ValueLayer.h>
```

Inheritance diagram for repast::BaseValueLayer:



Public Member Functions

- [BaseValueLayer](#) (const std::string &name)
Creates a [BaseValueLayer](#) with the specified name.
- std::string [name](#) () const
Gets the value layer's name.

Protected Attributes

- std::string [_name](#)

5.15.1 Detailed Description

Base implementation of a [ValueLayer](#).

A [ValueLayer](#) stores values by location.

5.15.2 Member Function Documentation

5.15.2.1 std::string repast::BaseValueLayer::name () const [inline]

Gets the value layer's name.

Returns

the name of the value layer.

The documentation for this class was generated from the following files:

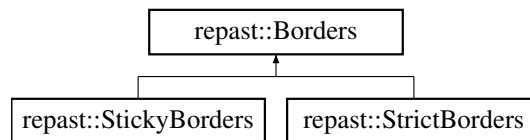
- repast_hpc/ValueLayer.h
- repast_hpc/ValueLayer.cpp

5.16 repast::Borders Class Reference

Base class for representations of border semantics (e.g.

```
#include <GridComponents.h>
```

Inheritance diagram for repast::Borders:



Public Member Functions

- **Borders** ([GridDimensions](#) d)
- void **transform** (const std::vector< int > &in, std::vector< int > &out) const
- void **transform** (const std::vector< double > &in, std::vector< double > &out) const
- bool **isPeriodic** () const

Protected Member Functions

- void **boundsCheck** (const std::vector< int > &pt) const
- void **boundsCheck** (const std::vector< double > &pt) const

Protected Attributes

- const [GridDimensions](#) **_dimensions**

5.16.1 Detailed Description

Base class for representations of border semantics (e.g.

Strict, Sticky, etc.)

The documentation for this class was generated from the following files:

- repast_hpc/GridComponents.h
- repast_hpc/GridComponents.cpp

5.17 repast::CartTopology Class Reference

Allows retrieval of the position of this process within the MPI Cartesian Topology into which it is placed.

```
#include <SharedBaseGrid.h>
```

Public Member Functions

- **CartTopology** (std::vector< int > processesPerDim, std::vector< double > origin, std::vector< double > extents, bool spacelsPeriodic, boost::mpi::communicator *world)
- void [getCoordinates](#) (int rank, std::vector< int > &coords)
Gets the coordinates in the MPI Cartesian Communicator for the specified rank.
- [GridDimensions](#) [getDimensions](#) (int rank)
Gets the [GridDimensions](#) boundaries for the specified rank.
- [GridDimensions](#) [getDimensions](#) (std::vector< int > &pCoordinates)
Gets the [GridDimensions](#) boundaries for the specified MPI coordinates.
- void **createNeighbors** ([Neighbors](#) &nghs)

5.17.1 Detailed Description

Allows retrieval of the position of this process within the MPI Cartesian Topology into which it is placed.

The documentation for this class was generated from the following files:

- repast_hpc/SharedBaseGrid.h
- repast_hpc/SharedBaseGrid.cpp

5.18 repast::CellContents< AgentContent, GPType > Class Template Reference

DEPRECATED Encapsulates the contents of a grid / space location so that it can be sent between processes.

```
#include <SharedBaseGrid.h>
```

Public Member Functions

- template<class Archive >
void **serialize** (Archive &ar, const unsigned int version)
- **CellContents** ([Point](#)< GPType > pt)

Public Attributes

- [Point](#)< GPType > **_pt**
- std::vector< AgentContent > **_objs**

Friends

- class **boost::serialization::access**

5.18.1 Detailed Description

```
template<typename AgentContent, typename GPType>class repast::CellContents< AgentContent, GPType >
```

DEPRECATED Encapsulates the contents of a grid / space location so that it can be sent between processes.

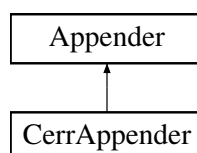
Deprecated Replaced by [ProjectionInfoPacket](#) as of Version 2.0

The documentation for this class was generated from the following file:

- repast_hpc/SharedBaseGrid.h

5.19 CerrAppender Class Reference

Inheritance diagram for CerrAppender:



Public Member Functions

- void **write** (const string &line)

Additional Inherited Members

The documentation for this class was generated from the following file:

- repast_hpc/logger.cpp

5.20 ConfigLexer Class Reference

Public Member Functions

- **ConfigLexer** (const string &file_name, boost::mpi::communicator *comm=0, int maxConfigFileSize=MAX_CONFIG_FILE_SIZE)
- TOKEN **next_token** ()
- string **key** ()
- string **value** ()
- string **error** ()
- int **line** ()
- void **reset** ()

The documentation for this class was generated from the following file:

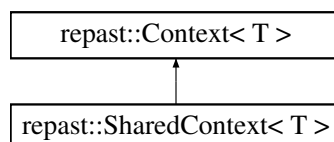
- repast_hpc/logger.cpp

5.21 repast::Context< T > Class Template Reference

Collection of agents of type T with set semantics.

```
#include <Context.h>
```

Inheritance diagram for repast::Context< T >:



Public Types

- typedef
boost::transform_iterator
< [SecondElement](#)< T >, typename
AgentMap::const_iterator > **const_iterator**
- typedef boost::filter_iterator
< [IsAgentType](#)< T >, typename
[Context](#)< T >::const_iterator > **const_bytype_iterator**

Public Member Functions

- virtual `~Context ()`
Destroys this context and the projections it contains.
- T * `addAgent (T *agent)`
Adds the agent to the context.
- virtual void `addProjection (Projection< T > *projection)`
Adds the specified projection to this context.
- `Projection< T > *getProjection (const std::string &name)`
Get the named Projection.
- void `removeAgent (const AgentId id)`
Removes the specified agent from this context.
- void `removeAgent (T *agent)`
Removes the specified agent from this context.
- T * `getAgent (const AgentId &id)`
Gets the specified agent.
- void `getRandomAgents (const int count, std::vector< T * > &agents)`
Gets at random the specified count of agents and returns them in the agents vector.
- const_iterator `begin () const`
Gets the start of iterator over the agents in this context.
- const_iterator `end () const`
Gets the end of an iterator over the agents in this context.
- const_bytype_iterator `byTypeBegin (int typeId) const`
Gets the start of an iterator over agents in this context of the specified type.
- const_bytype_iterator `byTypeEnd (int typeId) const`
Gets the end of an iterator over agents in this context of the specified type.
- bool `contains (const AgentId &id)`
Returns true if the specified agent is in this context, otherwise false.
- int `size () const`
Gets the size (number of agents) in this context.
- void `addValueLayer (BaseValueLayer *valueLayer)`
Adds a value layer to this context.
- template<typename ValueType , typename Borders >
 `DiscreteValueLayer< ValueType, Borders > *getDiscreteValueLayer (const std::string &valueLayerName)`
 Gets the named discrete value layer from this Context.
- template<typename ValueType , typename Borders >
 `ContinuousValueLayer< ValueType, Borders > *getContinuousValueLayer (const std::string &valueLayerName)`
 Gets the named continuous value layer from this Context.
- template<typename filterStruct >
 boost::filter_iterator
 < filterStruct, typename
 Context< T >::const_iterator > `filteredBegin (const filterStruct &fStruct)`
 Creates a filtered iterator over the set of agents in this context and returns it with a value equal to the beginning of the list.
- template<typename filterStruct >
 boost::filter_iterator
 < filterStruct, typename
 Context< T >::const_iterator > `filteredEnd (const filterStruct &fStruct)`
 Creates a filtered iterator over the set of agents in this context and returns it with a value equal to one step past end of the list.

- template<typename filterStruct >
 boost::filter_iterator
 < filterStruct, typename
[Context](#)< T >
 ::const_bytype_iterator > [byTypeFilteredBegin](#) (const int type, const filterStruct &fStruct)
Creates a filtered iterator over the set of agents in this context of the specified type (per their [AgentId](#) values), and returns it with a value equal to the beginning of the list.
- template<typename filterStruct >
 boost::filter_iterator
 < filterStruct, typename
[Context](#)< T >
 ::const_bytype_iterator > [byTypeFilteredEnd](#) (const int type, const filterStruct &fStruct)
Creates a filtered iterator over the set of agents in this context of the specified type (per their [AgentId](#) values), and returns it with a value equal to one past the end of the list.
- void [selectAgents](#) (std::set< T * > &selectedAgents, bool remove=false)
Gets a set of pointers to all agents in this context.
- void [selectAgents](#) (std::vector< T * > &selectedAgents, bool remove=false)
Gets a randomly ordered vector of pointers to all agents in this context.
- void [selectAgents](#) (int count, std::set< T * > &selectedAgents, bool remove=false)
Gets a set of pointers to a specified number of randomly selected agents.
- void [selectAgents](#) (int count, std::vector< T * > &selectedAgents, bool remove=false)
Gets a randomly ordered vector of pointers to a specified number of randomly selected agents.
- void [selectAgents](#) (std::set< T * > &selectedAgents, int type, bool remove=false, int popSize=-1)
Gets a set of pointers to all agents in this context of a specified type (per their [AgentId](#) values).
- void [selectAgents](#) (std::vector< T * > &selectedAgents, int type, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to all agents in this context of a specified type (per their [AgentId](#) values).
- void [selectAgents](#) (int count, std::set< T * > &selectedAgents, int type, bool remove=false, int popSize=-1)
Gets a set of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values).
- void [selectAgents](#) (int count, std::vector< T * > &selectedAgents, int type, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values).
- template<typename filterStruct >
 void [selectAgents](#) (std::set< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a set of pointers to all agents in this context matching a user-defined filter.
- template<typename filterStruct >
 void [selectAgents](#) (std::vector< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to all agents in this context matching a user-defined filter.
- template<typename filterStruct >
 void [selectAgents](#) (int count, std::set< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a set of pointers to a specified number of randomly selected agents matching a user-defined filter.
- template<typename filterStruct >
 void [selectAgents](#) (int count, std::vector< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to a specified number of randomly selected agents matching a user-defined filter.
- template<typename filterStruct >
 void [selectAgents](#) (std::set< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a set of pointers to all agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.
- template<typename filterStruct >
 void [selectAgents](#) (std::vector< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to a specified number of randomly selected agents matching a user-defined filter.

Gets a randomly ordered vector of pointers to all agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

- `template<typename filterStruct >`
`void selectAgents (int count, std::set< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)`

Gets a set of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

- `template<typename filterStruct >`
`void selectAgents (int count, std::vector< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)`

Gets a randomly ordered vector of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

- `void getProjectionInfo (AgentRequest req, std::map< std::string, std::vector< repast::ProjectionInfoPacket * > > &map, bool secondaryInfo=false, std::set< AgentId > *secondaryIds=0, int destProc=-1)`

Gets the projection information for all projections in this context, for all agents whose IDs are listed in the [AgentRequest](#).

- `void setProjectionInfo (std::map< std::string, std::vector< repast::ProjectionInfoPacket * > > &projInfo)`

Sets the projection information as specified.

- `void cleanProjectionInfo (std::set< AgentId > &agentsToKeep)`

Protected Attributes

- `std::vector< Projection< T > * > projections`

5.21.1 Detailed Description

`template<typename T>class repast::Context< T >`

Collection of agents of type T with set semantics.

Object identity and equality is determined by their [AgentId](#).

Template Parameters

<i>the</i>	type objects contained by the Context . The T must extends repast::Agent .
------------	--

5.21.2 Member Function Documentation

5.21.2.1 `template<typename T> T * repast::Context< T >::addAgent (T * agent)`

Adds the agent to the context.

Performs a check to ensure that no agent with the same ID (presumably the 'same' agent) has previously been added. If a matching ID is found, the new agent is not added, and the address of the pre-existing agent is returned. If no match is found, the agent is added and the return value is the same as the value passed

Parameters

<i>agent</i>	the agent to add
--------------	------------------

Returns

the address of the agent in the context; will be the same as the address passed if the agent was successfully added, but if there was already an agent with the same ID the address returned will be that of the pre-existing agent, which is not replaced.

5.21.2.2 `template<typename T> void repast::Context< T >::addProjection (Projection< T > * projection)`
`[virtual]`

Adds the specified projection to this context.

All the agents in this context will be added to the [Projection](#). Any agents subsequently added to this context will also be added to the [Projection](#).

Parameters

<i>projection</i>	the projection to add
-------------------	-----------------------

Reimplemented in [repast::SharedContext< T >](#).

5.21.2.3 `template<typename T> void repast::Context< T >::addValueLayer (BaseValueLayer * valueLayer)`

Adds a value layer to this context.

Parameters

<i>valueLayer</i>	the value layer to add
-------------------	------------------------

5.21.2.4 `template<typename T> const_iterator repast::Context< T >::begin () const` `[inline]`

Gets the start of iterator over the agents in this context.

The iterator dereferences into `shared_ptr<T>`. The actual agent can be accessed by dereferenceing the iter: `(*iter)->getId()` for example.

Returns

the start of iterator over the agents in this context.

5.21.2.5 `template<typename T> const_bytype_iterator repast::Context< T >::byTypeBegin (int typeld) const`
`[inline]`

Gets the start of an iterator over agents in this context of the specified type.

The type corresponds to the type component of an agent's [AgentId](#).

Parameters

<i>typeld</i>	the type of the agent. Only Agents whose <code>agentId.agentType()</code> is equal to this <code>typeld</code> will be included in the iterator
---------------	---

Returns

the start of an iterator over agents in this context of the specified type.

5.21.2.6 `template<typename T> const_bytype_iterator repast::Context< T >::byTypeEnd (int typeld) const`
`[inline]`

Gets the end of an iterator over agents in this context of the specified type.

The type corresponds to the type component of an agent's [AgentId](#).

Parameters

<i>typeId</i>	the type of the agent. Only Agents whose <code>agentId.agentType()</code> is equal to this <code>typeId</code> will be included in the iterator
---------------	---

Returns

the end of an iterator over agents in this context of the specified type.

5.21.2.7 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename Context< T>::const_bytype_iterator> repast::Context< T>::byTypeFilteredBegin (const int type, const filterStruct & fStruct)`

Creates a filtered iterator over the set of agents in this context of the specified type (per their [AgentId](#) values), and returns it with a value equal to the beginning of the list.

The struct can be any user-defined structure that implements a unary operator (see [IsAgentType](#)) that can be passed and which will become a filter to sort across the agent list, e.g.:

```
struct filter { bool operator()(const boost::shared_ptr<T>& ptr){ return (ptr->getAgentValue() == targetValue;) } }
```

This should allow filtering of agents by type and on any attribute.

Parameters

<i>fStruct</i>	an instance of the struct to be used as the filter
<i>type</i>	the numeric type of agents to be included in the list

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

Returns

an iterator positioned at the beginning of the list of agents meeting the filter's criteria

5.21.2.8 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename Context< T>::const_bytype_iterator> repast::Context< T>::byTypeFilteredEnd (const int type, const filterStruct & fStruct)`

Creates a filtered iterator over the set of agents in this context of the specified type (per their [AgentId](#) values), and returns it with a value equal to one past the end of the list.

The struct can be any user-defined structure that implements a unary operator (see [IsAgentType](#)) that can be passed and which will become a filter to sort across the agent list, e.g.:

```
struct filter { bool operator()(const boost::shared_ptr<T>& ptr){ return (ptr->getAgentValue() == targetValue;) } }
```

This should allow filtering of agents by type and on any attribute.

Parameters

<i>fStruct</i>	an instance of the struct to be used as the filter
<i>type</i>	the numeric type of agents to be included in the list

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

Returns

an iterator positioned at one past the end of the list of agents meeting the filter's criteria

5.21.2.9 `template<typename T> const_iterator repast::Context< T >::end () const [inline]`

Gets the end of an iterator over the agents in this context.

The iterator dereferences into `shared_ptr<T>`. The actual agent can be accessed by dereferenceing the iter: `(*iter)->getId()` for example.

Returns

the end of an iterator over the agents in this context

5.21.2.10 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename Context< T >::const_iterator> repast::Context< T >::filteredBegin (const filterStruct & fStruct)`

Creates a filtered iterator over the set of agents in this context and returns it with a value equal to the beginning of the list.

The struct can be any user-defined structure that implements a unary operator (see [IsAgentType](#)) that can be passed and which will become a filter to sort across the agent list, e.g.:

```
struct filter { bool operator()(const boost::shared_ptr<T>& ptr){ return (ptr->getAgentValue() == targetValue;) } }
```

This should allow filtering of agents by any attribute.

Parameters

<i>fStruct</i>	an instance of the struct to be used as the filter
----------------	--

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

Returns

an iterator positioned at the beginning of the list of agents meeting the filter's criteria

5.21.2.11 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename Context< T >::const_iterator> repast::Context< T >::filteredEnd (const filterStruct & fStruct)`

Creates a filtered iterator over the set of agents in this context and returns it with a value equal to one step past end of the list.

The struct can be any user-defined structure that implements a unary operator (see [IsAgentType](#)) that can be passed and which will become a filter to sort across the agent list, e.g.:

```
struct filter { bool operator()(const boost::shared_ptr<T>& ptr){ return (ptr->getAgentValue() == targetValue;) } }
```

This should allow filtering of agents by any attribute.

Parameters

<i>fStruct</i>	an instance of the struct to be used as the filter
----------------	--

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

Returns

an iterator positioned at one past the end of the list of agents meeting the filter's criteria

5.21.2.12 `template<typename T> T * repast::Context< T >::getAgent (const AgentId & id)`

Gets the specified agent.

Parameters

<i>the</i>	id of the agent to get.
------------	-------------------------

5.21.2.13 `template<typename T> template<typename ValueType , typename Borders > ContinuousValueLayer< ValueType, Borders > * repast::Context< T >::getContinuousValueLayer (const std::string & valueLayerName)`

Gets the named continuous value layer from this [Context](#).

The value layer must have been previously added.

Parameters

<i>valueLayerName</i>	the name of the value layer to get
-----------------------	------------------------------------

Template Parameters

<i>ValueType</i>	the numeric type contained by the value layer
<i>Borders</i>	the Border type of the value layer

Returns

the named continuous value layer from this [Context](#).

5.21.2.14 `template<typename T> template<typename ValueType , typename Borders > DiscreteValueLayer< ValueType, Borders > * repast::Context< T >::getDiscreteValueLayer (const std::string & valueLayerName)`

Gets the named discrete value layer from this [Context](#).

The value layer must have been previously added.

Parameters

<i>valueLayerName</i>	the name of the value layer to get
-----------------------	------------------------------------

Template Parameters

<i>ValueType</i>	the numeric type contained by the value layer
<i>Borders</i>	the Border type of the value layer

Returns

the named discrete value layer from this [Context](#).

5.21.2.15 `template<typename T> Projection< T > * repast::Context< T >::getProjection (const std::string & name)`

Get the named [Projection](#).

Parameters

<i>the</i>	name of the projection to get
------------	-------------------------------

Returns

the named [Projection](#) or 0 if no such [Projection](#) is found.

5.21.2.16 `template<typename T> void repast::Context< T >::getProjectionInfo (AgentRequest req, std::map< std::string, std::vector< repast::ProjectionInfoPacket * > > & map, bool secondaryInfo = false, std::set< AgentId > * secondaryIds = 0, int destProc = -1)`

Gets the projection information for all projections in this context, for all agents whose IDs are listed in the [Agent-Request](#).

The general sense of this method can be easily understood: given a list of agents, get the projection information for all of those agents. But there are some subtleties that should be kept in mind.

"The projection information for an agent" is misleading. In fact, the projection information that is needed can vary depending on the context and on the kind of projection.

Generally speaking, spaces return only one kind projection information: coordinate locations for the agent specified. This is the simplest case.

The more complicated case is given by graphs. A graph projection can return different sets of information depending on how that information will have to be used. The basic issue is that a graph projection returns sets of edges, and edges must be connected to other agents; this means that a mechanism must be in place for ensuring that the projection info that arrives can be used, which means that for a given 'ego' agent, all 'alter' agents that are connected to it by edges must also be on the receiving process. (Note: Repast HPC 1.0 versions sent all of the alter agents' content along with the edge send; this version does not do this, partly to minimize the amount of information being packaged and sent but also because the alternative method used is integrated with the normal bookkeeping for sharing agent information across processes (AgentRequests).) In different circumstances, different assumptions can be made about what information will be available on the receiving process. Note that the coordinate information is generally referred to as 'Primary' information, while edge information is 'secondary'; in a third category ('secondary IDs') are the IDs of the alter agents, which can be packaged separately.

The impact of this is that this function is generally called in the following ways:

- 1) When requesting agents: in this case, a copy of the agent will be sent from one process to another. No secondary information will be sent at all. This is because it is assumed that if an agent participated in a graph on the receiving process, it would already be present on that process and would not be being requested.
- 2) When synchronizing [Projection](#) Information: in this case, some secondary information (edges) is needed: the edges that connect the specified ego agent with edges on the receiving process. No secondary IDs are needed, because the only edges being sent are those that connect to agents on the receiving process, which will be assumed to already be available on that process.
- 3) When synchronizing [Agent](#) Status (moving agents from process to process): in this case, the full collection of projection information is needed, including all of the edges in which the specified agent participates and all of the secondary IDs. (The secondary IDs of agents that are already on the receiving process can be omitted, at least theoretically.) This allows the full reconstruction of [Projection](#) Information on the receiving process.

Parameters

<i>req</i>	List of IDs for agents whose information is requested
<i>map</i>	A map into which the projection information will be placed. Key values represent the names of the projections in this context.
<i>secondaryInfo</i>	true if the 'secondary' projection info must also be returned
<i>secondaryIds</i>	A set of IDs for agents who are referred to by the projection informaton being returned (may be null)
<i>destProc</i>	The Process that will be receiving this information (the information sent may be customized depending on the destination process). If not specified a larger set of information will be sent.

5.21.2.17 `template<typename T> void repast::Context< T >::getRandomAgents (const int count, std::vector< T * > & agents)`

Gets at random the specified count of agents and returns them in the agents vector.

Parameters

	<i>count</i>	the number of agents to get
out	<i>agents</i>	a vector where the agents will be returned

5.21.2.18 `template<typename T> void repast::Context< T >::removeAgent (const AgentId id)`

Removes the specified agent from this context.

Parameters

	<i>id</i>	the id of the agent to remove
--	-----------	-------------------------------

5.21.2.19 `template<typename T> void repast::Context< T >::selectAgents (std::set< T * > & selectedAgents, bool remove = false)`

Gets a set of pointers to all agents in this context.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

Parameters

out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)

5.21.2.20 `template<typename T> void repast::Context< T >::selectAgents (std::vector< T * > & selectedAgents, bool remove = false)`

Gets a randomly ordered vector of pointers to all agents in this context.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

Parameters

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)

5.21.2.21 `template<typename T> void repast::Context< T >::selectAgents (int count, std::set< T * > & selectedAgents, bool remove = false)`

Gets a set of pointers to a specified number of randomly selected agents.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)

5.21.2.22 `template<typename T> void repast::Context< T >::selectAgents (int count, std::vector< T * > & selectedAgents, bool remove = false)`

Gets a randomly ordered vector of pointers to a specified number of randomly selected agents.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)

5.21.2.23 `template<typename T> void repast::Context< T >::selectAgents (std::set< T * > & selectedAgents, int type, bool remove = false, int popSize = -1)`

Gets a set of pointers to all agents in this context of a specified type (per their [AgentId](#) values).

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.21.2.24 `template<typename T> void repast::Context< T >::selectAgents (std::vector< T * > & selectedAgents, int type, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to all agents in this context of a specified type (per their [AgentId](#) values).

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.21.2.25 `template<typename T> void repast::Context< T >::selectAgents (int count, std::set< T * > & selectedAgents, int type, bool remove = false, int popSize = -1)`

Gets a set of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values).

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.21.2.26 `template<typename T> void repast::Context< T >::selectAgents (int count, std::vector< T * > & selectedAgents, int type, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values).

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.21.2.27 `template<typename T> template<typename filterStruct> void repast::Context< T >::selectAgents (std::set< T* > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a set of pointers to all agents in this context matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

that can possibly be selected, all possible agents will be selected

Parameters

out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.21.2.28 `template<typename T> template<typename filterStruct> void repast::Context< T >::selectAgents (std::vector< T* > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to all agents in this context matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.21.2.29 `template<typename T> template<typename filterStruct> void repast::Context<T>::selectAgents (int count, std::set< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a set of pointers to a specified number of randomly selected agents matching a user-defined filter.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.21.2.30 `template<typename T> template<typename filterStruct> void repast::Context<T>::selectAgents (int count, std::vector< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to a specified number of randomly selected agents matching a user-defined filter.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.21.2.31 `template<typename T> template<typename filterStruct> void repast::Context< T >::selectAgents (std::set< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a set of pointers to all agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.21.2.32 `template<typename T> template<typename filterStruct> void repast::Context< T >::selectAgents (std::vector< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to all agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.21.2.33 `template<typename T> template<typename filterStruct> void repast::Context< T >::selectAgents (int count, std::set< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a set of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The `popSize` parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.21.2.34 `template<typename T> template<typename filterStruct> void repast::Context< T>::selectAgents (int count, std::vector< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The `popSize` parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.21.2.35 `template<typename T> void repast::Context< T>::setProjectionInfo (std::map< std::string, std::vector< repast::ProjectionInfoPacket * > > & projInfo)`

Sets the projection information as specified.

Parameters

<i>projInfo</i>	map where keys represent projections in this context and the values represent collections of projection information content that will be used to specify the relationships among the agents.
-----------------	--

The documentation for this class was generated from the following file:

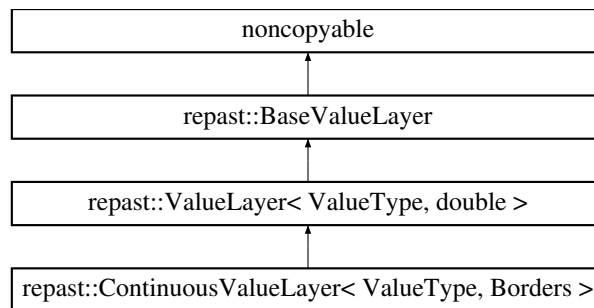
- repast_hpc/Context.h

5.22 repast::ContinuousValueLayer< ValueType, Borders > Class Template Reference

Continuous value layer whose location coordinates are double.

```
#include <ValueLayer.h>
```

Inheritance diagram for repast::ContinuousValueLayer< ValueType, Borders >:



Public Member Functions

- **ContinuousValueLayer** (const [ContinuousValueLayer](#)< ValueType, [Borders](#) > &other)
- [ContinuousValueLayer](#) & **operator=** (const [ContinuousValueLayer](#)< ValueType, [Borders](#) > &rhs)
- [ContinuousValueLayer](#) (const std::string &name, const [GridDimensions](#) &dimensions, const ValueType &defaultValue=ValueType())
Creates a [ContinuousValueLayer](#) whose cells contain a default value of ValueType() with the specified dimensions.
- ValueType & [get](#) (const [Point](#)< double > &pt)
Gets the value at the specified point.
- void [set](#) (const ValueType &value, const [Point](#)< double > &pt)
Sets the value at the specified point.

5.22.1 Detailed Description

```
template<typename ValueType, typename Borders>class repast::ContinuousValueLayer< ValueType, Borders >
```

Continuous value layer whose location coordinates are double.

Template Parameters

<i>ValueType</i>	the type of what the value layer stores.
<i>Borders</i>	the type of borders (wrapped / periodic, strict). Border types can be found in GridComponents.h

5.22.2 Constructor & Destructor Documentation

5.22.2.1 `template<typename ValueType , typename Borders > repast::ContinuousValueLayer< ValueType, Borders >::ContinuousValueLayer (const std::string & name, const GridDimensions & dimensions, const ValueType & defaultValue = ValueType ())`

Creates a [ContinuousValueLayer](#) whose cells contain a default value of `ValueType()` with the specified dimensions.

Parameters

<i>name</i>	the name of the ContinuousValueLayer
<i>dimension</i>	the dimensions of the ContinuousValueLayer
<i>dense</i>	whether or not the ValueLayer will be densely populated or not
<i>defaultValue</i>	the default value to return if no value has been set of a location. The default is the result of <code>ValueType()</code> .

5.22.3 Member Function Documentation

5.22.3.1 `template<typename ValueType , typename Borders > ValueType & repast::ContinuousValueLayer< ValueType, Borders >::get (const Point< double > & pt) [virtual]`

Gets the value at the specified point.

If no value has been set at the specified point then this returns the default value.

param *pt* the location to get the value of

Returns

the value at the specified point, or if no value has been set, then the default value.

Implements [repast::ValueLayer< ValueType, double >](#).

5.22.3.2 `template<typename ValueType , typename Borders > void repast::ContinuousValueLayer< ValueType, Borders >::set (const ValueType & value, const Point< double > & pt) [virtual]`

Sets the value at the specified point.

Parameters

<i>value</i>	the value
<i>pt</i>	the point where the value should be stored

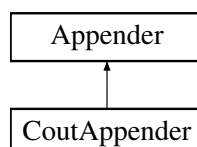
Implements [repast::ValueLayer< ValueType, double >](#).

The documentation for this class was generated from the following file:

- `repast_hpc/ValueLayer.h`

5.23 CoutAppender Class Reference

Inheritance diagram for CoutAppender:



Public Member Functions

- void **write** (const string &line)

Additional Inherited Members

The documentation for this class was generated from the following file:

- repast_hpc/logger.cpp

5.24 repast::data_type_traits< T > Struct Template Reference

Base class for specialized int and double type classes.

```
#include <SVDataSource.h>
```

5.24.1 Detailed Description

```
template<typename T>struct repast::data_type_traits< T >
```

Base class for specialized int and double type classes.

The documentation for this struct was generated from the following file:

- repast_hpc/SVDataSource.h

5.25 repast::data_type_traits< double > Struct Template Reference

Double data types for [SVDataSource](#) objects.

```
#include <SVDataSource.h>
```

Static Public Member Functions

- static SVDataSource::DataType **data_type** ()

5.25.1 Detailed Description

```
template<>struct repast::data_type_traits< double >
```

Double data types for [SVDataSource](#) objects.

The documentation for this struct was generated from the following file:

- repast_hpc/SVDataSource.h

5.26 repast::data_type_traits< int > Struct Template Reference

Int data types for [SVDataSource](#) objects.

```
#include <SVDataSource.h>
```

Static Public Member Functions

- static SVDataSource::DataType **data_type** ()

5.26.1 Detailed Description

```
template<> struct repast::data_type_traits< int >
```

Int data types for [SVDDataSource](#) objects.

The documentation for this struct was generated from the following file:

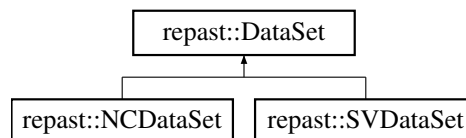
- repast_hpc/SVDDataSource.h

5.27 repast::DataSet Class Reference

Interface for recording and writing data.

```
#include <DataSet.h>
```

Inheritance diagram for repast::DataSet:



Public Member Functions

- virtual void [record](#) ()=0
Records the data.
- virtual void [write](#) ()=0
Writes the data.
- virtual void [close](#) ()=0
Closes the dataset, after which it must be recreated to be used.

5.27.1 Detailed Description

Interface for recording and writing data.

The documentation for this class was generated from the following file:

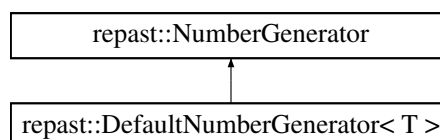
- repast_hpc/DataSet.h

5.28 repast::DefaultNumberGenerator< T > Class Template Reference

Adapts the templated boost::variate_generator to the [NumberGenerator](#) interface.

```
#include <Random.h>
```

Inheritance diagram for repast::DefaultNumberGenerator< T >:



Public Member Functions

- **DefaultNumberGenerator** (T generator)
- double [next](#) ()
Gets the "next" number from this Number Generator.

5.28.1 Detailed Description

```
template<typename T>class repast::DefaultNumberGenerator< T >
```

Adapts the templated boost::variate_generator to the [NumberGenerator](#) interface.

The documentation for this class was generated from the following file:

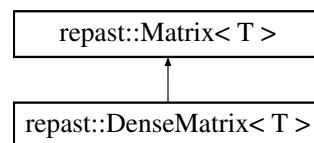
- repast_hpc/Random.h

5.29 repast::DenseMatrix< T > Class Template Reference

A dense matrix implementation that stores each cell individually.

```
#include <matrix.h>
```

Inheritance diagram for repast::DenseMatrix< T >:



Public Member Functions

- [DenseMatrix](#) (const [DenseMatrix](#)< T > &)
Creates a [DenseMatrix](#) as a copy of the specified [DenseMatrix](#).
- [DenseMatrix](#)< T > & **operator=** (const [DenseMatrix](#)< T > &)
- [DenseMatrix](#) (const [Point](#)< int > &shape, const T &defValue=T())
Creates a [DenseMatrix](#) of the specified shape and default value.
- T & [get](#) (const [Point](#)< int > &index)
Gets the value at the specified index.
- void [set](#) (const T &value, const [Point](#)< int > &index)
Sets the value at the specified index.

Additional Inherited Members

5.29.1 Detailed Description

```
template<typename T>class repast::DenseMatrix< T >
```

A dense matrix implementation that stores each cell individually.

The documentation for this class was generated from the following file:

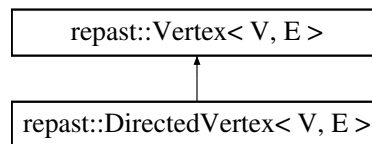
- repast_hpc/matrix.h

5.30 repast::DirectedVertex< V, E > Class Template Reference

Used internally by repast graphs / networks to encapsulate the vertices of a directed graph.

