

# CG Lab 7

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1. Write programs for designing simple animations using 2D transformation Concepts.

- Circle moving from left to right and vice versa
- Wind mill rotation
- Man walking
- Simple animation of football goal

**q1a:**

```
#include <GL/glut.h>
#include <bits/stdc++.h>
#include <iostream>
#include <math.h>
#include <unordered_map>
#include <vector>

using namespace std;

#define PI 3.14159265
double tx = -80;
bool flag = false; // right to left => false ; left to right => true
double radius = 15;

void put_pixel(double x, double y) { glVertex2d(x, y); }

void drawCircle(double xMiddle) {
    double yMiddle = 0;
    float pi = PI;
    glPointSize(1.0);
    glBegin(GL_POINTS);

    for (float i = 0.0; i <= 2 * pi; i += 0.05)
        put_pixel(xMiddle + (sin(i) * radius), yMiddle + (cos(i) * radius));

    glEnd();
}

void timer(int id) {
    if (tx >= 80)
```

```

    flag = true;
    if (tx <= -80)
        flag = false;

    if (!flag) {
        tx += 32;
        flag = false;

    } else {
        tx -= 32;
        flag = true;
    }
    glutPostRedisplay();
}

void display() {
    glClear(GL_COLOR_BUFFER_BIT);
    glLoadIdentity();
    glPointSize(3.0);

    drawCircle(tx + 15);

    glutTimerFunc(1000, timer, 1);

    glFlush();
}

void reshape(int w, int h) {
    glViewport(0, 0, w, h);
    glMatrixMode(GL_PROJECTION);
    glLoadIdentity();

    gluOrtho2D(-100, 100, -100, 100);

    glMatrixMode(GL_MODELVIEW);
    glLoadIdentity();
}

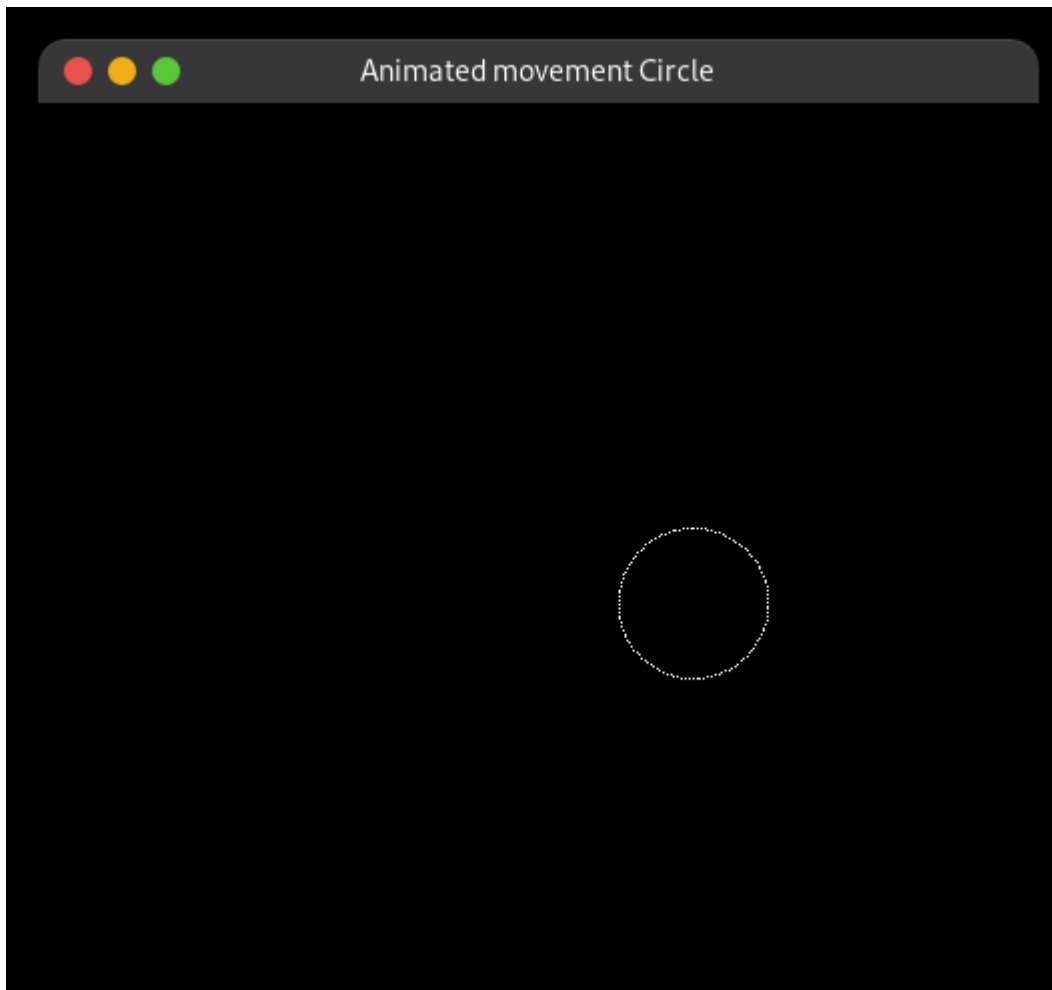
void init(void) { glClearColor(0, 0, 0, 0); }

int main(int argc, char **argv) {

    glutInit(&argc, argv);
    glutInitWindowPosition(200, 100);
    glutInitWindowSize(500, 500);
    glutInitDisplayMode(GLUT_RGB);

