Chapter 4: Quantum Circuits

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1 Quantum Circuits

1.1 Exercise

1.2 Exercise

Let $x \in \mathbb{R}$ and A a matrix such that $A^2 = I$. Show that

$$e^{iAx} = I\cos x + iA\sin x$$

Solution

From the definition of the *rotational operator* \hat{y} ,

$$R_a(-2\theta) = \cos\theta I + i\sin\theta A = e^{iA\theta}$$

1.3 Exercise

Show that, up to global phase, the $\frac{\pi}{8}$ gate satisfies $T=R_z(\frac{\pi}{4})$

Solution

$$R_z(\frac{\pi}{4}) = e^{-i\pi Z/8} = \begin{bmatrix} e^{-i\pi/8} & 0 \\ 0 & e^{i\pi/8} \end{bmatrix} = e^{-i\pi/8} \begin{bmatrix} 1 & 0 \\ 0 & e^{i\pi/4} \end{bmatrix} = T$$

1.4 Exercise

Express Hadamard gate H as a product of R_x and R_z rotations and $e^{i\phi}$ for some ϕ

Solution

Let
$$c = \frac{1}{\sqrt{2}}e^{i\phi/2}$$
.

Then
$$cR_x(\phi)R_z(\phi) = c(e^{-i\phi Y/2}e^{-i\phi Z/2}) = c(e^{-i\frac{\phi}{2}(X+Z)}) = c(e^{-i\frac{\phi}{\sqrt{2}}H}) = \frac{1}{\sqrt{2}}\begin{bmatrix} 1 & 1\\ 1 & e^{i\phi} \end{bmatrix}$$

$$\phi = (2k+1)\pi; \quad \forall k \in \mathbb{N}$$

$$\implies \frac{1}{\sqrt{2}}e^{-(2k+1)\pi/2}R_x((2k+1)\pi)R_z((2k+1)\pi) = \frac{1}{\sqrt{2}}\begin{bmatrix} 1 & 1 \\ 1 & e^{i(2k+1)\pi} \end{bmatrix} = \frac{1}{\sqrt{2}}\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = H.$$

1.5 Exercise

Prove that $(\hat{n}, \vec{\sigma})^2 = I$, and use this to verify that

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$$R_{\hat{n}}(\theta) \equiv e^{-i\theta\hat{n}\vec{\sigma}/2} = \cos\frac{\theta}{2}I - i\sin\frac{\theta}{2}(n_xX + n_yY + n_zZ)$$

where $\overrightarrow{\sigma}$ denotes the three component vector (X,Y,Z) of Pauli matrices and where \hat{n} is a real unit vector.

Solution

$$\hat{n} = (n_x, n_y, n_z) \in \mathbb{R}^3$$

$$\vec{\sigma} = (X, Y, Z)$$

$$A^2 = (\hat{n}\vec{\sigma})^2 = (n_x X + n_y Y + n_z Z)^2 = \begin{bmatrix} n_z & n_x - in_y \\ n_x + in_y & -n_z \end{bmatrix}^2$$

$$= \begin{bmatrix} n_x^2 + n_y^2 + n_z^2 & 0 \\ 0 & n_x^2 + n_y^2 + n_z^2 \end{bmatrix}$$

We are given \hat{n} is a unit vector $\implies n_x^2 + n_y^2 + n_z^2 = 1$

$$A^2 = I$$

From Exercise 1.4, we know $e^{iAx} = \cos(x)I + i\sin(x)A$ and using $A^2 = I$

$$A = \hat{n}\vec{\sigma} \text{ and } x = -\theta/2 \text{ so}$$

$$R_{\hat{n}}(\theta) = \cos(\theta/2) - i\sin(\theta/2)\hat{n}\vec{\sigma}$$

$$\implies \cos(\frac{\theta}{2}) - i\sin(\frac{\theta}{2})(n_x X + n_y Y + n_z Z)$$

1.6 Exercise-Block Sphere Interpretation of Rotations

 $R_{\hat{n}}(\theta)$ operators are referred to as rotation operators is the following fact, which you are to prove. Suppose a single qubit has a state represented by the Block vector $\overrightarrow{\lambda}$. Then the effect of the rotation $R_{\hat{n}}(\theta)$ on the state is to rotate it by an angle θ about the \hat{n} axis of the Block sphere. This fact explains the rather mysterious looking factor of two in the definition of the rotation matrices.

1.7 Exercise

Show that XYX = -Y and use this to prove that $XR_y(\theta)X = R_y(-\theta)$

Solution

$$\begin{split} XYX &= \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & i \\ -i & 0 \end{bmatrix} = -Y \\ XR_y(\theta)X &= \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \cos\left(\frac{\theta}{2}\right) & -\sin\left(\frac{\theta}{2}\right) \\ \sin\left(\frac{\theta}{2}\right) & \cos\left(\frac{\theta}{2}\right) \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} &= \begin{bmatrix} -\sin\left(\frac{\theta}{2}\right) & \cos\left(\frac{\theta}{2}\right) \\ \cos\left(\frac{\theta}{2}\right) & \sin\left(\frac{\theta}{2}\right) \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} &= \begin{bmatrix} \cos\left(\frac{\theta}{2}\right) & \sin\left(\frac{\theta}{2}\right) \\ -\sin\left(\frac{\theta}{2}\right) & \cos\left(\frac{\theta}{2}\right) \end{bmatrix} = R_y(-\theta) \end{split}$$

1.8 Exercise

An arbitrary single qubit unitary operator can be written in the form

$$U = e^{\alpha i} R_{\hat{n}}(\theta)$$

for some $\alpha, \theta \in \mathbb{R}$ and a three-dimensional unit vector \hat{n} .

- 1. Prove this fact
- 2. Find values for α , θ , and \hat{n} giving the Hadamard gate H.

3. Find values for α , θ , and \hat{n} giving the phase gate

$$S = \begin{bmatrix} 1 & 0 \\ 0 & i \end{bmatrix}.$$

Solution

1. A operator will be unitary if $U^{\dagger}U = I$ holds.

$$U = \cos(\theta/2)I - i\sin(\theta/2)A$$

and

$$U^{\dagger} = \cos(\theta/2)I + i\sin(\theta/2)A^{\dagger}$$

where

$$A = (\hat{n}, \vec{\sigma}) = (n_x X + n_y Y + n_z Z)$$

Then

$$U^{\dagger}U = \cos^2{(\theta/2)}I + \sin^2{(\theta/2)}A^{\dagger}A$$

From Exercise 5, we know $A = A^{\dagger} \implies A^{\dagger}A = I$

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$$U^{\dagger}U = I(\cos^2(\theta/2) + \sin^2(\theta/2)) = I$$

1.9 Exercise

1.10 Exercise

1.11 Exercise

1.12 Exercise

1.13 Exercise

1.14 Exercise

1.15 Exercise

1.16 Exercise

1.17 Exercise

Construct a CNOT gate from one controlled-Z gate and two Hadamard gates, where

$$Z = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

Solution

1.18 Exercise

Show that

Solution