```
#include <DirectedVertex.h>
```

Inheritance diagram for repast::DirectedVertex< V, E >:



Public Member Functions

- [DirectedVertex](#) (boost::shared_ptr< V > [item](#))
Creates a [DirectedVertex](#) that will contain the specified item.
- virtual boost::shared_ptr< E > [removeEdge](#) ([Vertex](#)< V, E > *other, [EdgeType](#) type)
Removes the edge of the specified type between this [Vertex](#) and the specified [Vertex](#).
- virtual boost::shared_ptr< E > [findEdge](#) ([Vertex](#)< V, E > *other, [EdgeType](#) type)
Finds the edge of the specified type between this [Vertex](#) and the specified vertex.
- virtual void [addEdge](#) ([Vertex](#)< V, E > *other, boost::shared_ptr< E > edge, [EdgeType](#) type)
Adds an edge of the specified type between this [Vertex](#) and the specified vertex.
- virtual void [successors](#) (std::vector< V * > &out)
Gets the successors of this [Vertex](#).
- virtual void [predecessors](#) (std::vector< V * > &out)
Gets the predecessors of this [Vertex](#).
- virtual void [adjacent](#) (std::vector< V * > &out)
Gets the Vertices adjacent to this [Vertex](#).
- virtual void [edges](#) ([EdgeType](#) type, std::vector< boost::shared_ptr< E > > &out)
Gets all the edges of the specified type in which this [Vertex](#) participates and return them in out.
- int [inDegree](#) ()
Gets the in degree of this [Vertex](#).
- int [outDegree](#) ()
Gets the out degree of this [Vertex](#).

5.30.1 Detailed Description

```
template<typename V, typename E>class repast::DirectedVertex< V, E >
```

Used internally by repast graphs / networks to encapsulate the vertices of a directed graph.

Template Parameters

<i>V</i>	the type of object stored by in a Vertex .
<i>E</i>	the EdgeType of the network.

5.30.2 Member Function Documentation

5.30.2.1 `template<typename V , typename E > void repast::DirectedVertex< V, E >::addEdge (Vertex< V, E > * other, boost::shared_ptr< E > edge, EdgeType type) [virtual]`

Adds an edge of the specified type between this [Vertex](#) and the specified vertex.

Parameters

<i>edge</i>	the edge to add
<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to add

Implements [repast::Vertex< V, E >](#).

5.30.2.2 `template<typename V , typename E > void repast::DirectedVertex< V, E >::adjacent (std::vector< V * > & out) [virtual]`

Gets the Vertices adjacent to this [Vertex](#).

Parameters

<i>out</i>	<i>the</i>	vector where the adjacent vectors will be put
------------	------------	---

Implements [repast::Vertex< V, E >](#).

5.30.2.3 `template<typename V , typename E > void repast::DirectedVertex< V, E >::edges (EdgeType type, std::vector< boost::shared_ptr< E > > & out) [virtual]`

Gets all the edges of the specified type in which this [Vertex](#) participates and return them in out.

Parameters

	<i>type</i>	the type of edges to get
<i>out</i>	<i>where</i>	the edges will be put.

Implements [repast::Vertex< V, E >](#).

5.30.2.4 `template<typename V , typename E > boost::shared_ptr< E > repast::DirectedVertex< V, E >::findEdge (Vertex< V, E > * other, EdgeType type) [virtual]`

Finds the edge of the specified type between this [Vertex](#) and the specified vertex.

Parameters

<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to remove

Returns

the found edge, or 0.

Implements [repast::Vertex< V, E >](#).

5.30.2.5 `template<typename V , typename E > int repast::DirectedVertex< V, E >::inDegree () [virtual]`

Gets the in degree of this [Vertex](#).

Returns

the in degree of this [Vertex](#).

Implements [repast::Vertex< V, E >](#).

5.30.2.6 `template<typename V, typename E> int repast::DirectedVertex< V, E >::outDegree () [virtual]`

Gets the out degree of this [Vertex](#).

Returns

the out degree of this [Vertex](#).

Implements [repast::Vertex< V, E >](#).

5.30.2.7 `template<typename V, typename E> void repast::DirectedVertex< V, E >::predecessors (std::vector< V * > & out) [virtual]`

Gets the predecessors of this [Vertex](#).

Parameters

out	the	vector where any predecessors will be put
-----	-----	---

Implements [repast::Vertex< V, E >](#).

5.30.2.8 `template<typename V, typename E> boost::shared_ptr< E > repast::DirectedVertex< V, E >::removeEdge (Vertex< V, E > * other, EdgeType type) [virtual]`

Removes the edge of the specified type between this [Vertex](#) and the specified [Vertex](#).

Parameters

other	the other end of the edge
type	the type of edge to remove

Returns

the removed edge if such an edge was found, otherwise 0.

Implements [repast::Vertex< V, E >](#).

5.30.2.9 `template<typename V, typename E> void repast::DirectedVertex< V, E >::successors (std::vector< V * > & out) [virtual]`

Gets the successors of this [Vertex](#).

Parameters

out	the	vector where any successors will be put
-----	-----	---

Implements [repast::Vertex< V, E >](#).

The documentation for this class was generated from the following file:

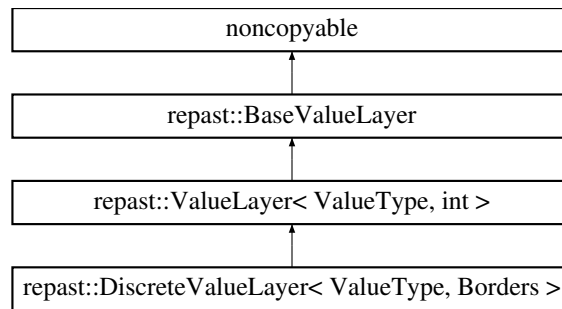
- repast_hpc/DirectedVertex.h

5.31 repast::DiscreteValueLayer< ValueType, Borders > Class Template Reference

Creates [ValueLayer](#) whose location coordinates are ints.

```
#include <ValueLayer.h>
```

Inheritance diagram for repast::DiscreteValueLayer< ValueType, Borders >:



Public Member Functions

- **DiscreteValueLayer** (const [DiscreteValueLayer](#)< [ValueType](#), [Borders](#) > &other)
- [DiscreteValueLayer](#) & **operator=** (const [DiscreteValueLayer](#)< [ValueType](#), [Borders](#) > &rhs)
- [DiscreteValueLayer](#) (const std::string &name, const [GridDimensions](#) &dimensions, bool dense, const [ValueType](#) &defaultValue=[ValueType](#)())
Creates a [DiscreteValueLayer](#) whose cells contain a default value of [ValueType](#)() with the specified dimensions.
- [ValueType](#) & [get](#) (const [Point](#)< int > &pt)
Gets the value at the specified point.
- void [set](#) (const [ValueType](#) &value, const [Point](#)< int > &pt)
Sets the value at the specified point.

5.31.1 Detailed Description

template<typename [ValueType](#), typename [Borders](#)>class repast::DiscreteValueLayer< [ValueType](#), [Borders](#) >

Creates [ValueLayer](#) whose location coordinates are ints.

Template Parameters

ValueType	the type of what the value layer stores.
Borders	the type of borders (wrapped / periodic, strict). Border types can be found in GridComponents.h

5.31.2 Constructor & Destructor Documentation

5.31.2.1 template<typename [ValueType](#) , typename [Borders](#) > repast::DiscreteValueLayer< [ValueType](#), [Borders](#) >::DiscreteValueLayer (const std::string & name, const [GridDimensions](#) & dimensions, bool dense, const [ValueType](#) & defaultValue = [ValueType](#)())

Creates a [DiscreteValueLayer](#) whose cells contain a default value of [ValueType](#)() with the specified dimensions.

Parameters

name	the name of the DiscreteValueLayer
dimension	the dimensions of the DiscreteValueLayer
dense	whether or not the ValueLayer will be densely populated or not
defaultValue	the default value to return if no value has been set of a location. The default is the result of ValueType () .

5.31.3 Member Function Documentation

5.31.3.1 `template<typename ValueType , typename Borders > ValueType & repast::DiscreteValueLayer< ValueType, Borders >::get (const Point< int > & pt) [virtual]`

Gets the value at the specified point.

If no value has been set at the specified point then this returns the default value.

param pt the location to get the value of

Returns

the value at the specified point, or if no value has been set, then the default value.

Implements [repast::ValueLayer< ValueType, int >](#).

5.31.3.2 `template<typename ValueType , typename Borders > void repast::DiscreteValueLayer< ValueType, Borders >::set (const ValueType & value, const Point< int > & pt) [virtual]`

Sets the value at the specified point.

Parameters

<i>value</i>	the value
<i>pt</i>	the point where the value should be stored

Implements [repast::ValueLayer< ValueType, int >](#).

The documentation for this class was generated from the following file:

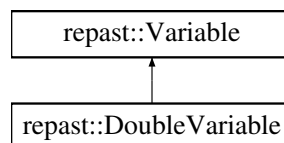
- `repast_hpc/ValueLayer.h`

5.32 repast::DoubleVariable Class Reference

Used in [SVDDataSet](#) to manage double data.

```
#include <Variable.h>
```

Inheritance diagram for repast::DoubleVariable:



Public Member Functions

- virtual void [write](#) (size_t index, std::ofstream &out)
Writes the data at the specified index to the specified ofstream.
- virtual void [insert](#) (double *array, size_t size)
Inserts all the doubles in the double array into the collection of data stored in this [Variable](#).
- virtual void [insert](#) (int *array, size_t size)
Inserts all the ints in the int array into the collection of data stored in this [Variable](#).
- virtual void [clear](#) ()
Clears this [Variable](#) of all the data stored in it.

5.32.1 Detailed Description

Used in [SVDDataSet](#) to manage double data.

5.32.2 Member Function Documentation

5.32.2.1 `void repast::DoubleVariable::insert (double * array, size_t size) [virtual]`

Inserts all the doubles in the double array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implements [repast::Variable](#).

5.32.2.2 `void repast::DoubleVariable::insert (int * array, size_t size) [virtual]`

Inserts all the ints in the int array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implements [repast::Variable](#).

5.32.2.3 `void repast::DoubleVariable::write (size_t index, std::ofstream & out) [virtual]`

Writes the data at the specified index to the specified ofstream.

Parameters

<i>index</i>	the index of the data to write
<i>out</i>	the ofstream to write the data to

Implements [repast::Variable](#).

The documentation for this class was generated from the following files:

- `repast_hpc/Variable.h`
- `repast_hpc/Variable.cpp`

5.33 `repast::EdgeExporter< E >` Class Template Reference

DEPRECATED Handles exporting edges created locally between one or more non-local agents.

```
#include <SharedNetwork.h>
```

Public Types

- `typedef std::map< int, std::vector< boost::shared_ptr< E >> * >::iterator` **EdgeMapIterator**

Public Member Functions

- void **addAgentExportRequest** (int exportTo, const [AgentId](#) &id)
- void **edgeRemoved** (boost::shared_ptr< E > edge, std::map< int, std::vector< std::pair< [AgentId](#), [AgentId](#) > > > &removeMap)
Whether or not this is exported the specified edge.
- void **addEdge** (boost::shared_ptr< E > edge)
Tests if the edge needs to be exported and if so adds it to the collection of edges to be exported.
- void **gatherReceivers** (std::vector< int > &out)
Gathers the receivers into out.
- void **gatherExporters** (std::vector< int > &out)
Gathers the procs that this will send export requests to into out.
- void **sendExportRequests** (boost::mpi::communicator &comm, std::vector< boost::mpi::request > &requests)
Send the export requests.
- std::map< int, std::vector< boost::shared_ptr< E > > * > & **getEdgesToExport** ()
Gets the edges to export.
- std::map< int, std::vector< boost::shared_ptr< E > > * > & **getExportedEdges** ()
Gets the edges this process is exporting.
- void **cleanUp** ()
Cleans up after exported edges have been sent and received.

Friends

- template<typename Vertex , typename Edge , typename AgentContent , typename EdgeContent , typename EdgeManager , typename AgentCreator >
void **createComplementaryEdges** ([SharedNetwork](#)< [Vertex](#), Edge, EdgeContent, EdgeManager > *net, [SharedContext](#)< [Vertex](#) > &context, EdgeManager &edgeManager, AgentCreator &creator)
Notifies other processes of any edges that have been created between nodes on this process and imported nodes.

5.33.1 Detailed Description

template<typename E>class repast::EdgeExporter< E >

DEPRECATED Handles exporting edges created locally between one or more non-local agents.

This also coordinates notification of which processes should be exporting to which in the case of edges where a node is foreign to the sending and receiving process.

All this is done internally in the [SharedNetwork](#).

Deprecated As of Version 2.0 replaced by [ProjectionInfoPacket](#)

5.33.2 Member Function Documentation

5.33.2.1 template<typename E > void repast::EdgeExporter< E >::gatherReceivers (std::vector< int > & out)

Gathers the receivers into out.

A receiver is a process this [EdgeExporter](#) should send an edge to.

5.33.2.2 `template<typename E> void repast::EdgeExporter< E >::sendExportRequests (boost::mpi::communicator & comm, std::vector< boost::mpi::request > & requests)`

Send the export requests.

This does an isend and the resulting requests are placed in the specified vector.

5.33.3 Friends And Related Function Documentation

5.33.3.1 `template<typename E> template<typename Vertex , typename Edge , typename AgentContent , typename EdgeContent , typename EdgeManager , typename AgentCreator > void createComplementaryEdges (SharedNetwork< Vertex, Edge, EdgeContent, EdgeManager > * net, SharedContext< Vertex > & context, EdgeManager & edgeManager, AgentCreator & creator) [friend]`

Notifies other processes of any edges that have been created between nodes on this process and imported nodes.

The other process will then create the complimentary edge. For example, if P1 creates an edge between A and B where B resides on P2, then this method will notify P2 to create the incoming edge A->B on its copy of B. Any unknown agents will be added to the context. For example, if P2 didn't have a reference to A, then A will be added to P2's context.

Parameters

<i>net</i>	the network in which to create the complementary edges or from which to send complementary edges
<i>context</i>	the context that contains the agents in the process
<i>edgeManager</i>	creates edges from EdgeContent and creates EdgeContent from an edge and a context.
<i>creator</i>	creates agents from AgentContent.

Template Parameters

<i>Vertex</i>	the vertex (agent) type
<i>Edge</i>	the edge type
<i>AgentContent</i>	the serializable struct or class that describes the agent state. It must contain a <code>getId()</code> method that returns the AgentId of the agent it describes.
<i>EdgeContent</i>	the serializable struct or class that describes edge state. At the very least EdgeContent must contain two public fields <code>sourceContent</code> and <code>targetContent</code> of type <code>AgentContent</code> . These represent the source and target of the edge.
<i>EdgeManager</i>	create edges from EdgeContent and provides EdgeContent given a context and an edge of type Edge. It must implement <code>void provideEdgeContent(constEdge* edge, std::vector<EdgeContent>& edgeContent)</code> and <code>Edge* createEdge(repast::Context<Vertex>& context, EdgeContent& edge);</code>
<i>AgentCreator</i>	creates agents from AgentContent, implementing the following method <code>Vertex* createAgent(constAgentContent& content);</code>

The documentation for this class was generated from the following file:

- `repast_hpc/SharedNetwork.h`

5.34 repast::EventCompare Class Reference

Compares ScheduledEvents based on their tick times.

```
#include <Schedule.h>
```

Public Member Functions

- `int operator()` (const [ScheduledEvent](#) *one, const [ScheduledEvent](#) *two)

5.34.1 Detailed Description

Compares ScheduledEvents based on their tick times.

The documentation for this class was generated from the following file:

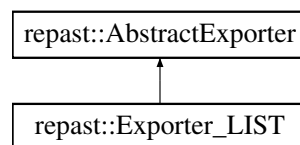
- repast_hpc/Schedule.h

5.35 repast::Exporter_LIST Class Reference

Maintains a list of agents being exported for each receiving process.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::Exporter_LIST:



Public Member Functions

- virtual void [registerIncomingRequests](#) (std::vector< [AgentRequest](#) > &requests)
Makes a record of the data receives (in the form of a vector of AgentRequests) so that the agents' data can be sent to the requesting processes.
- **Exporter_LIST** (StatusMap *outgoingStatusMap, [AgentExporterData](#) *outgoingAgentExporterInfo)
- virtual std::string [getReport](#) ()
Gets a printable report of the state of this object.

Additional Inherited Members

5.35.1 Detailed Description

Maintains a list of agents being exported for each receiving process.

An agent that is requested more than once will appear on this list more than once; canceling an agent just once removes only one of its appearances on this list. A 'send' will be created for a receiving process only if that process has entries in the list.

The documentation for this class was generated from the following files:

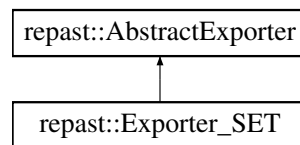
- repast_hpc/AgentImporterExporter.h
- repast_hpc/AgentImporterExporter.cpp

5.36 repast::Exporter_SET Class Reference

Maintains a set of agents being exported for each receiving process.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::Exporter_SET:



Public Member Functions

- virtual void [registerIncomingRequests](#) (std::vector< [AgentRequest](#) > &requests)
Makes a record of the data receives (in the form of a vector of AgentRequests) so that the agents' data can be sent to the requesting processes.
- **Exporter_SET** (StatusMap *outgoingStatusMap, [AgentExporterData](#) *outgoingAgentExporterInfo)
- virtual std::string [getReport](#) ()
Gets a printable report of the state of this object.

Additional Inherited Members

5.36.1 Detailed Description

Maintains a set of agents being exported for each receiving process.

An agent that is requested more than once will appear in this set only once; canceling an agent just once removes it from this set. A 'send' will be created for a receiving process only if that process has entries in the list.

The documentation for this class was generated from the following files:

- repast_hpc/AgentImporterExporter.h
- repast_hpc/AgentImporterExporter.cpp

5.37 repast::ExportRequest Class Reference

DEPRECATED Used to send a request for agent information from another process

```
#include <SharedNetwork.h>
```

Public Member Functions

- **ExportRequest** (int exportTo, [AgentId](#) id)
- [AgentId](#) **agent** () const
- int **exportTo** ()

Friends

- class **boost::serialization::access**

5.37.1 Detailed Description

DEPRECATED Used to send a request for agent information from another process

Deprecated As of Version 2.0

The documentation for this class was generated from the following files:

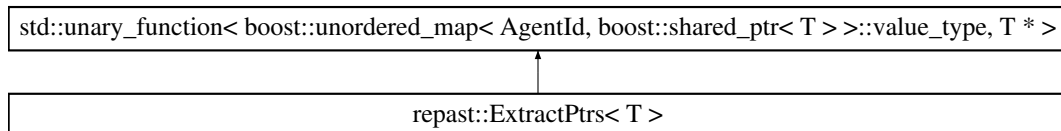
- repast_hpc/SharedNetwork.h
- repast_hpc/SharedNetwork.cpp

5.38 repast::ExtractPtrs< T > Struct Template Reference

Unary function that allows retrieving the occupants of locations.

```
#include <MultipleOccupancy.h>
```

Inheritance diagram for repast::ExtractPtrs< T >:



Public Member Functions

- `T * operator()` (typename boost::unordered_map< [AgentId](#), boost::shared_ptr< T > >::value_type &val)

5.38.1 Detailed Description

```
template<typename T>struct repast::ExtractPtrs< T >
```

Unary function that allows retrieving the occupants of locations.

The documentation for this struct was generated from the following file:

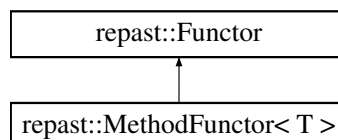
- repast_hpc/MultipleOccupancy.h

5.39 repast::Functor Class Reference

[Functor](#) interface.

```
#include <Schedule.h>
```

Inheritance diagram for repast::Functor:



Public Member Functions

- virtual void `operator()` ()=0

5.39.1 Detailed Description

[Functor](#) interface.

The documentation for this class was generated from the following files:

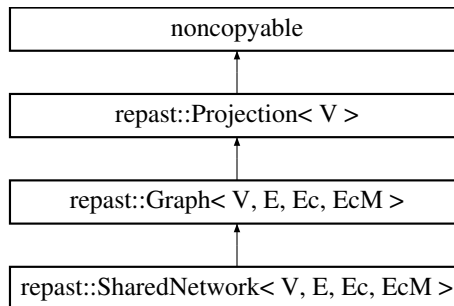
- `repast_hpc/Schedule.h`
- `repast_hpc/Schedule.cpp`

5.40 `repast::Graph< V, E, Ec, EcM >` Class Template Reference

[Graph](#) / Network implementation where agents are vertices in the graph.

```
#include <Graph.h>
```

Inheritance diagram for `repast::Graph< V, E, Ec, EcM >`:



Public Types

- typedef
`boost::transform_iterator
< NodeGetter< V, E >, typename
VertexMap::const_iterator >` `vertex_iterator`
An iterator over the agents that are the vertices in this [Graph](#).

Public Member Functions

- [Graph](#) (std::string [name](#), bool directed, EcM *edgeContentMgr)
Creates a [Graph](#) with the specified name.
- [Graph](#) (const [Graph](#)< V, E, Ec, EcM > &graph)
Copy constructor for the graph.
- [Graph](#) & **operator=** (const [Graph](#) &graph)
- virtual boost::shared_ptr< E > [addEdge](#) (V *source, V *target)
Adds an edge between source and target to this [Graph](#).
- virtual boost::shared_ptr< E > [addEdge](#) (V *source, V *target, double weight)
Adds an edge with the specified weight between source and target to this [Graph](#).
- virtual boost::shared_ptr< E > [findEdge](#) (V *source, V *target)
Gets the edge between the source and target or 0 if no such edge is found.
- virtual void [successors](#) (V *vertex, std::vector< V * > &out)
Gets the successors of the specified vertex and puts them in out.
- virtual void [predecessors](#) (V *vertex, std::vector< V * > &out)
Gets the predecessors of the specified vertex and puts them in out.
- virtual void [adjacent](#) (V *vertex, std::vector< V * > &out)
Gets all the agent adjacent to the specified vertex.
- virtual void [removeEdge](#) (V *source, V *target)
Removes the edge between source and target from this [Graph](#).
- virtual void [removeEdge](#) (const [AgentId](#) &source, const [AgentId](#) &target)

- Removes the edge between source and target from this [Graph](#).*
- virtual int [inDegree](#) (V *vertex)
Gets the in-degree of the specified vertex.
- virtual int [outDegree](#) (V *vertex)
Gets the out-degree of the specified vertex.
- int [edgeCount](#) () const
Gets the number of edges in this [Graph](#).
- int [vertexCount](#) () const
Gets the number of vertices in this [Graph](#).
- [vertex_iterator](#) [verticesBegin](#) ()
Gets the start of an iterator over all the vertices in this graph.
- [vertex_iterator](#) [verticesEnd](#) ()
Gets the end of an iterator over all the vertices in this graph.
- void [showEdges](#) ()
- virtual bool [isMaster](#) (E *e)=0
- virtual bool [keepsAgentsOnSyncProj](#) ()
Should return true if the [Projection](#) implemented can 'keep' some (non-local) agents during a projection information synchronization operation.
- virtual bool [sendsSecondaryAgentsOnStatusExchange](#) ()
Should return true if the [Projection](#) implemented will send secondary agents during a status exchange.
- virtual void [getInfoExchangePartners](#) (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)
Gets the set of processes with which this [Projection](#) exchanges projection info.
- virtual void [getAgentStatusExchangePartners](#) (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)
Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.
- virtual void [getProjectionInfo](#) (std::vector< [AgentId](#) > &agents, std::vector< [ProjectionInfoPacket](#) * > &packets, bool secondaryInfo=false, std::set< [AgentId](#) > *secondaryIds=0, int destProc=-1)
Convenience wrapper that gets all of the projection information for the agents specified (calls implementation in child class that gets only the information for one agent).
- virtual [ProjectionInfoPacket](#) * [getProjectionInfo](#) ([AgentId](#) id, bool secondaryInfo=false, std::set< [AgentId](#) > *secondaryIds=0, int destProc=-1)
- virtual void [updateProjectionInfo](#) ([ProjectionInfoPacket](#) *pip, [Context](#)< V > *context)
- virtual void [getRequiredAgents](#) (std::set< [AgentId](#) > &agentsToTest, std::set< [AgentId](#) > &agentsRequired, RADIUS radius=[Projection](#)< V >::PRIMARY)
- virtual void [getAgentsToPush](#) (std::set< [AgentId](#) > &agentsToTest, std::map< int, std::set< [AgentId](#) > > &agentsToPush)
Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.
- virtual void [cleanProjectionInfo](#) (std::set< [AgentId](#) > &agentsToKeep)
- void [clearConflictedEdges](#) ()
- void [getConflictedEdges](#) (std::set< boost::shared_ptr< E > > &conflictedEdges)

Public Attributes

- std::set< int > [ranksToSendProjInfoTo](#)
- std::set< int > [ranksToReceiveProjInfoFrom](#)
- std::set< int > [ranksToSendAgentStatusInfoTo](#)
- std::set< int > [ranksToReceiveAgentStatusInfoFrom](#)
- bool [keepsAgents](#)
- bool [sendsSecondaryAgents](#)

Protected Types

- typedef boost::unordered_map
< [AgentId](#), [Vertex](#)< V, E >
*, [HashId](#) > **VertexMap**
- typedef VertexMap::iterator **VertexMapIterator**
- typedef [Projection](#)< V >::RADIUS **RADIUS**

Protected Member Functions

- void **cleanUp** ()
- void **init** (const [Graph](#) &graph)
- virtual bool **addAgent** (boost::shared_ptr< V > agent)
- virtual void **removeAgent** (V *agent)
- virtual void **doAddEdge** (boost::shared_ptr< E > edge, bool allowOverwrite=true)

Protected Attributes

- int **edgeCount**_
- bool **isDirected**
- VertexMap **vertices**
- EcM * **edgeContentManager**

5.40.1 Detailed Description

template<typename V, typename E, typename Ec, typename EcM>class [repast::Graph](#)< V, E, Ec, EcM >

[Graph](#) / Network implementation where agents are vertices in the graph.

Template Parameters

<i>V</i>	the type agents in the graph. This type should extend repast::Agent
<i>E</i>	the edge type of the graph. This type should extend repast::RepastEdge .
<i>Ec</i>	class of serializable Edge Content
<i>EcM</i>	Class that is capable of transforming an Edge into Edge Content and vice versa

5.40.2 Constructor & Destructor Documentation

5.40.2.1 template<typename V, typename E, typename Ec, typename EcM> [repast::Graph](#)< V, E, Ec, EcM >::[Graph](#) (
std::string *name*, bool *directed*, EcM * *edgeContentMgr*) [inline]

Creates a [Graph](#) with the specified name.

Parameters

<i>name</i>	the name of the graph
<i>directed</i>	whether or not the created Graph is directed

5.40.3 Member Function Documentation

5.40.3.1 template<typename V, typename E, typename Ec, typename EcM > boost::shared_ptr< E > [repast::Graph](#)< V,
E, Ec, EcM >::addEdge (V * *source*, V * *target*) [virtual]

Adds an edge between source and target to this [Graph](#).

Parameters

<i>source</i>	the source of the edge
<i>target</i>	the target of the edge

Returns

the added edge.

5.40.3.2 `template<typename V , typename E , typename Ec , typename EcM > boost::shared_ptr< E > repast::Graph< V, E, Ec, EcM >::addEdge (V * source, V * target, double weight) [virtual]`

Adds an edge with the specified weight between source and target to this [Graph](#).

Parameters

<i>source</i>	the source of the edge
<i>target</i>	the target of the edge
<i>weight</i>	the weight of the edge

Returns

the added edge.

5.40.3.3 `template<typename V , typename E , typename Ec , typename EcM > void repast::Graph< V, E, Ec, EcM >::adjacent (V * vertex, std::vector< V * > & out) [virtual]`

Gets all the agent adjacent to the specified vertex.

Parameters

	<i>vertex</i>	the vertex whose adjacent agents we want to get
<i>out</i>	<i>the</i>	vector where the results will be put

5.40.3.4 `template<typename V, typename E, typename Ec, typename EcM> int repast::Graph< V, E, Ec, EcM >::edgeCount () const [inline]`

Gets the number of edges in this [Graph](#).

Returns

the number of edges in this [Graph](#).

5.40.3.5 `template<typename V , typename E , typename Ec , typename EcM > boost::shared_ptr< E > repast::Graph< V, E, Ec, EcM >::findEdge (V * source, V * target) [virtual]`

Gets the edge between the source and target or 0 if no such edge is found.

Parameters

<i>source</i>	the source of the edge to find
---------------	--------------------------------

<i>target</i>	the target of the edge to find
---------------	--------------------------------

Returns

the found edge or 0.

```
5.40.3.6 template<typename V , typename E , typename Ec , typename EcM > void repast::Graph< V, E, Ec, EcM
>::getAgentStatusExchangePartners ( std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom )
[virtual]
```

Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.

In the most general case this will be all other processors. However, simulations where agents move in spaces will usually exchange agents only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Projection< V >](#).

```
5.40.3.7 template<typename V , typename E , typename Ec , typename EcM > void repast::Graph< V, E, Ec, EcM
>::getAgentsToPush ( std::set< AgentId > & agentsToTest, std::map< int, std::set< AgentId > > &
agentsToPush ) [virtual]
```

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Implements [repast::Projection< V >](#).

```
5.40.3.8 template<typename V , typename E , typename Ec , typename EcM > void repast::Graph< V, E, Ec, EcM
>::getInfoExchangePartners ( std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom ) [virtual]
```

Gets the set of processes with which this [Projection](#) exchanges projection info.

In the most general case this will be all other processors; this is the case for graphs, where agent connections can be arbitrary. However, spaces usually exchange information only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Projection< V >](#).

```
5.40.3.9 template<typename V , typename E , typename Ec , typename EcM > int repast::Graph< V, E, Ec, EcM >::inDegree
( V * vertex ) [virtual]
```

Gets the in-degree of the specified vertex.

Returns

the in-degree of the specified vertex.

```
5.40.3.10 template<typename V , typename E , typename Ec , typename EcM> virtual bool repast::Graph< V, E, Ec, EcM
>::keepsAgentsOnSyncProj( ) [inline], [virtual]
```

Should return true if the [Projection](#) implemented can 'keep' some (non-local) agents during a projection information synchronization operation.

Generally spaces will allow all non-local agents to be deleted, but graphs keep the non-local agents that participate in Master edges.

It is possible to override these. A graph projection can be created that does not permit non-local agents to be 'kept'. This would be an extremely unusual use case, but it is possible.

Note that these are used for optimization. If no projection in a given context keeps any agents, several steps in the synchronization algorithm can be omitted. Of course, omitting these steps when a projection actually retains agents can caused undefined problems.

Returns

true if this projection will keep non-local agents during a projection information synchronziation event, false if it will not.

Implements [repast::Projection< V >](#).

5.40.3.11 `template<typename V , typename E , typename Ec , typename EcM > int repast::Graph< V, E, Ec, EcM >::outDegree (V * vertex) [virtual]`

Gets the out-degree of the specified vertex.

Returns

the out-degree of the specified vertex.

5.40.3.12 `template<typename V , typename E , typename Ec , typename EcM > void repast::Graph< V, E, Ec, EcM >::predecessors (V * vertex, std::vector< V * > & out) [virtual]`

Gets the predecessors of the specified vertex and puts them in out.

Parameters

	<i>vertex</i>	the vertex whose predecessors we want to get
<i>out</i>	<i>where</i>	the predecessors will be returned

5.40.3.13 `template<typename V , typename E , typename Ec , typename EcM > void repast::Graph< V, E, Ec, EcM >::removeEdge (V * source, V * target) [virtual]`

Removes the edge between source and target from this [Graph](#).

Parameters

<i>source</i>	the source of the edge
<i>target</i>	the target of the edge

Reimplemented in [repast::SharedNetwork< V, E, Ec, EcM >](#).

5.40.3.14 `template<typename V , typename E , typename Ec , typename EcM > void repast::Graph< V, E, Ec, EcM >::removeEdge (const AgentId & source, const AgentId & target) [virtual]`

Removes the edge between source and target from this [Graph](#).

Parameters

<i>source</i>	the id of the vertex that is the source of the edge
<i>target</i>	the id of the vertex that is the target of the edge

5.40.3.15 `template<typename V, typename E, typename Ec, typename EcM> virtual bool repast::Graph< V, E, Ec, EcM >::sendsSecondaryAgentsOnStatusExchange () [inline], [virtual]`

Should return true if the [Projection](#) implemented will send secondary agents during a status exchange.

Generally spaces do not and graphs do.

If no secondary agents will be sent, portions of the algorithm can be omitted for optimization.

Returns

true if the [Projection](#) returns secondary agents, false if not

Implements [repast::Projection< V >](#).

5.40.3.16 `template<typename V , typename E , typename Ec , typename EcM > void repast::Graph< V, E, Ec, EcM >::successors (V * vertex, std::vector< V * > & out) [virtual]`

Gets the successors of the specified vertex and puts them in out.

Parameters

	<i>vertex</i>	the vertex whose successors we want to get
<i>out</i>	<i>where</i>	the successors will be returned

5.40.3.17 `template<typename V, typename E, typename Ec, typename EcM> int repast::Graph< V, E, Ec, EcM >::vertexCount () const [inline]`

Gets the number of vertices in this [Graph](#).

Returns

the number of vertices in this [Graph](#).

5.40.3.18 `template<typename V, typename E, typename Ec, typename EcM> vertex_iterator repast::Graph< V, E, Ec, EcM >::verticesBegin () [inline]`

Gets the start of an iterator over all the vertices in this graph.

The iterator dereferences to a pointer to agents of type V.

Returns

the start of an iterator over all the vertices in this graph.

5.40.3.19 `template<typename V, typename E, typename Ec, typename EcM> vertex_iterator repast::Graph< V, E, Ec, EcM >::verticesEnd () [inline]`

Gets the end of an iterator over all the vertices in this graph.

The iterator dereferences to a pointer to agents of type V.

Returns

the end of an iterator over all the vertices in this graph.

The documentation for this class was generated from the following file:

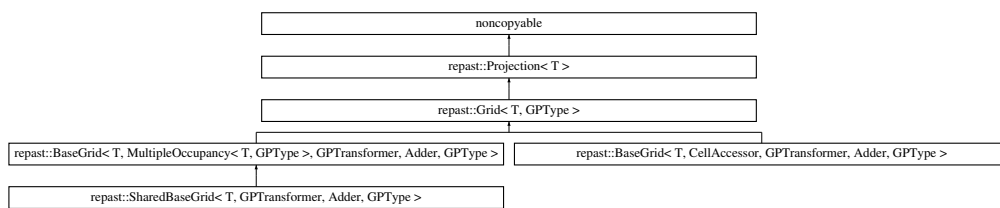
- repast_hpc/Graph.h

5.41 repast::Grid< T, GPTYPE > Class Template Reference

Abstract interface for Grids and ContinuousSpaces.

