**HIW 3.0 Checklist/Troubleshooting**

Last updated: 4/24/2024 CK

**<Logging into the computers>**

* 2 ThinkPad X1’s
  + First computer: **HIW-3** (Full device name: **HIW-3.adcu.columbia.edu**)
  + Second computer: **Delphi** (Full device name: **Delphi.adcu.columbia.edu**)
* Before logging in, make sure the computers are connected to either (A) Columbia U Secure wifi or (B) Ethernet cable
* Log into both computers with Courtney’s UNI credentials
  + Username: **jk4817** (it might already prompt you to log into user “Jihoo Kim”)
  + Password: **135Kjhandaakjh!c**
  + The same credentials are used for both computers when remoting in as well.

**<Setting up the computers>** (skip this if the computers are already configured)

* Turn off screen saver
* Make sure computers don’t go to sleep
  + Setting > System > Power & battery > Screen and sleep
  + Set all 4 options to “Never”
* Turn off auto-updates
  + Download WUB: <https://www.sordum.org/9470/windows-update-blocker-v1-7/>
  + Click on “Disable Updates” and then “Apply Now”

**<Running the experiment>** - 4 cages and 2 computers

**\*\*\*Reminder before each run**

* Put half the regular amount of the brown strips and bedding
* Make sure there’s food in the cage
* Periodically check for computer data storage and make sure it isn’t full

**BOX CONFIGURATION**

|  |  |
| --- | --- |
| Box 1 | Box 3 |
| Box 2 | Box 4 |

\*\* HIW-3 computer : Box 1 & 2

\*\* Delphi computer: Box 3 & 4

* Make sure all the lines are hooked up
  + CoolDrive (N=4) is powered and connected to the Output Expander (N=4) and the final valve (N=4)
    - Power the CoolDrive FIRST before passing the logic
  + Camera (N=4) is connected to the Output Expander (N=4)
  + Camera is directly plugged into the computer (DON’T PLUG CAMERA CABLE TO THE USB EXPANDER HUB – IT WILL RESULT IN DROPPING FRAMES)
  + USB Expander Hub (N=2) is plugged into the computer
  + USB Expander Hub is plugged in with Harp expander cable (N=4)
  + Ethernet cable (N=2) is directly plugged into the computer with an adapter
  + Computers are powered
* Restart all the programs before each run (only in the prototyping stage when testing new github pull requests)
  + Bonsai
  + Github Desktop
  + Visual Studio Code
* Make sure to you’re using the correct Bonsai workflow
  + **[This PC]** >**[Windows (C:)]** > **[Users]** > **[jk4817]** or **[jk4817.adcu]** > **[Delphi]** > **[.bonsai]**
  + Run the Setup file (only if you can’t see the Bonsai program icon in the folder)
  + **[Run as Administrator]** the Bonsai program in the same folder **[.bonsai]**
  + Open file in **[This PC]** > **[Windows (C:)]** > **[Users]** > **[jk4817]** or **[jk4817.adcu]** > **[Delphi]** > **[src]** > **[DelphiMain]**
  + Open Github Desktop, and make sure…
    - Current repository = **[Delphi]**
    - Current branch = **[Main]**
  + In Github Desktop, click **[Pull origin]** if there have been any changes
  + In Bonsai, click **[Reload extensions]** (the button on the far right in the same row as the start button) if there have been any changes
  + Open Visual Studio Code and make sure you’re working on the **[Main]** branch
  + Check the **rule yml** files you’re going to use and make sure everything’s correct
  + Make 4 **[DelphiSession]** files if you don’t see them (copy and paste the already-existing DelphiSession file and rename them)
    - **HIW-3 Computer:** DelphiSession1, DelphiSession2
    - **Delphi Computer:** DelphiSession3, DelphiSession4
  + In VSCode, click on each **[DelphiSession]** and make sure all the parameters are correct

