

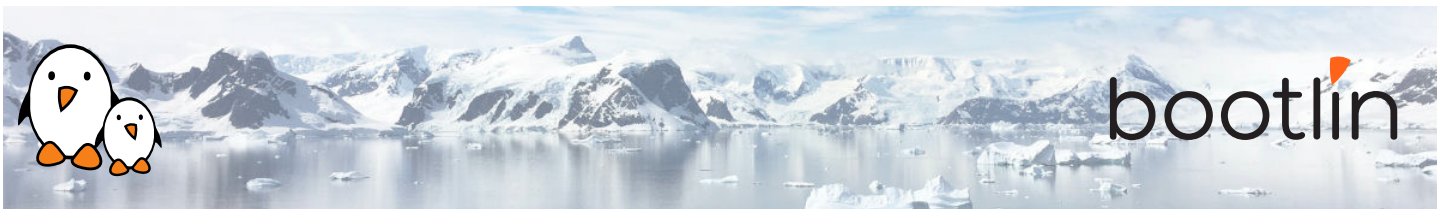


Yocto Project and OpenEmbedded development training

On-line seminar, 4 sessions of 4 hours

Latest update: February 24, 2023

Title	Yocto Project and OpenEmbedded development training
Training objectives	<ul style="list-style-type: none">• Be able to understand the role and principle of an embedded Linux build system, and compare Yocto Project/OpenEmbedded to other tools offering similar functionality.• Be able to configure and build basic embedded Linux system with Yocto, and install the result on an embedded platform.• Be able to write and extend recipes, for your own packages or customizations.• Be able to use existing layers of recipes, and create your own new layers.• Be able to integrate support for your own embedded board into a BSP layer.• Be able to create custom images.• Be able to use the tools and workflows suitable to develop applications with the Yocto Project SDK.
Duration	Four half days - 16 hours (4 hours per half day)
Pedagogics	<ul style="list-style-type: none">• Lectures delivered by the trainer, over video-conference. Participants can ask questions at any time.• Practical demonstrations done by the trainer, based on practical labs, over video-conference. Participants can ask questions at any time. Optionally, participants who have access to the hardware accessories can reproduce the practical labs by themselves.• Instant messaging for questions between sessions (replies under 24h, outside of week-ends and bank holidays).• Electronic copies of presentations, lab instructions and data files. They are freely available at https://bootlin.com/doc/training/yocto.
Trainer	One of the engineers listed on: https://bootlin.com/training/trainers/
Language	Oral lectures: English, French, Italian. Materials: English.
Audience	Companies and engineers interested in using the Yocto Project to build their embedded Linux system.

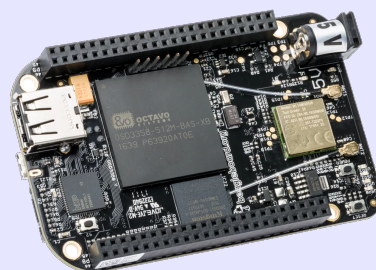


Prerequisites	<ul style="list-style-type: none"> • Knowledge and practice of UNIX or GNU/Linux commands: participants must be familiar with the Linux command line. Participants lacking experience on this topic should get trained by themselves, for example with our freely available on-line slides at bootlin.com/blog/command-line/. • Minimal experience in embedded Linux development: participants should have a minimal understanding of the architecture of embedded Linux systems: role of the Linux kernel vs. user-space, development of Linux user-space applications in C. Following Bootlin's <i>Embedded Linux</i> course at bootlin.com/training/embedded-linux/ allows to fulfill this pre-requisite. • Minimal English language level: B1, according to the <i>Common European Framework of References for Languages</i>, for our sessions in English. See bootlin.com/pub/training/cefr-grid.pdf for self-evaluation.
Required equipment	<ul style="list-style-type: none"> • Computer with the operating system of your choice, with the Google Chrome or Chromium browser for videoconferencing. • Webcam and microphone (preferably from an audio headset) • High speed access to the Internet
Certificate	Only the participants who have attended all training sessions, and who have scored over 50% of correct answers at the final evaluation will receive a training certificate from Bootlin.
Disabilities	Participants with disabilities who have special needs are invited to contact us at training@bootlin.com to discuss adaptations to the training course.

Hardware, first option

BeagleBone Black board

- An ARM AM335x processor from Texas Instruments (Cortex-A8 based), 3D acceleration, etc.
- 512 MB of RAM
- 2 GB of on-board eMMC storage (4 GB in Rev C)
- USB host and device
- HDMI output
- 2 x 46 pins headers, to access UARTs, SPI buses, I2C buses and more.





