The relativistic Force Law and the Dynamics of a lingle Porticle.

Now, the generalized form of Newton's second laws's.

$$\vec{F} = \frac{d}{dt}(\vec{b})$$

$$\vec{F} = \frac{d}{dt}\left(\frac{m_0\vec{u}}{\sqrt{1-u^2/c^2}}\right) \qquad (1)$$

Kinetic energy in classical mechanics, and relativistic.

$$K = \int_{u=0}^{u=4} \overline{F} \cdot d\vec{J}$$

$$= \int_{0}^{u=0} F dn \qquad (one dimension)$$

$$= \int_{0}^{u=0} m_{0} \frac{du}{dt} du = \int_{0}^{u=0} m_{0} du \left(\frac{du}{dt}\right) = \int_{0}^{u=0} m_{0} u du$$

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NowMit relativistic;

$$K = \int_{0}^{4} \frac{d}{dt} (mu) dn = \int_{0}^{4} d(mu) \frac{dn}{dt}.$$

$$K = \int_{0}^{4} (mu) du + u dm) U$$

$$K = \int_{0}^{4} (mu) du + u^{2} dm) \qquad (2m^{2} - m^{2})^{2} = m_{0}^{2} (mu)^{2} = m_{0}^{2} = m_{0}^{2$$

$$\omega = \frac{m_0}{\sqrt{1-4^2/2}} \Rightarrow c^2 m^2 - m^2 4^2 = m_0^2 (2)$$

 $c^2 m^2 - m^2 q^2 = m_a^2 c^2$ andifferentiation, $2c^2mdm-2m^2udu-2u^2mdm=0$ $c^2 dm - mudu - y^2 dm = 0$ Q. L. $y^2 dm + my dy = c^2 dm$ 08 $K = \int_{1}^{4} (mu \, du + u^2 dm)$ $= \int_{m}^{m} e^{2} dm = c^{2} m \int_{0}^{m} e^{2} dm - m_{o}c^{2}.$ $K = mc^2 - mc^2$ $K = \frac{m_0 c^2}{\sqrt{1-u^2/r^2}} - m_0 c^2$ $K = m_0 c^2 \left[\frac{1}{\sqrt{1-u^2/c^2}} - L \right]$ $K = (mc^2) m_0 c^2$ E = total energy-K= E-moc2 $E = m_0c^2 + K$ total Enny rest

$$k = m_0 c^2 \left[(1 - w^2)_{(1)}^{-1/2} - 1 \right]$$

$$k = m_0 c^2 \left[(1 - w^2)_{(2)}^{-1/2} - 1 \right]$$

$$k = m_0 c^2 \cdot \frac{1}{2} \cdot \frac{u^2}{e^2}$$

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$$(CJaun'cal definition of K.E. 1'3)$$

$$volatined under alphaximation of W.E. 1'3$$

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 $(K + m_0(^2)^2 = b^2c^2 + m_0^2c^4)$ - (P)

$$E^2 = b^2 c^2 + m_0^2 c^4$$
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on differentiation,

$$\frac{dE}{db} = c \frac{1}{2} \left(b^2 + m_0^2 c^2 \right)^{\frac{1}{2} - 1} (2b + 0)$$

$$= \frac{bc}{\sqrt{b^2 + m_0^2 c^2}} = \frac{b(2)}{\sqrt{b^2 + m_0^2 c^2}} = \frac{b(2)}{E}$$

$$\frac{dE}{db} = \frac{bc^2}{E}$$

$$\frac{dC}{db} = \frac{10 m y \sqrt{2}}{me^2} = 4$$

$$As \vec{F} = m\vec{l}$$

$$\vec{E} = mc^2$$

$$\frac{dE}{db} = U$$

$$\vec{F} = \frac{d\vec{b}}{dt} = \frac{d}{dt} (m\vec{u})$$

$$\vec{F} = m \frac{d\vec{u}}{dt} + \vec{u} \frac{dm}{dt}$$
 — (12)

$$4SE=m(^2 \Rightarrow m=\frac{\epsilon}{2})^2$$

$$\frac{dm}{dt} = \frac{1}{c^2} \frac{d\varepsilon}{dt} = \frac{1}{c^2} \frac{d}{dt} \left(\frac{K + mc^2}{t^2} \right) = \frac{1}{c^2} \frac{dk}{dt}$$

$$\frac{dm}{dt} = \frac{1}{c^2} \frac{\vec{F} \cdot \vec{J} \vec{J}}{dt} = \frac{1}{c^2} \vec{F} \cdot \frac{d\vec{J}}{dt}$$

$$\frac{dm}{dt} = \frac{\vec{F} \cdot \vec{V}}{C^2} \quad . \tag{13}$$

So
$$\vec{F} = m \frac{d\vec{u}}{dt} + \vec{u} \frac{(\vec{F} \cdot \vec{u})}{c^2}$$
 — (14)
 \vec{a} (acceleration)

$$\vec{a} = \frac{d\vec{v}}{dt} = \frac{\vec{F}}{m} - \frac{\vec{v}}{mc^2} (\vec{F}, \vec{v}) - (15)$$

$$\vec{a} \cdot \vec{u} = \frac{\vec{F} \cdot \vec{u}}{m} - \frac{\vec{u} \cdot \vec{u}}{mc^2} (\vec{F} \cdot \vec{u}) = \frac{\vec{F} \cdot \vec{u}}{m} (1 - \frac{u^2}{c^2})$$

$$a_{11} = \frac{F_{11}}{m} \left(1 - \frac{y^2}{\ell^2} \right)$$

$$a_{11} = \frac{F_{11}}{m_{0}} (1 - u^{2}/e^{2})^{2} (1 - v^{2}/e^{2})$$

$$a_{11} = \frac{F_{11}}{m_{0}} (1 - v^{2}/e^{2})^{2}$$

$$F_{11} = \frac{a_{11}}{(1 - v^{2}/e^{2})^{2}}$$

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