

30-Day FreeRTOS Course for ESP32 Using ESP-IDF

(Day 4)

“Creating and
Deleting Tasks”





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1. Overview

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On Day 4, you'll learn:

- How to **create tasks** in FreeRTOS using ESP-IDF
- Understanding task creation parameters
- How to get and use **task handles**
- How to **delete tasks** safely
- Best practices for task lifecycle management
- Practical examples

By the end of this lesson, you'll be able to start and stop tasks cleanly in your ESP32 applications.



2. Tasks in FreeRTOS

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A task in FreeRTOS is a lightweight thread of execution that runs independently. Each task has:

- Its own **stack**
- Its own **priority**
- A unique **function** that defines what it does
- An optional **handle** to control it

FreeRTOS multitasks using preemptive scheduling, meaning multiple tasks share CPU time according to their priority.



3. Creating Tasks

3. Creating Tasks

The standard API to create a task is:

```
1 BaseType_t xTaskCreate(  
2     TaskFunction_t pvTaskCode,    // Task function  
3     const char * const pcName,    // Task name (for debugging)  
4     const uint32_t usStackDepth,  // Stack size in words  
5     void *pvParameters,          // Parameters passed to the task  
6     UBaseType_t uxPriority,       // Task priority  
7     TaskHandle_t *pxCreatedTask  // Pointer to task handle  
8 );
```

Parameters Explained:

Parameter	Description
pvTaskCode	Pointer to the function that implements the task.
pcName	A human-readable name (appears in debugging tools).
usStackDepth	Stack size in words , not bytes (e.g., 2048 means 2048×4 bytes on ESP32).
pvParameters	Pointer to data passed to the task (can be NULL).
uxPriority	Task priority (0 = lowest).
pxCreatedTask	Returns a task handle (optional).

3. Creating Tasks

Returns:

- `pdPASS` if task creation succeeded
- `errCOULD_NOT_ALLOCATE_REQUIRED_MEMORY` if not enough memory



4. Deleting Tasks

4. Deleting Tasks

Tasks can delete themselves or be deleted by another task.

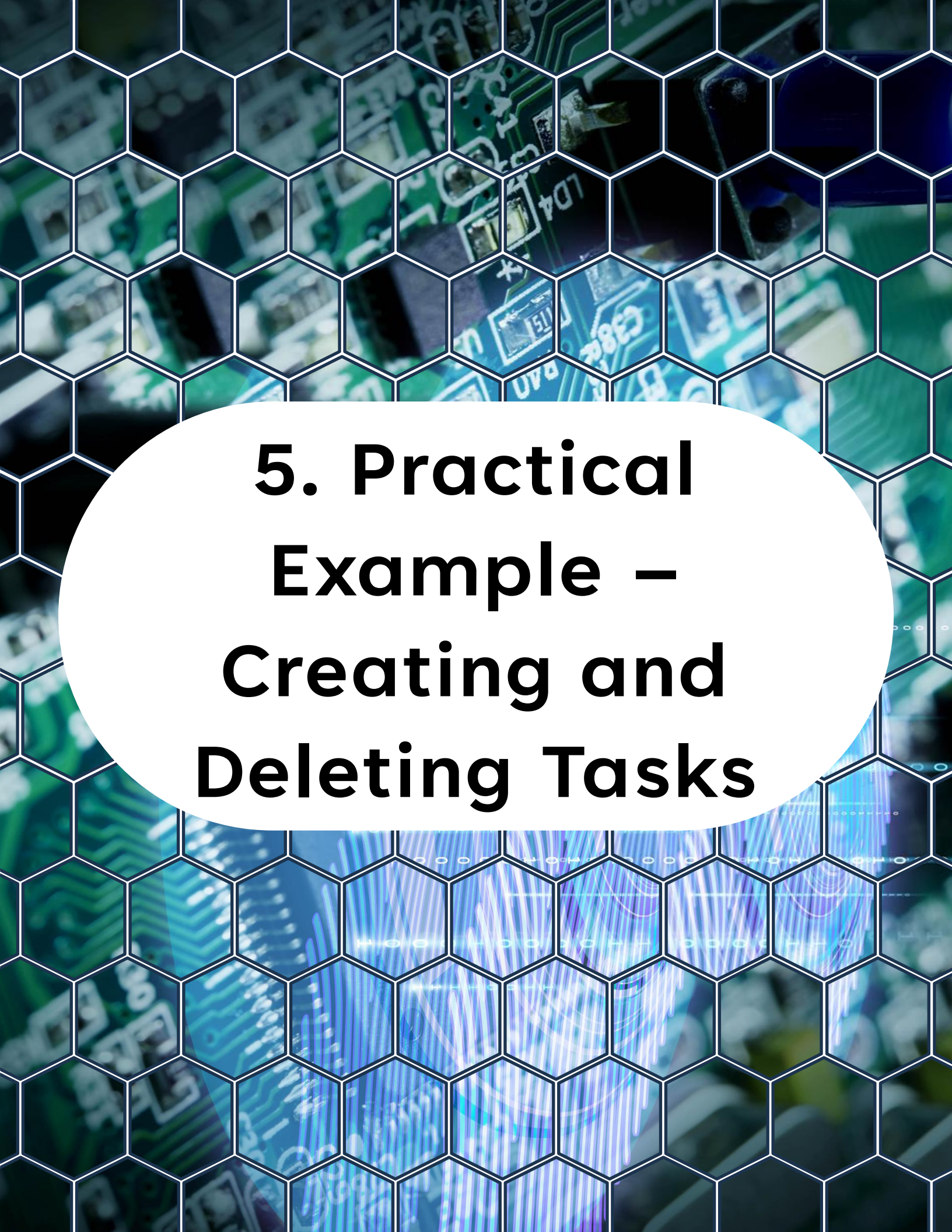
API:

```
1 void vTaskDelete(TaskHandle_t xTaskToDelete);
```

