

# Embedded Linux boot time optimization training

On-site training, 3 days Latest update: February 24, 2023

Title	Embedded Linux boot time optimization training
Training objectives	<ul> <li>Be able to use various tools and techniques to measure the boot time of an embedded Linux system.</li> <li>Be able to reduce the boot time spent during the <i>user-space</i> initialization.</li> <li>Be able to reduce the boot time spent during the <i>kernel</i> initialization.</li> <li>Be able to reduce the boot time spent during the <i>bootloader</i> initialization.</li> <li>Be able to use advanced and alternatives techniques of boot time optimization.</li> </ul>
Duration	Three days - 24 hours (8 hours per day)
Pedagogics	<ul> <li>Lectures delivered by the trainer: 40% of the duration</li> <li>Practical labs done by participants: 60% of the duration</li> <li>Electronic copies of presentations, lab instructions and data files. They are freely available at https://bootlin.com/doc/training/boot-time.</li> </ul>
Trainer	One of the engineers listed on: https://bootlin.com/training/trainers/
Language	Oral lectures: English, French. Materials: English.
Audience	People developing embedded Linux systems. People supporting embedded Linux system developers.



Prerequisites	<ul> <li>Knowledge and practice of UNIX or GNU/Linux commands: participants must be familiar with the Linux command line. Participants lacking experience on this topic should get trained by themselves, for example with our freely available on-line slides at bootlin.com/blog/command-line/.</li> <li>Minimal experience in embedded Linux development: participants should have a minimal understanding of the architecture of embedded Linux systems: role of the Linux kernel vs. user-space, development of Linux user-space applications in C. Following Bootlin's Embedded Linux course at bootlin.com/training/embedded-linux/ allows to fulfill this pre-requisite.</li> <li>Minimal English language level: B1, according to the Common European Framework of References for Languages, for our sessions in English. See bootlin.com/pub/training/cefr-grid.pdf for self-evaluation.</li> </ul>
Required equipment	<ul> <li>Video projector</li> <li>One PC computer on each desk (for one or two persons) with at least 8 GB of RAM, and Ubuntu Linux 20.04 installed in a free partition of at least 30 GB</li> <li>Distributions others than Ubuntu Linux 20.04 are not supported, and using Linux in a virtual machine is not supported.</li> <li>Unfiltered and fast connection to Internet: at least 50 Mbit/s of download bandwidth, and no filtering of web sites or protocols.</li> <li>PC computers with valuable data must be backed up before being used in our sessions.</li> </ul>
Certificate	Only the participants who have attended all training sessions, and who have scored over 50% of correct answers at the final evaluation will receive a training certificate from Bootlin.
Disabilities	Participants with disabilities who have special needs are invited to contact us at <i>training@bootlin.com</i> to discuss adaptations to the training course.



#### Hardware

The hardware platform used for the practical labs of this training session is the **BeagleBone Black** board, which features:

- An ARM AM335x processor from Texas Instruments (Cortex-A8 based), 3D acceleration, etc.
- 512 MB of RAM
- 2 GB of on-board eMMC storage (4 GB in Rev C)
- USB host and device
- HDMI output
- 2 x 46 pins headers, to access UARTs, SPI buses, I2C buses and more.



#### **Practical labs**

The practical labs of this training session use the following hardware peripherals:

- A USB webcam
- An LCD and touchscreen cape connected to the BeagleBone Black board, to display the video captured by the webcam.
- We will also use an Arduino board as a way to measure boot time with accurary, demonstrating a hardware boot time measurement technique.



# Day 1 - Morning

#### **Lecture - Principles**

- · How to measure boot time
- Main ideas

#### **Lab** - Preparing the system

- Downloading bootloader, kernel and Buildroot source code
- Board setup, setting up serial communication
- Configure Buildroot and build the system
- Configure and build the U-Boot bootloader.
   Prepare an SD card and boot the bootloader from it.
- Configure and build the kernel. Boot the system

## Day 1 - Afternoon

#### **Lecture - Measuring time**

- Generic software techniques
- Hardware techniques
- Specific solutions for each stage

#### **Lab** - Measuring time - Software solution

- Modify the system to measure time at various steps
- Timing messages on the serial console
- Timing the execution of the application

#### Lab - Measuring time - Hardware solution

- Measure total boot time by toggling a GPIO
- Setting up an Arduino board
- Preparing a test circuit with a 7-segment display
- Modifying the DTS to configuring Bone Black pins as GPIOs
- Making the application drive the custom GPIOs

#### **Lecture - Toolchain optimizations**

- Introduction to toolchains
- C libraries
- · Size information
- Measuring executable performance with time



#### **Lab - Toolchain optimizations**

- · Measuring application execution time
- Switching to a Thumb2 toolchain
- Generate a Buildroot SDK to rebuild faster

## **Day 2- Morning**

# Lecture - Application optimization

- Using strace and ltrace
- Other profiling techniques

#### **Lab - Application optimization**

- Finding unnecessary configuration options in applications
- Modifying configuration options through Buildroot
- Experiments with strace to trace program execution

#### **Lecture - Optimizing system initialization**

- Using BusyBox bootchartd
- Optimizing init scripts
- Possibility to start your application directly

#### **Lab - Optimizing system initialization**

- Using Buildroot to remove unnecessary scripts and commands
- Access-time based technique to identify unused files
- Simplifying BusyBox
- Starting the application as the init program



# Day 2 - Afternoon

#### **Lecture - Filesystem optimizations**

- Available filesystems, performance and boot time aspects
- Making UBIFS faster
- Tweaks for reducing boot time
- Booting on an initramfs
- Using static executables: licensing constraints

#### **Lab - Filesystem optimizations**

- Trying and measuring two block filesystems: ext4 and SquashFS.
- Trying and measuring the initramfs solution. Constraints due to this solution.

#### **Lecture - Kernel optimizations**

- Using *Initcall debug* to generate a boot graph
- Compression and size features
- Reducing or suppressing console output
- Multiple tweaks to reduce boot time

#### **Lab** - Kernel optimizations

- Generating and analyzing a boot graph for the kernel
- Find and eliminate unnecessary kernel features
- Find the best kernel compression solution for our system

### Day 3 - Morning

#### Lab - Kernel optimizations

• Continued from Day 2



### Day 3 - Afternoon

#### **Lecture - Bootloader optimizations**

- Generic tips for reducing U-Boot's size and boot time
- · Optimizing U-Boot scripts and kernel loading
- Skipping the bootloader How to modify U-Boot to enable its *Falcon mode*

#### Lecture - U-Boot Falcon mode

- · Principles and goals
- The Device Tree preparation work that U-Boot does to prepare Linux kernel booting
- Using the spl export command to do this work in advance
- Modifying U-Boot's source code and configuring it for directly booting Linux and skipping the U-Boot second stage.
- Example instructions and setups for booting from MMC and NAND flash
- · How to debug Falcon mode
- · How to fall back to U-Boot
- Limitations

#### **Lab** - **Bootloader** optimizations

- Using the above techniques to make the bootloader as quick as possible.
- Switching to faster storage
- Configuring U-Boot for *Falcon mode* booting, skipping U-Boot's second stage.

#### Wrap-up - Achieved results

- Sharing and comparing results achieved by the various groups
- · Questions and answers, experience sharing with the trainer