```
#include <Grid.h>
```

Inheritance diagram for repast::Grid< T, GPTYPE >:



Public Member Functions

- [Grid](#) (std::string name)
Creates a [Grid](#) with the specified name.
- virtual bool [contains](#) (const [AgentId](#) &id)=0
Gets whether or not this grid contains the agent with the specified id.
- virtual bool [moveTo](#) (const [AgentId](#) &id, const [Point](#)< GPTYPE > &pt)=0
Moves the specified agent to the specified point.
- virtual std::pair< bool, [Point](#)< GPTYPE > > [moveByVector](#) (const T *agent, double distance, const std::vector< double > &anglesInRadians)=0
Moves the specified object the specified distance from its current position along the specified angle.
- virtual std::pair< bool, [Point](#)< GPTYPE > > [moveByDisplacement](#) (const T *agent, const std::vector< GPTYPE > &displacement)=0
Moves the specified object from its current location by the specified amount.
- virtual const [GridDimensions](#) [dimensions](#) () const =0
Gets the dimensions of this [Grid](#).
- virtual T * [getObjectAt](#) (const [Point](#)< GPTYPE > &pt) const =0
Gets the first object found at the specified point, or NULL if there is no such object.
- virtual void [getObjectsAt](#) (const [Point](#)< GPTYPE > &pt, std::vector< T * > &out) const =0
Gets all the objects found at the specified point.
- virtual bool [getLocation](#) (const T *agent, std::vector< GPTYPE > &out) const =0
Gets the location of this agent and puts it in the specified vector.
- virtual bool [getLocation](#) (const [AgentId](#) &id, std::vector< GPTYPE > &out) const =0
Gets the location of this agent and puts it in the specified vectors.
- virtual void [getDisplacement](#) (const [Point](#)< GPTYPE > &pt1, const [Point](#)< GPTYPE > &pt2, std::vector< GPTYPE > &out) const =0
Gets vector difference between point 1 and point 2, putting the result in out.
- virtual double [getDistance](#) (const [Point](#)< GPTYPE > &pt1, const [Point](#)< GPTYPE > &pt2) const =0

- Gets the distance between the two grid points.*
 - virtual double `getDistanceSq` (const `Point`< `GType` > &pt1, const `Point`< `GType` > &pt2) const =0
- Gets the square of the distance between the two grid points.*
 - virtual void `translate` (const `Point`< `GType` > &location, const `Point`< `GType` > &displacement, std::vector< `GType` > &out) const =0
- Translates the specified location by the specified displacement put the result in out.*
 - virtual void `transform` (const std::vector< `GType` > &location, std::vector< `GType` > &out) const =0
- Transforms the specified location using the properties (e.g.*
 - virtual bool `isPeriodic` () const =0
- Gets whether or not this grid is periodic (i.e.*
 - virtual `ProjectionInfoPacket` * `getProjectionInfo` (`AgentId` id, bool secondaryInfo=false, std::set< `AgentId` > *secondaryIds=0, int destProc=-1)=0
- virtual void `updateProjectionInfo` (`ProjectionInfoPacket` *pip, `Context`< `T` > *context)=0
- virtual void `getRequiredAgents` (std::set< `AgentId` > &agentsToTest, std::set< `AgentId` > &agentsRequired, `RADIUS` radius=`Projection`< `T` >::PRIMARY)
- Given a set of agents to test, gets the subset that must be kept in order to fulfill the projection's 'contract' to the specified radius.*
 - virtual void `getAgentsToPush` (std::set< `AgentId` > &agentsToTest, std::map< int, std::set< `AgentId` > > &agentsToPush)=0
- Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.*
 - virtual bool `keepsAgentsOnSyncProj` ()
- Should return true if the `Projection` implemented can 'keep' some (non-local) agents during a projection information synchronization operation.*
 - virtual bool `sendsSecondaryAgentsOnStatusExchange` ()
- Should return true if the `Projection` implemented will send secondary agents during a status exchange.*
 - virtual void `getInfoExchangePartners` (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)=0
- Gets the set of processes with which this `Projection` exchanges projection info.*
 - virtual void `getAgentStatusExchangePartners` (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)=0
- Gets the set of processes with which this `Projection` exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.*
 - virtual void `cleanProjectionInfo` (std::set< `AgentId` > &agentsToKeep)

Additional Inherited Members

5.41.1 Detailed Description

template<typename T, typename GType>class repast::Grid< T, GType >

Abstract interface for Grids and ContinuousSpaces.

Template Parameters

<i>T</i>	the type of objects this <code>Grid</code> contains
<i>GType</i>	the coordinate type of the grid point locations. This must be an int or a double.

5.41.2 Constructor & Destructor Documentation

5.41.2.1 template<typename T, typename GType> repast::Grid< T, GType >::Grid (std::string name) [inline]

Creates a `Grid` with the specified name.

Parameters

<i>name</i>	the name of the Grid . This should be unique among Projections.
-------------	---

5.41.3 Member Function Documentation

5.41.3.1 `template<typename T, typename GPType> virtual bool repast::Grid< T, GPType >::contains (const AgentId & id) [pure virtual]`

Gets whether or not this grid contains the agent with the specified id.

Parameters

<i>id</i>	the id of the agent to check
-----------	------------------------------

Returns

true if the grid contains the agent, otherwise false.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

5.41.3.2 `template<typename T, typename GPType> virtual const GridDimensions repast::Grid< T, GPType >::dimensions () const [pure virtual]`

Gets the dimensions of this [Grid](#).

Returns

the dimensions of this [Grid](#).

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

5.41.3.3 `template<typename T, typename GPType> virtual void repast::Grid< T, GPType >::getAgentStatus-ExchangePartners (std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom) [pure virtual]`

Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.

In the most general case this will be all other processors. However, simulations where agents move in spaces will usually exchange agents only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Projection< T >](#).

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), and [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#).

5.41.3.4 `template<typename T, typename GPTYPE> virtual void repast::Grid< T, GPTYPE >::getAgentsToPush (std::set< AgentId > & agentsToTest, std::map< int, std::set< AgentId > > & agentsToPush) [pure virtual]`

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Implements [repast::Projection< T >](#).

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPTYPE >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#), and [repast::SharedDiscreteSpace< T, GPTransformer, Adder >](#).

5.41.3.5 `template<typename T, typename GPTYPE> virtual void repast::Grid< T, GPTYPE >::getDisplacement (const Point< GPTYPE > & pt1, const Point< GPTYPE > & pt2, std::vector< GPTYPE > & out) const [pure virtual]`

Gets vector difference between point 1 and point 2, putting the result in out.

Parameters

	<i>p1</i>	the first point
	<i>p2</i>	the second point
out	<i>the</i>	vector where the difference will be put

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

5.41.3.6 `template<typename T, typename GPTYPE> virtual double repast::Grid< T, GPTYPE >::getDistance (const Point< GPTYPE > & pt1, const Point< GPTYPE > & pt2) const [pure virtual]`

Gets the distance between the two grid points.

Parameters

	<i>p1</i>	the first point
	<i>p2</i>	the second point

Returns

the distance between pt1 and pt2.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

5.41.3.7 `template<typename T, typename GPTYPE> virtual double repast::Grid< T, GPTYPE >::getDistanceSq (const Point< GPTYPE > & pt1, const Point< GPTYPE > & pt2) const [pure virtual]`

Gets the square of the distance between the two grid points.

Parameters

<i>p1</i>	the first point
<i>p2</i>	the second point

Returns

the square of the distance between pt1 and pt2.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

5.41.3.8 `template<typename T, typename GPType> virtual void repast::Grid< T, GPType >::getInfoExchangePartners (std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom) [pure virtual]`

Gets the set of processes with which this [Projection](#) exchanges projection info.

In the most general case this will be all other processors; this is the case for graphs, where agent connections can be arbitrary. However, spaces usually exchange information only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Projection< T >](#).

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), and [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#).

5.41.3.9 `template<typename T, typename GPType> virtual bool repast::Grid< T, GPType >::getLocation (const T * agent, std::vector< GPType > & out) const [pure virtual]`

Gets the location of this agent and puts it in the specified vector.

The x coordinate will be the first value, the y the second and so on.

Parameters

	<i>agent</i>	the agent whose location we want to get
<i>out</i>	<i>the</i>	vector where the agents location will be put

Returns

true if the location was successfully found, otherwise false.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

5.41.3.10 `template<typename T, typename GPType> virtual bool repast::Grid< T, GPType >::getLocation (const AgentId & id, std::vector< GPType > & out) const [pure virtual]`

Gets the location of this agent and puts it in the specified vectors.

The x coordinate will be the first value, the y the second and so on.

Parameters

	<i>id</i>	the id of the agent whose location we want to get
out	<i>out</i>	the agent's location will be put into this vector

Returns

true if the location was successfully found, otherwise false.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

5.41.3.11 `template<typename T, typename GPType> virtual T* repast::Grid< T, GPType >::getObjectAt (const Point< GPType > & pt) const` [pure virtual]

Gets the first object found at the specified point, or NULL if there is no such object.

Returns

the first object found at the specified point, or NULL if there is no such object.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

5.41.3.12 `template<typename T, typename GPType> virtual void repast::Grid< T, GPType >::getObjectsAt (const Point< GPType > & pt, std::vector< T* > & out) const` [pure virtual]

Gets all the objects found at the specified point.

The found objects will be put into the out parameter.

Parameters

	<i>pt</i>	the point to get all the objects at
out	<i>out</i>	the vector into which the found objects will be put

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

5.41.3.13 `template<typename T, typename GPType> virtual void repast::Grid< T, GPType >::getRequiredAgents (std::set< AgentId > & agentsToTest, std::set< AgentId > & agentsRequired, RADIUS radius = Projection< T >::PRIMARY)` [inline],[virtual]

Given a set of agents to test, gets the subset that must be kept in order to fulfill the projection's 'contract' to the specified radius.

Generally spaces do not require any agents, but graphs do- generally the non-local ends to master copies of edges.

Implements [repast::Projection< T >](#).

5.41.3.14 `template<typename T, typename GPType> virtual bool repast::Grid< T, GPType >::isPeriodic () const` [pure virtual]

Gets whether or not this grid is periodic (i.e.

toroidal).

Returns

true if this [Grid](#) is periodic, otherwise false.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

5.41.3.15 `template<typename T, typename GPTYPE> virtual bool repast::Grid< T, GPTYPE >::keepsAgentsOnSyncProj ()`
`[inline], [virtual]`

Should return true if the [Projection](#) implemented can 'keep' some (non-local) agents during a projection information synchronization operation.

Generally spaces will allow all non-local agents to be deleted, but graphs keep the non-local agents that participate in Master edges.

It is possible to override these. A graph projection can be created that does not permit non-local agents to be 'kept'. This would be an extremely unusual use case, but it is possible.

Note that these are used for optimization. If no projection in a given context keeps any agents, several steps in the synchronization algorithm can be omitted. Of course, omitting these steps when a projection actually retains agents can caused undefined problems.

Returns

true if this projection will keep non-local agents during a projection information synchronziation event, false if it will not.

Implements [repast::Projection< T >](#).

5.41.3.16 `template<typename T, typename GPTYPE> virtual std::pair<bool, Point<GPTYPE> > repast::Grid< T, GPTYPE >::moveByDisplacement (const T * agent, const std::vector< GPTYPE > & displacement)` `[pure virtual]`

Moves the specified object from its current location by the specified amount.

For example `moveByDisplacement(object, 3, -2, 1)` will move the object by 3 along the x-axis, -2 along the y and 1 along the z. The displacement argument can be less than the number of dimensions in the space in which case the remaining argument will be set to 0. For example, `moveByDisplacement(object, 3)` will move the object 3 along the x-axis and 0 along the y and z axes, assuming a 3D grid.

Parameters

<i>agent</i>	the object to move
<i>displacement</i>	the amount to move the object

Returns

a pair containing a bool that indicates whether the move was a success or not, and the point where the agent was moved to.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

```
5.41.3.17 template<typename T, typename GPTYPE> virtual std::pair<bool, Point<GPTYPE> > repast::Grid< T, GPTYPE
>::moveByVector ( const T * agent, double distance, const std::vector< double > & anglesInRadians ) [pure
virtual]
```

Moves the specified object the specified distance from its current position along the specified angle.

For example, `moveByVector(object, 1, Grid.NORTH)` will move the object 1 unit "north" up the y-axis, assuming a 2D grid. Similarly, `grid.moveByVector(object, 2, 0, Math.toRadians(90), 0)` will rotate 90 degrees around the y-axis, thus moving the object 2 units along the z-axis.

Note that the radians / degrees are incremented in a anti-clockwise fashion, such that 0 degrees is "east", 90 degrees is "north", 180 is "west" and 270 is "south."

Parameters

<i>agent</i>	the object to move
<i>distance</i>	the distance to move
<i>anglesInRadians</i>	the angle to move along in radians.

Returns

a pair containing a bool that indicates whether the move was a success or not, and the point where the agent was moved to.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

```
5.41.3.18 template<typename T, typename GPTYPE> virtual bool repast::Grid< T, GPTYPE >::moveTo ( const AgentId &
id, const Point< GPTYPE > & pt ) [pure virtual]
```

Moves the specified agent to the specified point.

Parameters

<i>id</i>	the id of the agent to move
<i>pt</i>	where to move the agent to

Returns

true if the move was successful, otherwise false

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPTYPE >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

```
5.41.3.19 template<typename T, typename GPTYPE> virtual bool repast::Grid< T, GPTYPE
>::sendsSecondaryAgentsOnStatusExchange ( ) [inline],[virtual]
```

Should return true if the [Projection](#) implemented will send secondary agents during a status exchange.

Generally spaces do not and graphs do.

If no secondary agents will be sent, portions of the algorithm can be omitted for optimization.

Returns

true if the [Projection](#) returns secondary agents, false if not

Implements [repast::Projection< T >](#).

5.41.3.20 `template<typename T, typename GPTYPE> virtual void repast::Grid< T, GPTYPE >::transform (const std::vector< GPTYPE > & location, std::vector< GPTYPE > & out) const [pure virtual]`

Transforms the specified location using the properties (e.g. toroidal) of this space.

Parameters

	<i>location</i>	the location to transform
<i>out</i>	<i>out</i>	the vector where the result of the transform will be put

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

5.41.3.21 `template<typename T, typename GPTYPE> virtual void repast::Grid< T, GPTYPE >::translate (const Point< GPTYPE > & location, const Point< GPTYPE > & displacement, std::vector< GPTYPE > & out) const [pure virtual]`

Translates the specified location by the specified displacement put the result in out.

Parameters

	<i>location</i>	the initial location
	<i>displacement</i>	the amount to translate the location by
<i>out</i>	<i>out</i>	the vector where the result of the translation is put

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

The documentation for this class was generated from the following file:

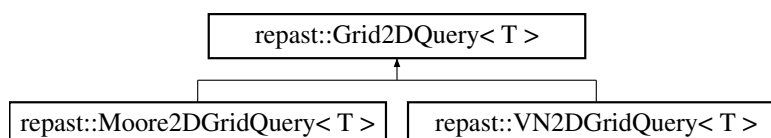
- [repast_hpc/Grid.h](#)

5.42 repast::Grid2DQuery< T > Class Template Reference

Base class for neighborhood queries on discrete Grids.

```
#include <Grid2DQuery.h>
```

Inheritance diagram for `repast::Grid2DQuery< T >`:



Public Member Functions

- [Grid2DQuery](#) (const [Grid](#)< T, int > *grid)
Creates [Grid2DQuery](#) that will query the specified [Grid](#).
- virtual void [query](#) (const [Point](#)< int > ¢er, int range, bool includeCenter, std::vector< T * > &out) const =0
Queries the [Grid](#) for the neighbors surrounding the center point within a specified range.

Protected Attributes

- const [Grid](#)< T, int > * **_grid**
- int **minMax** [2][2]

5.42.1 Detailed Description

template<typename T>class repast::Grid2DQuery< T >

Base class for neighborhood queries on discrete Grids.

Template Parameters

<i>T</i>	the type of object in the Grid .
----------	--

5.42.2 Member Function Documentation

5.42.2.1 template<typename T > virtual void repast::Grid2DQuery< T >::query (const [Point](#)< int > & center, int range, bool includeCenter, std::vector< T * > & out) const [pure virtual]

Queries the [Grid](#) for the neighbors surrounding the center point within a specified range.

What constitutes the neighborhood is determines by subclass implementors.

Parameters

	<i>center</i>	the center of the neighborhood
	<i>range</i>	the range of the neighborhood out from the center
	<i>includeCenter</i>	whether or not to include any agents at the center
out	<i>the</i>	neighboring agents will be returned in this vector

Implemented in [repast::Moore2DGridQuery< T >](#), and [repast::VN2DGridQuery< T >](#).

The documentation for this class was generated from the following file:

- repast_hpc/Grid2DQuery.h

5.43 repast::GridBufferSyncher< T, GPType > Class Template Reference

DEPRECATED Helper class that provides support for synchronizing a grid / space buffer.

```
#include <SharedBaseGrid.h>
```

Public Member Functions

- **GridBufferSyncher** (boost::mpi::communicator *world)
- std::vector< [CellContents](#)< T, GPType > > * **received** (size_t index)

- int **nghRank** (size_t index)
- size_t **vecsSize** ()
- void **send** (int rank, std::vector< [CellContents](#)< T, GPType > > &contents, int tag)
Sends the contents to the rank.
- void **receive** ([Neighbor](#) *ngh, int tag)
- void **wait** ()

5.43.1 Detailed Description

template<typename T, typename GPType>class repast::GridBufferSyncher< T, GPType >

DEPRECATED Helper class that provides support for synchronizing a grid / space buffer.

Deprecated As of Version 2.0

The documentation for this class was generated from the following file:

- repast_hpc/SharedBaseGrid.h

5.44 repast::GridDimensions Class Reference

Basic structure for specifying grid dimensions.

```
#include <GridDimensions.h>
```

Public Member Functions

- **GridDimensions** ([Point](#)< double > extent)
- **GridDimensions** ([Point](#)< double > **origin**, [Point](#)< double > extent)
Creates a [GridDimensions](#) with the specified origin and extent.
- bool **contains** (const [Point](#)< int > &pt) const
- bool **contains** (const std::vector< int > &pt) const
- bool **contains** (const [Point](#)< double > &pt) const
- bool **contains** (const std::vector< double > &pt) const
- const [Point](#)< double > & **origin** () const
Gets the origin.
- const [Point](#)< double > & **extents** () const
Gets the extents along each dimension.
- const double & **origin** (int index) const
- const double & **extents** (int index) const
- size_t **dimensionCount** () const

Friends

- bool **operator==** (const [GridDimensions](#) &one, const [GridDimensions](#) &two)
- std::ostream & **operator<<** (std::ostream &os, const [GridDimensions](#) &dimensions)

5.44.1 Detailed Description

Basic structure for specifying grid dimenions.

Structure is to specify (using instances of [Point](#)) the origin and the extent, so that an origin of (-100, -100) and an extent of (200, 200) represents a rectangle with corners at (-100, -100), (-100, 100), (100, 100), and (100, -100).

The documentation for this class was generated from the following files:

- repast_hpc/GridDimensions.h
- repast_hpc/GridDimensions.cpp

5.45 repast::GridMovePacket< PtType > Struct Template Reference

Encapsulates info about an agent moving off the grid: the rank it moved to, its grid location, and the agent id.

```
#include <GridMovePackets.h>
```

Public Member Functions

- **GridMovePacket** (const [Point](#)< PtType > &pt, const [AgentId](#) &id, int rank)
- template<class Archive >
void **serialize** (Archive &ar, const unsigned int version)

Public Attributes

- [Point](#)< PtType > **_pt**
- [AgentId](#) **_id**
- int **_rank**

5.45.1 Detailed Description

```
template<typename PtType>struct repast::GridMovePacket< PtType >
```

Encapsulates info about an agent moving off the grid: the rank it moved to, its grid location, and the agent id.

The documentation for this struct was generated from the following file:

- repast_hpc/GridMovePackets.h

5.46 repast::GridMovePackets< PtType > Class Template Reference

A collection of [GridMovePacket](#) objects, kept in a map per destination process.

```
#include <GridMovePackets.h>
```

Public Member Functions

- void **addPacket** (const [GridMovePacket](#)< PtType > &packet)
- void **clear** ()
- void **removePacketFor** (const [AgentId](#) &id)
Removes any GridMovePacket-s associated with the specified agent id.
- void **send** (std::vector< boost::mpi::request > &requests, boost::mpi::communicator world)
- void **receivers** (std::vector< int > &receivers)

5.46.1 Detailed Description

```
template<typename PtType>class repast::GridMovePackets< PtType >
```

A collection of [GridMovePacket](#) objects, kept in a map per destination process.

The documentation for this class was generated from the following file:

- repast_hpc/GridMovePackets.h

5.47 repast::GridPointHolder< T, GPType > Struct Template Reference

Encapsulates a grid point and what is held in it.

```
#include <BaseGrid.h>
```

Public Attributes

- bool **inGrid**
- [Point](#)< GPType > **point**
- boost::shared_ptr< T > **ptr**

5.47.1 Detailed Description

```
template<typename T, typename GPType>struct repast::GridPointHolder< T, GPType >
```

Encapsulates a grid point and what is held in it.

The documentation for this struct was generated from the following file:

- repast_hpc/BaseGrid.h

5.48 repast::HashGridPoint< T > Struct Template Reference

Class that allows retrieval of hash value for [Point](#) objects.

```
#include <Point.h>
```

Public Member Functions

- std::size_t **operator()** (const [Point](#)< T > &pt) const

5.48.1 Detailed Description

```
template<typename T>struct repast::HashGridPoint< T >
```

Class that allows retrieval of hash value for [Point](#) objects.

The documentation for this struct was generated from the following file:

- repast_hpc/Point.h

5.49 repast::HashId Struct Reference

operator() implementation that returns the hashcode of an [AgentId](#).

```
#include <AgentId.h>
```

Public Member Functions

- `std::size_t operator() (const AgentId &id) const`

5.49.1 Detailed Description

operator() implementation that returns the hashcode of an [AgentId](#).

The documentation for this struct was generated from the following file:

- `repast_hpc/AgentId.h`

5.50 repast::HashVertex< V, E > Struct Template Reference

Hashes a [Vertex](#) using the hashcode of the [AgentId](#) that the vertex contains.

```
#include <Vertex.h>
```

Public Member Functions

- `std::size_t operator() (Vertex< V, E > *vertex) const`

5.50.1 Detailed Description

```
template<typename V, typename E>struct repast::HashVertex< V, E >
```

Hashes a [Vertex](#) using the hashcode of the [AgentId](#) that the vertex contains.

The documentation for this struct was generated from the following file:

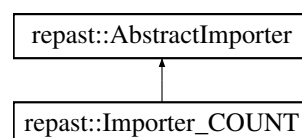
- `repast_hpc/Vertex.h`

5.51 repast::Importer_COUNT Class Reference

Importer that maintains a simple count of the agents being sent from each sending process.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::Importer_COUNT:



Public Member Functions

- virtual void [registerOutgoingRequests](#) ([AgentRequest](#) &req)
Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.
- virtual void [importedAgentIsRemoved](#) (const [AgentId](#) &id)
Notifies this importer that the agent that it (presumably) has been importing has been removed from the simulation on its home process, and the information for that agent will no longer be sent.
- virtual void [importedAgentIsMoved](#) (const [AgentId](#) &id, int newProcess)
Notifies this importer that the agent that it (presumably) has been importing from another process has been moved; its information will now be received from its new home process (unless the agent was moved to this process)
- virtual std::string [getReport](#) ()
Get a printable indication of the data in this object.
- virtual void [getSetOfAgentsBeingImported](#) (std::set< [AgentId](#) > &set)

Additional Inherited Members

5.51.1 Detailed Description

Importer that maintains a simple count of the agents being sent from each sending process.

When the count for a given process is zero no mpi 'receive' is created for that process; when the count is nonzero, a 'receive' is created. Note that no record of which agents are requested is kept, only the count of agents requested is kept.

5.51.2 Member Function Documentation

5.51.2.1 void Importer_COUNT::registerOutgoingRequests ([AgentRequest](#) & req) [virtual]

Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.

The record must at a minimum indicate which other processes are sending agent information, but may include other information, such as how many times a particular agent has been requested.

Implements [repast::AbstractImporter](#).

The documentation for this class was generated from the following files:

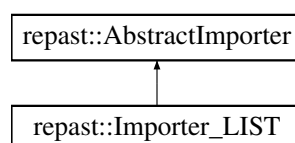
- repast_hpc/AgentImporterExporter.h
- repast_hpc/AgentImporterExporter.cpp

5.52 repast::Importer_LIST Class Reference

Importer that maintains a list of the agents being sent from each sending process.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::Importer_LIST:



Public Member Functions

- virtual void **registerOutgoingRequests** ([AgentRequest](#) &req)
Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.
- virtual void **importedAgentsRemoved** (const [AgentId](#) &id)
Notifies this importer that the agent that it (presumably) has been importing has been removed from the simulation on its home process, and the information for that agent will no longer be sent.
- virtual void **importedAgentsMoved** (const [AgentId](#) &id, int newProcess)
Notifies this importer that the agent that it (presumably) has been importing from another process has been moved; its information will now be received from its new home process (unless the agent was moved to this process)
- virtual std::string **getReport** ()
Get a printable indication of the data in this object.
- virtual void **getSetOfAgentsBeingImported** (std::set< [AgentId](#) > &set)
- virtual void **clear** ()

Additional Inherited Members

5.52.1 Detailed Description

Importer that maintains a list of the agents being sent from each sending process.

If there are no agents being sent the size of the list will be zero and no mpi 'receive' will be created; for non-zero-length lists a single mpi 'receiver' is created. An agent that is requested twice is placed in the list twice. Semantically this means that an agent cancellation will remove the agent from the list exactly once, but also that removing an agent from the list who is not found in the list will not reduce the list size (c.f. the 'count' version, where every cancellation reduces the count whether the specific agent being canceled was ever requested at all).

5.52.2 Member Function Documentation

5.52.2.1 void Importer_LIST::registerOutgoingRequests ([AgentRequest](#) & req) [virtual]

Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.

The record must at a minimum indicate which other processes are sending agent information, but may include other information, such as how many times a particular agent has been requested.

Implements [repast::AbstractImporter](#).

The documentation for this class was generated from the following files:

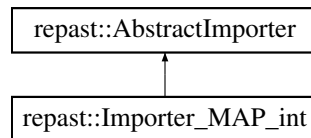
- repast_hpc/AgentImporterExporter.h
- repast_hpc/AgentImporterExporter.cpp

5.53 repast::Importer_MAP_int Class Reference

Importer that maintains a map of agents being sent from each sending process and a count of the number of times that agent was requested.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::Importer_MAP_int:



Public Member Functions

- virtual void [registerOutgoingRequests](#) ([AgentRequest](#) &req)
Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.
- virtual void [importedAgentsRemoved](#) (const [AgentId](#) &id)
Notifies this importer that the agent that it (presumably) has been importing has been removed from the simulation on its home process, and the information for that agent will no longer be sent.
- virtual void [importedAgentsMoved](#) (const [AgentId](#) &id, int newProcess)
Notifies this importer that the agent that it (presumably) has been importing from another process has been moved; its information will now be received from its new home process (unless the agent was moved to this process)
- virtual std::string [getReport](#) ()
Get a printable indication of the data in this object.
- virtual void [getSetOfAgentsBeingImported](#) (std::set< [AgentId](#) > &set)
- virtual void [clear](#) ()

Additional Inherited Members

5.53.1 Detailed Description

Importer that maintains a map of agents being sent from each sending process and a count of the number of times that agent was requested.

This is semantically equivalent to a 'LIST' type, but may be more or less appropriate in specific contexts based on performance. Duplicate requests for an agent increment the count associated with that agent; canceling a request reduces that count. If a given sending process has no agents being shared, no mpi 'receive' will be created, but if there are agents being shared, a 'receive' will be created.

5.53.2 Member Function Documentation

5.53.2.1 void Importer_MAP_int::registerOutgoingRequests ([AgentRequest](#) & req) [virtual]

Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.

The record must at a minimum indicate which other processes are sending agent information, but may include other information, such as how many times a particular agent has been requested.

Implements [repast::AbstractImporter](#).

The documentation for this class was generated from the following files:

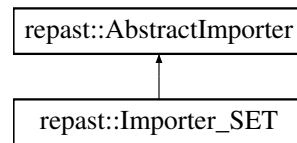
- repast_hpc/AgentImporterExporter.h
- repast_hpc/AgentImporterExporter.cpp

5.54 repast::Importer_SET Class Reference

Importer that maintains a set of agents being sent from each sending process.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for `repast::Importer_SET`:



Public Member Functions

- virtual void `registerOutgoingRequests` (`AgentRequest` &req)
Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.
- virtual void `importedAgentsRemoved` (const `AgentId` &id)
Notifies this importer that the agent that it (presumably) has been importing has been removed from the simulation on its home process, and the information for that agent will no longer be sent.
- virtual void `importedAgentsMoved` (const `AgentId` &id, int newProcess)
Notifies this importer that the agent that it (presumably) has been importing from another process has been moved; its information will now be received from its new home process (unless the agent was moved to this process)
- virtual std::string `getReport` ()
Get a printable indication of the data in this object.
- virtual void `getSetOfAgentsBeingImported` (std::set< `AgentId` > &set)
- virtual void `clear` ()

Additional Inherited Members

5.54.1 Detailed Description

Importer that maintains a set of agents being sent from each sending process.

Note that because this is a set, an agent may appear in it only once, no matter how many times it is requested. Canceling the agent will remove it from the set, even if the agent was requested multiple duplicate times. If the set for a given process is size zero, no mpi 'receive' will be created; if the set has any elements, an mpi 'receive' will be created.

5.54.2 Member Function Documentation

5.54.2.1 void `Importer_SET::registerOutgoingRequests` (`AgentRequest` & req) [virtual]

Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.

The record must at a minimum indicate which other processes are sending agent information, but may include other information, such as how many times a particular agent has been requested.

Implements `repast::AbstractImporter`.

The documentation for this class was generated from the following files:

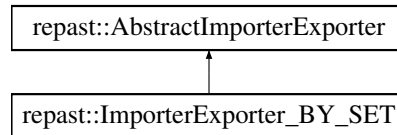
- `repast_hpc/AgentImporterExporter.h`
- `repast_hpc/AgentImporterExporter.cpp`

5.55 repast::ImporterExporter_BY_SET Class Reference

Implementation of the [AbstractImporterExporter](#) class that wraps a collection of [AbstractImporterExporter](#) objects that can be referenced by name.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::ImporterExporter_BY_SET:



Public Member Functions

- virtual const std::set< int > & **getExportingProcesses** ()
- const std::set< int > & **getExportingProcesses** (std::string setName)
- virtual void **registerOutgoingRequests** ([AgentRequest](#) &request)
- void **registerOutgoingRequests** ([AgentRequest](#) &request, std::string setName, AGENT_IMPORTER_EXPORTER_TYPE setType=DEFAULT_ENUM_SYMBOL)
- virtual void **importedAgentsRemoved** (const [AgentId](#) &id)
- virtual void **importedAgentsMoved** (const [AgentId](#) &id, int newProcess)
- virtual void **importedAgentsNowLocal** (const [AgentId](#) &id)
- virtual const
AbstractExporter::StatusMap * **getOutgoingStatusChanges** ()
- virtual const std::set< int > & **getProcessesExportedTo** ()
- const std::set< int > & **getProcessesExportedTo** (std::string setName)
- virtual void **registerIncomingRequests** (std::vector< [AgentRequest](#) > &requests)
- void **registerIncomingRequests** (std::vector< [AgentRequest](#) > &requests, std::string setName)
- virtual void **agentRemoved** (const [AgentId](#) &id)
- virtual void **agentMoved** (const [AgentId](#) &id, int newProcess)
- virtual void **incorporateAgentExporterInfo** (std::map< int, [AgentRequest](#) * > info)
- void **incorporateAgentExporterInfo** (std::map< std::string, std::map< int, [AgentRequest](#) * > * > info)
- virtual void **clearStatusMap** ()
- virtual AgentExporterInfo * **getAgentExportInfo** (int destProc)
- virtual void **clearAgentExportInfo** ()
- virtual const std::map< int,
[AgentRequest](#) > & **getAgentsToExport** ()
- const std::map< int,
[AgentRequest](#) > & **getAgentsToExport** (std::string setName)
- virtual std::string **version** ()
Returns the version of this [AbstractImporterExporter](#).
- void **dropSet** (std::string setName)
- virtual std::string **getReport** ()
Gets a printable report of the state of this object.
- virtual void **getSetOfAgentsBeingImported** (std::set< [AgentId](#) > &set)
- void **getSetOfAgentsBeingImported** (std::set< [AgentId](#) > &set, std::string excludeSet)
- virtual void **clear** ()
- void **clear** (std::string setName)
- virtual void **clearExporter** ()
- void **clearExporter** (std::string setName)
- void **clearExportToSpecificProc** (int rank)

Additional Inherited Members

5.55.1 Detailed Description

Implementation of the [AbstractImporterExporter](#) class that wraps a collection of [AbstractImporterExporter](#) objects that can be referenced by name.

Each object can contain a different collection of agents, which were requested with an associated name for the importer/exporter to be used. They can then be updated separately, allowing for improved performance under certain circumstances.

5.55.2 Member Function Documentation

5.55.2.1 `std::string ImporterExporter_BY_SET::version () [virtual]`

Returns the version of this [AbstractImporterExporter](#).

The version is a string that indicates the semantic version of the importer and the exporter (e.g. "COUNT_LIST")

Implements [repast::AbstractImporterExporter](#).

The documentation for this class was generated from the following files:

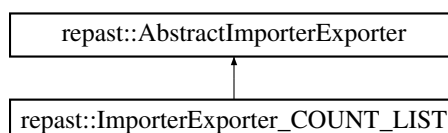
- `repast_hpc/AgentImporterExporter.h`
- `repast_hpc/AgentImporterExporter.cpp`

5.56 `repast::ImporterExporter_COUNT_LIST` Class Reference

An implementation of [AbstractImporterExporter](#) that uses an importer of type '[Importer_COUNT](#)' and an exporter of type '[Exporter_LIST](#)'.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for `repast::ImporterExporter_COUNT_LIST`:



Public Member Functions

- **`ImporterExporter_COUNT_LIST`** (`AbstractExporter::StatusMap *outgoingStatusMap`, [AgentExporterData](#) `*outgoingAgentExporterInfo`)
- `virtual std::string version ()`

Returns the version of this [AbstractImporterExporter](#).

Additional Inherited Members

5.56.1 Detailed Description

An implementation of [AbstractImporterExporter](#) that uses an importer of type '[Importer_COUNT](#)' and an exporter of type '[Exporter_LIST](#)'.

5.56.2 Member Function Documentation

5.56.2.1 std::string ImporterExporter_COUNT_LIST::version () [virtual]

Returns the version of this [AbstractImporterExporter](#).

The version is a string that indicates the semantic version of the importer and the exporter (e.g. "COUNT_LIST")

Implements [repast::AbstractImporterExporter](#).

The documentation for this class was generated from the following files:

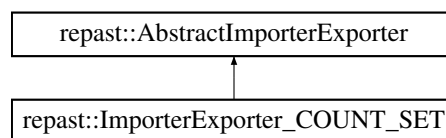
- repast_hpc/AgentImporterExporter.h
- repast_hpc/AgentImporterExporter.cpp

5.57 repast::ImporterExporter_COUNT_SET Class Reference

An implementation of [AbstractImporterExporter](#) that uses an importer of type '[Importer_COUNT](#)' and an exporter of type '[Exporter_SET](#)'.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::ImporterExporter_COUNT_SET:



Public Member Functions

- **ImporterExporter_COUNT_SET** ([AbstractExporter::StatusMap](#) *outgoingStatusMap, [AgentExporterData](#) *outgoingAgentExporterInfo)
- virtual std::string [version](#) ()

Returns the version of this [AbstractImporterExporter](#).

Additional Inherited Members

5.57.1 Detailed Description

An implementation of [AbstractImporterExporter](#) that uses an importer of type '[Importer_COUNT](#)' and an exporter of type '[Exporter_SET](#)'.

5.57.2 Member Function Documentation

5.57.2.1 std::string ImporterExporter_COUNT_SET::version () [virtual]

Returns the version of this [AbstractImporterExporter](#).

The version is a string that indicates the semantic version of the importer and the exporter (e.g. "COUNT_LIST")

Implements [repast::AbstractImporterExporter](#).

The documentation for this class was generated from the following files:

- repast_hpc/AgentImporterExporter.h

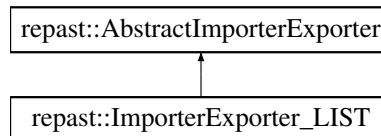
- `repast_hpc/AgentImporterExporter.cpp`

5.58 repast::ImporterExporter_LIST Class Reference

An implementation of [AbstractImporterExporter](#) that uses an importer of type '[Importer_LIST](#)' and an exporter of type '[Exporter_LIST](#)'.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for `repast::ImporterExporter_LIST`:



Public Member Functions

- **ImporterExporter_LIST** (`AbstractExporter::StatusMap *outgoingStatusMap`, [AgentExporterData](#) *outgoing-AgentExporterInfo)
- virtual `std::string version ()`
Returns the version of this [AbstractImporterExporter](#).

Additional Inherited Members

5.58.1 Detailed Description

An implementation of [AbstractImporterExporter](#) that uses an importer of type '[Importer_LIST](#)' and an exporter of type '[Exporter_LIST](#)'.

5.58.2 Member Function Documentation

5.58.2.1 `std::string ImporterExporter_LIST::version ()` [virtual]

Returns the version of this [AbstractImporterExporter](#).

The version is a string that indicates the semantic version of the importer and the exporter (e.g. "COUNT_LIST")

Implements [repast::AbstractImporterExporter](#).

The documentation for this class was generated from the following files:

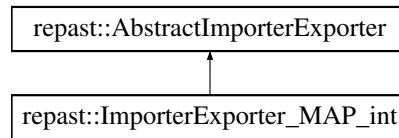
- `repast_hpc/AgentImporterExporter.h`
- `repast_hpc/AgentImporterExporter.cpp`

5.59 repast::ImporterExporter_MAP_int Class Reference

An implementation of [AbstractImporterExporter](#) that uses an importer of type '[Importer_MAP_int](#)' and an exporter of type '[Exporter_LIST](#)'.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for `repast::ImporterExporter_MAP_int`:



Public Member Functions

- **ImporterExporter_MAP_int** (AbstractExporter::StatusMap *outgoingStatusMap, [AgentExporterData](#) *outgoingAgentExporterInfo)
- virtual std::string [version](#) ()
Returns the version of this [AbstractImporterExporter](#).

Additional Inherited Members

5.59.1 Detailed Description

An implementation of [AbstractImporterExporter](#) that uses an importer of type '[Importer_MAP_int](#)' and an exporter of type '[Exporter_LIST](#)'.

5.59.2 Member Function Documentation

5.59.2.1 std::string ImporterExporter_MAP_int::version () [virtual]

Returns the version of this [AbstractImporterExporter](#).

The version is a string that indicates the semantic version of the importer and the exporter (e.g. "COUNT_LIST")

Implements [repast::AbstractImporterExporter](#).

The documentation for this class was generated from the following files:

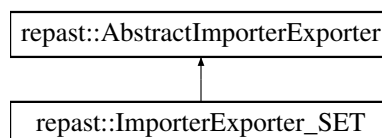
- repast_hpc/AgentImporterExporter.h
- repast_hpc/AgentImporterExporter.cpp

5.60 repast::ImporterExporter_SET Class Reference

An implementation of [AbstractImporterExporter](#) that uses an importer of type '[Importer_SET](#)' and an exporter of type '[Exporter_LIST](#)'.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::ImporterExporter_SET:



Public Member Functions

- **ImporterExporter_SET** (AbstractExporter::StatusMap *outgoingStatusMap, [AgentExporterData](#) *outgoingAgentExporterInfo)

- virtual std::string [version](#) ()

Returns the version of this [AbstractImporterExporter](#).

Additional Inherited Members

5.60.1 Detailed Description

An implementation of [AbstractImporterExporter](#) that uses an importer of type '[Importer_SET](#)' and an exporter of type '[Exporter_LIST](#)'.

5.60.2 Member Function Documentation

5.60.2.1 std::string ImporterExporter_SET::version () [virtual]

Returns the version of this [AbstractImporterExporter](#).

The version is a string that indicates the semantic version of the importer and the exporter (e.g. "COUNT_LIST")

Implements [repast::AbstractImporterExporter](#).

The documentation for this class was generated from the following files:

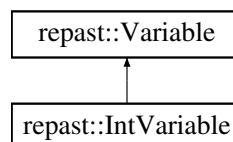
- repast_hpc/AgentImporterExporter.h
- repast_hpc/AgentImporterExporter.cpp

5.61 repast::IntVariable Class Reference

Used in [SVDDataSet](#) to manage integer data.