```

```
glutCreateWindow("Animated movement Circle");  
init();  
glutDisplayFunc(display);  
glutReshapeFunc(reshape);  
glutMainLoop();  
}
```



q1b:

```
#include <GL/glut.h>
#include <bits/stdc++.h>
#include <iostream>
#include <math.h>
#include <unordered_map>
#include <vector>

using namespace std;

#define PI 3.14159265
double degree = 0;

void put_pixel(double x, double y) { glVertex2d(x, y); }

vector<vector<double>> multiplyMatrix(vector<vector<double>> a,
                                     vector<vector<double>> b) {
    vector<vector<double>> resMatrix(3, vector<double>(3, 0));
    for (int i = 0; i < 3; ++i) {
        for (int j = 0; j < 3; ++j) {
            for (int k = 0; k < 3; ++k) {
                resMatrix[i][j] += a[i][k] * b[k][j];
            }
        }
    }
    return resMatrix;
}

vector<vector<double>> set_rotate_matrix(double degree) {
    vector<vector<double>> rMatrix{
        {cos(degree * PI / 180), sin(degree * PI / 180), 0},
        {sin(-1 * degree * PI / 180), cos(degree * PI / 180), 0},
        {0, 0, 1}};
    return rMatrix;
}

void drawBladeOne() {
    vector<vector<double>> points = {{-40, -30, 1}, {0, 0, 1}, {-38, -40, 1}};
    vector<vector<double>> outputMatrix = set_rotate_matrix(degree);
    points = multiplyMatrix(points, outputMatrix);

    glBegin(GL_TRIANGLES);

    for (vector<double> point : points)
```

```

    put_pixel(point[0], point[1]);
    glEnd();
}

void drawBladeTwo() {
    vector<vector<double>> points = {
        {40, -30, 1},
        {0, 0, 1},
        {38, -40, 1},
    };

    vector<vector<double>> outputMatrix = set_rotate_matrix(degree);
    points = multiplyMatrix(points, outputMatrix);

    glBegin(GL_TRIANGLES);
    for (vector<double> point : points)
        put_pixel(point[0], point[1]);
    glEnd();
}

void drawBladeThree() {
    vector<vector<double>> points = {{-5, 50, 1}, {0, 0, 1}, {5, 45, 1}};

    vector<vector<double>> outputMatrix = set_rotate_matrix(degree);
    points = multiplyMatrix(points, outputMatrix);

    glBegin(GL_TRIANGLES);
    for (vector<double> point : points)
        put_pixel(point[0], point[1]);
    glEnd();
}

void timer(int id) {
    degree += 30;
    if (degree == 360)
        degree = 0;
    glutPostRedisplay();
}

void display() {
    glClear(GL_COLOR_BUFFER_BIT);
    glLoadIdentity();
    glPointSize(3.0);

    drawBladeOne();
    drawBladeTwo();
}