|  |  |
| --- | --- |
| **METADATA** | |
| Animal ID | Depends |
| loggingRootPath | **DelphiSession1:** C:\Users\jk4817\temp\_data\_box1  **DelphiSession2:** C:\Users\jk4817\temp\_data\_box2  **DelphiSession3:** C:\Users\jk4817.adcu\temp\_data\_box3  **DelphiSession4:** C:\Users\jk4817.adcu\temp\_data\_box4 |
| remoteTransferRootPath | **DelphiSession1**: \\locker-smb.engram.rc.zi.columbia.edu\axel-locker\piriform\behavior\HIW3\_Robocopy\_Rawdata\Robocopy\_Box1\_Rawdata  **DelphiSession2**: \\locker-smb.engram.rc.zi.columbia.edu\axel-locker\piriform\behavior\HIW3\_Robocopy\_Rawdata\Robocopy\_Box2\_Rawdata  **DelphiSession3**: \\locker-smb.engram.rc.zi.columbia.edu\axel-locker\piriform\behavior\HIW3\_Robocopy\_Rawdata\Robocopy\_Box3\_Rawdata  **DelphiSession4**: \\locker-smb.engram.rc.zi.columbia.edu\axel-locker\piriform\behavior\HIW3\_Robocopy\_Rawdata\Robocopy\_Box4\_Rawdata |
| chargeTime | 0.2 |
| minimumPokeTime | 0.01 |
| maximumPokeTime | 10 |
| robocopyTimeInterval | 3600 |
| maxVideoLength | 60 |
| minOdorDelivery | 0.1 |
| maxOdorDelivery | 10 |
| switchTime1 | 0.01 |
| switchTime2 | 0.02 |
| useVacuum | false (depends) |
| vacuumDelay | 0.005 (will change) |
| vacuumDuration | 0.05 (will change) |
|  | |
| **CAMERA PROPERTIES** | |
| imagingRate | 60 |
| exposureTime | 10000 |
| serialNumber | “[FLIR camera serial number 8 digits]”  \*make sure you don’t put in the number for another camera filming another box |
| preEventTime | 2.5 |
| postEventTime | 2.5 |
|  | |
| **HARP PROPERTIES** | |
| comPort | COM#  \*Check the COM options in the Bonsai window > Pick one, apply it to VSCode and try running Bonsai > confirm that it runs and lights up the correct Output Expander > if it spits out errors, try another COM#  \*As long as the Output Expander cable stays connected to the computer via the *same* USB port, the COM# won’t change |
| showHarpLeds | true (depends) |
|  | |
| **LINE MAPPINGS** | |
| odorMap | - {name: "OdorA", line: 6}  - {name: "OdorB", line: 7}  - {name: "OdorC", line: 8}  - {name: "OdorD", line: 9} |
| portLine | 0 |
| vacuumLine | 2 |
| auxLine | 0 |
| cameraTriggerLine | Pwm0ToOut1 |

* Click **[ctrl + S]** on VSCode to save the changes
* Make necessary changes in Bonsai
  + Click anywhere on **[Workflow]** window, and ControlKeys will pop up on the right
  + Select the correct **rule yml file**
  + Change the stop session function key to… **Shift + 1** (for Box 1), **Shift + 2** (for Box 2), **Shift + 3** (for Box 3), **Shift + 4** (for Box 4)
* Turn on the 2 nitrogen tanks
  + Make sure you have enough gas (full tank is 2500 lpm)
  + Pressure gauge on the tank’s flow regulator is ~20
  + Bottle – 0.05 lpm per bottle (0.15 per box when using 3 odors)
  + Air – 0.05 lpm
  + Top 2 regulators are for bottles, bottom 2 are for air going into final valves
  + \*\*\*For rotameters, check the floats and the conversion document to dial in the correct flow rate
  + **(WILL UPDATE WITH SPECIFIC ROTAMETERS AND FLOW RATES)**
* Start the Bonsai program and press **[Shift + F1]** to start the cameraand **[Shift + Space]** to load the rule
  + Make a poke with the program and smell the port, making sure the final valve is opening, the odors are changing correctly and the lines are not clogged
  + Open livestream from the **[Workflow]** window **[Value.Image]** and check that the camera focus/depth is desirable. Adjust focus/exposure accordingly by turning the knobs on the camera.
* Stop the program and check for data files in the robocopy destinations in the “piriform” folder, and once you confirm that robocopy is running properly, delete these test files.
  + Put the mice in
  + Screw in the poke port
* Start the experiment
  + Make sure to click **[Shift + Space]** to load the rule
    - When you’re changing the rule, double-check the rule file in VSCode that it is written correctly
  + Open livestream video and DelphiVisualizer for convenience
  + Make sure there are no dropping frames ([Camera Controller] window > click on both the Spinnaker node and the node preceding it – check that the two numbers align)
  + Make sure the blue service requisition card is on the cage

**When you’re done with the experiment…**

* Press **[Shift + (whatever box number)]** to stop the bonsai instance instead of clicking on the stop button
* Check that the odor valves + final valve are closed

\*Record who ran when in which box in the “HIW3\_Experiment\_Records\_2024” Excel File in the piriform locker > HIW 3.0

**Tips**

* **Opening DelphiVisualizer**
  + **[Workflow] > [TableLayoutPanel]** node

**Troubleshooting**

* **Poke detection failure**
  + Check jumpers on Harp expander breakout and that they’re receiving input from the software and not the physical buttons on the breakout
  + In the Bonsai workflow, [Devices] [Delphi Controller] [LineMappings.AuxLine], start the workflow, and check that it’s Aux 0, not Aux 1
  + In the Bonsai workflow, [Devices] > [Delphi Controller] > [HasFlag], start the workflow, and check that it’s Aux 0, not Aux1
  + If you detect an error, change it in VSCode
    - [DelphiSession] > “auxLine” > Set to 0
* **Changes made in VSCode are not being reflected in Bonsai**
  + You’re most likely using the wrong directory.
  + [This PC] > [Windows (C:)] > [Users] > [jk4817] or [jk4817.adcu] > [Delphi]
  + Type “cmd” where the path is
  + Type “code .” in terminal + enter
  + VSCode will open; work on “DelphiSession.” Any changes you make here AND saved will be reflected on Bonsai.