```
#include <Variable.h>
```

Inheritance diagram for repast::IntVariable:



Public Member Functions

- virtual void [write](#) (size_t index, std::ofstream &out)
Writes the data at the specified index to the specified ofstream.
- virtual void [insert](#) (double *array, size_t size)
Inserts all the doubles in the double array into the collection of data stored in this [Variable](#).
- virtual void [insert](#) (int *array, size_t size)
Inserts all the ints in the int array into the collection of data stored in this [Variable](#).
- virtual void [clear](#) ()
Clears this [Variable](#) of all the data stored in it.

5.61.1 Detailed Description

Used in [SVDDataSet](#) to manage integer data.

5.61.2 Member Function Documentation

5.61.2.1 void repast::IntVariable::insert (double * array, size_t size) [virtual]

Inserts all the doubles in the double array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implements [repast::Variable](#).

5.61.2.2 void repast::IntVariable::insert (int * array, size_t size) [virtual]

Inserts all the ints in the int array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implements [repast::Variable](#).

5.61.2.3 void repast::IntVariable::write (size_t index, std::ofstream & out) [virtual]

Writes the data at the specified index to the specified ofstream.

Parameters

<i>index</i>	the index of the data to write
<i>out</i>	the ofstream to write the data to

Implements [repast::Variable](#).

The documentation for this class was generated from the following files:

- repast_hpc/Variable.h
- repast_hpc/Variable.cpp

5.62 repast::IsAgentType< T > Struct Template Reference

Struct that allows filtering by [Agent](#) Type.

```
#include <AgentId.h>
```

Public Member Functions

- **IsAgentType** (int typeId)
- bool **operator()** (const boost::shared_ptr< T > &ptr)
- bool **operator()** (const T *agent)

Public Attributes

- int **_typeId**

5.62.1 Detailed Description

```
template<typename T>struct repast::IsAgentType< T >
```

Struct that allows filtering by [Agent](#) Type.

The documentation for this struct was generated from the following file:

- repast_hpc/AgentId.h

5.63 repast::IsLocalAgent< T > Struct Template Reference

Used in a filter iterator to filter on local agents only.

```
#include <SharedContext.h>
```

Public Member Functions

- **IsLocalAgent** (int rankInCommunicator)
- bool **operator()** (const boost::shared_ptr< T > &ptr)

Public Attributes

- int **rank**

5.63.1 Detailed Description

```
template<typename T>struct repast::IsLocalAgent< T >
```

Used in a filter iterator to filter on local agents only.

The documentation for this struct was generated from the following file:

- repast_hpc/SharedContext.h

5.64 repast::IsNotType< T > Struct Template Reference

Struct that allows filtering by [!\(Agent](#) Type)

```
#include <AgentId.h>
```

Public Member Functions

- **IsNotType** (int typeId)
- bool **operator()** (const boost::shared_ptr< T > &ptr)
- bool **operator()** (const T *agent)

Public Attributes

- int **_typeId**

5.64.1 Detailed Description

```
template<typename T>struct repast::IsNotType< T >
```

Struct that allows filtering by !([Agent](#) Type)

The documentation for this struct was generated from the following file:

- repast_hpc/AgentId.h

5.65 repast::ItemReceipt< E > Class Template Reference

DEPRECATED Receipt for edges Class used to receive edges being sent.

```
#include <SharedNetwork.h>
```

Public Member Functions

- **ItemReceipt** (int source)

Public Attributes

- std::vector< E > **items**
- int **source_**

5.65.1 Detailed Description

```
template<typename E>class repast::ItemReceipt< E >
```

DEPRECATED Receipt for edges Class used to receive edges being sent.

Deprecated As of Version 2.0 replaced by [ProjectionInfoPacket](#) objects.

The documentation for this class was generated from the following file:

- repast_hpc/SharedNetwork.h

5.66 repast::KEBuilder< V, E, Ec, EcM > Class Template Reference

Buils KE type networks.

```
#include <NetworkBuilder.h>
```

Public Member Functions

- void **build** ([repast::Properties](#) &props, [repast::Graph](#)< V, E, Ec, EcM > *graph)
Builds the network.

5.66.1 Detailed Description

```
template<typename V, typename E, typename Ec, typename EcM>class repast::KEBuilder< V, E, Ec, EcM >
```

Buils KE type networks.

See Klemm and Eguiluz, "Growing scale-free network with small world behavior" in Phys. Rev. E 65.

5.66.2 Member Function Documentation

```
5.66.2.1 template<typename V , typename E , typename Ec , typename EcM > void repast::KEBuilder< V, E, Ec, EcM
>::build ( repast::Properties & props, repast::Graph< V, E, Ec, EcM > * graph )
```

Buils the network.

The graph should contains the vertices the build the network with and props should contain the M values.

Parameters

<i>props</i>	a Properties containing a property "ke.model.m" that specifies the M value.
<i>graph</i>	the graph to build the network

The documentation for this class was generated from the following file:

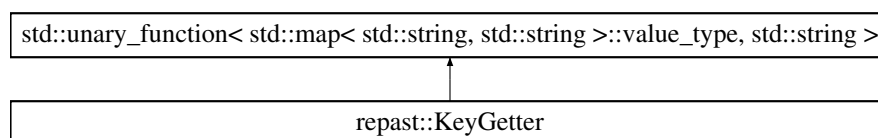
- repast_hpc/NetworkBuilder.h

5.67 repast::KeyGetter Struct Reference

Unary function used in a transform_iterator that allows the map iterator to return the keys.

```
#include <Properties.h>
```

Inheritance diagram for repast::KeyGetter:



Public Member Functions

- std::string **operator()** (const std::map< std::string, std::string >::value_type &value) const

5.67.1 Detailed Description

Unary function used in a transform_iterator that allows the map iterator to return the keys.

The documentation for this struct was generated from the following files:

- repast_hpc/Properties.h
- repast_hpc/Properties.cpp

5.68 Log4CL Class Reference

Public Member Functions

- [Logger](#) & **get_logger** (std::string logger_name)
- void **close** ()

Static Public Member Functions

- static [Log4CL](#) * **instance** ()
- static void **configure** (int, const std::string &, boost::mpi::communicator *comm=0, int maxConfigFileSize=MAX_CONFIG_FILE_SIZE)
- static void **configure** (int)

Protected Member Functions

- **Log4CL** (int)

Friends

- class **Log4CLConfigurator**

The documentation for this class was generated from the following files:

- repast_hpc/logger.h
- repast_hpc/logger.cpp

5.69 Log4CLConfigurator Class Reference

Public Member Functions

- [Log4CL](#) * **configure** (const std::string &config_file, int proc_id, boost::mpi::communicator *comm=0, int maxConfigFileSize=MAX_CONFIG_FILE_SIZE)

The documentation for this class was generated from the following files:

- repast_hpc/logger.h
- repast_hpc/logger.cpp

5.70 Logger Class Reference

Public Member Functions

- **Logger** (const std::string, LOG_LEVEL, int proc_id)
- void **log** (LOG_LEVEL, const std::string msg)
- void **close** ()
- void **add_appender** ([Appender](#) *appender)

The documentation for this class was generated from the following files:

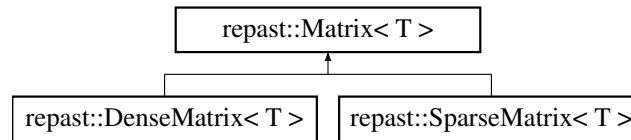
- repast_hpc/logger.h
- repast_hpc/logger.cpp

5.71 repast::Matrix< T > Class Template Reference

Base class for matrix implementations.

```
#include <matrix.h>
```

Inheritance diagram for repast::Matrix< T >:



Public Member Functions

- **Matrix** (const **Point**< int > &size, const T &defaultValue=T())
Creates a matrix of the specified size and with the specified default value.
- virtual T & **get** (const **Point**< int > &index)=0
Gets the value at the specified index.
- virtual void **set** (const T &value, const **Point**< int > &index)=0
Sets the value at the specified index.
- T & **operator[]** (const **Point**< int > &index)
- const T & **operator[]** (const **Point**< int > &index) const
- const T & **defaultValue** () const
Gets the default value of any unset matrix cell.
- const **Point**< int > **shape** () const
Gets the shape (i.e.

Protected Member Functions

- int **calcIndex** (const **Point**< int > &index)
- void **boundsCheck** (const **Point**< int > &index)
- void **create** ()

Protected Attributes

- int * **stride**
- T **defValue**
- **Point**< int > **_size**
- int **dCount**

5.71.1 Detailed Description

```
template<typename T>class repast::Matrix< T >
```

Base class for matrix implementations.

5.71.2 Constructor & Destructor Documentation

5.71.2.1 `template<typename T> repast::Matrix< T >::Matrix (const Point< int > & size, const T & defaultValue = T ()) [explicit]`

Creates a matrix of the specified size and with the specified default value.

Parameters

<i>size</i>	the size of the matrix in each dimension
-------------	--

5.71.3 Member Function Documentation

5.71.3.1 `template<typename T> const Point<int> repast::Matrix< T >::shape () const` `[inline]`

Gets the shape (i.e.

the length of each dimensions) of the matrix.

The documentation for this class was generated from the following file:

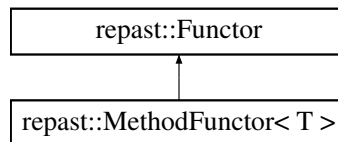
- `repast_hpc/matrix.h`

5.72 `repast::MethodFunctor< T >` Class Template Reference

Adapts a no-arg method call on an object instance to a [Functor](#) interface.

```
#include <Schedule.h>
```

Inheritance diagram for `repast::MethodFunctor< T >`:



Public Member Functions

- **MethodFunctor** (`T *_obj`, `void(T::*_fptr)()`)
- void **operator()** ()

5.72.1 Detailed Description

```
template<typename T> class repast::MethodFunctor< T >
```

Adapts a no-arg method call on an object instance to a [Functor](#) interface.

This is used by the [Schedule](#) code to schedule method calls on objects.

Template Parameters

<i>T</i>	the object type on which the call will be made.
----------	---

The documentation for this class was generated from the following file:

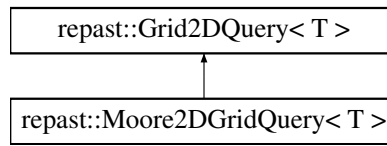
- `repast_hpc/Schedule.h`

5.73 `repast::Moore2DGridQuery< T >` Class Template Reference

Neighborhood query that gathers neighbors in a Moore (N, S, E, W, NE, etc.) neighborhood.

```
#include <Moore2DGridQuery.h>
```

Inheritance diagram for repast::Moore2DGridQuery< T >:



Public Member Functions

- [Moore2DGridQuery](#) (const [Grid](#)< T, int > *grid)
Creates [Moore2DGridQuery](#) that will query the specified [Grid](#).
- virtual void [query](#) (const [Point](#)< int > ¢er, int range, bool includeCenter, std::vector< T * > &out) const
Queries the [Grid](#) for the Moore neighbors surrounding the center point within a specified range.

Additional Inherited Members

5.73.1 Detailed Description

```
template<typename T>class repast::Moore2DGridQuery< T >
```

Neighborhood query that gathers neighbors in a Moore (N, S, E, W, NE, etc.) neighborhood.

Template Parameters

<i>T</i>	the type of agents in the Grid
----------	--

5.73.2 Member Function Documentation

5.73.2.1 `template<typename T> void repast::Moore2DGridQuery< T >::query (const Point< int > ¢er, int range, bool includeCenter, std::vector< T * > &out) const` [virtual]

Queries the [Grid](#) for the Moore neighbors surrounding the center point within a specified range.

Parameters

	<i>center</i>	the center of the neighborhood
	<i>range</i>	the range of the neighborhood out from the center
	<i>includeCenter</i>	whether or not to include any agents at the center
<i>out</i>	<i>the</i>	neighboring agents will be returned in this vector

Implements [repast::Grid2DQuery< T >](#).

The documentation for this class was generated from the following file:

- repast_hpc/Moore2DGridQuery.h

5.74 repast::MultipleOccupancy< T, GPType > Class Template Reference

Multiple Occupancy cell accessor for accessing the occupants of locations in a [Grid](#).

```
#include <MultipleOccupancy.h>
```

Public Member Functions

- `T * get (const Point< GPTYPE > &location) const`
Gets the first object found at the specified location.
- `void getAll (const Point< GPTYPE > &location, std::vector< T * > &out) const`
Gets all the items found at the specified location.
- `bool put (boost::shared_ptr< T > &agent, const Point< GPTYPE > &location)`
Puts the specified item at the specified location.
- `void remove (boost::shared_ptr< T > &agent, const Point< GPTYPE > &location)`
Removes the specified item from the specified location.

5.74.1 Detailed Description

`template<typename T, typename GPTYPE>class repast::MultipleOccupancy< T, GPTYPE >`

Multiple Occupancy cell accessor for accessing the occupants of locations in a [Grid](#).

Each locations can have multiple occupants.

Parameters

<i>T</i>	the type of object in the Grid
<i>GPTYPE</i>	the coordinate type of the grid point locations. This must be an int or a double.

5.74.2 Member Function Documentation

5.74.2.1 `template<typename T, typename GPTYPE> T * repast::MultipleOccupancy< T, GPTYPE >::get (const Point< GPTYPE > & location) const`

Gets the first object found at the specified location.

Parameters

<i>location</i>	the location to get the object at
-----------------	-----------------------------------

Returns

the first object found at the specified location or 0 if there are no objects at the specified location.

5.74.2.2 `template<typename T, typename GPTYPE> void repast::MultipleOccupancy< T, GPTYPE >::getAll (const Point< GPTYPE > & location, std::vector< T * > & out) const`

Gets all the items found at the specified location.

Parameters

	<i>location</i>	the location to get the items at
<i>out</i>	<i>the</i>	found items will be returned in this vector

5.74.2.3 `template<typename T, typename GPTYPE> bool repast::MultipleOccupancy< T, GPTYPE >::put (boost::shared_ptr< T > & agent, const Point< GPTYPE > & location)`

Puts the specified item at the specified location.

Parameters

<i>agent</i>	the item to put
<i>location</i>	the location to put the item at

5.74.2.4 `template<typename T, typename GType> void repast::MultipleOccupancy< T, GType >::remove (boost::shared_ptr< T > & agent, const Point< GType > & location)`

Removes the specified item from the specified location.

Parameters

<i>agent</i>	the item to remove
<i>location</i>	the location to remove the item from

The documentation for this class was generated from the following file:

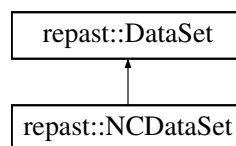
- repast_hpc/MultipleOccupancy.h

5.75 repast::NCDataSet Class Reference

Provides data recording and writing into a single file in NetCDF format.

```
#include <NCDataSet.h>
```

Inheritance diagram for repast::NCDataSet:



Public Member Functions

- void [record](#) ()
Records the data.
- void [write](#) ()
Writes the data.
- void [close](#) ()
Closes the dataset, after which it must be recreated to be used.

Friends

- class **NCDataSetBuilder**

5.75.1 Detailed Description

Provides data recording and writing into a single file in NetCDF format.

A [NCDataSet](#) uses rank 0 to write to a single file from multiple pan-process data sources. A [NCDataSet](#) should be built using a [NCDataSetBuilder](#).

The documentation for this class was generated from the following files:

- repast_hpc/NCDataSet.h
- repast_hpc/NCDataSet.cpp

5.76 repast::NCDataSetBuilder Class Reference

Used to build NCDataSets to record data in NetCDF format.

```
#include <NCDataSetBuilder.h>
```

Public Member Functions

- [NCDataSetBuilder](#) (std::string file, const [Schedule](#) &schedule)
Creates an [NCDataSetBuilder](#) that will write to the specified file and get its tick counts from the specified schedule.
- [NCDataSetBuilder](#) & addDataSource ([NCDataSource](#) *source)
Adds a [NCDataSource](#) to this [NCDataSetBuilder](#).
- [NCDataSet](#) * createDataSet ()
Creates the [NCDataSet](#) defined by this [NCDataSetBuilder](#).

5.76.1 Detailed Description

Used to build NCDataSets to record data in NetCDF format.

Steps for use are:

1. Create a [NCDataSetBuilder](#).
2. Add NCDataSources to the builder using the createNCDataSource functions. Each DataSource defines a variable and where the data for that variable will be retrieved. Recording data on the [NCDataSet](#) produced by the builder will record this data for each variable.
3. Call createDataSet to create the [NCDataSet](#).
4. [Schedule](#) calls to record and write on the [NCDataSet](#).

5.76.2 Constructor & Destructor Documentation

5.76.2.1 repast::NCDataSetBuilder::NCDataSetBuilder (std::string file, const Schedule & schedule)

Creates an [NCDataSetBuilder](#) that will write to the specified file and get its tick counts from the specified schedule.

Parameters

<i>file</i>	the name of the file to write to. Only rank 0 will actually write to this file.
<i>schedule</i>	the schedule to get tick counts from

5.76.3 Member Function Documentation

5.76.3.1 NCDataSetBuilder & repast::NCDataSetBuilder::addDataSource (NCDataSource * source)

Adds a [NCDataSource](#) to this [NCDataSetBuilder](#).

The added [NCDataSource](#) defines a variable and where the data for that variable will be retrieved. Recording data on the [NCDataSet](#) produced by this builder will record this data for each variable.

5.76.3.2 NCDataSet * repast::NCDataSetBuilder::createDataSet ()

Creates the [NCDataSet](#) defined by this [NCDataSetBuilder](#).

The caller is responsible for properly deleting the returned pointer.

Returns

the created [NCDataSet](#).

The documentation for this class was generated from the following files:

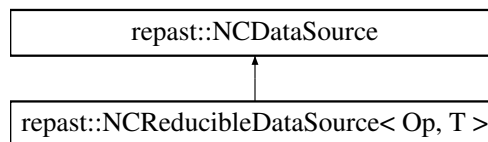
- repast_hpc/NCDataSetBuilder.h
- repast_hpc/NCDataSetBuilder.cpp

5.77 repast::NCDataSource Class Reference

Data source used internally by NCDataSets.

```
#include <NCDataSource.h>
```

Inheritance diagram for repast::NCDataSource:



Public Member Functions

- **NCDataSource** (std::string name)
- virtual void **record** ()=0
- virtual void **write** (NcVar *var)=0
- virtual NcType **ncType** ()=0
- const std::string **name** () const

Protected Attributes

- std::string **_name**

5.77.1 Detailed Description

Data source used internally by NCDataSets.

The documentation for this class was generated from the following file:

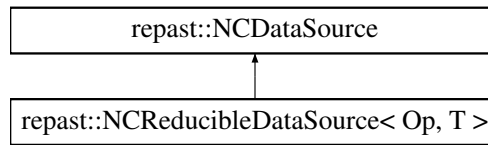
- repast_hpc/NCDataSource.h

5.78 repast::NCReducibleDataSource< Op, T > Class Template Reference

Source of data and a reduction operation.

```
#include <NCReducibleDataSource.h>
```

Inheritance diagram for `repast::NCReducibleDataSource< Op, T >`:



Public Member Functions

- **NCReducibleDataSource** (std::string name, [TDataSource< T > *dataSource](#), Op op)
- virtual NcType **ncType** ()
- virtual void **record** ()
- virtual void **write** (NcVar *var)

Protected Attributes

- Op **op_**
- std::vector< T > **data**
- [TDataSource< T > * dataSource_](#)
- int **rank**
- int **start**

5.78.1 Detailed Description

```
template<typename Op, typename T>class repast::NCReducibleDataSource< Op, T >
```

Source of data and a reduction operation.

Used internally by a [NCDataSet](#) to store the data sources. their associated ops etc.

The documentation for this class was generated from the following file:

- `repast_hpc/NCReducibleDataSource.h`

5.79 repast::NcTypeTrait< T > Struct Template Reference

Base class for specialized int and double NcType classes.

```
#include <NCDataSource.h>
```

5.79.1 Detailed Description

```
template<typename T>struct repast::NcTypeTrait< T >
```

Base class for specialized int and double NcType classes.

The documentation for this struct was generated from the following file:

- `repast_hpc/NCDataSource.h`

5.80 `repast::NcTypeTrait< double >` Struct Template Reference

Used for converting to NetCDF Data, double type.

```
#include <NCDataSource.h>
```

Static Public Attributes

- static const NcType **type** = ncDouble

5.80.1 Detailed Description

```
template<> struct repast::NcTypeTrait< double >
```

Used for converting to NetCDF Data, double type.

The documentation for this struct was generated from the following file:

- `repast_hpc/NCDataSource.h`

5.81 `repast::NcTypeTrait< int >` Struct Template Reference

Used for converting to NetCDF Data, int type.

```
#include <NCDataSource.h>
```

Static Public Attributes

- static const NcType **type** = ncInt

5.81.1 Detailed Description

```
template<> struct repast::NcTypeTrait< int >
```

Used for converting to NetCDF Data, int type.

The documentation for this struct was generated from the following file:

- `repast_hpc/NCDataSource.h`

5.82 `repast::Neighbor` Class Reference

Contains the rank and boundaries of a semantically adjacent process (that is, a process that manages the space that is adjacent to the simulation space managed by this process).

```
#include <SharedBaseGrid.h>
```

Public Member Functions

- **Neighbor** (int rank, [GridDimensions](#) bounds)
- int **rank** () const
- [GridDimensions](#) **bounds** () const

5.82.1 Detailed Description

Contains the rank and boundaries of a semantically adjacent process (that is, a process that manages the space that is adjacent to the simulation space managed by this process).

The documentation for this class was generated from the following files:

- repast_hpc/SharedBaseGrid.h
- repast_hpc/SharedBaseGrid.cpp

5.83 repast::Neighbors Class Reference

Provides lookup of grid topology process neighbors given a point in the pan process grid.

```
#include <SharedBaseGrid.h>
```

Public Types

- enum [Location](#) {
E, W, N, S,
NE, NW, SE, SW }

Describes the relative location of grid topology process neighbors.

Public Member Functions

- void [addNeighbor](#) ([Neighbor](#) *ngh, [Neighbors::Location](#) location)
Adds a neighbor at the specified location.
- [Neighbor](#) * [neighbor](#) ([Neighbors::Location](#) location) const
Gets the neighbor at the specified location.
- [Neighbor](#) * [findNeighbor](#) (const std::vector< int > &pt)
Finds the neighbor that contains the specified point.
- [Neighbor](#) * [findNeighbor](#) (const std::vector< double > &pt)
Finds the neighbor that contains the specified point.
- void [getNeighborRanks](#) (std::set< int > &ranks)

Static Public Attributes

- static const int **LOCATION_SIZE** = 8

Friends

- std::ostream & **operator**<< (std::ostream &os, const [Neighbors](#) &nghs)

5.83.1 Detailed Description

Provides lookup of grid topology process neighbors given a point in the pan process grid.

5.83.2 Member Function Documentation

5.83.2.1 `Neighbor * repast::Neighbors::findNeighbor (const std::vector< int > & pt)`

Finds the neighbor that contains the specified point.

Returns

the found neighbor

5.83.2.2 `Neighbor * repast::Neighbors::findNeighbor (const std::vector< double > & pt)`

Finds the neighbor that contains the specified point.

Returns

the found neighbor

5.83.2.3 `Neighbor * repast::Neighbors::neighbor (Neighbors::Location location) const`

Gets the neighbor at the specified location.

Parameters

<i>location</i>	the location of the neighbor.
-----------------	-------------------------------

The documentation for this class was generated from the following files:

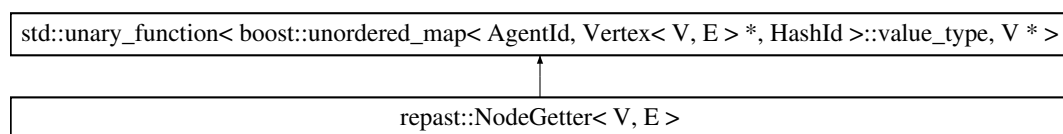
- `repast_hpc/SharedBaseGrid.h`
- `repast_hpc/SharedBaseGrid.cpp`

5.84 `repast::NodeGetter< V, E >` Struct Template Reference

Unary function used in the `transform_iterator` that allows an iterator over the vertex map to return the node.

```
#include <Vertex.h>
```

Inheritance diagram for `repast::NodeGetter< V, E >`:



Public Member Functions

- `V * operator() (const typename boost::unordered_map< AgentId, Vertex< V, E > *, HashId >::value_type &value) const`

5.84.1 Detailed Description

```
template<typename V, typename E>struct repast::NodeGetter< V, E >
```

Unary function used in the `transform_iterator` that allows an iterator over the vertex map to return the node.

The documentation for this struct was generated from the following file:

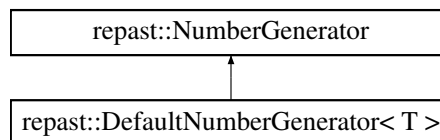
- `repast_hpc/Vertex.h`

5.85 repast::NumberGenerator Class Reference

Number generator interface.

```
#include <Random.h>
```

Inheritance diagram for `repast::NumberGenerator`:



Public Member Functions

- virtual double `next` ()=0
Gets the "next" number from this Number Generator.

5.85.1 Detailed Description

Number generator interface.

The documentation for this class was generated from the following file:

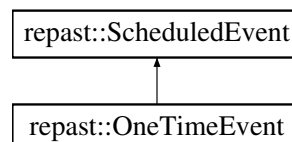
- `repast_hpc/Random.h`

5.86 repast::OneTimeEvent Class Reference

`ScheduledEvent` that will only execute only once.

```
#include <Schedule.h>
```

Inheritance diagram for `repast::OneTimeEvent`:



Public Member Functions

- **OneTimeEvent** (double, `RepastEvent` *)
- virtual bool `reschedule` (std::priority_queue< `ScheduledEvent` *, std::vector< `ScheduledEvent` * >, `EventCompare` > &)
Always returns false, as it does not reschedule itself.

Additional Inherited Members

5.86.1 Detailed Description

[ScheduledEvent](#) that will only execute only once.

The documentation for this class was generated from the following files:

- repast_hpc/Schedule.h
- repast_hpc/Schedule.cpp

5.87 repast::Point< T > Class Template Reference

A N-dimensional [Point](#) representation.

```
#include <Point.h>
```

Public Types

- typedef std::vector< T >
::const_iterator **const_iterator**

Public Member Functions

- [Point](#) (T x)
Creates a one dimensional point with the specified value.
- [Point](#) (T x, T y)
Creates a two dimensional point with the specified values.
- [Point](#) (T x, T y, T z)
Creates a three dimensional point with the specified values.
- [Point](#) (std::vector< T > coordinates)
Creates a multi-dimensional point with the specified values.
- T [getX](#) () const
Gets the x coordinate of the point.
- T [getY](#) () const
Gets the y coordinate of the point.
- T [getZ](#) () const
Gets the z coordinate of the point.
- T [getCoordinate](#) (int coordIndex) const
Gets the coordinate of the point in the specified dimension.
- void [add](#) (const [Point](#)< T > &pt)
Adds the specified GridPoint to this GridPoint.
- size_t [dimensionCount](#) () const
Gets the number of dimensions of this point.
- const T & [operator\[\]](#) (size_t index) const
Gets the coordinate value at the specified index.
- T & [operator\[\]](#) (size_t index)
Gets the coordinate value at the specified index.
- const std::vector< T > & [coords](#) () const
Gets the coordinates of this point as a vector.
- const_iterator [begin](#) () const

Gets the start of an iterator over the coordinates of this point.

- `const_iterator` `end` () `const`

Gets the end of an iterator over the coordinates of this point.

- `void` `copy` (`std::vector< T > &out`) `const`

Copies the point into the specified vector.

Friends

- `struct` `HashGridPoint< T >`
- `class` `boost::serialization::access`
- `bool` `operator==` (`const` `Point< T >` `&one`, `const` `Point< T >` `&two`)
- `std::ostream &` `operator<<` (`std::ostream &os`, `const` `Point< T >` `&pt`)

5.87.1 Detailed Description

```
template<typename T>class repast::Point< T >
```

A N-dimensional `Point` representation.

N dimensional point for addressing matrix locations.

Parameters

<code>T</code>	a numeric type. In repast and relogo these are limited to int and double.
----------------	---

5.87.2 Constructor & Destructor Documentation

5.87.2.1 `template<typename T> repast::Point< T >::Point (T x)` `[explicit]`

Creates a one dimensional point with the specified value.

Parameters

<code>x</code>	the x coordinate of the point
----------------	-------------------------------

5.87.2.2 `template<typename T> repast::Point< T >::Point (T x, T y)`

Creates a two dimensional point with the specified values.

Parameters

<code>x</code>	the x coordinate of the point
<code>y</code>	the y coordinate of the point

5.87.2.3 `template<typename T> repast::Point< T >::Point (T x, T y, T z)`

Creates a three dimensional point with the specified values.

Parameters

<code>x</code>	the x coordinate of the point
<code>y</code>	the y coordinate of the point
<code>z</code>	the z coordinate of the point

5.87.2.4 `template<typename T> repast::Point< T >::Point (std::vector< T > coordinates)`

Creates a multi-dimensional point with the specified values.

Parameters

<i>coordinates</i>	the coordinate values of the point. The first element will be x, the second y and so on.
--------------------	--

5.87.3 Member Function Documentation

5.87.3.1 `template<typename T> void repast::Point< T >::add (const Point< T > & pt)`

Adds the specified GridPoint to this GridPoint.

This GridPoint contains the result.

Exceptions

<i>invalid_argument</i>	exception if the pt doesn't have the same number of dimensions as this GridPoint.
-------------------------	---

5.87.3.2 `template<typename T> const_iterator repast::Point< T >::begin () const [inline]`

Gets the start of an iterator over the coordinates of this point.

Returns

the start of an iterator over the coordinates of this point.

5.87.3.3 `template<typename T> const std::vector<T>& repast::Point< T >::coords () const [inline]`

Gets the coordinates of this point as a vector.

Returns

a vector containing the coordinates of this point.

5.87.3.4 `template<typename T> void repast::Point< T >::copy (std::vector< T > & out) const`

Copies the point into the specified vector.

Assumes the array is the same length as this GridPoint.

Parameters

<i>out</i>	<i>the</i>	vector to copy the point coordinates into
------------	------------	---

5.87.3.5 `template<typename T> size_t repast::Point< T >::dimensionCount () const [inline]`

Gets the number of dimensions of this point.

Returns

the number of dimensions of this point.

5.87.3.6 `template<typename T> const_iterator repast::Point< T >::end () const [inline]`

Gets the end of an iterator over the coordinates of this point.

Returns

the end of an iterator over the coordinates of this point.

5.87.3.7 `template<typename T> T repast::Point< T >::getCoordinate (int coordIndex) const`

Gets the coordinate of the point in the specified dimension.

Parameters

<i>coordIndex</i>	the dimension of the point to get the coordinate for. X is the first, y is the second and so on.
-------------------	--

Returns

the coordinate of the point in the specified dimension.

Exceptions

<i>an</i>	<code>out_of_range</code> exception if this GridPoint has doesn't have the specified dimension.
-----------	---

5.87.3.8 `template<typename T> T repast::Point< T >::getX () const`

Gets the x coordinate of the point.

Returns

the x coordinate of the point.

5.87.3.9 `template<typename T> T repast::Point< T >::getY () const`

Gets the y coordinate of the point.

Returns

the y coordinate of the point.

Exceptions

<i>an</i>	<code>out_of_range</code> exception if this GridPoint has less than 2 dimensions.
-----------	---

5.87.3.10 `template<typename T> T repast::Point< T >::getZ () const`

Gets the z coordinate of the point.

Returns

the z coordinate of the point.

Exceptions

<i>an</i>	<code>out_of_range</code> exception if this GridPoint has less than 3 dimensions.
-----------	---

5.87.3.11 `template<typename T> const T& repast::Point< T >::operator[] (size_t index) const` `[inline]`

Gets the coordinate value at the specified index.

Parameters

<i>index</i>	the dimension of the point to get the coordinate for. X is the first, y is the second and so on.
--------------	--

Returns

the coordinate of the point in the specified dimension.

5.87.3.12 `template<typename T> T& repast::Point< T >::operator[] (size_t index) [inline]`

Gets the coordinate value at the specified index.

Parameters

<i>index</i>	the dimension of the point to get the coordinate for. X is the first, y is the second and so on.
--------------	--

Returns

the coordinate of the point in the specified dimension.

The documentation for this class was generated from the following file:

- repast_hpc/Point.h

5.88 repast::Probltem Class Reference

Helper class for calculating outcomes based on a set of probabilities that sum to 1.