```

```

drawBladeThree();

glBegin(GL_POLYGON);
put_pixel(-1, 0);
put_pixel(1, 0);
put_pixel(1, -70);
put_pixel(-1, -70);
glEnd();

glutTimerFunc(200, timer, 1);

glFlush();
}

void reshape(int w, int h) {
    glViewport(0, 0, w, h);
    glMatrixMode(GL_PROJECTION);
    glLoadIdentity();

    gluOrtho2D(-100, 100, -100, 100);

    glMatrixMode(GL_MODELVIEW);
    glLoadIdentity();
}

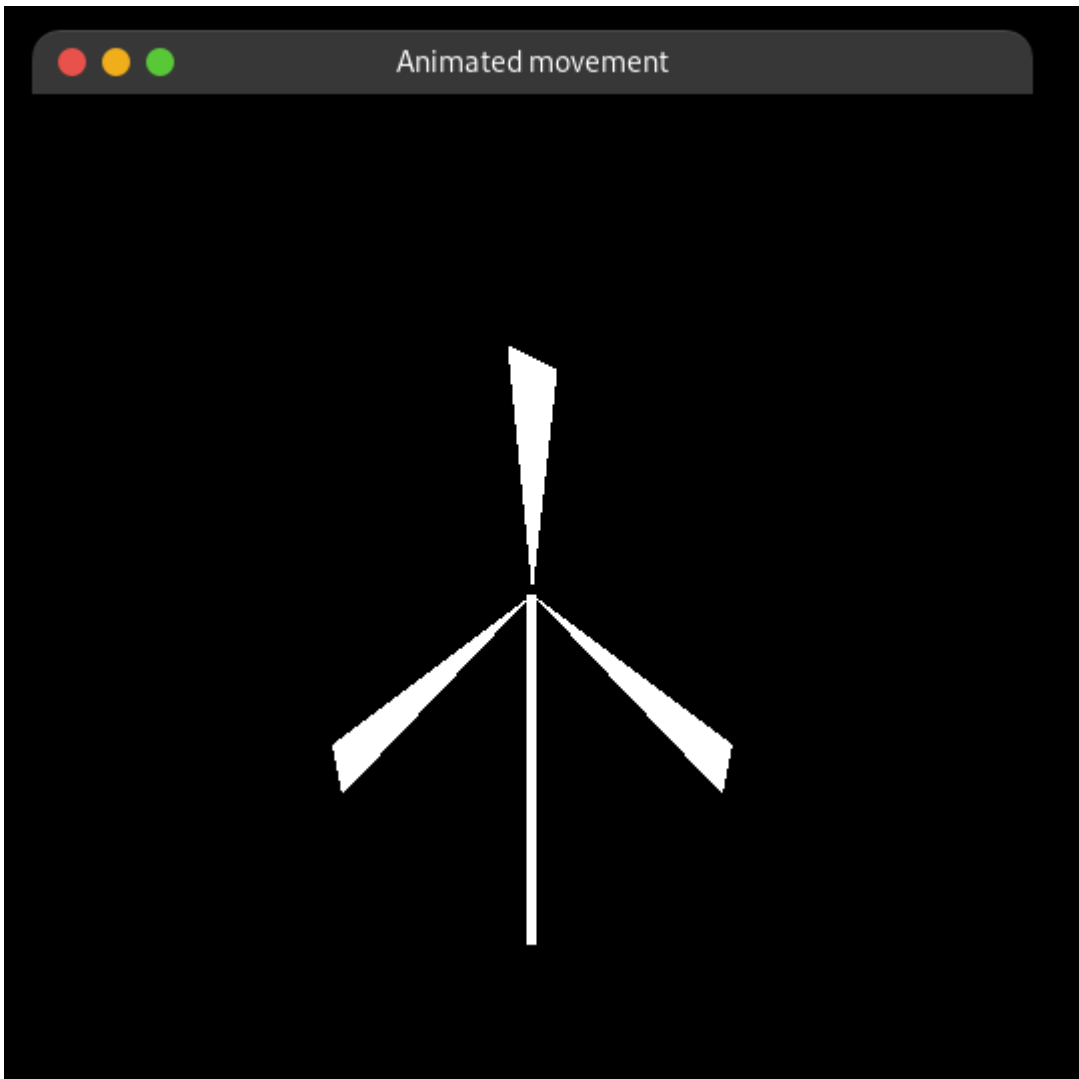
void init(void) { glClearColor(0, 0, 0, 0); }

int main(int argc, char **argv) {

    glutInit(&argc, argv);
    glutInitWindowPosition(200, 100);
    glutInitWindowSize(500, 500);
    glutInitDisplayMode(GLUT_RGB);

    glutCreateWindow("Animated movement");
    init();
    glutDisplayFunc(display);
    glutReshapeFunc(reshape);
    glutMainLoop();
}