Hardware, second option

One of these Discovery Kits from STMicroelectronics: **STM32MP157A-DK1**, **STM32MP157D-DK1**, **STM32MP157C-DK2** or **STM32MP157F-DK2**

- STM32MP157 (dual Cortex-A7) CPU from STMicroelectronics
- USB powered
- 512 MB DDR3L RAM
- Gigabit Ethernet port
- 4 USB 2.0 host ports
- 1 USB-C OTG port
- 1 Micro SD slot
- On-board ST-LINK/V2-1 debugger
- Arduino Uno v3-compatible headers
- Audio codec
- Misc: buttons, LEDs
- LCD touchscreen (DK2 kits only)



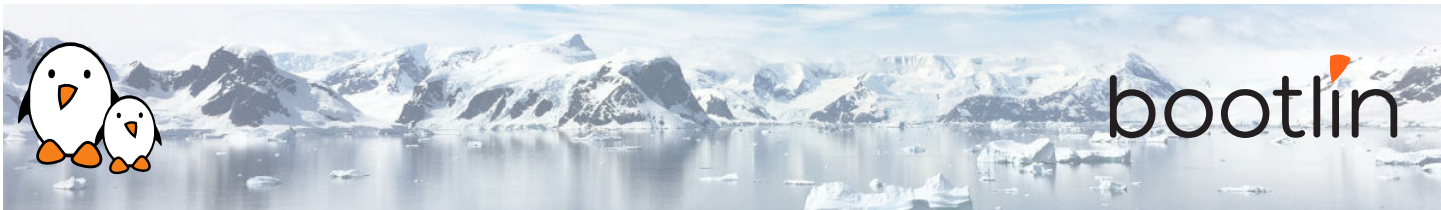
Day 1 - Morning

Lecture - Introduction to embedded Linux build systems

- Overview of an embedded Linux system architecture
- Methods to build a root filesystem image
- Usefulness of build systems

Lecture - Overview of the Yocto Project and the Poky reference system Lab - First Yocto Project build

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|--|---|
| <ul style="list-style-type: none">• Organization of the project source tree• Building a root filesystem image using the Yocto Project | <ul style="list-style-type: none">• Downloading the Poky reference build system• Building a system image |
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Day 1 - Afternoon

Lecture - Using Yocto Project - basics

- Organization of the build output
- Flashing and installing the system image

Lab - Flashing and booting

- Flashing and booting the image on the board

Lecture - Using Yocto Project - advanced usage

- Configuring the build system
- Customizing the package selection

Lab - Using NFS and configuring the build

- Configuring the board to boot over NFS
- Learn how to use the `PREFERRED_PROVIDER` mechanism

Day 2 - Morning

Lecture - Writing recipes - basics

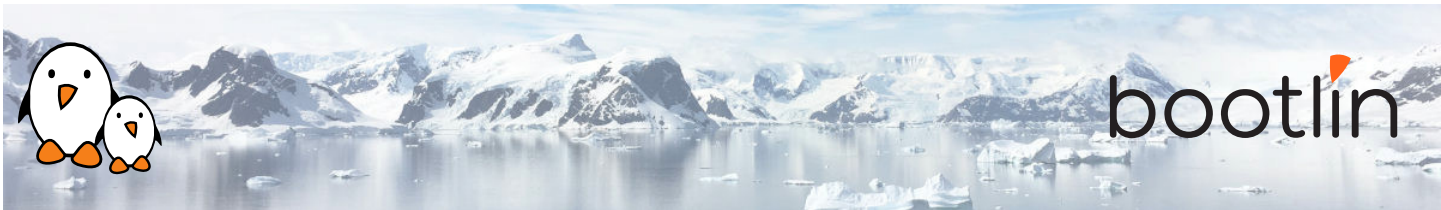
- Writing a minimal recipe
- Adding dependencies
- Development workflow with *bitbake*

Lab - Adding an application to the build

- Writing a recipe for *nInvaders*
- Adding *nInvaders* to the final image

Lecture - Writing recipes - advanced features

- Extending and overriding recipes
- Adding steps to the build process
- Learn about classes
- Analysis of examples
- Logging
- Debugging dependencies



Day 2 - Afternoon

Lecture - Layers

- What layers are
- Where to find layers
- Creating a layer

Lab - Writing a layer

- Learn how to write a layer
- Add the layer to the build
- Move *nInvaders* to the new layer

Day 3 - Morning

Lecture - Writing a BSP

- Extending an existing BSP
- Adding a new machine
- Bootloaders
- Linux and the linux-yocto recipe
- Adding a custom image type

Lab - Implementing the kernel changes

- Extend the kernel recipe to add the nunchuk driver
- Configure the kernel to compile the nunchuk driver
- Play *nInvaders*

Day 3 - Afternoon

Lecture - Creating a custom image

- Writing an image recipe
- Adding users/groups
- Adding custom configuration
- Writing and using package groups recipes

Lab - Creating a custom image

- Writing a custom image recipe
- Adding *nInvaders* to the custom image



Lecture - Creating and using an SDK

- Understanding the purpose of an SDK for the application developer
- Building an SDK for the custom image

Lab - Experimenting with the SDK

- Building an SDK
- Using the Yocto Project SDK