```
#include <NetworkBuilder.h>
```

Public Member Functions

- **Probltem** (int i, double lb, double ub)
- bool **contains** (double val)
- int **index** () const

5.88.1 Detailed Description

Helper class for calculating outcomes based on a set of probabilities that sum to 1.

The documentation for this class was generated from the following files:

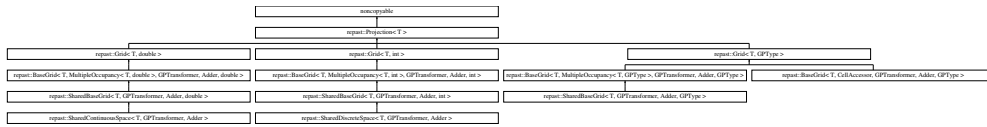
- repast_hpc/NetworkBuilder.h
- repast_hpc/NetworkBuilder.cpp

5.89 repast::Projection< T > Class Template Reference

Abstract base class for all Projections.

```
#include <Projection.h>
```

Inheritance diagram for repast::Projection< T >:



Public Types

- enum **RADIUS** { **PRIMARY**, **SECONDARY** }

Public Member Functions

- **Projection** (std::string **name**)
Creates a projection with specified name.
- const std::string **name** () const
Gets the name of this projection.
- void **addFilterVal** (int type)
Adds an entry to the list of agent types that can be added to this projection.
- void **removeFilterVal** (int type)
Removes an entry from the list of agent types that can be added to this projection.
- void **clearFilter** ()
Clears the list of agent types that can be added to this projection; the result is that the filter is empty, and any agent can be added.
- bool **agentCanBeAdded** (boost::shared_ptr< T > agent)
Returns true if the agent can be added to the projection, which will be the case if the filter list is empty or if the agent's type is in the filter list.
- virtual bool **keepsAgentsOnSyncProj** ()=0
*Should return true if the **Projection** implemented can 'keep' some (non-local) agents during a projection information synchronization operation.*
- virtual bool **sendsSecondaryAgentsOnStatusExchange** ()=0
*Should return true if the **Projection** implemented will send secondary agents during a status exchange.*
- virtual void **getInfoExchangePartners** (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)=0
*Gets the set of processes with which this **Projection** exchanges projection info.*
- virtual void **getAgentStatusExchangePartners** (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)=0
*Gets the set of processes with which this **Projection** exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.*
- virtual void **getRequiredAgents** (std::set< AgentId > &agentsToTest, std::set< AgentId > &agentsRequired, RADIUS radius=PRIMARY)=0
Given a set of agents to test, gets the subset that must be kept in order to fulfill the projection's 'contract' to the specified radius.
- virtual void **getAgentsToPush** (std::set< AgentId > &agentsToTest, std::map< int, std::set< AgentId > > &agentsToPush)=0
Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.
- virtual void **getProjectionInfo** (std::vector< AgentId > &agents, std::vector< ProjectionInfoPacket * > &packets, bool secondaryInfo=false, std::set< AgentId > *secondaryIds=0, int destProc=-1)
Convenience wrapper that gets all of the projection information for the agents specified (calls implementation in child class that gets only the information for one agent).
- void **updateProjectionInfo** (std::vector< ProjectionInfoPacket * > &pips, Context< T > *context)
Updates the projection information for the agents in this projection according to the information contained in the vector of information packets passed.
- virtual void **cleanProjectionInfo** (std::set< AgentId > &agentsToKeep)=0
- virtual void **balance** ()

Protected Member Functions

- virtual bool **addAgent** (boost::shared_ptr< T > agent)=0
- virtual void **removeAgent** (T *agent)=0
- virtual [ProjectionInfoPacket](#) * **getProjectionInfo** ([AgentId](#) id, bool secondaryInfo=false, std::set< [AgentId](#) > *secondaryIds=0, int destProc=-1)=0
- virtual void **updateProjectionInfo** ([ProjectionInfoPacket](#) *pip, [Context](#)< T > *context)=0

Protected Attributes

- std::string **name_**
- std::set< int > **filter**

Friends

- class **Context**< T >

5.89.1 Detailed Description

```
template<typename T>class repast::Projection< T >
```

Abstract base class for all Projections.

5.89.2 Constructor & Destructor Documentation

5.89.2.1 `template<typename T> repast::Projection< T >::Projection (std::string name)` `[inline]`

Creates a projection with specified name.

Parameters

<i>name</i>	the name of the projection. This must be unique across projections
-------------	--

5.89.3 Member Function Documentation

5.89.3.1 `template<typename T> void repast::Projection< T >::addFilterVal (int type)` `[inline]`

Adds an entry to the list of agent types that can be added to this projection.

Note: no indication if type is already listed

Parameters

<i>type</i>	type to be added
-------------	------------------

5.89.3.2 `template<typename T> bool repast::Projection< T >::agentCanBeAdded (boost::shared_ptr< T > agent)` `[inline]`

Returns true if the agent can be added to the projection, which will be the case if the filter list is empty or if the agent's type is in the filter list.

Parameters

<i>agent</i>	pointer to the agent to be tested
--------------	-----------------------------------

5.89.3.3 `template<typename T> virtual void repast::Projection< T >::getAgentStatusExchangePartners (std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom) [pure virtual]`

Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.

In the most general case this will be all other processors. However, simulations where agents move in spaces will usually exchange agents only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::Graph< V, E, Ec, EcM >](#), [repast::Grid< T, GPType >](#), [repast::Grid< T, double >](#), and [repast::Grid< T, int >](#).

5.89.3.4 `template<typename T> virtual void repast::Projection< T >::getAgentsToPush (std::set< AgentId > & agentsToTest, std::map< int, std::set< AgentId > > & agentsToPush) [pure virtual]`

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#), [repast::Graph< V, E, Ec, EcM >](#), [repast::Grid< T, GPType >](#), [repast::Grid< T, double >](#), [repast::Grid< T, int >](#), and [repast::SharedDiscreteSpace< T, GPTransformer, Adder >](#).

5.89.3.5 `template<typename T> virtual void repast::Projection< T >::getInfoExchangePartners (std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom) [pure virtual]`

Gets the set of processes with which this [Projection](#) exchanges projection info.

In the most general case this will be all other processors; this is the case for graphs, where agent connections can be arbitrary. However, spaces usually exchange information only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::Graph< V, E, Ec, EcM >](#), [repast::Grid< T, GPType >](#), [repast::Grid< T, double >](#), and [repast::Grid< T, int >](#).

5.89.3.6 `template<typename T> virtual void repast::Projection< T >::getRequiredAgents (std::set< AgentId > & agentsToTest, std::set< AgentId > & agentsRequired, RADIUS radius = PRIMARY) [pure virtual]`

Given a set of agents to test, gets the subset that must be kept in order to fulfill the projection's 'contract' to the specified radius.

Generally spaces do not require any agents, but graphs do- generally the non-local ends to master copies of edges.

Implemented in [repast::Grid< T, GPType >](#), [repast::Grid< T, double >](#), and [repast::Grid< T, int >](#).

5.89.3.7 `template<typename T> virtual bool repast::Projection< T >::keepsAgentsOnSyncProj () [pure virtual]`

Should return true if the [Projection](#) implemented can 'keep' some (non-local) agents during a projection information synchronization operation.

Generally spaces will allow all non-local agents to be deleted, but graphs keep the non-local agents that participate in Master edges.

It is possible to override these. A graph projection can be created that does not permit non-local agents to be 'kept'. This would be an extremely unusual use case, but it is possible.

Note that these are used for optimization. If no projection in a given context keeps any agents, several steps in the synchronization algorithm can be omitted. Of course, omitting these steps when a projection actually retains agents can caused undefined problems.

Returns

true if this projection will keep non-local agents during a projection information synchronziation event, false if it will not.

Implemented in [repast::Graph< V, E, Ec, EcM >](#), [repast::Grid< T, GPType >](#), [repast::Grid< T, double >](#), and [repast::Grid< T, int >](#).

5.89.3.8 `template<typename T> void repast::Projection< T >::removeFilterVal (int type) [inline]`

Removes an entry from the list of agent types that can be added to this projection.

Note: no indication if type is not listed

Parameters

<i>type</i>	entry to be removed
-------------	---------------------

5.89.3.9 `template<typename T> virtual bool repast::Projection< T >::sendsSecondaryAgentsOnStatusExchange () [pure virtual]`

Should return true if the [Projection](#) implemented will send secondary agents during a status exchange.

Generally spaces do not and graphs do.

If no secondary agents will be sent, portions of the algorithm can be omitted for optimization.

Returns

true if the [Projection](#) returns secondary agents, false if not

Implemented in [repast::Graph< V, E, Ec, EcM >](#), [repast::Grid< T, GPType >](#), [repast::Grid< T, double >](#), and [repast::Grid< T, int >](#).

The documentation for this class was generated from the following file:

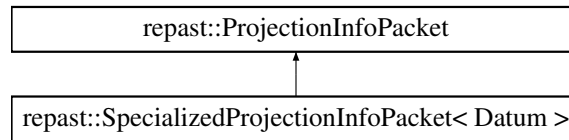
- `repast_hpc/Projection.h`

5.90 repast::ProjectionInfoPacket Class Reference

Serializable packet that can contain projection information regardless of the type of projection (network or spatial).

```
#include <Projection.h>
```

Inheritance diagram for `repast::ProjectionInfoPacket`:



Public Member Functions

- **ProjectionInfoPacket** ([AgentId](#) agentId)
- template<class Archive >
void **serialize** (Archive &ar, const unsigned int version)
- virtual bool **isEmpty** ()

Public Attributes

- [AgentId](#) id

Friends

- class **boost::serialization::access**

5.90.1 Detailed Description

Serializable packet that can contain projection information regardless of the type of projection (network or spatial).

The documentation for this class was generated from the following file:

- repast_hpc/Projection.h

5.91 repast::Properties Class Reference

Map type object that contains key, value(string) properties.

```
#include <Properties.h>
```

Public Types

- typedef
boost::transform_iterator
< [KeyGetter](#), std::map
< std::string, std::string >
::const_iterator > **key_iterator**

Public Member Functions

- [Properties](#) ()
Creates an empty [Properties](#).
- [Properties](#) (const std::string &file, boost::mpi::communicator *comm=0, int maxPropFileSize=MAX_PROP_ - FILE_SIZE)
Creates a new [Properties](#) using the properties defined in the specified file.

- [Properties](#) (const std::string &file, int argc, char **argv, boost::mpi::communicator *comm=0, int maxPropFileSize=MAX_PROP_FILE_SIZE)
Creates a new [Properties](#) using the properties defined in the specified file and any properties specified in Key=Val format in the argument array.
- [Properties](#) (int argc, char **argv)
Creates a new [Properties](#) using the properties specified in Key=Val format in the argument.
- void [putProperty](#) (const std::string &key, std::string value)
Puts a property into this [Properties](#) with the specified key and value.
- void [putProperty](#) (const std::string &key, long double value)
Puts a property into this [Properties](#) with the specified key and value.
- std::string [getProperty](#) (const std::string &key) const
Gets the property with the specified key.
- bool [contains](#) (const std::string &key) const
Gets whether or not this [Properties](#) contains the specified key.
- key_iterator [keys_begin](#) () const
Gets the start of an iterator over this [Properties](#)' keys.
- key_iterator [keys_end](#) () const
Gets the end of an iterator over this [Properties](#)' keys.
- void [readFile](#) (const std::string &file, boost::mpi::communicator *comm=0, int maxPropFileSize=MAX_PROP_FILE_SIZE)
Adds any properties defined in the specified file.
- void [processCommandLineArguments](#) (int argc, char **argv)
Processes a char** array of the given size; any component that has an equals sign is entered as a property value, overriding any previous entry read from the properties file.
- int [size](#) () const
Gets the number of properties in this [Properties](#).
- void [log](#) (std::string logName, std::vector< std::string > *keysToWrite=0)
Writes the contents of the properties file to the specified repast log (at 'INFO' log level)
- void [writeToSVFile](#) (std::string fileName, std::string separator=",")
Writes the contents of the properties file to the specified separated-value file.
- void [writeToSVFile](#) (std::string fileName, std::vector< std::string > &keysToWrite, std::string separator=",")
Writes the contents of the properties file to the specified separated-value file.

5.91.1 Detailed Description

Map type object that contains key, value(string) properties.

A [Properties](#) instance can be constructed from a file. Each line is a property with the key and value separated by =. For example,

```
some.property = 3
```

```
another.property = hello
```

5.91.2 Constructor & Destructor Documentation

5.91.2.1 `repast::Properties::Properties (const std::string & file, boost::mpi::communicator * comm = 0, int maxPropFileSize = MAX_PROP_FILE_SIZE)`

Creates a new [Properties](#) using the properties defined in the specified file.

Each line is a property with the key and value separated by =. For example,

```
some.property = 3
```

```
another.property = hello
```


Parameters

<i>file</i>	the properties file path
<i>comm</i>	pointer to a communicator; if null (the default), all processes read the properties file separately. If a communicator is provided, rank 0 reads the file and broadcasts it to all other ranks.
<i>maxPropFileSize</i>	optional parameter; if the properties file is larger than the default MAX_PROP_FILE_SIZE, the new size can be passed here.

5.91.2.2 `repast::Properties::Properties (const std::string & file, int argc, char ** argv, boost::mpi::communicator * comm = 0, int maxPropFileSize = MAX_PROP_FILE_SIZE)`

Creates a new [Properties](#) using the properties defined in the specified file and any properties specified in Key=Val format in the argument array.

[Properties](#) in the argument array will supersede any in the properties file.

Each line in the properties file is a property with the key and value separated by =. For example,

some.property = 3

another.property = hello

Parameters

<i>file</i>	the properties file path
<i>argc</i>	count of the elements in the argv array
<i>array</i>	of char* that may include Key=Value pairs. Elements with no '=' are ignored.
<i>comm</i>	pointer to a communicator; if null (the default), all processes read the properties file separately. If a communicator is provided, rank 0 reads the file and broadcasts it to all other ranks.
<i>maxPropFileSize</i>	optional parameter; if the properties file is larger than the default MAX_PROP_FILE_SIZE, the new size can be passed here.

5.91.2.3 `repast::Properties::Properties (int argc, char ** argv)`

Creates a new [Properties](#) using the properties specified in Key=Val format in the argument.

Parameters

<i>argc</i>	count of the elements in the argv array
<i>array</i>	of char* that may include Key=Value pairs. Elements with no '=' are ignored.

5.91.3 Member Function Documentation

5.91.3.1 `bool repast::Properties::contains (const std::string & key) const`

Gets whether or not this [Properties](#) contains the specified key.

Parameters

<i>key</i>	the property key
------------	------------------

5.91.3.2 `string repast::Properties::getProperty (const std::string & key) const`

Gets the property with the specified key.

Parameters

<i>key</i>	the property key
------------	------------------

Returns

the value for that key, or an empty string if the property is not found.

5.91.3.3 `key_iterator repast::Properties::keys_begin () const` `[inline]`

Gets the start of an iterator over this [Properties](#)' keys.

Returns

the start of an iterator over this [Properties](#)' keys.

5.91.3.4 `key_iterator repast::Properties::keys_end () const` `[inline]`

Gets the end of an iterator over this [Properties](#)' keys.

Returns

the end of an iterator over this [Properties](#)' keys.

5.91.3.5 `void repast::Properties::log (std::string logName, std::vector< std::string > * keysToWrite = 0)` `[inline]`

Writes the contents of the properties file to the specified repast log (at 'INFO' log level)

Parameters

<i>logName</i>	name of the log to use
<i>keysToWrite</i>	optional; if included, writes only the keys included in the vector and their values, in the order they appear in the vector. Will write blank values for any key name in the vector that is not in the properties file. If not included, all properties and their values are written, in map order.

5.91.3.6 `void repast::Properties::processCommandLineArguments (int argc, char ** argv)`

Processes a char** array of the given size; any component that has an equals sign is entered as a property value, overriding any previous entry read from the properties file.

Parameters

<i>argc</i>	the number of entries in the array
<i>argv</i>	the array of char values to be mapped

5.91.3.7 `void repast::Properties::putProperty (const std::string & key, std::string value)`

Puts a property into this [Properties](#) with the specified key and value.

Parameters

<i>key</i>	the property key
<i>value</i>	the property value

5.91.3.8 void repast::Properties::putProperty (const std::string & *key*, long double *value*)

Puts a property into this [Properties](#) with the specified key and value.

Note that even though the second argument can be passed as a numeric value, it is stored as a string

Parameters

<i>key</i>	the property key
<i>value</i>	the property value

5.91.3.9 void repast::Properties::readFile (const std::string & *file*, boost::mpi::communicator * *comm* = 0, int *maxPropFileSize* = MAX_PROP_FILE_SIZE)

Adds any properties defined in the specified file.

Each line is a property with the key and value separated by =. For example,

some.property = 3

another.property = hello

Parameters

<i>file</i>	the properties file path
<i>comm</i>	pointer to a communicator; if null (the default), all processes read the properties file separately. If a communicator is provided, rank 0 reads the file and broadcasts it to all other ranks.

5.91.3.10 int repast::Properties::size () const [inline]

Gets the number of properties in this [Properties](#).

Returns

the number of properties in this [Properties](#).

5.91.3.11 void repast::Properties::writeToSVFile (std::string *fileName*, std::string *separator* = " , ")

Writes the contents of the properties file to the specified separated-value file.

If the file does not exist it is created and a header line is written with the key values.

Parameters

<i>fileName</i>	name
-----------------	------

5.91.3.12 void repast::Properties::writeToSVFile (std::string *fileName*, std::vector< std::string > & *keysToWrite*, std::string *separator* = " , ")

Writes the contents of the properties file to the specified separated-value file.

If the file does not exist it is created and a header line is written with the key values.

Parameters

<i>fileName</i>	name
-----------------	------

The documentation for this class was generated from the following files:

- repast_hpc/Properties.h
- repast_hpc/Properties.cpp

5.92 repast::Random Class Reference

Methods for working with random distributions, draws etc.

```
#include <Random.h>
```

Public Member Functions

- void [putGenerator](#) (const std::string &id, [NumberGenerator](#) *generator)
Puts the named generator into this [Random](#).
- [NumberGenerator](#) * [getGenerator](#) (const std::string &id)
Gets the named generator or 0 if the name is not found.
- boost::mt19937 & [engine](#) ()
Gets the random number engine from which the distributions are created.
- boost::uint32_t [seed](#) ()
Gets the current seed.
- double [nextDouble](#) ()
Gets the next double in the range [0, 1).
- [DoubleUniformGenerator](#) [createUniDoubleGenerator](#) (double from, double to)
Creates a generator that produces doubles in the range [from, to).
- [IntUniformGenerator](#) [createUniIntGenerator](#) (int from, int to)
Creates a generator that produces ints in the range [from, to).
- [TriangleGenerator](#) [createTriangleGenerator](#) (double lowerBound, double mostLikely, double upperBound)
Creates a triangle generator with the specified properties.
- [CauchyGenerator](#) [createCauchyGenerator](#) (double median, double sigma)
*pdf: $p(x) = \sigma / (\pi * (\sigma^2 + (x - \text{median})^2))$*
- [ExponentialGenerator](#) [createExponentialGenerator](#) (double lambda)
*pdf: $p(x) = \lambda * \exp(-\lambda * x)$*
- [NormalGenerator](#) [createNormalGenerator](#) (double mean, double sigma)
Creates a normal generator.
- [LogNormalGenerator](#) [createLogNormalGenerator](#) (double mean, double sigma)
*Produces random numbers with $p(x) = 1/(x * \text{normal_sigma} * \sqrt{2*\pi}) * \exp(-(\log(x) - \text{normal_mean})^2 / (2*\text{normal_sigma}^2))$ for $x > 0$, where $\text{normal_mean} = \log(\text{mean}^2 / (\text{sigma}^2 + \text{mean}^2))$ and $\text{normal_sigma} = \sqrt{\log(1 + \text{sigma}^2 / \text{mean}^2)}$*

Static Public Member Functions

- static void [initialize](#) (boost::uint32_t [seed](#))
Initialize the [Random](#) singleton with the specified seed.
- static [Random](#) * [instance](#) ()
Gets the singleton instance of this [Random](#).

Protected Member Functions

- **Random** (boost::uint32_t [seed](#))

5.92.1 Detailed Description

Methods for working with random distributions, draws etc.

5.92.2 Member Function Documentation

5.92.2.1 CauchyGenerator repast::Random::createCauchyGenerator (double *median*, double *sigma*)

pdf: $p(x) = \sigma / (\pi * (\sigma^2 + (x - \text{median})^2))$

Parameters

<i>median</i>	
<i>sigma</i>	

Returns

a Cauchy generator.

5.92.2.2 ExponentialGenerator repast::Random::createExponentialGenerator (double *lambda*)

pdf: $p(x) = \lambda * \exp(-\lambda * x)$

Parameters

<i>lambda</i>	must be > 0
---------------	-------------

Returns

an exponential generator.

5.92.2.3 NormalGenerator repast::Random::createNormalGenerator (double *mean*, double *sigma*)

Creates a normal generator.

pdf: $p(x) = 1/\sqrt{2*\pi*\sigma} * \exp(-(x - \text{mean})^2 / (2*\sigma^2))$

5.92.2.4 TriangleGenerator repast::Random::createTriangleGenerator (double *lowerBound*, double *mostLikely*, double *upperBound*)

Creates a triangle generator with the specified properties.

A TriangleGenerator produces a floating point value x where $\text{lowerBound} \leq x \leq \text{upperBound}$ and *mostLikely* is the most probable value for x .

Parameters

<i>lowerBound</i>	the lower bound of the values produced by the generator
<i>mostLikely</i>	the most likely value produced by the generator
<i>upperBound</i>	the upper bound of the values produced by the generator

Returns

a triangle generator.

5.92.2.5 DoubleUniformGenerator `repast::Random::createUniDoubleGenerator (double from, double to)`

Creates a generator that produces doubles in the range [from, to).
inclusive of from, exclusive of to.

Parameters

<i>from</i>	the range start (inclusive)
<i>to</i>	the range end (exclusive)

Returns

a generator that produces doubles in the range [from, to).

5.92.2.6 IntUniformGenerator repast::Random::createUnlntGenerator (int *from*, int *to*)

Creates a generator that produces ints in the range [from, to].

Parameters

<i>from</i>	the range start (inclusive)
<i>to</i>	the range end (inclusive)

Returns

a generator that produces ints in the range [from, to].

5.92.2.7 boost::mt19937& repast::Random::engine () [inline]

Gets the random number engine from which the distributions are created.

Returns

he random number engine from which the distributions are created.

5.92.2.8 NumberGenerator * repast::Random::getGenerator (const std::string & *id*)

Gets the named generator or 0 if the name is not found.

Parameters

<i>id</i>	the name of the generator to get
-----------	----------------------------------

5.92.2.9 void repast::Random::initialize (boost::uint32_t *seed*) [static]

Initialize the [Random](#) singleton with the specified seed.

Parameters

<i>the</i>	seed to initialize the random number generator with.
------------	--

5.92.2.10 double repast::Random::nextDouble ()

Gets the next double in the range [0, 1).

Returns

the next double in the range [0, 1).

5.92.2.11 `void repast::Random::putGenerator (const std::string & id, NumberGenerator * generator)`

Puts the named generator into this [Random](#).

Added generators will be deleted by [Random](#) when it is destroyed.

Parameters

<i>the</i>	id of the generator
<i>generator</i>	the generator to add

5.92.2.12 `boost::uint32_t repast::Random::seed () [inline]`

Gets the current seed.

Returns

the current seed.

The documentation for this class was generated from the following files:

- repast_hpc/Random.h
- repast_hpc/Random.cpp

5.93 repast::RandomAccess< I > Class Template Reference

Given an iterator and a number of elements, creates a data structure that allows efficient access to those elements.

```
#include <Random.h>
```

Public Member Functions

- [RandomAccess](#) (I beginning, int size)
Constructs a [RandomAccess](#) instance for this iterator.
- [I get](#) (int index)
Gets the element at the specified index.

5.93.1 Detailed Description

```
template<typename I>class repast::RandomAccess< I >
```

Given an iterator and a number of elements, creates a data structure that allows efficient access to those elements.

Is only valid as long as the iterator is valid.

The basic implementation creates a vector of ordered pairs linking an integer and an iterator pointing to an element in the original iteration set. To find the nth element, the algorithm searches backwards through the list of 'landmarks', finds the highest landmark lower than n, chooses the iterator associated with that landmark, and steps forward until n is reached, adding new landmarks if appropriate. So given landmarks:

0 - pointer to element 0 100 - pointer to element 100 200 - pointer to element 200

if the request for element 438 is given, the algorithm will search backward and find landmark 200; it will then step forward, adding landmarks for 300 and 400, until element 438 is reached and returned.

Assuming that requests are evenly distributed, optimum interval for landmarks is the square root of the size of the list, and performance for the algorithm will be in log(size) time.

Note that other implementations are possible- for example, checking if enough memory would allow a completely indexed list. A long-term possibility is allowing the user to specify (for example, specify that the algorithm with lowest memory cost be used even though memory is initially available, perhaps because other routines will be filling that memory while this object is in use).

5.93.2 Constructor & Destructor Documentation

5.93.2.1 `template<typename I> repast::RandomAccess< I >::RandomAccess (I beginning, int size)`
`[inline]`

Constructs a [RandomAccess](#) instance for this iterator.

Parameters

<i>beginning</i>	
<i>size</i>	

5.93.3 Member Function Documentation

5.93.3.1 `template<typename I> I repast::RandomAccess< I >::get (int index)` `[inline]`

Gets the element at the specified index.

Parameters

<i>index</i>	
--------------	--

The documentation for this class was generated from the following file:

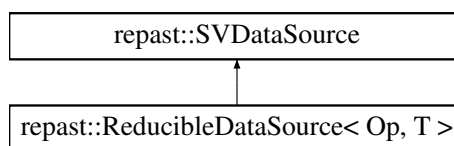
- `repast_hpc/Random.h`

5.94 repast::ReducibleDataSource< Op, T > Class Template Reference

Source of data and a reduction operation.

```
#include <ReducibleDataSource.h>
```

Inheritance diagram for `repast::ReducibleDataSource< Op, T >`:



Public Member Functions

- **ReducibleDataSource** (std::string name, [TDataSource](#)< T > *dataSource, Op op)
- virtual void **record** ()
- virtual void **write** ([Variable](#) *var)
- virtual [SVDDataSource::DataType](#) **type** () const

Protected Attributes

- `Op_op`

- `std::vector< T > data`
- `TDataSource< T > * _dataSource`
- `int rank`

5.94.1 Detailed Description

`template<typename Op, typename T>class repast::ReducibleDataSource< Op, T >`

Source of data and a reduction operation.

Used internally by a [SVDDataSet](#) to store the data sources. their associated ops etc.

The documentation for this class was generated from the following file:

- `repast_hpc/ReducibleDataSource.h`

5.95 repast::RepastEdge< V > Class Template Reference

Default graph / network edge implementation.

```
#include <Edge.h>
```

Public Types

- enum **MASTER_NODE** { **DEFAULT**, **SOURCE**, **TARGET** }

Public Member Functions

- [RepastEdge](#) (`V *source`, `V *target`, `MASTER_NODE useTargetAsMaster=DEFAULT`)
Creates a [RepastEdge](#) with the specified source and target and a default weight of 1.
- [RepastEdge](#) (`V *source`, `V *target`, `double weight`, `MASTER_NODE useTargetAsMaster=DEFAULT`)
Creates a [RepastEdge](#) with the specified source, target, and weight.
- [RepastEdge](#) (`boost::shared_ptr< V > source`, `boost::shared_ptr< V > target`, `MASTER_NODE useTargetAsMaster=DEFAULT`)
Creates a [RepastEdge](#) with the specified source and target and a default weight of 1.
- [RepastEdge](#) (`boost::shared_ptr< V > source`, `boost::shared_ptr< V > target`, `double weight`, `MASTER_NODE useTargetAsMaster=DEFAULT`)
Creates a [RepastEdge](#) with the specified source, target, and weight.
- [RepastEdge](#) (`const RepastEdge &edge`)
Copy constructor that creates a [RepastEdge](#) from another [RepastEdge](#).
- `V * source () const`
Gets the source of this [RepastEdge](#).
- `V * target () const`
Gets the target of this [RepastEdge](#).
- `void target (V *target)`
- `void source (V *source)`
- `double weight () const`
Gets the weight of this [RepastEdge](#).
- `void weight (double wt)`
- `bool usesTargetAsMaster ()`
- `void markConflicted ()`
- `void clearConflicted ()`
- `bool isConflicted ()`

5.95.1 Detailed Description

`template<typename V> class repast::RepastEdge< V >`

Default graph / network edge implementation.

Template Parameters

<code>V</code>	agent type that is the source and target of the edge
----------------	--

5.95.2 Constructor & Destructor Documentation

5.95.2.1 `template<typename V > repast::RepastEdge< V >::RepastEdge (V * source, V * target, MASTER_NODE useTargetAsMaster = DEFAULT)`

Creates a [RepastEdge](#) with the specified source and target and a default weight of 1.

Parameters

<i>source</i>	the edge source
<i>target</i>	the edge target

5.95.2.2 `template<typename V > repast::RepastEdge< V >::RepastEdge (V * source, V * target, double weight, MASTER_NODE useTargetAsMaster = DEFAULT)`

Creates a [RepastEdge](#) with the specified source, target, and weight.

Parameters

<i>source</i>	the edge source
<i>target</i>	the edge target
<i>weight</i>	the edge weight

5.95.2.3 `template<typename V > repast::RepastEdge< V >::RepastEdge (boost::shared_ptr< V > source, boost::shared_ptr< V > target, MASTER_NODE useTargetAsMaster = DEFAULT)`

Creates a [RepastEdge](#) with the specified source and target and a default weight of 1.

Parameters

<i>source</i>	the edge source
<i>target</i>	the edge target

5.95.2.4 `template<typename V > repast::RepastEdge< V >::RepastEdge (boost::shared_ptr< V > source, boost::shared_ptr< V > target, double weight, MASTER_NODE useTargetAsMaster = DEFAULT)`

Creates a [RepastEdge](#) with the specified source, target, and weight.

Parameters

<i>source</i>	the edge source
<i>target</i>	the edge target
<i>weight</i>	the edge weight

5.95.3 Member Function Documentation

5.95.3.1 `template<typename V> V* repast::RepastEdge< V >::source () const [inline]`

Gets the source of this [RepastEdge](#).

Returns

the source of this [RepastEdge](#).

5.95.3.2 `template<typename V> V* repast::RepastEdge< V >::target () const [inline]`

Gets the target of this [RepastEdge](#).

Returns

the target of this [RepastEdge](#).

5.95.3.3 `template<typename V> double repast::RepastEdge< V >::weight () const [inline]`

Gets the weight of this [RepastEdge](#).

Returns

the weight of this [RepastEdge](#).

The documentation for this class was generated from the following file:

- `repast_hpc/Edge.h`

5.96 `repast::RepastEdgeContent< V >` Struct Template Reference

Serializable; also, does not include agent content, only agent IDs.

```
#include <Edge.h>
```

Public Member Functions

- `template<class Archive >`
void **serialize** (Archive &ar, const unsigned int version)
- **RepastEdgeContent** ([RepastEdge](#)< V > *edge)

Public Attributes

- [AgentId](#) **source**
- [AgentId](#) **target**
- double **weight**
- bool **usesTargetAsMaster**

Friends

- class **boost::serialization::access**

5.96.1 Detailed Description

`template<typename V>struct repast::RepastEdgeContent< V >`

Serializable; also, does not include agent content, only agent IDs.

Template Parameters

<i>V</i>	type for vertices; must provide AgentID
----------	---

The documentation for this struct was generated from the following file:

- repast_hpc/Edge.h

5.97 repast::RepastEdgeContentManager< V > Class Template Reference

Class for creating RepastEdges from [RepastEdgeContent](#), and vice versa.

```
#include <Edge.h>
```

Public Member Functions

- [RepastEdge](#)< V > * **createEdge** ([RepastEdgeContent](#)< V > &content, [Context](#)< V > *context)
- [RepastEdgeContent](#)< V > * **provideEdgeContent** ([RepastEdge](#)< V > *edge)

5.97.1 Detailed Description

```
template<typename V>class repast::RepastEdgeContentManager< V >
```

Class for creating RepastEdges from [RepastEdgeContent](#), and vice versa.

Template Parameters

<i>V</i>	type for vertices; must provide AgentID
----------	---

The documentation for this class was generated from the following file:

- repast_hpc/Edge.h

5.98 repast::RepastEvent Class Reference

General class linking a function pointer to a specific tick.