- Pass `NULL` to delete the **calling task** (self-delete).
- Pass a valid task handle to delete another task.

Important:

Deleting a task **does not free heap memory automatically**. The memory is reclaimed by FreeRTOS when the task is deleted.



5. Practical Example – Creating and Deleting Tasks

5. Practical Example – Creating and Deleting Tasks

Code Example



```
1  #include <stdio.h>
2  #include "freertos/FreeRTOS.h"
3  #include "freertos/task.h"
4
5  TaskHandle_t task_handle_hello = NULL;
6
7  void hello_task(void *pvParameters) {
8      int counter = 0;
9      while (1) {
10         printf("Hello Task running, counter = %d\n", counter++);
11         vTaskDelay(pdMS_TO_TICKS(1000));
12         if (counter >= 5) {
13             printf("Hello Task deleting itself...\n");
14             vTaskDelete(NULL); // Delete self
15         }
16     }
17 }
18
19 void control_task(void *pvParameters) {
20     printf("Control Task running...\n");
21     vTaskDelay(pdMS_TO_TICKS(3000));
22     if (task_handle_hello != NULL) {
23         printf("Control Task deleting Hello Task...\n");
24         vTaskDelete(task_handle_hello); // Delete other task
25     }
26     vTaskDelete(NULL);
27 }
28
29 void app_main() {
30     // Create Hello Task
31     xTaskCreate(
32         hello_task,           // Task function
33         "Hello Task",        // Name
34         2048,                 // Stack size (words)
35         NULL,                 // Parameters
```


5. Practical Example – Creating and Deleting Tasks

```
31 xTaskCreate(  
32     hello_task,          // Task function  
33     "Hello Task",        // Name  
34     2048,                // Stack size (words)  
35     NULL,                // Parameters  
36     5,                   // Priority  
37     &task_handle_hello // Handle  
38 );  
39  
40 // Create Control Task  
41 xTaskCreate(  
42     control_task,  
43     "Control Task",  
44     2048,  
45     NULL,  
46     4,  
47     NULL  
48 );  
49 }
```

Expected Output:

Hello Task running, counter = 0

Control Task running...

Hello Task running, counter = 1

Hello Task running, counter = 2

Control Task deleting Hello Task...

Hello Task running, counter = 3



6. Best Practices for Task Creation & Deletion

6. Best Practices for Task Creation & Deletion



Always check return values from

`xTaskCreate()`



Keep stack sizes minimal but sufficient (use

`uxTaskGetStackHighWaterMark()` to measure)



Avoid frequent creation/deletion – it can

fragment memory



Prefer reusing tasks by

suspending/resuming rather than deleting when possible



Avoid deleting system tasks like the idle

task or timer service task



7. Summary

7. Summary

- **Task creation** uses `xTaskCreate()` or `xTaskCreatePinnedToCore()`
- **Task deletion** uses `vTaskDelete()` with a handle or `NULL` for self-deletion
- **Task handles** let you control tasks after creation
- Clean lifecycle management prevents memory leaks and undefined behavior



8. Challenge for Today

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Create two tasks:

- **Blink Task** – blinks an LED every 500 ms, self-deletes after 10 blinks
- **Manager Task** – deletes the Blink Task after 5 seconds if still running

Observe how task deletion behaves in the monitor output.