```



q1c:

```
#include <GL/glut.h>
#include <bits/stdc++.h>
#include <iostream>
#include <math.h>
#include <unordered_map>
#include <vector>

using namespace std;

#define PI 3.14159265
double degree = 53.2;
double txCenter = -60;

vector<vector<double>> leftLegPoints = {{-60, 0, 1}, {-65, -10, 1}};

vector<vector<double>> leftHandPoints = {{-60, 12, 1}, {-65, 2, 1}};

vector<vector<double>> rightLegPoints = {{-60, 0, 1}, {-55, -10, 1}};

vector<vector<double>> rightHandPoints = {{-60, 12, 1}, {-55, 2, 1}};

bool leftLegBack = true; // assumption: Left leg back, right leg front initially

void put_pixel(float r, float g, float b, double x, double y) {
    glColor3f(r, g, b);
    glVertex2d(x, y);
}

/*
Flow:
1. Back leg (bl) rotates by 53.2 and coincides with front leg(fl) about the txCenter point
2. Translate the bl forward by 10 units in the x-axis
3. Rotate the fl in clockwise direction by 53.2 about its own point
4. We update the new txCenter to txCenter + 10, fl becomes bl and bl becomes fl
5. We repeat step 1-4 till txCenter < 90
*/

vector<vector<double>> multiplyMatrix(vector<vector<double>> a,
                                     vector<vector<double>> b) {
    vector<vector<double>> resMatrix(a.size(), vector<double>(3, 0));
```



```

    for (int i = 0; i < a.size(); ++i) {
        for (int j = 0; j < 3; ++j) {
            for (int k = 0; k < 3; ++k) {
                resMatrix[i][j] += a[i][k] * b[k][j];
            }
        }
    }
    return resMatrix;
}

vector<vector<double>> set_translation_matrix(int dx, int dy) {
    vector<vector<double>> tMatrix{
        {1, 0, 0}, {0, 1, 0}, {(double)dx, (double)dy, 1}};
    return tMatrix;
}

vector<vector<double>> set_rotate_matrix(double degree) {
    vector<vector<double>> rMatrix{
        {cos(degree * PI / 180), sin(degree * PI / 180), 0},
        {sin(-1 * degree * PI / 180), cos(degree * PI / 180), 0},
        {0, 0, 1}};
    return rMatrix;
}

vector<vector<double>> set_rotate_point_matrix(double degree, int px,
int py) {
    // T(-px, -py).R(degree).T(px, py)
    vector<vector<double>> rPointMatrix(3, vector<double>(3, 0));
    rPointMatrix = multiplyMatrix(set_translation_matrix(-1 * px, -1 *
py),
                                set_rotate_matrix(degree));
    rPointMatrix = multiplyMatrix(rPointMatrix, set_translation_matrix(px,
py));
    return rPointMatrix;
}

void walk() {
    vector<vector<double>> step1Matrix =
        set_rotate_point_matrix(degree, txCenter, 0);
    vector<vector<double>> step2Matrix = set_translation_matrix(10, 0);
    vector<vector<double>> step3MatrixLeg =
        set_rotate_point_matrix(-1 * degree, txCenter + 5, -10);

    if (leftLegBack) {
        leftLegPoints = multiplyMatrix(leftLegPoints, step1Matrix);
    }
}

```

```

    leftLegPoints = multiplyMatrix(leftLegPoints, step2Matrix);
    rightLegPoints = multiplyMatrix(rightLegPoints, step3MatrixLeg);

    leftLegBack = false;
} else {
    rightLegPoints = multiplyMatrix(rightLegPoints, step1Matrix);
    rightLegPoints = multiplyMatrix(rightLegPoints, step2Matrix);
    leftLegPoints = multiplyMatrix(leftLegPoints, step3MatrixLeg);

    leftLegBack = true;
}

txCenter += 10;
vector<vector<double>> step4Matrix = set_translation_matrix(0, 12);
leftHandPoints = multiplyMatrix(leftLegPoints, step4Matrix);
rightHandPoints = multiplyMatrix(rightLegPoints, step4Matrix);
}

void drawLegs() {
    // left leg
    glBegin(GL_LINES);

    for (auto point : leftLegPoints)
        put_pixel(0, 1, 1, point[0], point[1]);
    glEnd();

    // right leg
    glBegin(GL_LINES);
    for (auto point : rightLegPoints)
        put_pixel(1, 0, 1, point[0], point[1]);
    glEnd();
}

void drawHands() {
    // left hand
    glBegin(GL_LINES);

    for (auto point : leftHandPoints)
        put_pixel(0, 1, 1, point[0], point[1]);
    glEnd();

    // right hand
    glBegin(GL_LINES);
    for (auto point : rightHandPoints)
        put_pixel(1, 0, 1, point[0], point[1]);
    glEnd();
}