```
#include <Schedule.h>
```

Public Attributes

- double **tick**
- boost::shared_ptr< [Functor](#) > **func_ptr**

5.98.1 Detailed Description

General class linking a function pointer to a specific tick.

The documentation for this class was generated from the following files:

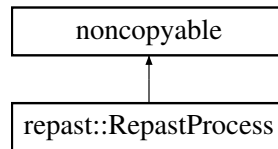
- repast_hpc/Schedule.h
- repast_hpc/Schedule.cpp

5.99 repast::RepastProcess Class Reference

Encapsulates the process in which repast is running and manages interprocess communication etc.

```
#include <RepastProcess.h>
```

Inheritance diagram for repast::RepastProcess:



Public Types

- enum **EXCHANGE_PATTERN** { **POLL**, **USE_CURRENT**, **USE_LAST_OR_POLL**, **USE_LAST_OR_USE_CURRENT** }

Public Member Functions

- void **agentRemoved** (const **AgentId** &id)
NON USER API.
- void **moveAgent** (const **AgentId** &id, int process)
NON USER API.
- void **addExportedAgent** (int importingProcess, **AgentId** id)
NON USER API.
- void **addImportedAgent** (**AgentId** id)
NON USER API.
- int **rank** () const
Gets the rank of this process.
- int **worldSize** () const
Gets the number of processes in the world.
- void **done** ()
*Notifies this **RepastProcess** that simulation has completed.*
- **ScheduleRunner** & **getScheduleRunner** ()
*Gets the **ScheduleRunner** used by this **RepastProcess**.*
- boost::mpi::communicator * **getCommunicator** ()
- void **dropImporterExporterSet** (std::string setName)
- std::string **ImporterExporterVersion** ()
- std::string **ImporterExporterReport** ()
- template<typename T, typename Content, typename Provider, typename Updater, typename AgentCreator >
void **requestAgents** (**SharedContext**< T > &context, **AgentRequest** &request, Provider &provider, Updater &updater, AgentCreator &creator, std::string setName=DEFAULT_AGENT_REQUEST_SET, AGENT_IMPORTER_EXPORTER_TYPE setType=DEFAULT_ENUM_SYMBOL)
Request agents from other processes.
- template<typename Content, typename Provider, typename Updater >
void **synchronizeAgentStates** (Provider &provider, Updater &updater, std::string setName=REQUEST_AGENTS_ALL)
Synchronizes the state values of shared agents.
- template<typename T, typename Content, typename Provider, typename Updater, typename AgentCreator >
void **synchronizeProjectionInfo** (**SharedContext**< T > &context, Provider &provider, Updater &updater, AgentCreator &creator, EXCHANGE_PATTERN exchangePattern=POLL, bool declareNoAgentsKeptOnAnyProcess=false)

Synchronizes the [Projection](#) information for shared projections.

- `template<typename T, typename Content, typename Provider, typename AgentCreator, typename Updater >
void synchronizeAgentStatus (SharedContext< T > &context, Provider &provider, Updater &updater, Agent-
Creator &creator, EXCHANGE_PATTERN exchangePattern=POLL)`

Synchronizes the status (moved or died) of all agents across processes.

Static Public Member Functions

- `static RepastProcess * init (std::string propsfile, boost::mpi::communicator *comm=0, int maxConfigFile-
Size=MAX_CONFIG_FILE_SIZE)`
Initialize this [RepastProcess](#).
- `static RepastProcess * instance ()`
Gets this [RepastProcess](#).
- `static boost::mpi::communicator * communicator ()`

Protected Member Functions

- `RepastProcess (boost::mpi::communicator *comm=0)`
- `void saveProjInfoSRProcs (std::vector< int > &sends, std::vector< int > &recvs)`
- `void saveAgentStatusInfoSRProcs (std::vector< int > &sends, std::vector< int > &recvs)`

5.99.1 Detailed Description

Encapsulates the process in which repast is running and manages interprocess communication etc.

This is singleton to insure that there is one per actual process.

5.99.2 Member Function Documentation

5.99.2.1 void repast::RepastProcess::addExportedAgent (int *importingProcess*, *AgentId* *id*)

NON USER API.

Notifies this [RepastProcess](#) that it is exporting the specified agent to the specified process. This sort of notification is done automatically when requesting agents, but agents may get added in other ways.

5.99.2.2 void repast::RepastProcess::addImportedAgent (*AgentId* *id*)

NON USER API.

Notifies this [RepastProcess](#) that it is importing the specified agent. This sort of notification is normally done automatically when requesting agents, but imports can occur in other ways.

5.99.2.3 void repast::RepastProcess::agentRemoved (const *AgentId* & *id*)

NON USER API.

Notifies this [RepastProcess](#) that the specified agent has been removed (e.g. the agent "died").

5.99.2.4 void repast::RepastProcess::done ()

Notifies this [RepastProcess](#) that simulation has completed.

This should be called when the simulation has completed.

5.99.2.5 `ScheduleRunner& repast::RepastProcess::getScheduleRunner () [inline]`

Gets the [ScheduleRunner](#) used by this [RepastProcess](#).

Returns

the [ScheduleRunner](#) used by this [RepastProcess](#).

5.99.2.6 `RepastProcess * repast::RepastProcess::init (std::string propsfile, boost::mpi::communicator * comm = 0, int maxConfigFileSize = MAX_CONFIG_FILE_SIZE) [static]`

Initialize this [RepastProcess](#).

This must be called before the [RepastProcess](#) is used. If a configuration properties file is specified this properties file will be used to configure logging.

Parameters

<i>propsfile</i>	a configuration properties file. This can be an empty string.
------------------	---

5.99.2.7 `RepastProcess * repast::RepastProcess::instance () [static]`

Gets this [RepastProcess](#).

Returns

this [RepastProcess](#) instance.

5.99.2.8 `void repast::RepastProcess::moveAgent (const AgentId & id, int process)`

NON USER API.

Notifies this [RepastProcess](#) that the specified agent should be moved from this process to the specified process.

Parameters

<i>id</i>	the id of the agent to be moved
<i>process</i>	the process to move the agent to

5.99.2.9 `int repast::RepastProcess::rank () const [inline]`

Gets the rank of this process.

Returns

the rank of this process.

5.99.2.10 `template<typename T, typename Content, typename Provider, typename Updater, typename AgentCreator> void repast::RepastProcess::requestAgents (SharedContext< T > & context, AgentRequest & request, Provider & provider, Updater & updater, AgentCreator & creator, std::string setName = DEFAULT_AGENT_REQUEST_SET, AGENT_IMPORTER_EXPORTER_TYPE setType = DEFAULT_ENUM_SYMBOL)`

Request agents from other processes.

Requests agents from one process to others.

Copies of the requested agents' Content are retrieved from their respective processes, created using the Agent-Creator and added to the specified context.

Parameters

<i>context</i>	the context to which the requested agents will be added
<i>request</i>	the AgentRequest containing the ids of the requested agents
<i>provider</i>	provides Content for a given an AgentRequest
<i>creator</i>	creates agents of type T given Content.

Template Parameters

<i>T</i>	the type of the agents in the context
<i>Content</i>	the serializable struct or class that describes the state of agents
<i>Provider</i>	given an AgentRequest , a Provider provides the Content for the requested agents, implementing void provideContent(const AgentRequest &, std::vector<Content>&)
<i>AgentCreator</i>	a class that can create agents from Content, implementing T* createAgent(Content&).

5.99.2.11 `template<typename Content , typename Provider , typename Updater > void repast::RepastProcess::synchronizeAgentStates (Provider & provider, Updater & updater, std::string setName = REQUEST_AGENTS_ALL)`

Synchronizes the state values of shared agents.

Does not change the [Projection](#) information for those agents.

5.99.2.12 `template<typename T , typename Content , typename Provider , typename AgentCreator , typename Updater > void repast::RepastProcess::synchronizeAgentStatus (SharedContext< T > & context, Provider & provider, Updater & updater, AgentCreator & creator, EXCHANGE_PATTERN exchangePattern = POLL)`

Synchronizes the status (moved or died) of all agents across processes.

Parameters

<i>context</i>	the SharedContext that contains the agents on this proceses
<i>provider</i>	the class that provides agents given an AgentRequest
<i>creator</i>	creates agents of type T given Content.

Template Parameters

<i>T</i>	the type of agents in the context
<i>Content</i>	the serializable struct or class that describes an agents state.
<i>Provider</i>	a class that provides Content, when given an AgentRequest , implementing void provideContent(const repast::AgentRequest&, std::vector<Content>& out)
<i>AgentCreator</i>	a class that can create agents from Content, implementing T* createAgent(Content&).

The documentation for this class was generated from the following files:

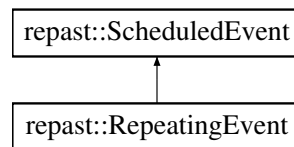
- repast_hpc/RepastProcess.h
- repast_hpc/RepastProcess.cpp

5.100 repast::RepeatingEvent Class Reference

[ScheduledEvent](#) that executes repeatedly.

```
#include <Schedule.h>
```

Inheritance diagram for repast::RepeatingEvent:



Public Member Functions

- **RepeatingEvent** (double start, double _interval, [RepastEvent](#) *)
- virtual bool [reschedule](#) (std::priority_queue< [ScheduledEvent](#) *, std::vector< [ScheduledEvent](#) * >, [EventCompare](#) > &)

Returns true if this event is rescheduled on the specified queue, otherwise false.

Additional Inherited Members

5.100.1 Detailed Description

[ScheduledEvent](#) that executes repeatedly.

This will reschedule itself repeatedly at the appropriate interval.

The documentation for this class was generated from the following files:

- repast_hpc/Schedule.h
- repast_hpc/Schedule.cpp

5.101 repast::Request_Packet< Content > Class Template Reference

Contains information sent as agents are exchanged, either in response to requests or agent movement.

```
#include <RepastProcess.h>
```

Public Member Functions

- **Request_Packet** (std::vector< Content > *agentContent, std::map< std::string, std::vector< [ProjectionInfoPacket](#) * > > *projectionInfo)
- template<class Archive >
void **serialize** (Archive &ar, const unsigned int version)

Public Attributes

- std::vector< Content > * **agentContentPtr**
- std::map< std::string, std::vector< [ProjectionInfoPacket](#) * > > * **projectionInfoPtr**

Friends

- class **boost::serialization::access**

5.101.1 Detailed Description

```
template<typename Content> class repast::Request_Packet< Content >
```

Contains information sent as agents are exchanged, either in response to requests or agent movement.

Contains both agent raw information (of type 'Content') and projection information.

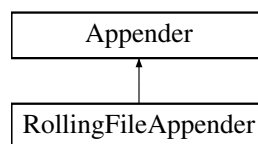
Note: A 'Packet' is responsible for deleting the objects to which it points This is essentially not optional: when boost sends the Packet via MPI the locations at which it places the different elements are not known (no 'new' is called in the user code). Some code must be written to track these down and delete, and it is manifestly easier to provide that code in the Packet itself than to rewrite where needed, inspecting the Packet for the locations

The documentation for this class was generated from the following file:

- repast_hpc/RepastProcess.h

5.102 RollingFileAppender Class Reference

Inheritance diagram for RollingFileAppender:



Public Member Functions

- **RollingFileAppender** (const string name, const string file_name, int max_backup, int max_size)
- virtual void **write** (const string &log_line)
- virtual void **close** ()

Additional Inherited Members

The documentation for this class was generated from the following file:

- repast_hpc/logger.cpp

5.103 repast::Schedule Class Reference

The simulation schedule queue.

```
#include <Schedule.h>
```

Public Types

- typedef boost::shared_ptr
< Functor > FunctorPtr

Typedef of for the functors that get scheduled.

Public Member Functions

- `ScheduledEvent * schedule_event` (double *at*, `FunctorPtr` *functor*)
Schedule the specified functor to execute once at the specified tick.
- `ScheduledEvent * schedule_event` (double *start*, double *interval*, `FunctorPtr` *func*)
Schedules the specified functor to execute start at start, and at the specified interval thereafter.
- void `execute` ()
- double `getCurrentTick` () const
Gets the current simulation tick.
- double `getNextTick` () const
Gets the next tick at which the next events will be executed.

5.103.1 Detailed Description

The simulation schedule queue.

This wraps a priority queue to schedule repast ScheduledEvents.

5.103.2 Member Function Documentation

5.103.2.1 double repast::Schedule::getCurrentTick () const `[inline]`

Gets the current simulation tick.

Returns

the current simulation tick.

5.103.2.2 double repast::Schedule::getNextTick () const `[inline]`

Gets the next tick at which the next events will be executed.

Returns

the next tick at which the next events will be executed.

5.103.2.3 ScheduledEvent * repast::Schedule::schedule_event (double *at*, `FunctorPtr` *functor*)

Schedule the specified functor to execute once at the specified tick.

Parameters

<i>at</i>	the tick to execute at
<i>functor</i>	the functor to schedule

Returns

the event that has been scheduled

5.103.2.4 ScheduledEvent * repast::Schedule::schedule_event (double *start*, double *interval*, `FunctorPtr` *func*)

Schedules the specified functor to execute start at start, and at the specified interval thereafter.

Parameters

<i>start</i>	
<i>interval</i>	
<i>func</i>	

Returns

the event that has been scheduled

The documentation for this class was generated from the following files:

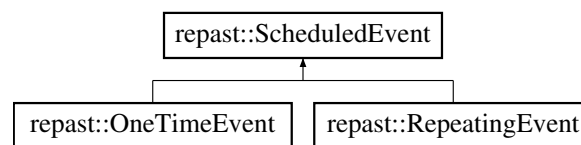
- repast_hpc/Schedule.h
- repast_hpc/Schedule.cpp

5.104 repast::ScheduledEvent Class Reference

The object that is placed (scheduled) in the priority queue for execution.

```
#include <Schedule.h>
```

Inheritance diagram for repast::ScheduledEvent:



Public Member Functions

- **ScheduledEvent** (double, [RepastEvent](#) *)
- virtual bool [reschedule](#) (std::priority_queue< [ScheduledEvent](#) *, std::vector< [ScheduledEvent](#) * >, [EventCompare](#) > &)=0
Returns true if this event is rescheduled on the specified queue, otherwise false.
- [RepastEvent](#) * [get_event](#) ()
Gets the [RepastEvent](#) that this [ScheduleEvent](#) wraps.

Protected Attributes

- [RepastEvent](#) * **event**
- double **start**

Friends

- class **EventCompare**

5.104.1 Detailed Description

The object that is placed (scheduled) in the priority queue for execution.

The documentation for this class was generated from the following files:

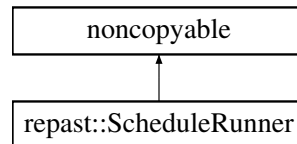
- repast_hpc/Schedule.h
- repast_hpc/Schedule.cpp

5.105 repast::Scheduler Class Reference

Runs the [Schedule](#) by popping events off of the [Schedule](#) and executing them; also provides methods for scheduling events.

```
#include <Schedule.h>
```

Inheritance diagram for repast::Scheduler:



Public Member Functions

- **Scheduler** (boost::mpi::communicator *world)
- [ScheduledEvent](#) * [scheduleEvent](#) (double at, [Schedule::FuncPtr](#) func)
Schedules the [FuncPtr](#) to execute at the specified tick.
- [ScheduledEvent](#) * [scheduleEvent](#) (double start, double interval, [Schedule::FuncPtr](#) func)
Schedules the [FuncPtr](#) to execute at the specified start tick and every interval thereafter.
- void [scheduleEndEvent](#) ([Schedule::FuncPtr](#) func)
Schedules the specified functor to execute when the simulation ends.
- void [scheduleStop](#) (double at)
Schedules the simulation to stop at the specified tick.
- void [run](#) ()
Starts and runs the simulation schedule.
- double [currentTick](#) ()
Gets the current tick.
- void [stop](#) ()
Stops the simulation.
- const [Schedule](#) & [schedule](#) ()
Gets the schedule executed by this simulation runner.

5.105.1 Detailed Description

Runs the [Schedule](#) by popping events off of the [Schedule](#) and executing them; also provides methods for scheduling events.

Simulation events should be scheduled for execution using this class which is accessible via [RepastProcess::instance\(\)->getScheduler\(\)](#)

5.105.2 Member Function Documentation

5.105.2.1 double repast::Scheduler::currentTick () [inline]

Gets the current tick.

Returns

the current tick

5.105.2.2 `const Schedule& repast::ScheduleRunner::schedule () [inline]`

Gets the schedule executed by this simulation runner.

Returns

the schedule used by this simulation runner.

5.105.2.3 `void repast::ScheduleRunner::scheduleEndEvent (Schedule::FunctorPtr func)`

Schedules the specified functor to execute when the simulation ends.

Parameters

<i>func</i>	the functor to execute when the simulation ends
-------------	---

5.105.2.4 `ScheduledEvent * repast::ScheduleRunner::scheduleEvent (double at, Schedule::FunctorPtr func)`

Schedules the [Functor](#) to execute at the specified tick.

Parameters

<i>at</i>	the time to execute at
<i>func</i>	the functor to execute

Returns

the event that was scheduled for the func

5.105.2.5 `ScheduledEvent * repast::ScheduleRunner::scheduleEvent (double start, double interval, Schedule::FunctorPtr func)`

Schedules the [Functor](#) to execute at the specified start tick and every interval thereafter.

Parameters

<i>start</i>	the time to start at
<i>interval</i>	the interval to execute at
<i>func</i>	the functor to execute

Returns

the event that was scheduled for the func

5.105.2.6 `void repast::ScheduleRunner::scheduleStop (double at)`

Schedules the simulation to stop at the specified tick.

Parameters

<i>at</i>	the tick at which the simulation should stop
-----------	--

The documentation for this class was generated from the following files:

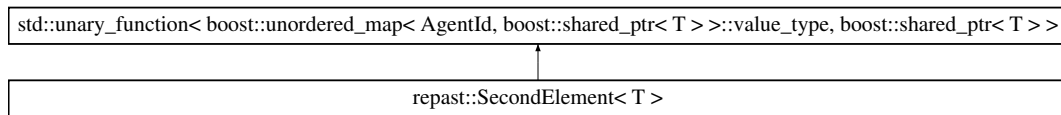
- repast_hpc/Schedule.h
- repast_hpc/Schedule.cpp

5.106 repast::SecondElement< T > Struct Template Reference

Unary function used in the transform_iterator that allows context iterators to return the agent maps values.

```
#include <Context.h>
```

Inheritance diagram for repast::SecondElement< T >:



Public Member Functions

- boost::shared_ptr< T > **operator()** (const typename boost::unordered_map< [AgentId](#), boost::shared_ptr< T >::value_type &value) const

5.106.1 Detailed Description

```
template<typename T>struct repast::SecondElement< T >
```

Unary function used in the transform_iterator that allows context iterators to return the agent maps values.

The documentation for this struct was generated from the following file:

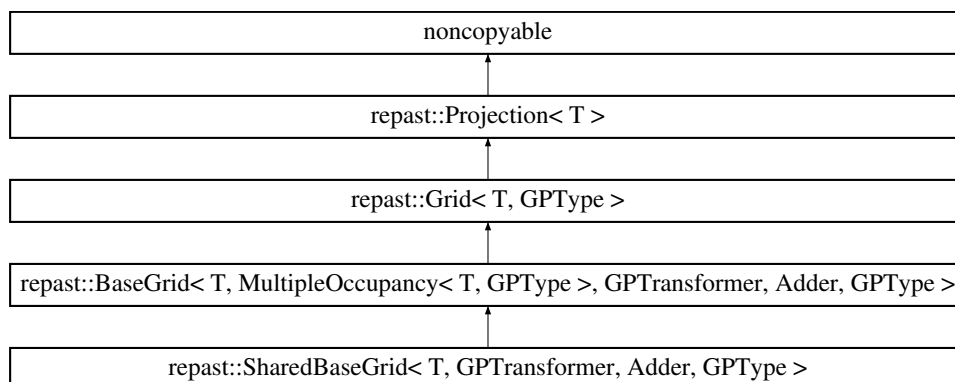
- repast_hpc/Context.h

5.107 repast::SharedBaseGrid< T, GPTransformer, Adder, GPType > Class Template Reference

[Grid](#) / Space implementation specialized for the distributed context.

```
#include <SharedBaseGrid.h>
```

Inheritance diagram for repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >:



Public Member Functions

- void **balance** ()

- [SharedBaseGrid](#) (std::string [name](#), [GridDimensions](#) [gridDims](#), std::vector< int > [processDims](#), int [buffer](#), boost::mpi::communicator *[world](#))
Creates a SharedGrid with the specified name.
- [GridDimensions](#) [bounds](#) () const
Gets the local bounds of this SharedGrid.
- virtual const [GridDimensions](#) [dimensions](#) () const
Gets the local bounds of this SharedGrid.
- void [synchMove](#) ()
Synchronizes the movement of agents off on one grid and onto another.
- void [initSynchBuffer](#) ([SharedContext](#)< T > &[context](#))
Initializes the synch buffer operation.
- virtual bool [moveTo](#) (const [AgentId](#) &[id](#), const std::vector< GPType > &[newLocation](#))
Moves the specified agent to the specified location.
- virtual bool [moveTo](#) (const [AgentId](#) &[id](#), const [Point](#)< GPType > &[pt](#))
Moves the specified agent to the specified point.
- virtual void [removeAgent](#) (T *[agent](#))
- virtual void [getRequiredAgents](#) (std::set< [AgentId](#) > &[agentsToTest](#), std::set< [AgentId](#) > &[agentsRequired](#))
- virtual void [getAgentsToPush](#) (std::set< [AgentId](#) > &[agentsToTest](#), std::map< int, std::set< [AgentId](#) > > &[agentsToPush](#))
Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.
- virtual void [getInfoExchangePartners](#) (std::set< int > &[psToSendTo](#), std::set< int > &[psToReceiveFrom](#))
Gets the set of processes with which this [Projection](#) exchanges projection info.
- virtual void [getAgentStatusExchangePartners](#) (std::set< int > &[psToSendTo](#), std::set< int > &[psToReceiveFrom](#))
Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.
- virtual void [updateProjectionInfo](#) ([ProjectionInfoPacket](#) *[pip](#), [Context](#)< T > *[context](#))

Protected Types

- typedef [repast::BaseGrid](#)< T, [MultipleOccupancy](#)< T, GPType > , GPTransformer, Adder, GPType > **GridBaseType**

Protected Member Functions

- [GridDimensions](#) [createSendBufferBounds](#) ([Neighbors::Location](#) [location](#))
- virtual void [synchMoveTo](#) (const [AgentId](#) &[id](#), const [Point](#)< GPType > &[pt](#))=0
- void [getMovingAgentInfo](#) (std::map< int, std::vector< [AgentId](#) > > &[agentsToMove](#), [GridMovePackets](#)< GPType > &[outgoing](#))
- bool [locationIsInBuffer](#) ([Point](#)< GPType > &[pt](#))
- bool [agentIsInBuffer](#) ([AgentId](#) &[id](#))

Protected Attributes

- int [_buffer](#)
- [GridDimensions](#) [localBounds](#)
- [Neighbors](#) [nghs](#)
- std::vector< [AgentId](#) > [buffered](#)
- int [rank](#)
- boost::mpi::communicator * [comm](#)

5.107.1 Detailed Description

`template<typename T, typename GPTransformer, typename Adder, typename GPType>class repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >`

[Grid](#) / Space implementation specialized for the distributed context.

Each [SharedBaseGrid](#) of the same name running on different processes is part of a pan process grid. This class manages this local part of the grid and its communication with its process neighbors. Users can specify a buffer size that determines how much of the neighboring grids are visible in this grid. For example, if this grid originates at 0x0 and ends at 3x3, a buffer of 1 would make the locations (4,0), (4,1) (4,2) ... (4,4) and (0,4), (1,4)... (4,4) visible in this grid. The [SharedBaseGrid](#) takes many template parameters. Default variations of these that define typical grids and spaces are given in SharedGrids in SharedSpace.h

Template Parameters

<i>T</i>	the type of objects contained by this BaseGrid
<i>GPTransformer</i>	transforms cell points according to the topology (e.g. periodic) of the BaseGrid .
<i>Adder</i>	determines how objects are added to the grid from its associated context.
<i>GPType</i>	the coordinate type of the grid point locations. This must be an int or a double.

5.107.2 Constructor & Destructor Documentation

5.107.2.1 `template<typename T , typename GPTransformer , typename Adder , typename GPType >
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::SharedBaseGrid (std::string name,
GridDimensions gridDims, std::vector< int > processDims, int buffer, boost::mpi::communicator * world)`

Creates a SharedGrid with the specified name.

Parameters

<i>name</i>	the name of this SharedBaseGrid
<i>gridDims</i>	the dimensions of the entire pan-process grid
<i>processDims</i>	the number of processes in each dimension. This must divide evenly into gridDims.
<i>buffer</i>	the size of the buffer between this part of the pan-process grid and its neighbors.

5.107.3 Member Function Documentation

5.107.3.1 `template<typename T, typename GPTransformer, typename Adder, typename GPType> GridDimensions
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::bounds () const [inline]`

Gets the local bounds of this SharedGrid.

The local bounds are the dimensions of the section of the pan-process grid represented by this SharedGrid.

Returns

the local bounds of this SharedGrid.

5.107.3.2 `template<typename T, typename GPTransformer, typename Adder, typename GPType> virtual const
GridDimensions repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::dimensions () const
[inline], [virtual]`

Gets the local bounds of this SharedGrid.

The local bounds are the dimensions of the section of the pan-process grid represented by this SharedGrid.

Returns

the local bounds of this SharedGrid.

Reimplemented from [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#).

5.107.3.3 `template<typename T, typename GPTransformer, typename Adder, typename GPType> virtual void
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::getAgentStatusExchangePartners (std::set<
int > & psToSendTo, std::set< int > & psToReceiveFrom) [inline],[virtual]`

Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.

In the most general case this will be all other processors. However, simulations where agents move in spaces will usually exchange agents only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Grid< T, GPType >](#).

5.107.3.4 `template<typename T , typename GPTransformer , typename Adder , typename GPType > void
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::getAgentsToPush (std::set< AgentId > &
agentsToTest, std::map< int, std::set< AgentId > > & agentsToPush) [virtual]`

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Reimplemented from [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#).

Reimplemented in [repast::SharedDiscreteSpace< T, GPTransformer, Adder >](#).

5.107.3.5 `template<typename T, typename GPTransformer, typename Adder, typename GPType> virtual void
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::getInfoExchangePartners (std::set< int > &
psToSendTo, std::set< int > & psToReceiveFrom) [inline],[virtual]`

Gets the set of processes with which this [Projection](#) exchanges projection info.

In the most general case this will be all other processors; this is the case for graphs, where agent connections can be arbitrary. However, spaces usually exchange information only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Grid< T, GPType >](#).

5.107.3.6 `template<typename T, typename GPTransformer , typename Adder , typename GPType > void
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::initSynchBuffer (SharedContext< T > &
context)`

Initializes the synch buffer operation.

This should be called before synchronizing the buffers themselves.

Parameters

<i>the</i>	SharedContext that contains this SharedGrid projection.
------------	---

5.107.3.7 `template<typename T , typename GPTransformer , typename Adder , typename GPType> bool
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::moveTo (const AgentId & id, const
std::vector< GPType > & newLocation) [virtual]`

Moves the specified agent to the specified location.

Returns true if the move was successful otherwise false. The agent must be already added to the context associated with this space, otherwise this throws an `out_of_range` exception if the new location out of bounds.

Parameters

<i>id</i>	the id of the agent to move
<i>newLocation</i>	the location to move to

Returns

true if the move was successful, otherwise false

Reimplemented from [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#).

5.107.3.8 `template<typename T , typename GPTransformer , typename Adder , typename GPType> bool
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::moveTo (const AgentId & id, const Point<
GPType > & pt) [virtual]`

Moves the specified agent to the specified point.

Parameters

<i>id</i>	the id of the agent to move
<i>pt</i>	where to move the agent to

Returns

true if the move was successful, otherwise false

Reimplemented from [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#).

5.107.3.9 `template<typename T , typename GPTransformer , typename Adder , typename GPType > void
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::synchMove ()`

Synchronizes the movement of agents off on one grid and onto another.

If there is any chance that an agent has moved off the local dimensions of this SharedGrid and into those managed by another then this must be called.

The documentation for this class was generated from the following file:

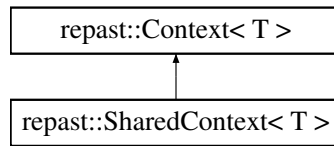
- `repast_hpc/SharedBaseGrid.h`

5.108 repast::SharedContext< T > Class Template Reference

[Context](#) implementation specialized for the parallel distributed simulation.

