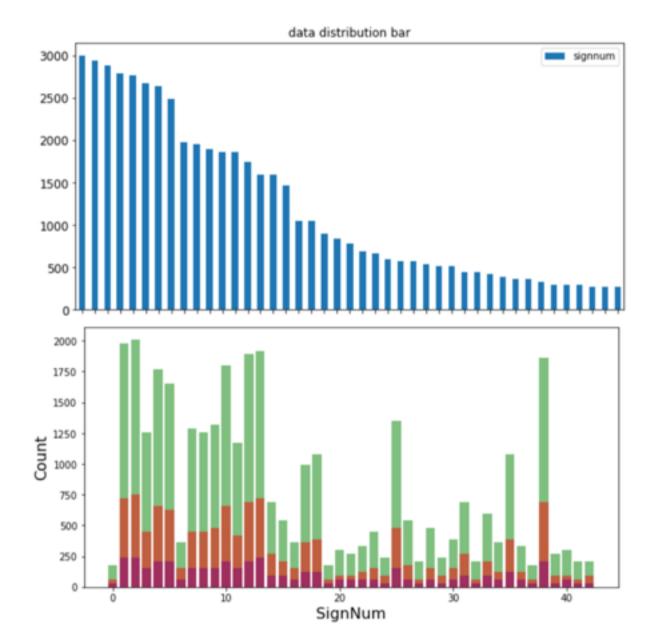
# **Traffic Sign Classifier**

#### 1. Dataset Summary

Training Set: 34799 samples Validation Set: 4410 samples Test Set: 12630 samples Dataset shape is (32,32,3)

## 2. Exploratory Visualization

Use pandas to summary the dataset:



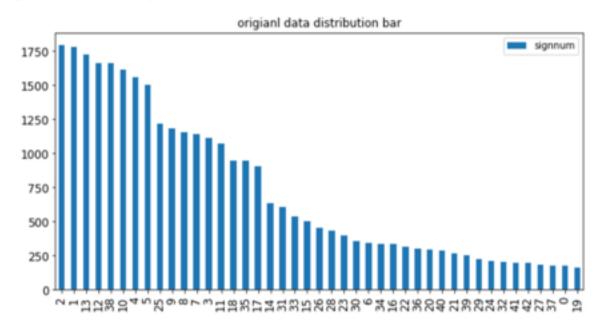
Summary: The training validation and test data is kind of has very similar distribution on different traffic sign, but the overall dataset is un-balanced, 50km/h traffic sign get 3000 samples, while 20km/h get only 500 below.

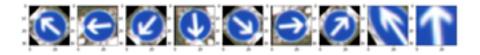
Later I found out the sign that has less sample is more likely to be predict as result, it make sense since it has less feature to match with since it has data sample to capture the feature from.

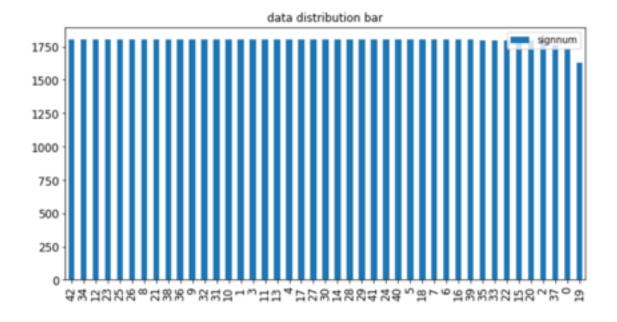
## 3. Augment the training data

rotation,
translation
zoom
flips
color perturbation

#### (31367, 32, 32, 3)







The translation process like perspective, affine method, I use the same method for all picture and rotate 8 times for every picture which is not suitable for some picture, like the one which rotation has real meaning, and I got validation accuracy and test accuracy drop a little bit by augment training data.

```
grayscale, normalize
```

0.971(validation accuracy)

0.904(test accuracy)

0(accuracy on real image)

#### augment, no normalize

0.941

0.846

0.231

## No augment, normalize

0.956

0.873

0.154

augment, normalize

0.965

0.857

0.231

## Summary:

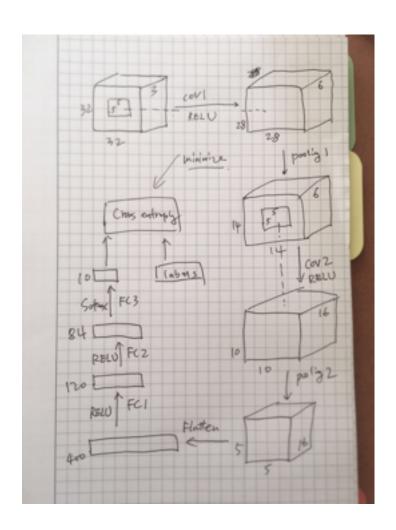
Grayscale help to increase the validation and test accuracy, but not on real accuracy, it overfit on the dataset.

Augment really help the real accuracy.

Normalize help at least not do harm in any situation

#### 4. Model Architecture

2 conv, 2 polling, 3 fully-connected, 1 flatten and several activation node



#### 5. Model Training

```
logits = MyNet(x)
cross_entropy =
tf.nn.softmax_cross_entropy_with_logits(labels=one_hot_y, logits=logits)
loss_operation = tf.reduce_mean(cross_entropy)
optimizer = tf.train.AdamOptimizer(learning_rate = rate)
training_operation = optimizer.minimize(loss_operation)
```

#### 6. Solution Approach

Use Adam optimizer to minimize the cross entropy between predict and real labels of the label, and run 10 epoch with 128 as batch size and 0.001 as learning rate.

7. Acquiring New Images
Download 12 image from website.

#### 8. Performance on New Image

Test Accuracy = 0.385

Place to improvement: the color space and the photo clarity is quite different comping with dataset and real image, this could cause some error. Sometime the background and also perspective angle from the real image can give the model a hard time. and can we add more layer so the model can recognize more feature?

## 9. Model Certainty - Softmax Probabilities