```

```

}

void drawCircle(double xMiddle) {
    double yMiddle = 19;
    float pi = PI;
    glPointSize(3.0);
    glBegin(GL_POINTS);

    for (float i = 0.0; i <= 2 * pi; i += 0.05)
        put_pixel(1, 1, 1, xMiddle + (sin(i) * 4), yMiddle + (cos(i) * 4));

    glEnd();
}

void timer(int id) {
    if (txCenter <= 75)
        walk();
    glutPostRedisplay();
}

void display() {
    glClear(GL_COLOR_BUFFER_BIT);
    glLoadIdentity();
    glPointSize(3.0);
    glLineWidth(3);

    drawLegs();
    drawHands();

    glBegin(GL_LINES);
    put_pixel(1, 1, 1, txCenter, 0);
    put_pixel(1, 1, 1, txCenter, 15);
    glEnd();

    drawCircle(txCenter);

    glutTimerFunc(1000, timer, 1);

    glFlush();
}

void reshape(int w, int h) {
    glViewport(0, 0, w, h);
    glMatrixMode(GL_PROJECTION);
    glLoadIdentity();

```

```
gluOrtho2D(-100, 100, -100, 100);

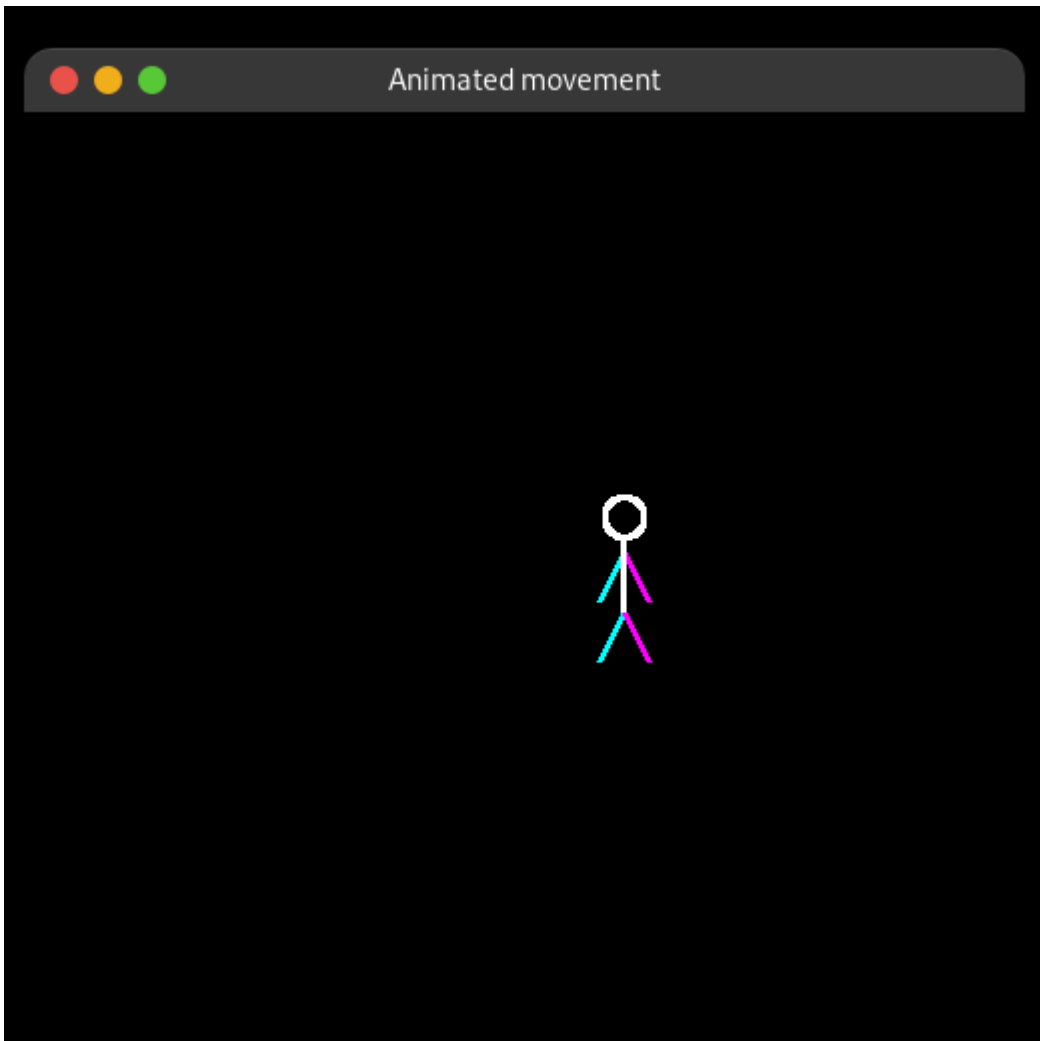
glMatrixMode(GL_MODELVIEW);
glLoadIdentity();
}

void init(void) { glClearColor(0, 0, 0, 0); }

int main(int argc, char **argv) {

    glutInit(&argc, argv);
    glutInitWindowPosition(200, 100);
    glutInitWindowSize(500, 500);
    glutInitDisplayMode(GLUT_RGB);

    glutCreateWindow("Animated movement");
    init();
    glutDisplayFunc(display);
    glutReshapeFunc(reshape);
    glutMainLoop();
}
```