```
#include <SharedContext.h>
```

Inheritance diagram for repast::SharedContext< T >:



Public Types

- enum **filterLocalFlag** { **LOCAL** = 1, **NON_LOCAL** = 0 }
- typedef boost::filter_iterator
< [IsLocalAgent](#)< T >, typename
[Context](#)< T >::const_iterator > **const_local_iterator**
- typedef boost::filter_iterator
< [AgentStateFilter](#)< T >
, typename [Context](#)< T >
::const_iterator > **const_state_aware_iterator**
- typedef boost::filter_iterator
< [AgentStateFilter](#)< T >
, typename [Context](#)< T >
::const_bytype_iterator > **const_state_aware_bytype_iterator**
- typedef [Projection](#)< T >::RADIUS **RADIUS**

Public Member Functions

- **SharedContext** (boost::mpi::communicator *comm)
- const_local_iterator [localBegin](#) () const
Gets the start of iterator over the local agents in this context.
- const_local_iterator [localEnd](#) () const
Gets the end of an iterator over the local agents in this context.
- void [removeAgent](#) (const [AgentId](#) id)
Removes the specified agent from this context.
- void [removeAgent](#) (T *agent)
Removes the specified agent from this context.
- void [importedAgentRemoved](#) (const [AgentId](#) &id)
Notifies this context that the specified non-local agent has been removed and this context should then delete that agent from itself.
- void [incrementProjRefCount](#) (const [AgentId](#) &id)
Increments the projection reference count for the specified agent.
- void [decrementProjRefCount](#) (const [AgentId](#) &id)
Decrements the projection reference count for the specified agent.
- const_state_aware_iterator [begin](#) (filterLocalFlag local)
Gets the start of an iterator that will iterate over only local or non-local agents.
- const_state_aware_iterator [end](#) (filterLocalFlag local)
Gets the end of an iterator that will iterate over only local or non-local agents.
- const_state_aware_bytype_iterator [byTypeBegin](#) (filterLocalFlag local, int type)
Gets the start of an iterator that will iterate over only local or non-local agents of a certain type (per their [AgentId](#) value)
- const_state_aware_bytype_iterator [byTypeEnd](#) (filterLocalFlag local, int type)
Gets the end of an iterator that will iterate over only local or non-local agents of a certain type (per their [AgentId](#) value)

- `template<typename filterStruct >`
`boost::filter_iterator`
`< filterStruct, typename`
`SharedContext< T >`
`::const_state_aware_iterator > filteredBegin` (filterLocalFlag local, filterStruct &fStruct)
Gets the start of an iterator that will iterate over only local or non-local agents meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)
- `template<typename filterStruct >`
`boost::filter_iterator`
`< filterStruct, typename`
`SharedContext< T >`
`::const_state_aware_iterator > filteredEnd` (filterLocalFlag local, filterStruct &fStruct)
Gets the end of an iterator that will iterate over only local or non-local agents meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)
- `template<typename filterStruct >`
`boost::filter_iterator`
`< filterStruct, typename`
`SharedContext< T >`
`::const_state_aware_bytype_iterator > byTypeFilteredBegin` (filterLocalFlag local, int type, filterStruct &fStruct)
Gets the start of an iterator that will iterate over only local or non-local agents of the specified type and meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)
- `template<typename filterStruct >`
`boost::filter_iterator`
`< filterStruct, typename`
`SharedContext< T >`
`::const_state_aware_bytype_iterator > byTypeFilteredEnd` (filterLocalFlag local, int type, filterStruct &fStruct)
Gets the end of an iterator that will iterate over only local or non-local agents of the specified type and meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)
- `void selectAgents` (filterLocalFlag localOrNonLocalOnly, std::set< T * > &selectedAgents, bool remove=false, int popSize=-1)
Gets a set of pointers to all local or non-local agents in this context.
- `void selectAgents` (filterLocalFlag localOrNonLocalOnly, std::vector< T * > &selectedAgents, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to all local or non-local agents in this context.
- `void selectAgents` (filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > &selectedAgents, bool remove=false, int popSize=-1)
Gets a set of pointers to a specified number of randomly selected local or non-local agents.
- `void selectAgents` (filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > &selectedAgents, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents.
- `void selectAgents` (filterLocalFlag localOrNonLocalOnly, std::set< T * > &selectedAgents, int type, bool remove=false, int popSize=-1)
Gets a set of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values).
- `void selectAgents` (filterLocalFlag localOrNonLocalOnly, std::vector< T * > &selectedAgents, int type, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values).
- `void selectAgents` (filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > &selectedAgents, int type, bool remove=false, int popSize=-1)
Gets a set of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values).
- `void selectAgents` (filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > &selectedAgents, int type, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values).

- template<typename filterStruct >
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, std::set< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a set of pointers to all local or non-local agents in this context matching a user-defined filter.
- template<typename filterStruct >
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, std::vector< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to all local or non-local agents in this context matching a user-defined filter.
- template<typename filterStruct >
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a set of pointers to a specified number of randomly selected local or non-local agents matching a user-defined filter.
- template<typename filterStruct >
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents matching a user-defined filter.
- template<typename filterStruct >
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, std::set< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a set of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.
- template<typename filterStruct >
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, std::vector< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.
- template<typename filterStruct >
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a set of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.
- template<typename filterStruct >
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)
Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.
- bool [keepsAgentsOnSyncProj](#) ()
Returns true if any of the projections in this context will try to 'keep' non-local agents during a synchronize projection operation.
- bool [sendsSecondaryDataOnStatusExchange](#) ()
- void [getProjInfoExchangePartners](#) (std::set< int > &sends, std::set< int > &recvs)
- void [getAgentStatusInfoExchangePartners](#) (std::set< int > &sends, std::set< int > &recvs)
- void [getRequiredAgents](#) (std::set< [AgentId](#) > &agentsToTest, std::set< [AgentId](#) > &agentsToKeep, RADIUS radius=[Projection](#)< T >::PRIMARY)
Given a set of agents to test, returns the set of those agents that must be kept in order to keep required projection information.
- void [getNonlocalAgentsToDrop](#) (std::set< [AgentId](#) > &agentsToKeep, std::set< [AgentId](#) > &agentsToDrop, RADIUS radius=[Projection](#)< T >::PRIMARY)
Given an initial set of agents that must be kept a priori, add any agents that must be kept due to projection requirements, and return the set of all non-local agents that can be dropped.
- void [getAgentsToPushToOtherProcesses](#) (std::map< int, std::set< [AgentId](#) > > &agentsToPush)
- virtual void [addProjection](#) ([Projection](#)< T > *projection)
Adds the specified projection to this context.

Public Attributes

- [IsLocalAgent](#)< T > **localPredicate**
- [AgentStateFilter](#)< T > **LOCAL_FILTER**
- [AgentStateFilter](#)< T > **NON_LOCAL_FILTER**
- `std::vector< std::string >` **getAgentsToPushProjOrder**

Additional Inherited Members

5.108.1 Detailed Description

`template<typename T>class repast::SharedContext< T >`

[Context](#) implementation specialized for the parallel distributed simulation.

A [SharedContext](#) contains both local, that is, agents whose behavior is run on the [SharedContext](#)'s process and foreign agents, that is, copies of agents whose behavior is run on some other process.

Parameters

<i>T</i>	the type of agents in the context.
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5.108.2 Member Function Documentation

5.108.2.1 `template<typename T> void repast::SharedContext< T >::addProjection (Projection< T > * projection)`
[virtual]

Adds the specified projection to this context.

All the agents in this context will be added to the [Projection](#). Any agents subsequently added to this context will also be added to the [Projection](#).

Parameters

<i>projection</i>	the projection to add
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Reimplemented from [repast::Context< T >](#).

5.108.2.2 `template<typename T> boost::filter_iterator< AgentStateFilter< T >, typename Context< T >::const_iterator > repast::SharedContext< T >::begin (filterLocalFlag local)`

Gets the start of an iterator that will iterate over only local or non-local agents.

Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
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5.108.2.3 `template<typename T> boost::filter_iterator< AgentStateFilter< T >, typename Context< T >::const_bytype_iterator > repast::SharedContext< T >::byTypeBegin (filterLocalFlag local, int type)`

Gets the start of an iterator that will iterate over only local or non-local agents of a certain type (per their [AgentId](#) value)

Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>type</i>	type to included

5.108.2.4 `template<typename T> boost::filter_iterator< AgentStateFilter< T >, typename Context< T >::const_bytype_iterator> repast::SharedContext< T>::byTypeEnd (filterLocalFlag local, int type)`

Gets the end of an iterator that will iterate over only local or non-local agents of a certain type (per their [AgentId](#) value)

Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>type</i>	type to included

5.108.2.5 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename SharedContext< T>::const_state_aware_bytype_iterator> repast::SharedContext< T>::byTypeFilteredBegin (filterLocalFlag local, int type, filterStruct & fStruct)`

Gets the start of an iterator that will iterate over only local or non-local agents of the specified type and meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)

Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>type</i>	type to be included
<i>filter</i>	struct with unary operator (boost::shared_ptr<T>) that returns true or false; used to selectively include agents.

Template Parameters

<i>filterStruct</i>	the class of the filter to be used
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5.108.2.6 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename SharedContext< T>::const_state_aware_bytype_iterator> repast::SharedContext< T>::byTypeFilteredEnd (filterLocalFlag local, int type, filterStruct & fStruct)`

Gets the end of an iterator that will iterate over only local or non-local agents of the specified type and meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)

Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>type</i>	type to be included
<i>filter</i>	struct with unary operator (boost::shared_ptr<T>) that returns true or false; used to selectively include agents.

Template Parameters

<i>filterStruct</i>	the class of the filter to be used
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5.108.2.7 `template<typename T> void repast::SharedContext< T>::decrementProjRefCount (const AgentId & id)`

Decrements the projection reference count for the specified agent.

Parameters

<i>id</i>	the id of the agent
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5.108.2.8 `template<typename T> boost::filter_iterator< AgentStateFilter< T>, typename Context< T>::const_iterator> repast::SharedContext< T>::end (filterLocalFlag local)`

Gets the end of an iterator that will iterate over only local or non-local agents.

Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
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5.108.2.9 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename SharedContext< T>::const_state_aware_iterator> repast::SharedContext< T>::filteredBegin (filterLocalFlag local, filterStruct & fStruct)`

Gets the start of an iterator that will iterate over only local or non-local agents meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)

Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>filter</i>	struct with unary operator (boost::shared_ptr<T>) that returns true or false; used to selectively include agents.

Template Parameters

<i>filterStruct</i>	the class of the filter to be used
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5.108.2.10 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename SharedContext< T>::const_state_aware_iterator> repast::SharedContext< T>::filteredEnd (filterLocalFlag local, filterStruct & fStruct)`

Gets the end of an iterator that will iterate over only local or non-local agents meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)

Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>filter</i>	struct with unary operator (boost::shared_ptr<T>) that returns true or false; used to selectively include agents.

Template Parameters

<i>filterStruct</i>	the class of the filter to be used
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5.108.2.11 `template<typename T> void repast::SharedContext< T>::importedAgentRemoved (const AgentId & id)`

Notifies this context that the specified non-local agent has been removed and this context should then delete that agent from itself.

Parameters

<i>id</i>	the id of the agent that was removed
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5.108.2.12 `template<typename T > void repast::SharedContext< T >::incrementProjRefCount (const AgentId & id)`

Increments the projection reference count for the specified agent.

Parameters

<i>id</i>	the id of the agent
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5.108.2.13 `template<typename T> bool repast::SharedContext<T>::keepsAgentsOnSyncProj ()`

Returns true if any of the projections in this context will try to 'keep' non-local agents during a synchronize projection operation.

(Generally graphs keep local agents that are part of master copies of links, but spaces do not keep any local agents.)

5.108.2.14 `template<typename T> boost::filter_iterator<IsLocalAgent<T>, typename Context<T>::const_iterator> repast::SharedContext<T>::localBegin () const`

Gets the start of iterator over the local agents in this context.

The iterator dereferences into `shared_ptr<T>`. The actual agent can be accessed by dereferencing the iter: `(*iter)->getId()` for example.

Returns

the start of iterator over the local agents in this context.

5.108.2.15 `template<typename T> boost::filter_iterator<IsLocalAgent<T>, typename Context<T>::const_iterator> repast::SharedContext<T>::localEnd () const`

Gets the end of an iterator over the local agents in this context.

The iterator dereferences into `shared_ptr<T>`. The actual agent can be accessed by dereferenceing the iter: `(*iter)->getId()` for example.

5.108.2.16 `template<typename T> void repast::SharedContext<T>::removeAgent (const AgentId id)`

Removes the specified agent from this context.

If the agent is non-local, this checks to make sure that it is not referenced by any projection before its removed.

Parameters

<i>id</i>	the id of the agent to remove
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5.108.2.17 `template<typename T> void repast::SharedContext<T>::removeAgent (T * agent)`

Removes the specified agent from this context.

If the agent is non-local, this checks to make sure that it is not referenced by any projection before its removed.

Parameters

<i>agent</i>	the agent to remove
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5.108.2.18 `template<typename T> void repast::SharedContext<T>::selectAgents (filterLocalFlag localOrNonLocalOnly, std::set<T*> & selectedAgents, bool remove = false, int popSize = -1)`

Gets a set of pointers to all local or non-local agents in this context.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.108.2.19 `template<typename T > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, std::vector< T * > & selectedAgents, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to all local or non-local agents in this context.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.108.2.20 `template<typename T > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > & selectedAgents, bool remove = false, int popSize = -1)`

Gets a set of pointers to a specified number of randomly selected local or non-local agents.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected

out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.108.2.21 `template<typename T > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > & selectedAgents, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNonLocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.108.2.22 `template<typename T > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, std::set< T * > & selectedAgents, int type, bool remove = false, int popSize = -1)`

Gets a set of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values).

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNonLocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.108.2.23 `template<typename T > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, std::vector< T * > & selectedAgents, int type, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values).

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.108.2.24 `template<typename T > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > & selectedAgents, int type, bool remove = false, int popSize = -1)`

Gets a set of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values).

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.108.2.25 `template<typename T > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > & selectedAgents, int type, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values).

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

5.108.2.26 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, std::set< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a set of pointers to all local or non-local agents in this context matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
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5.108.2.27 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, std::vector< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to all local or non-local agents in this context matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
--	-----------------------------	---

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.108.2.28 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a set of pointers to a specified number of randomly selected local or non-local agents matching a user-defined filter.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNonLocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.108.2.29 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents matching a user-defined filter.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.108.2.30 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, std::set< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a set of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.108.2.31 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, std::vector< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.108.2.32 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a set of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

5.108.2.33 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents (filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1)`

Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The `popSize` parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

The documentation for this class was generated from the following file:

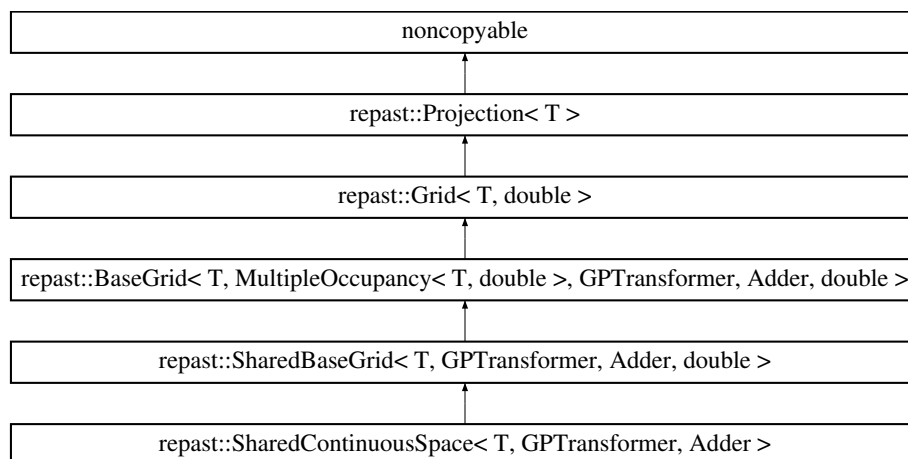
- `repat_hpc/SharedContext.h`

5.109 repast::SharedContinuousSpace< T, GPTransformer, Adder > Class Template Reference

Continuous space [SharedBaseGrid](#) implementation.

```
#include <SharedContinuousSpace.h>
```

Inheritance diagram for `repast::SharedContinuousSpace< T, GPTransformer, Adder >`:



Public Member Functions

- **SharedContinuousSpace** (std::string [name](#), [GridDimensions](#) gridDims, std::vector< int > processDims, int buffer, boost::mpi::communicator *world)
- template<typename AgentContent, typename Provider, typename AgentsCreator >
void [synchBuffer](#) ([SharedContext](#)< T > &context, Provider &provider, AgentsCreator &creator)
Synchronize the buffer area of this SharedGrid with its neighbors.

- `template<typename AgentContent , typename ContentProvider , typename ContentReceiver >`
`void synchBuffer (SharedContext< T > &context, ContentProvider &provider, ContentReceiver &receiver)`

Protected Member Functions

- virtual void **synchMoveTo** (const [AgentId](#) &id, const [Point](#)< double > &pt)

5.109.1 Detailed Description

`template<typename T, typename GPTransformer, typename Adder>class repast::SharedContinuousSpace< T, GPTransformer, Adder >`

Continuous space [SharedBaseGrid](#) implementation.

This primarily adds the buffer synchronization appropriate for this type. Default templated typical SharedContinuousSpaces are defined in SharedGrids.

See Also

[SharedBaseGrid](#) for more details.

Template Parameters

<i>T</i>	the type of objects contained by this BaseGrid
<i>GPTransformer</i>	transforms cell points according to the topology (e.g. periodic) of the BaseGrid .
<i>Adder</i>	determines how objects are added to the grid from its associated context.

5.109.2 Member Function Documentation

5.109.2.1 `template<typename T , typename GPTransformer , typename Adder > template<typename AgentContent , typename Provider , typename AgentsCreator > void repast::SharedContinuousSpace< T, GPTransformer, Adder >::synchBuffer (SharedContext< T > & context, Provider & provider, AgentsCreator & creator)`

Synchronize the buffer area of this SharedGrid with its neighbors.

This will copy the buffer area from the neighbors into this SharedGrid. This should be called immediately after `initSynchBuffer`.

Parameters

<i>context</i>	the SharedContext that contains the agents in this SharedGrid.
<i>provider</i>	a class that provides AgentContent for the agents being buffered in neighboring grids.
<i>creator</i>	a class that creates a agents of type T when given AgentContent.

Template Parameters

<i>T</i>	the type of agent in this SharedGrid
<i>AgentContent</i>	the serializable struct or class that describes the state of agents.
<i>Provider</i>	a class that provides AgentContent for aagents, implementing void provideContent(T* agent, std::vector<AgentContent>& out)
<i>AgentsCreator</i>	a class that creates agents given AgentContent, implementing void createAgents(std::vector<AgentContent>& contents, std::vector<T*>& out). Creating agents from the vector of content and placing them in out.

The documentation for this class was generated from the following file:

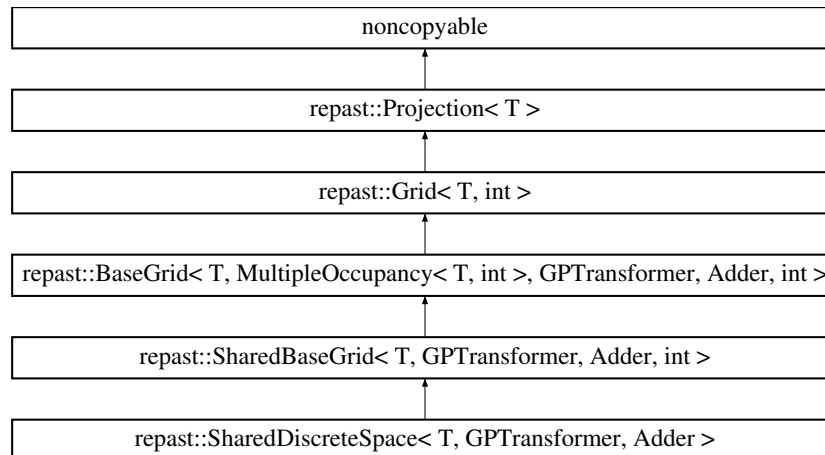
- `repast_hpc/SharedContinuousSpace.h`

5.110 `repast::SharedDiscreteSpace< T, GPTransformer, Adder >` Class Template Reference

Discrete matrix-like [SharedBaseGrid](#) implementation.

```
#include <SharedDiscreteSpace.h>
```

Inheritance diagram for `repast::SharedDiscreteSpace< T, GPTransformer, Adder >`:



Public Member Functions

- **SharedDiscreteSpace** (std::string [name](#), [GridDimensions](#) gridDims, std::vector< int > processDims, int buffer, boost::mpi::communicator *world)
- template<typename AgentContent , typename Provider , typename AgentsCreator >
void [synchBuffer](#) ([SharedContext](#)< T > &context, Provider &provider, AgentsCreator &creator)
Synchronize the buffer area of this [SharedDiscreteSpace](#) with its neighbors.
- virtual void [getAgentsToPush](#) (std::set< [AgentId](#) > &agentsToTest, std::map< int, std::set< [AgentId](#) > > &agentsToPush)
Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.
- template<typename AgentContent , typename ContentProvider , typename ContentReceiver >
void **synchBuffer** ([SharedContext](#)< T > &context, ContentProvider &provider, ContentReceiver &receiver)

Protected Member Functions

- virtual void **synchMoveTo** (const [AgentId](#) &id, const [Point](#)< int > &pt)

5.110.1 Detailed Description

```
template<typename T, typename GPTransformer, typename Adder>class repast::SharedDiscreteSpace< T, GPTransformer, Adder >
```

Discrete matrix-like [SharedBaseGrid](#) implementation.

This primarily adds the buffer synchronization appropriate for this type. Default templated typical SharedGrid types are defined in SharedGrids.

See Also

[SharedBaseGrid](#) for more details.

Template Parameters

<i>T</i>	the type of objects contained by this BaseGrid
<i>GPTransformer</i>	transforms cell points according to the topology (e.g. periodic) of the BaseGrid .
<i>Adder</i>	determines how objects are added to the grid from its associated context.

5.110.2 Member Function Documentation

5.110.2.1 `template<typename T, typename GPTransformer, typename Adder> void repast::SharedDiscreteSpace< T, GPTransformer, Adder >::getAgentsToPush (std::set< AgentId > & agentsToTest, std::map< int, std::set< AgentId >> & agentsToPush) [virtual]`

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Reimplemented from [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#).

5.110.2.2 `template<typename T, typename GPTransformer, typename Adder> template<typename AgentContent, typename Provider, typename AgentsCreator> void repast::SharedDiscreteSpace< T, GPTransformer, Adder >::synchBuffer (SharedContext< T > & context, Provider & provider, AgentsCreator & creator)`

Synchronize the buffer area of this [SharedDiscreteSpace](#) with its neighbors.

This will copy the buffer area from the neighbors into this [SharedDiscreteSpace](#). This should be called immediately after `initSynchBuffer`.

Parameters

<i>context</i>	the SharedContext that contains the agents in this SharedDiscreteSpace .
<i>provider</i>	a class that provides AgentContent for the agents being buffered in neighboring grids.
<i>creator</i>	a class that creates a agents of type T when given AgentContent.

Template Parameters

<i>T</i>	the type of agent in this SharedDiscreteSpace
<i>AgentContent</i>	the serializable struct or class that describes the state of agents.
<i>Provider</i>	a class that provides AgentContent for aagents, implementing void provideContent(T* agent, std::vector<AgentContent>& out)
<i>AgentsCreator</i>	a class that creates agents given AgentContent, implementing void createAgents(std::vector<AgentContent>& contents, std::vector<T*>& out). Creating agents from the vector of content and placing them in out.

The documentation for this class was generated from the following file:

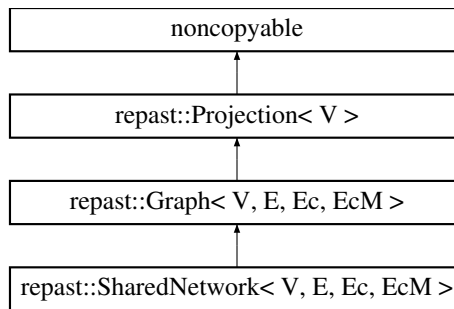
- `repast_hpc/SharedDiscreteSpace.h`

5.111 repast::SharedNetwork< V, E, Ec, EcM > Class Template Reference

Network implementation that can be shared across processes.

```
#include <SharedNetwork.h>
```

Inheritance diagram for `repast::SharedNetwork< V, E, Ec, EcM >`:



Public Member Functions

- **SharedNetwork** (std::string name, bool directed, EcM *edgeContentMgr)
Creates a [SharedNetwork](#) with the specified name and whether or not the network is directed.
- void **addSender** (int rank)
NON USER API.
- void **removeSender** (int rank)
NON USER API Decrements the count of edges that are sent from rank to this network.
- void **removeEdge** (V *source, V *target)
Removes the edge between source and target from this [Graph](#).
- void **addEdge** (boost::shared_ptr< E > edge)
Add an edge to this [SharedNetwork](#).
- void **synchRemovedEdges** ()
Synchronizes any removed edges that are have been copied across processes.
- virtual bool **isMaster** (E *e)
Returns true if this is a master link; will be a master link if its master node is local.

Protected Member Functions

- virtual bool **addAgent** (boost::shared_ptr< V > agent)
- virtual void **removeAgent** (V *agent)
- virtual void **doAddEdge** (boost::shared_ptr< E > edge)

Friends

- template<typename Vertex , typename Edge , typename AgentContent , typename EdgeContent , typename EdgeManager , typename AgentCreator >
void **createComplementaryEdges** ([SharedNetwork](#)< [Vertex](#), Edge, EdgeContent, EdgeManager > *net, [SharedContext](#)< [Vertex](#) > &context, EdgeManager &edgeManager, AgentCreator &creator)
Notifies other processes of any edges that have been created between nodes on this process and imported nodes.
- template<typename Vertex , typename Edge , typename EdgeContent , typename EdgeManager >
void **synchEdges** ([SharedNetwork](#)< [Vertex](#), Edge, EdgeContent, EdgeManager > *, EdgeManager &)
Synchronizes any edges that have been created as complementary edges.

Additional Inherited Members

5.111.1 Detailed Description

template<typename V, typename E, typename Ec, typename EcM>class repast::SharedNetwork< V, E, Ec, EcM >

Network implementation that can be shared across processes.

Networks are shared across processes by creating edges between local and non-local agents on a process. The createComplementaryEdges function will create complementary edges across processes in those cases. For example, if an edge is created between A1 and B2 on process 1 where B2 is copy of B1 on process 2, then creating complementary edges will create a copy of that edge on process 2, importing A1 into process 2 if necessary.

Template Parameters

<i>V</i>	the agent (vertex) type
<i>E</i>	the edge type. The edge type must be contain a constructor that takes a source and target of type V and extends RepastEdge . RepastEdge can also be used.

5.111.2 Constructor & Destructor Documentation

5.111.2.1 `template<typename V , typename E , typename Ec , typename EcM > repast::SharedNetwork< V, E, Ec, EcM >::SharedNetwork (std::string name, bool directed, EcM * edgeContentMgr)`

Creates a [SharedNetwork](#) with the specified name and whether or not the network is directed.

Parameters

<i>the</i>	network name
<i>directed</i>	if true the network will be directed, otherwise not.

5.111.3 Member Function Documentation

5.111.3.1 `template<typename V , typename E , typename Ec , typename EcM > void repast::SharedNetwork< V, E, Ec, EcM >::addEdge (boost::shared_ptr< E > edge)`

Add an edge to this [SharedNetwork](#).

Parameters

<i>edge</i>	the edge to add
-------------	-----------------

5.111.3.2 `template<typename V , typename E , typename Ec , typename EcM > void repast::SharedNetwork< V, E, Ec, EcM >::addSender (int rank)`

NON USER API.

Increments the count of edges that are sent from rank to this network.

5.111.3.3 `template<typename V, typename E, typename Ec, typename EcM> virtual bool repast::SharedNetwork< V, E, Ec, EcM >::isMaster (E * e) [inline], [virtual]`

Returns true if this is a master link; will be a master link if its master node is local.

The master node is usually the edge 'source', but if the usesTargetAsMaster flag is set to true then the 'target' is the master node.

Implements [repast::Graph< V, E, Ec, EcM >](#).

5.111.3.4 `template<typename V , typename E , typename Ec , typename EcM > void repast::SharedNetwork< V, E, Ec, EcM >::removeEdge (V * source, V * target) [virtual]`

Removes the edge between source and target from this [Graph](#).

Parameters

<i>source</i>	the source of the edge
<i>target</i>	the target of the edge

Reimplemented from [repast::Graph< V, E, Ec, EcM >](#).

5.111.4 Friends And Related Function Documentation

5.111.4.1 `template<typename V, typename E, typename Ec, typename EcM> template<typename Vertex , typename Edge , typename AgentContent , typename EdgeContent , typename EdgeManager , typename AgentCreator > void createComplementaryEdges (SharedNetwork< Vertex, Edge, EdgeContent, EdgeManager > * net, SharedContext< Vertex > & context, EdgeManager & edgeManager, AgentCreator & creator) [friend]`

Notifies other processes of any edges that have been created between nodes on this process and imported nodes.

The other process will then create the complimentary edge. For example, if P1 creates an edge between A and B where B resides on P2, then this method will notify P2 to create the incoming edge A->B on its copy of B. Any unknown agents will be added to the context. For example, if P2 didn't have a reference to A, then A will be added to P2's context.

Parameters

<i>net</i>	the network in which to create the complementary edges or from which to send complementary edges
<i>context</i>	the context that contains the agents in the process
<i>edgeManager</i>	creates edges from EdgeContent and creates EdgeContent from an edge and a context.
<i>creator</i>	creates agents from AgentContent.

Template Parameters

Vertex	the vertex (agent) type
<i>Edge</i>	the edge type
<i>AgentContent</i>	the serializable struct or class that describes the agent state. It must contain a <code>getId()</code> method that returns the AgentId of the agent it describes.
<i>EdgeContent</i>	the serializable struct or class that describes edge state. At the very least EdgeContent must contain two public fields <code>sourceContent</code> and <code>targetContent</code> of type <code>AgentContent</code> . These represent the source and target of the edge.
<i>EdgeManager</i>	create edges from EdgeContent and provides EdgeContent given a context and an edge of type Edge. It must implement <code>void provideEdgeContent(constEdge* edge, std::vector<EdgeContent>& edgeContent)</code> and <code>Edge* createEdge(repast::Context<Vertex>& context, EdgeContent& edge);</code>
<i>AgentCreator</i>	creates agents from AgentContent, implementing the following method <code>Vertex* createAgent(constAgentContent& content);</code>

5.111.4.2 `template<typename V, typename E, typename Ec, typename EcM> template<typename Vertex , typename Edge , typename EdgeContent , typename EdgeManager > void synchEdges (SharedNetwork< Vertex, Edge, EdgeContent, EdgeManager > * net, EdgeManager & edgeManager) [friend]`

Synchronizes any edges that have been created as complementary edges.

This only necessary if the edges have been deleted or their state has been changed in some way.

Parameters

<i>net</i>	the network in which to create the complementary edges or from which to send complementary edges
------------	--

<i>edgeManager</i>	updates edges from EdgeContent and creates EdgeContent from an edge and a context.
--------------------	--

Template Parameters

<i>Vertex</i>	the vertex (agent) type
<i>Edge</i>	the edge type
<i>EdgeContent</i>	the serializable struct or class that describes edge state.
<i>EdgeManager</i>	updates edges from EdgeContent and provides EdgeContent given a context and an edge of type Edge. It must implement void provideEdgeContent(const Edge* edge, std::vector<EdgeContent>& edgeContent) and void receiveEdgeContent(const EdgeContent& content);

The documentation for this class was generated from the following file:

- repast_hpc/SharedNetwork.h

5.112 repast::SharedSpaces< T > Struct Template Reference

Struct within which multiple kinds of shared space are typedef-ed.

```
#include <SharedSpaces.h>
```

Public Types

- typedef [SharedDiscreteSpace](#)< T, [WrapAroundBorders](#), [SimpleAdder](#)< T > > [SharedWrappedDiscreteSpace](#)
Discrete grid space with periodic (toroidal) borders.
- typedef [SharedDiscreteSpace](#)< T, [StrictBorders](#), [SimpleAdder](#)< T > > [SharedStrictDiscreteSpace](#)
Discrete grid space with strict borders.
- typedef [SharedContinuousSpace](#)< T, [WrapAroundBorders](#), [SimpleAdder](#)< T > > [SharedWrappedContinuousSpace](#)
Continuous space with periodic (toroidal) borders.
- typedef [SharedContinuousSpace](#)< T, [StrictBorders](#), [SimpleAdder](#)< T > > [SharedStrictContinuousSpace](#)
Continuous space with strict borders.

5.112.1 Detailed Description

```
template<typename T>struct repast::SharedSpaces< T >
```

Struct within which multiple kinds of shared space are typedef-ed.

5.112.2 Member Typedef Documentation

5.112.2.1 `template<typename T > typedef SharedContinuousSpace<T, StrictBorders, SimpleAdder<T> > repast::SharedSpaces< T >::SharedStrictContinuousSpace`

Continuous space with strict borders.

Any added agents are not given a location, but are in "grid limbo" until moved via a grid move call.

5.112.2.2 `template<typename T> typedef SharedDiscreteSpace<T, StrictBorders, SimpleAdder<T>> repast::SharedSpaces< T>::SharedStrictDiscreteSpace`

Discrete grid space with strict borders.

Any added agents are not given a location, but are in "grid limbo" until moved via a grid move call.

5.112.2.3 `template<typename T> typedef SharedContinuousSpace<T, WrapAroundBorders, SimpleAdder<T>> repast::SharedSpaces< T>::SharedWrappedContinuousSpace`

Continuous space with periodic (toroidal) borders.

Any added agents are not given a location, but are in "grid limbo" until moved via a grid move call.

5.112.2.4 `template<typename T> typedef SharedDiscreteSpace<T, WrapAroundBorders, SimpleAdder<T>> repast::SharedSpaces< T>::SharedWrappedDiscreteSpace`

Discrete grid space with periodic (toroidal) borders.

Any added agents are not given a location, but are in "grid limbo" until moved via a grid move call.

The documentation for this struct was generated from the following file:

- repast_hpc/SharedSpaces.h

5.113 repast::SimpleAdder< T > Class Template Reference

Basic class for adding elements to grids.

```
#include <GridComponents.h>
```

Public Member Functions

- `template<typename GridType>`
void **init** ([GridDimensions](#) dimensions, GridType *grid)
- bool **add** (boost::shared_ptr< T > agent)

5.113.1 Detailed Description

```
template<typename T> class repast::SimpleAdder< T >
```

Basic class for adding elements to grids.

NOTE: This does NOT actually add the element to the grid; this simply returns 'true' and leaves the actual addition to the grid up to the user. Other classes may do other things (e.g. add to a random location) but this one does NOT.

The documentation for this class was generated from the following file:

- repast_hpc/GridComponents.h

5.114 repast::SingleOccupancy< T, GPType > Class Template Reference

Single Occupancy cell accessor for accessing the occupants of locations in a [Grid](#).

```
#include <SingleOccupancy.h>
```

Public Member Functions

- `T * get (const Point< GPTYPE > &location) const`
Gets the object found at the specified location.
- `void getAll (const Point< GPTYPE > &location, std::vector< T * > &out) const`
Gets the item found at the specified location.
- `bool put (boost::shared_ptr< T > &agent, const Point< GPTYPE > &location)`
Puts the specified item at the specified location.
- `void remove (boost::shared_ptr< T > &agent, const Point< GPTYPE > &location)`
Removes the specified item from the specified location.

5.114.1 Detailed Description

template<typename T, typename GPTYPE>class repast::SingleOccupancy< T, GPTYPE >

Single Occupancy cell accessor for accessing the occupants of locations in a [Grid](#).

Each locations can have only a single occupant.

Parameters

<i>T</i>	the type of object in the Grid
<i>GPTYPE</i>	the coordinate type of the grid point locations. This must be an int or a double.

5.114.2 Member Function Documentation

5.114.2.1 `template<typename T, typename GPTYPE > T * repast::SingleOccupancy< T, GPTYPE >::get (const Point< GPTYPE > & location) const`

Gets the object found at the specified location.

Parameters

<i>location</i>	the location to get the object at
-----------------	-----------------------------------

Returns

the first object found at the specified location or 0 if there are no objects at the specified location.

5.114.2.2 `template<typename T, typename GPTYPE > void repast::SingleOccupancy< T, GPTYPE >::getAll (const Point< GPTYPE > & location, std::vector< T * > & out) const`

Gets the item found at the specified location.

Parameters

	<i>location</i>	the location to get the item at
<i>out</i>	<i>the</i>	found item will be returned in this vector

5.114.2.3 `template<typename T, typename GPTYPE > bool repast::SingleOccupancy< T, GPTYPE >::put (boost::shared_ptr< T > & agent, const Point< GPTYPE > & location)`

Puts the specified item at the specified location.

Parameters

<i>agent</i>	the item to put
<i>location</i>	the location to put the item at

5.114.2.4 `template<typename T , typename GType > void repast::SingleOccupancy< T, GType >::remove (boost::shared_ptr< T > & agent, const Point< GType > & location)`

Removes the specified item from the specified location.

Parameters

<i>agent</i>	the item to remove
<i>location</i>	the location to remove the item from

The documentation for this class was generated from the following file:

- repast_hpc/SingleOccupancy.h

5.115 repast::Spaces< T > Struct Template Reference

Struct within which multiple kinds of space are typedef-ed.

```
#include <Spaces.h>
```

Public Types

- typedef [BaseGrid](#)< T, [SingleOccupancy](#)< T, int >, [StrictBorders](#), [SimpleAdder](#)< T >, int > **SingleStrictDiscreteSpace**
- typedef [BaseGrid](#)< T, [SingleOccupancy](#)< T, int >, [WrapAroundBorders](#), [SimpleAdder](#)< T >, int > **SingleWrappedDiscreteSpace**
- typedef [BaseGrid](#)< T, [MultipleOccupancy](#)< T, int >, [StrictBorders](#), [SimpleAdder](#)< T >, int > **MultipleStrictDiscreteSpace**
- typedef [BaseGrid](#)< T, [MultipleOccupancy](#)< T, int >, [WrapAroundBorders](#), [SimpleAdder](#)< T >, int > **MultipleWrappedDiscreteSpace**
- typedef [BaseGrid](#)< T, [SingleOccupancy](#)< T, double >, [StrictBorders](#), [SimpleAdder](#)< T >, double > **SingleStrictContinuousSpace**
- typedef [BaseGrid](#)< T, [SingleOccupancy](#)< T, double >, [WrapAroundBorders](#), [SimpleAdder](#)< T >, double > **SingleWrappedContinuousSpace**
- typedef [BaseGrid](#)< T, [MultipleOccupancy](#)< T, double >, [StrictBorders](#), [SimpleAdder](#)< T >, double > **MultipleStrictContinuousSpace**

- typedef [BaseGrid](#)< T, [MultipleOccupancy](#)< T, double >, [WrapAroundBorders](#), [SimpleAdder](#)< T >, double > **MultipleWrappedContinuousSpace**

5.115.1 Detailed Description

```
template<typename T>struct repast::Spaces< T >
```

Struct within which multiple kinds of space are typedef-ed.

The documentation for this struct was generated from the following file:

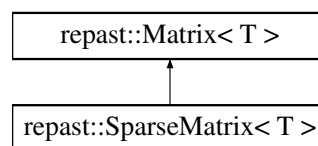
- repast_hpc/Spaces.h

5.116 repast::SparseMatrix< T > Class Template Reference

A sparse matrix implementation that stores values in a map.

```
#include <matrix.h>
```

Inheritance diagram for repast::SparseMatrix< T >:



Public Member Functions

- **SparseMatrix** (const [SparseMatrix](#)< T > &)
- [SparseMatrix](#)< T > & **operator=** (const [SparseMatrix](#)< T > &)
- [SparseMatrix](#) (const [Point](#)< int > &size, const T &defValue=T())
Creates a [DenseMatrix](#) of the specified shape and default value.
- T & [get](#) (const [Point](#)< int > &index)
Gets the value at the specified index.
- void [set](#) (const T &value, const [Point](#)< int > &index)
Sets the value at the specified index.

Additional Inherited Members

5.116.1 Detailed Description

```
template<typename T>class repast::SparseMatrix< T >
```

A sparse matrix implementation that stores values in a map.

This should be used when the majority of the matrix cells contain the default value.

The documentation for this class was generated from the following file:

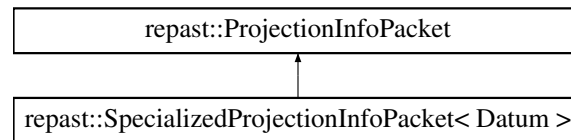
- repast_hpc/matrix.h

5.117 repast::SpecializedProjectionInfoPacket< Datum > Class Template Reference

Serializable packet that can contain projection information of a specific kind using the template parameter.

```
#include <Projection.h>
```

Inheritance diagram for repast::SpecializedProjectionInfoPacket< Datum >:



Public Member Functions

- **SpecializedProjectionInfoPacket** ([AgentId](#) agentId)
- **SpecializedProjectionInfoPacket** ([AgentId](#) agentId, std::vector< Datum > projectionData)
- **SpecializedProjectionInfoPacket** ([AgentId](#) agentId, std::set< Datum > projectionData)
- template<class Archive >
void **serialize** (Archive &ar, const unsigned int version)
- virtual bool **isEmpty** ()

Public Attributes

- std::vector< Datum > **data**

Friends

- class **boost::serialization::access**

5.117.1 Detailed Description

```
template<typename Datum>class repast::SpecializedProjectionInfoPacket< Datum >
```

Serializable packet that can contain projection information of a specific kind using the template parameter.

The documentation for this class was generated from the following file:

- repast_hpc/Projection.h

5.118 SRManager Class Reference

Coordinates send and receive between processes by notifying processes to expect a send from X other processes.

```
#include <SRManager.h>
```

Public Member Functions

- [SRManager](#) (boost::mpi::communicator *comm)
Creates an [SRManager](#) that uses the specified communicator.
- [SRManager](#) (boost::mpi::communicator *comm, int *toSend, int *toRecv)

Creates an [SRManager](#) that uses the specified communicator, using the user-specified arrays instead of its internal arrays.

- void [mark](#) (int pos)
Marks the position in the array as 'true' (sets to one).
- void [setVal](#) (int pos, int val)
Sets the value at the given index in the array.
- void [clear](#) ()
Clears the send and receive arrays (sets all values to 0).
- void [retrieveSources](#) ()
Performs the actual send operation, populating the receive array with values from the other processes' send arrays.
- void [retrieveSources](#) (std::vector< int > &sources)
Performs the send operation and populates the vector passed with values representing all elements in the array that have non-zero values after the receive.
- void [retrieveSources](#) (const std::vector< int > &targets, std::vector< int > &sources, int tag=0)
Populates the send array based on the values listed in the 'targets' vector (which should be a list of process IDs to which this processer will send information) then performs the send operation, then populates the vector passed with values representing all elements in the receive array that have non-zero values after the receive.

5.118.1 Detailed Description

Coordinates send and receive between processes by notifying processes to expect a send from X other processes.

5.118.2 Constructor & Destructor Documentation

5.118.2.1 SRManager::SRManager (boost::mpi::communicator * comm)

Creates an [SRManager](#) that uses the specified communicator.

Parameters

<i>comm</i>	the communicator to use
-------------	-------------------------

5.118.2.2 SRManager::SRManager (boost::mpi::communicator * comm, int * toSend, int * toRecv)

Creates an [SRManager](#) that uses the specified communicator, using the user-specified arrays instead of its internal arrays.

The ability to use external arrays is a convenience for conditions in which it is useful to maintain the array of values for other purposes but exchange them using the [SRManager](#).

Parameters

<i>comm</i>	the communicator to use
<i>toSend</i>	the array to be used as the send array
<i>toRecv</i>	the array to be used as the receive array If the pointer passed for the receive array is null, an internal array will be used. This is to provide for situations in which the user wishes to maintain the send array but not the receive array.

5.118.3 Member Function Documentation

5.118.3.1 void SRManager::mark (int pos)

Marks the position in the array as 'true' (sets to one).

Parameters

<i>pos</i>	the position in the array to be set, AKA the processor to which information will be sent.
------------	---

5.118.3.2 void SRManager::retrieveSources (std::vector< int > & *sources*)

Performs the send operation and populates the vector passed with values representing all elements in the array that have non-zero values after the receive.

Parameters

<i>sources</i>	vector that will have a list of all processes that sent non-zero values to this one
----------------	---

5.118.3.3 void SRManager::retrieveSources (const std::vector< int > & *targets*, std::vector< int > & *sources*, int *tag* = 0)

Populates the send array based on the values listed in the 'targets' vector (which should be a list of process IDs to which this processor will send information) then performs the send operation, then populates the vector passed with values representing all elements in the receive array that have non-zero values after the receive.

Parameters

<i>targets</i>	vector of integers representing process to which this one intends to send information
<i>sources</i>	vector that will be populated with list of integers representing processes that will send this process information optional parameter, now obsolete (included for backward compatibility with boost-based SRManager prior to 2.0 release.

5.118.3.4 void SRManager::setVal (int *pos*, int *val*)

Sets the value at the given index in the array.

Note: Does not perform error checking; user should ensure that index value is valid.

Parameters

<i>pos</i>	index value for position in array to be set
<i>val</i>	value to which the array element should be set

The documentation for this class was generated from the following files:

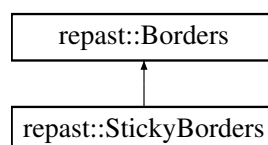
- repast_hpc/SRManager.h
- repast_hpc/SRManager.cpp

5.119 repast::StickyBorders Class Reference

Implements sticky border semantics: translates out side of the border are clamped to the border coordinates.

```
#include <GridComponents.h>
```

Inheritance diagram for repast::StickyBorders:



Public Member Functions

- **StickyBorders** ([GridDimensions](#) d)
- void **translate** (const std::vector< double > &oldPos, std::vector< double > &newPos, const std::vector< double > &displacement) const
- void **translate** (const std::vector< int > &oldPos, std::vector< int > &newPos, const std::vector< int > &displacement) const

Additional Inherited Members

5.119.1 Detailed Description

Implements sticky border semantics: translates out side of the border are clamped to the border coordinates.

Tranforms outside the border throw an exception.

The documentation for this class was generated from the following files:

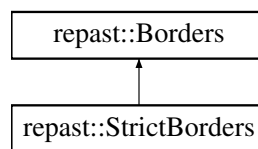
- repast_hpc/GridComponents.h
- repast_hpc/GridComponents.cpp

5.120 repast::StrictBorders Class Reference

Implements strict grid border semantics: anything outside the dimensions is out of bounds.

```
#include <GridComponents.h>
```

Inheritance diagram for repast::StrictBorders:



Public Member Functions

- **StrictBorders** ([GridDimensions](#) d)
- void **translate** (const std::vector< double > &oldPos, std::vector< double > &newPos, const std::vector< double > &displacement) const
- void **translate** (const std::vector< int > &oldPos, std::vector< int > &newPos, const std::vector< int > &displacement) const

Additional Inherited Members

5.120.1 Detailed Description

Implements strict grid border semantics: anything outside the dimensions is out of bounds.

The documentation for this class was generated from the following files:

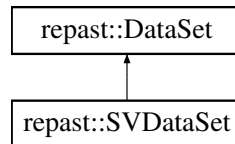
- repast_hpc/GridComponents.h
- repast_hpc/GridComponents.cpp

5.121 repast::SVDataSet Class Reference

Encapsulates data recording to a single plain text file, separating the recorded values using a specified separator value.

```
#include <SVDataSet.h>
```

Inheritance diagram for repast::SVDataSet:



Public Member Functions

- void [record](#) ()
Records data from any added data sources.
- void [write](#) ()
Writes any recorded data to a file.
- void [close](#) ()
Closes the data set.

Friends

- class **SVDataSetBuilder**

5.121.1 Detailed Description

Encapsulates data recording to a single plain text file, separating the recorded values using a specified separator value.

An [SVDataSet](#) uses rank 0 to write to a single file from multiple pan-process data sources. A [SVDataSet](#) should be built using a [SVDataSetBuilder](#).

The documentation for this class was generated from the following files:

- repast_hpc/SVDataSet.h
- repast_hpc/SVDataSet.cpp

5.122 repast::SVDataSetBuilder Class Reference

Used to build SVDataSets to record data in plain text tabular format.

```
#include <SVDataSetBuilder.h>
```

Public Member Functions

- [SVDataSetBuilder](#) (const std::string &file, const std::string &separator, const [Schedule](#) &schedule)
Creates a [SVDataSetBuilder](#) that will create a [SVDataSet](#) that will write to the specified file and use the specified string as a data value separator.
- [SVDataSetBuilder](#) & [addDataSource](#) ([SVDataSource](#) *source)

Adds a DataSource to the [DataSet](#) produced by this builder.

- [SVDataSet](#) * `createDataSet` ()

Creates the DataSource defined by this builder.

5.122.1 Detailed Description

Used to build SVDataSets to record data in plain text tabular format.

Steps for use are:

1. Create a [SVDataSetBuilder](#).
2. Add SVDataSources to the builder using the `createSVDataSource` functions. Each data source defines a column in the output and where the data for that column will be retrieved. Recording data on the [SVDataSet](#) produced by the builder will record this data for each column.
3. Call `createDataSet` to create the [SVDataSet](#).
4. [Schedule](#) calls to record and write on the [SVDataSet](#).

5.122.2 Constructor & Destructor Documentation

5.122.2.1 `repast::SVDataSetBuilder::SVDataSetBuilder (const std::string & file, const std::string & separator, const Schedule & schedule)`

Creates a [SVDataSetBuilder](#) that will create a [SVDataSet](#) that will write to the specified file and use the specified string as a data value separator.

Tick info will be gathered from the specified schedule.

Parameters

<i>file</i>	the file path where the data will be recorded to
<i>separator</i>	a string used to separate the data values (e.g. a ",").

5.122.3 Member Function Documentation

5.122.3.1 `SVDataSetBuilder & repast::SVDataSetBuilder::addDataSource (SVDataSource * source)`

Adds a DataSource to the [DataSet](#) produced by this builder.

The `createDataSource` functions can be used to create Data Sources. Each data source defines a column in the output and where the data for that column will be retrieved. Recording data on the [SVDataSet](#) produced by the builder will record this data for each column.

Parameters

<i>source</i>	the data source to add
---------------	------------------------

5.122.3.2 `SVDataSet * repast::SVDataSetBuilder::createDataSet ()`

Creates the DataSource defined by this builder.

This can only be called once. The caller is responsible for properly deleting the returned pointer.

The documentation for this class was generated from the following files:

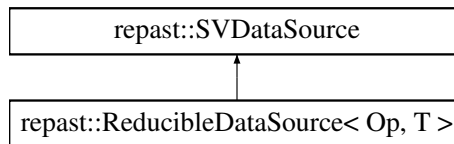
- `repast_hpc/SVDataSetBuilder.h`
- `repast_hpc/SVDataSetBuilder.cpp`

5.123 repast::SVDataSource Class Reference

Data source for data to be written into separated-value data sets.

```
#include <SVDataSource.h>
```

Inheritance diagram for repast::SVDataSource:



Public Types

- enum **DataType** { **INT**, **DOUBLE** }

Public Member Functions

- **SVDataSource** (const std::string &name)
- virtual void **record** ()=0
- virtual void **write** ([Variable](#) *var)=0
- virtual DataType **type** () const =0
- const std::string **name** () const

Protected Attributes

- std::string **_name**

5.123.1 Detailed Description

Data source for data to be written into separated-value data sets.

The documentation for this class was generated from the following file:

- repast_hpc/SVDataSource.h

5.124 repast::SyncStatus_Packet< Content > Class Template Reference

Class that contains information sent in conjunction with synchronizing agent status (agents moving or being removed from the simulation).

```
#include <RepastProcess.h>
```

Public Member Functions

- **SyncStatus_Packet** (std::vector< Content > *agentContent, std::map< std::string, std::vector< [Projection-InfoPacket](#) * > > *projectionInfo, std::set< [AgentId](#) > *secondaryIds, AgentExporterInfo *exporterInfo)
- **SyncStatus_Packet** * **deleteExporterInfo** ()
This method includes a very odd construction that arises because the Packet must delete the exporter info on the process to which it has been sent, but it cannot delete the exporter info on the process from which it was sent.
- template<class Archive >
void **serialize** (Archive &ar, const unsigned int version)

Public Attributes

- std::vector< Content > * **agentContentPtr**
- std::map< std::string, std::vector< [ProjectionInfoPacket](#) * > > * **projectionInfoPtr**
- std::set< [AgentId](#) > * **secondaryIdsPtr**
- AgentExporterInfo * **exporterInfoPtr**

Friends

- class **boost::serialization::access**

5.124.1 Detailed Description

template<typename Content>class repast::SyncStatus_Packet< Content >

Class that contains information sent in conjunction with synchronizing agent status (agents moving or being removed from the simulation).

May contain secondary agent information (that is, agents that must newly be created as non-local agents on the receiving process due to obligations of projection contracts and the new existence of the agents being moved to that process).

Note the unusual requirement of the deletion of exporter information.

5.124.2 Member Function Documentation

5.124.2.1 template<typename Content> SyncStatus_Packet* repast::SyncStatus_Packet< Content >::deleteExporterInfo () [inline]

This method includes a very odd construction that arises because the Packet *must* delete the exporter info on the process to which it has been sent, but it *cannot* delete the exporter info on the process from which it was sent.

The solution is to call this function manually on the receiving process, but not call it on the sending proc.

The pointer returned allows the abbreviation:

```
delete instance.deleteExporterInfo();
```

The documentation for this class was generated from the following file:

- repast_hpc/RepastProcess.h

5.125 repast::TDataSource< T > Class Template Reference

Interface for class that act as datasoures for DataSets.

```
#include <TDataSource.h>
```

Public Member Functions

- virtual T [getData](#) ()=0
Gets the data.

5.125.1 Detailed Description

`template<typename T>class repast::TDataSource< T >`

Interface for class that act as datasoures for DataSets.

Template Parameters

<i>T</i>	the type of the data
----------	----------------------

5.125.2 Member Function Documentation

5.125.2.1 `template<typename T> virtual T repast::TDataSource< T >::getData ()` [pure virtual]

Gets the data.

Returns

the current data.

The documentation for this class was generated from the following file:

- repast_hpc/TDataSource.h

5.126 repast::Timer Class Reference

Simple timing class.

```
#include <Utilities.h>
```

Public Member Functions

- void [start](#) ()
Starts the timer.
- long double [stop](#) ()
Stops the timer and returns the number of milliseconds elapsed since calling [start\(\)](#).

5.126.1 Detailed Description

Simple timing class.

Calling [start\(\)](#) starts the timer, calling stop returns the milliseconds since calling start.

5.126.2 Member Function Documentation

5.126.2.1 `long double repast::Timer::stop ()`

Stops the timer and returns the number of milliseconds elapsed since calling [start\(\)](#).

Returns

the number of milliseconds elapsed since calling [start\(\)](#).

The documentation for this class was generated from the following files:

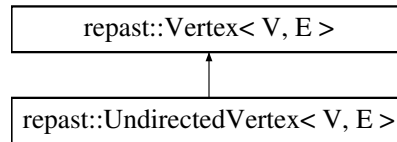
- repast_hpc/Utilities.h
- repast_hpc/Utilities.cpp

5.127 repast::UndirectedVertex< V, E > Class Template Reference

A vertex in an undirected network.

```
#include <UndirectedVertex.h>
```

Inheritance diagram for repast::UndirectedVertex< V, E >:



Public Member Functions

- **UndirectedVertex** (boost::shared_ptr< V > item)
- virtual boost::shared_ptr< E > **removeEdge** (Vertex< V, E > *other, EdgeType type)
Removes the edge of the specified type between this Vertex and the specified Vertex.
- virtual boost::shared_ptr< E > **findEdge** (Vertex< V, E > *other, EdgeType type)
Finds the edge of the specified type between this Vertex and the specified vertex.
- virtual void **addEdge** (Vertex< V, E > *other, boost::shared_ptr< E > edge, EdgeType type)
Adds an edge of the specified type between this Vertex and the specified vertex.
- virtual void **successors** (std::vector< V * > &out)
Gets the successors of this Vertex.
- virtual void **predecessors** (std::vector< V * > &out)
Gets the predecessors of this Vertex.
- virtual void **adjacent** (std::vector< V * > &out)
Gets the Vertices adjacent to this Vertex.
- virtual void **edges** (EdgeType type, std::vector< boost::shared_ptr< E > > &out)
Gets all the edges of the specified type in which this Vertex participates and return them in out.
- int **inDegree** ()
Gets the in degree of this Vertex.
- int **outDegree** ()
Gets the out degree of this Vertex.

5.127.1 Detailed Description

```
template<typename V, typename E>class repast::UndirectedVertex< V, E >
```

A vertex in an undirected network.

Template Parameters

V	the vertex type
E	the edge type. The edge type must be or extend RepastEdge .

5.127.2 Member Function Documentation

5.127.2.1 `template<typename V , typename E > void repast::UndirectedVertex< V, E >::addEdge (Vertex< V, E > * other, boost::shared_ptr< E > edge, EdgeType type) [virtual]`

Adds an edge of the specified type between this Vertex and the specified vertex.

Parameters

<i>edge</i>	the edge to add
<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to add

Implements [repast::Vertex< V, E >](#).

5.127.2.2 `template<typename V , typename E > void repast::UndirectedVertex< V, E >::adjacent (std::vector< V * > & out) [virtual]`

Gets the Vertices adjacent to this [Vertex](#).

Parameters

<i>out</i>	<i>the</i>	vector where the adjacent vectors will be put
------------	------------	---

Implements [repast::Vertex< V, E >](#).

5.127.2.3 `template<typename V , typename E > void repast::UndirectedVertex< V, E >::edges (EdgeType type, std::vector< boost::shared_ptr< E > > & out) [virtual]`

Gets all the edges of the specified type in which this [Vertex](#) participates and return them in out.

Parameters

	<i>type</i>	the type of edges to get
<i>out</i>	<i>where</i>	the edges will be put.

Implements [repast::Vertex< V, E >](#).

5.127.2.4 `template<typename V , typename E > boost::shared_ptr< E > repast::UndirectedVertex< V, E >::findEdge (Vertex< V, E > * other, EdgeType type) [virtual]`

Finds the edge of the specified type between this [Vertex](#) and the specified vertex.

Parameters

<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to remove

Returns

the found edge, or 0.

Implements [repast::Vertex< V, E >](#).

5.127.2.5 `template<typename V , typename E > int repast::UndirectedVertex< V, E >::inDegree () [virtual]`

Gets the in degree of this [Vertex](#).

Returns

the in degree of this [Vertex](#).

Implements [repast::Vertex< V, E >](#).

5.127.2.6 `template<typename V , typename E > int repast::UndirectedVertex< V, E >::outDegree () [virtual]`

Gets the out degree of this [Vertex](#).

Returns

the out degree of this [Vertex](#).

Implements [repast::Vertex< V, E >](#).

5.127.2.7 `template<typename V , typename E > void repast::UndirectedVertex< V, E >::predecessors (std::vector< V * > & out) [virtual]`

Gets the predecessors of this [Vertex](#).

Parameters

out	the	vector where any predecessors will be put
-----	-----	---

Implements [repast::Vertex< V, E >](#).

5.127.2.8 `template<typename V , typename E > boost::shared_ptr< E > repast::UndirectedVertex< V, E >::removeEdge (Vertex< V, E > * other, EdgeType type) [virtual]`

Removes the edge of the specified type between this [Vertex](#) and the specified [Vertex](#).

Parameters

other	the other end of the edge
type	the type of edge to remove

Returns

the removed edge if such an edge was found, otherwise 0.

Implements [repast::Vertex< V, E >](#).

5.127.2.9 `template<typename V , typename E > void repast::UndirectedVertex< V, E >::successors (std::vector< V * > & out) [virtual]`

Gets the successors of this [Vertex](#).

Parameters

out	the	vector where any successors will be put
-----	-----	---

Implements [repast::Vertex< V, E >](#).

The documentation for this class was generated from the following file:

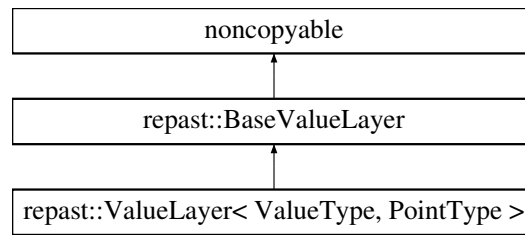
- `repast_hpc/UndirectedVertex.h`

5.128 `repast::ValueLayer< ValueType, PointType >` Class Template Reference

A collection that stores values at point locations.

```
#include <ValueLayer.h>
```

Inheritance diagram for `repast::ValueLayer< ValueType, PointType >`:



Public Member Functions

- **ValueLayer** (const std::string &name, const GridDimensions &dimensions)
- virtual ValueType & **get** (const Point< PointType > &pt)=0
Gets the value at the specified point.
- virtual void **set** (const ValueType &value, const Point< PointType > &pt)=0
Sets the value at the specified point.
- ValueType & **operator[]** (const Point< PointType > &pt)
Gets the value at the specified point.
- const ValueType & **operator[]** (const Point< PointType > &pt) const
Gets the value at the specified point.
- const GridDimensions **dimensions** () const
Gets the dimensions of this ValueLayer.
- const Point< int > **shape** () const
Gets the extents of this ValueLayer.

Protected Member Functions

- void **translate** (std::vector< PointType > &pt)
Translates pt by dimensions origin.

Protected Attributes

- GridDimensions **_dimensions**

5.128.1 Detailed Description

template<typename ValueType, typename PointType>class repast::ValueLayer< ValueType, PointType >

A collection that stores values at point locations.

Template Parameters

<i>ValueType</i>	the type stored by the value layer.
<i>the</i>	coordinate type (int or double) of the point locations.

5.128.2 Member Function Documentation

5.128.2.1 template<typename ValueType, typename PointType> const GridDimensions repast::ValueLayer< ValueType, PointType >::dimensions () const [inline]

Gets the dimensions of this ValueLayer.

Returns

the dimensions of this [ValueLayer](#).

5.128.2.2 `template<typename ValueType, typename PointType> virtual ValueType& repast::ValueLayer< ValueType, PointType >::get (const Point< PointType > & pt) [pure virtual]`

Gets the value at the specified point.

If no value has been set at the specified point then this returns some default value. Subclasses will determine the default value.

param pt the location to get the value of

Returns

the value at the specified point, or if no value has been set, then some default value.

Implemented in [repast::ContinuousValueLayer< ValueType, Borders >](#), and [repast::DiscreteValueLayer< ValueType, Borders >](#).

5.128.2.3 `template<typename ValueType , typename PointType> ValueType & repast::ValueLayer< ValueType, PointType >::operator[] (const Point< PointType > & pt)`

Gets the value at the specified point.

If no value has been set at the specified point then this returns some default value. Subclasses will determine the default value.

param pt the location to get the value of

Returns

the value at the specified point, or if no value has been set, then some default value.

5.128.2.4 `template<typename ValueType , typename PointType> const ValueType & repast::ValueLayer< ValueType, PointType >::operator[] (const Point< PointType > & pt) const`

Gets the value at the specified point.

If no value has been set at the specified point then this returns some default value. Subclasses will determine the default value.

param pt the location to get the value of

Returns

the value at the specified point, or if no value has been set, then some default value.

5.128.2.5 `template<typename ValueType, typename PointType> virtual void repast::ValueLayer< ValueType, PointType >::set (const ValueType & value, const Point< PointType > & pt) [pure virtual]`

Sets the value at the specified point.

Parameters

<i>value</i>	the value
<i>pt</i>	the point where the value should be stored

Implemented in [repast::ContinuousValueLayer< ValueType, Borders >](#), and [repast::DiscreteValueLayer< ValueType, Borders >](#).

5.128.2.6 `template<typename ValueType, typename PointType> const Point<int> repast::ValueLayer< ValueType, PointType >::shape () const [inline]`

Gets the extents of this [ValueLayer](#).

Returns

the extents of this [ValueLayer](#).

The documentation for this class was generated from the following file:

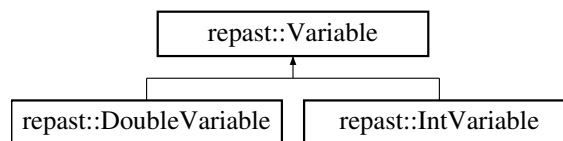
- [repast_hpc/ValueLayer.h](#)

5.129 repast::Variable Class Reference

Used in [SVDDataSet](#) to manage and store the data.

```
#include <Variable.h>
```

Inheritance diagram for `repast::Variable`:



Public Member Functions

- virtual void [write](#) (size_t index, std::ofstream &out)=0
Writes the data at the specified index to the specified ofstream.
- virtual void [insert](#) (double *array, size_t size)=0
Inserts all the doubles in the double array into the collection of data stored in this [Variable](#).
- virtual void [insert](#) (int *array, size_t size)=0
Inserts all the ints in the int array into the collection of data stored in this [Variable](#).
- virtual void [clear](#) ()=0
Clears this [Variable](#) of all the data stored in it.

5.129.1 Detailed Description

Used in [SVDDataSet](#) to manage and store the data.

5.129.2 Member Function Documentation

5.129.2.1 `virtual void repast::Variable::insert (double * array, size_t size) [pure virtual]`

Inserts all the doubles in the double array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implemented in [repast::DoubleVariable](#), and [repast::IntVariable](#).

5.129.2.2 `virtual void repast::Variable::insert (int * array, size_t size) [pure virtual]`

Inserts all the ints in the int array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implemented in [repast::DoubleVariable](#), and [repast::IntVariable](#).

5.129.2.3 `virtual void repast::Variable::write (size_t index, std::ofstream & out) [pure virtual]`

Writes the data at the specified index to the specified ofstream.

Parameters

<i>index</i>	the index of the data to write
<i>out</i>	the ofstream to write the data to

Implemented in [repast::DoubleVariable](#), and [repast::IntVariable](#).

The documentation for this class was generated from the following file:

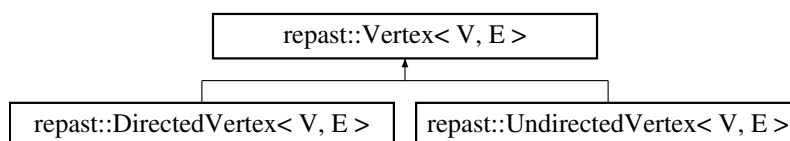
- [repast_hpc/Variable.h](#)

5.130 `repast::Vertex< V, E >` Class Template Reference

Used internally by repast graphs / networks to encapsulate Vertices.

```
#include <Vertex.h>
```

Inheritance diagram for `repast::Vertex< V, E >`:



Public Types

- enum [EdgeType](#) { **INCOMING**, **OUTGOING** }
Enum that identifies whether an edge is incoming or outgoing.
- typedef boost::unordered_map
`< Vertex< V, E >`
`*, boost::shared_ptr< E >`
`, HashVertex< V, E > > AdjListMap`
Typedef for the adjacency list map that contains the other Vertices that this [Vertex](#) links to.
- typedef `AdjListMap::iterator` **AdjListMapIterator**

Public Member Functions

- [Vertex](#) (boost::shared_ptr< V > [item](#))
Creates a [Vertex](#) that contains the specified item.
- virtual boost::shared_ptr< E > [removeEdge](#) ([Vertex](#) *other, [EdgeType](#) type)=0
Removes the edge of the specified type between this [Vertex](#) and the specified [Vertex](#).
- virtual boost::shared_ptr< E > [findEdge](#) ([Vertex](#) *other, [EdgeType](#) type)=0
Finds the edge of the specified type between this [Vertex](#) and the specified vertex.
- virtual void [addEdge](#) ([Vertex](#)< V, E > *other, boost::shared_ptr< E > edge, [EdgeType](#) type)=0
Adds an edge of the specified type between this [Vertex](#) and the specified vertex.
- virtual void [successors](#) (std::vector< V * > &out)=0
Gets the successors of this [Vertex](#).
- virtual void [predecessors](#) (std::vector< V * > &out)=0
Gets the predecessors of this [Vertex](#).
- virtual void [adjacent](#) (std::vector< V * > &out)=0
Gets the Vertices adjacent to this [Vertex](#).
- virtual void [edges](#) ([EdgeType](#) type, std::vector< boost::shared_ptr< E > > &out)=0
Gets all the edges of the specified type in which this [Vertex](#) participates and return them in out.
- virtual int [inDegree](#) ()=0
Gets the in degree of this [Vertex](#).
- virtual int [outDegree](#) ()=0
Gets the out degree of this [Vertex](#).
- boost::shared_ptr< V > [item](#) () const
Gets the item that this [Vertex](#) contains.

Protected Member Functions

- boost::shared_ptr< E > [removeEdge](#) ([Vertex](#)< V, E > *other, [AdjListMap](#) *adjMap)
- void [getItems](#) ([AdjListMap](#) *adjMap, std::vector< V * > &out)
- void [edges](#) ([AdjListMap](#) *adjMap, std::vector< boost::shared_ptr< E > > &out)

Protected Attributes

- boost::shared_ptr< V > [ptr](#)

Friends

- struct [NodeGetter](#)< V, E >

5.130.1 Detailed Description

template<typename V, typename E>class repast::Vertex< V, E >

Used internally by repast graphs / networks to encapsulate Vertices.

Template Parameters

V	the type of object stored by in a Vertex .
-------------------	--

<i>E</i>	the edge type of the network.
----------	-------------------------------

5.130.2 Constructor & Destructor Documentation

5.130.2.1 `template<typename V, typename E > repast::Vertex< V, E >::Vertex (boost::shared_ptr< V > item)`

Creates a [Vertex](#) that contains the specified item.

Parameters

<i>item</i>	the item the Vertex should contain
-------------	--

5.130.3 Member Function Documentation

5.130.3.1 `template<typename V, typename E> virtual void repast::Vertex< V, E >::addEdge (Vertex< V, E > * other, boost::shared_ptr< E > edge, EdgeType type) [pure virtual]`

Adds an edge of the specified type between this [Vertex](#) and the specified vertex.

Parameters

<i>edge</i>	the edge to add
<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to add

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

5.130.3.2 `template<typename V, typename E> virtual void repast::Vertex< V, E >::adjacent (std::vector< V * > & out) [pure virtual]`

Gets the Vertices adjacent to this [Vertex](#).

Parameters

<i>out</i>	<i>the</i>	vector where the adjacent vectors will be put
------------	------------	---

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

5.130.3.3 `template<typename V, typename E> virtual void repast::Vertex< V, E >::edges (EdgeType type, std::vector< boost::shared_ptr< E > > & out) [pure virtual]`

Gets all the edges of the specified type in which this [Vertex](#) participates and return them in out.

Parameters

	<i>type</i>	the type of edges to get
<i>out</i>	<i>where</i>	the edges will be put.

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

5.130.3.4 `template<typename V, typename E> virtual boost::shared_ptr<E> repast::Vertex< V, E >::findEdge (Vertex< V, E > * other, EdgeType type) [pure virtual]`

Finds the edge of the specified type between this [Vertex](#) and the specified vertex.

Parameters

<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to remove

Returns

the found edge, or 0.

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

5.130.3.5 `template<typename V, typename E> virtual int repast::Vertex< V, E >::inDegree () [pure virtual]`

Gets the in degree of this [Vertex](#).

Returns

the in degree of this [Vertex](#).

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

5.130.3.6 `template<typename V, typename E> boost::shared_ptr<V> repast::Vertex< V, E >::item () const [inline]`

Gets the item that this [Vertex](#) contains.

Returns

the item.

5.130.3.7 `template<typename V, typename E> virtual int repast::Vertex< V, E >::outDegree () [pure virtual]`

Gets the out degree of this [Vertex](#).

Returns

the out degree of this [Vertex](#).

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

5.130.3.8 `template<typename V, typename E> virtual void repast::Vertex< V, E >::predecessors (std::vector< V * > & out) [pure virtual]`

Gets the predecessors of this [Vertex](#).

Parameters

out	<i>the</i>	vector where any predecessors will be put
-----	------------	---

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

5.130.3.9 `template<typename V, typename E> virtual boost::shared_ptr<E> repast::Vertex< V, E >::removeEdge (Vertex< V, E > * other, EdgeType type) [pure virtual]`

Removes the edge of the specified type between this [Vertex](#) and the specified [Vertex](#).

Parameters

<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to remove

Returns

the removed edge if such an edge was found, otherwise 0.

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

5.130.3.10 `template<typename V, typename E> virtual void repast::Vertex< V, E >::successors (std::vector< V * > & out) [pure virtual]`

Gets the successors of this [Vertex](#).

Parameters

<i>out</i>	<i>the</i>	vector where any successors will be put
------------	------------	---

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

The documentation for this class was generated from the following file:

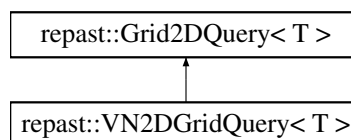
- [repast_hpc/Vertex.h](#)

5.131 repast::VN2DGridQuery< T > Class Template Reference

Neighborhood query that gathers neighbors in a Von Neumann (N, S, E, W) neighborhood.

```
#include <VN2DGridQuery.h>
```

Inheritance diagram for `repast::VN2DGridQuery< T >`:



Public Member Functions

- **VN2DGridQuery** (const [Grid](#)< T, int > *grid)
- virtual void [query](#) (const [Point](#)< int > ¢er, int range, bool includeCenter, std::vector< T * > &out) const
Queries the [Grid](#) for the Von Neumann neighbors surrounding the center point within a specified range.

Additional Inherited Members

5.131.1 Detailed Description

```
template<typename T>class repast::VN2DGridQuery< T >
```

Neighborhood query that gathers neighbors in a Von Neumann (N, S, E, W) neighborhood.

Template Parameters

<i>T</i>	the type of agents in the Grid
----------	--

5.131.2 Member Function Documentation

5.131.2.1 `template<typename T> void repast::VN2DGridQuery< T>::query (const Point< int> & center, int range, bool includeCenter, std::vector< T*> & out) const` `[virtual]`

Queries the [Grid](#) for the Von Neumann neighbors surrounding the center point within a specified range.

Parameters

	<i>center</i>	the center of the neighborhood
	<i>range</i>	the range of the neighborhood out from the center
	<i>includeCenter</i>	whether or not to include any agents at the center
<i>out</i>	<i>the</i>	neighboring agents will be returned in this vector

Implements [repast::Grid2DQuery< T>](#).

The documentation for this class was generated from the following file:

- `repast_hpc/VN2DGridQuery.h`

5.132 repast::WrapAroundBorders Class Reference

Implements periodic wrap around style border semantics.

```
#include <GridComponents.h>
```

Public Member Functions

- **WrapAroundBorders** ([GridDimensions](#) dimensions)
- void **transform** (const std::vector< int> &in, std::vector< int> &out) const
- void **transform** (const std::vector< double> &in, std::vector< double> &out) const
- void **translate** (const std::vector< double> &oldPos, std::vector< double> &newPos, const std::vector< double> &displacement) const
- void **translate** (const std::vector< int> &oldPos, std::vector< int> &newPos, const std::vector< int> &displacement) const
- void **init** (const [GridDimensions](#) &dimensions)
- bool **isPeriodic** () const

5.132.1 Detailed Description

Implements periodic wrap around style border semantics.

Points that are outside the borders are wrapped until the point is inside the borders.

The documentation for this class was generated from the following files:

- `repast_hpc/GridComponents.h`
- `repast_hpc/GridComponents.cpp`