q1d:

```
#include <GL/glut.h>
#include <bits/stdc++.h>
#include <iostream>
#include <math.h>
#include <unordered_map>
#include <vector>

using namespace std;

#define PI 3.14159265
double degree = 45;
double xCoord = -80;
double yCoord = 25;

/*
Flow:
1. Rotate the center of circle about the origin by 45 degree
2. Continue rotating till the y > 0
3. Once, y <= 0 just follow translation in the y axis in the down
direction
4. Continue step 3 till y > -70
5. Once y <= -70, remove the circle
*/

void put_pixel(double x, double y) { glVertex2d(x, y); }

vector<vector<double>> multiplyMatrix(vector<vector<double>> a,
                                     vector<vector<double>> b) {
    vector<vector<double>> resMatrix(a.size(), vector<double>(3, 0));
    for (int i = 0; i < a.size(); ++i) {
        for (int j = 0; j < 3; ++j) {
            for (int k = 0; k < 3; ++k) {
                resMatrix[i][j] += a[i][k] * b[k][j];
            }
        }
    }
    return resMatrix;
}

vector<vector<double>> set_translation_matrix(int dx, int dy) {
    vector<vector<double>> tMatrix{
        {1, 0, 0}, {0, 1, 0}, {(double)dx, (double)dy, 1}};
    return tMatrix;
}
```

```

vector<vector<double>> set_rotate_matrix(double degree) {
    vector<vector<double>> rMatrix{
        {cos(degree * PI / 180), sin(degree * PI / 180), 0},
        {sin(-1 * degree * PI / 180), cos(degree * PI / 180), 0},
        {0, 0, 1}};
    return rMatrix;
}

void drawGoal() {
    glBegin(GL_POLYGON);
    put_pixel(-90, -92);
    put_pixel(90, -92);
    put_pixel(90, -70);
    put_pixel(-90, -70);
    glEnd();
}

void drawBall(double x, double y) {
    double pi = PI;
    float radius = 10;
    glPointSize(3.0);
    glBegin(GL_POINTS);

    for (float i = 0.0; i <= 2 * pi; i += 0.05)
        put_pixel(x + (sin(i) * radius), y + (cos(i) * radius));

    glEnd();
}

void goalAnimation() {
    vector<vector<double>> point = {{xCoord, yCoord, 1}};

    if (yCoord > 0) {
        vector<vector<double>> mat = set_rotate_matrix(-1 * degree);
        point = multiplyMatrix(point, mat);

        xCoord = point[0][0];
        yCoord = point[0][1];
    } else if (yCoord <= 0 && yCoord > -70) {
        vector<vector<double>> mat = set_translation_matrix(0, -10);
        point = multiplyMatrix(point, mat);

        xCoord = point[0][0];
        yCoord = point[0][1];
    } else {

```

```

        xCoord = -80;
        yCoord = 25;
    }
}

void timer(int id) {
    goalAnimation();
    glutPostRedisplay();
}

void display() {
    glClear(GL_COLOR_BUFFER_BIT);
    glLoadIdentity();
    glPointSize(3.0);

    drawBall(xCoord, yCoord);
    drawGoal();

    glutTimerFunc(300, timer, 1);

    glFlush();
}

void reshape(int w, int h) {
    glViewport(0, 0, w, h);
    glMatrixMode(GL_PROJECTION);
    glLoadIdentity();

    gluOrtho2D(-100, 100, -100, 100);

    glMatrixMode(GL_MODELVIEW);
    glLoadIdentity();
}

void init(void) { glClearColor(0, 0, 0, 0); }

int main(int argc, char **argv) {

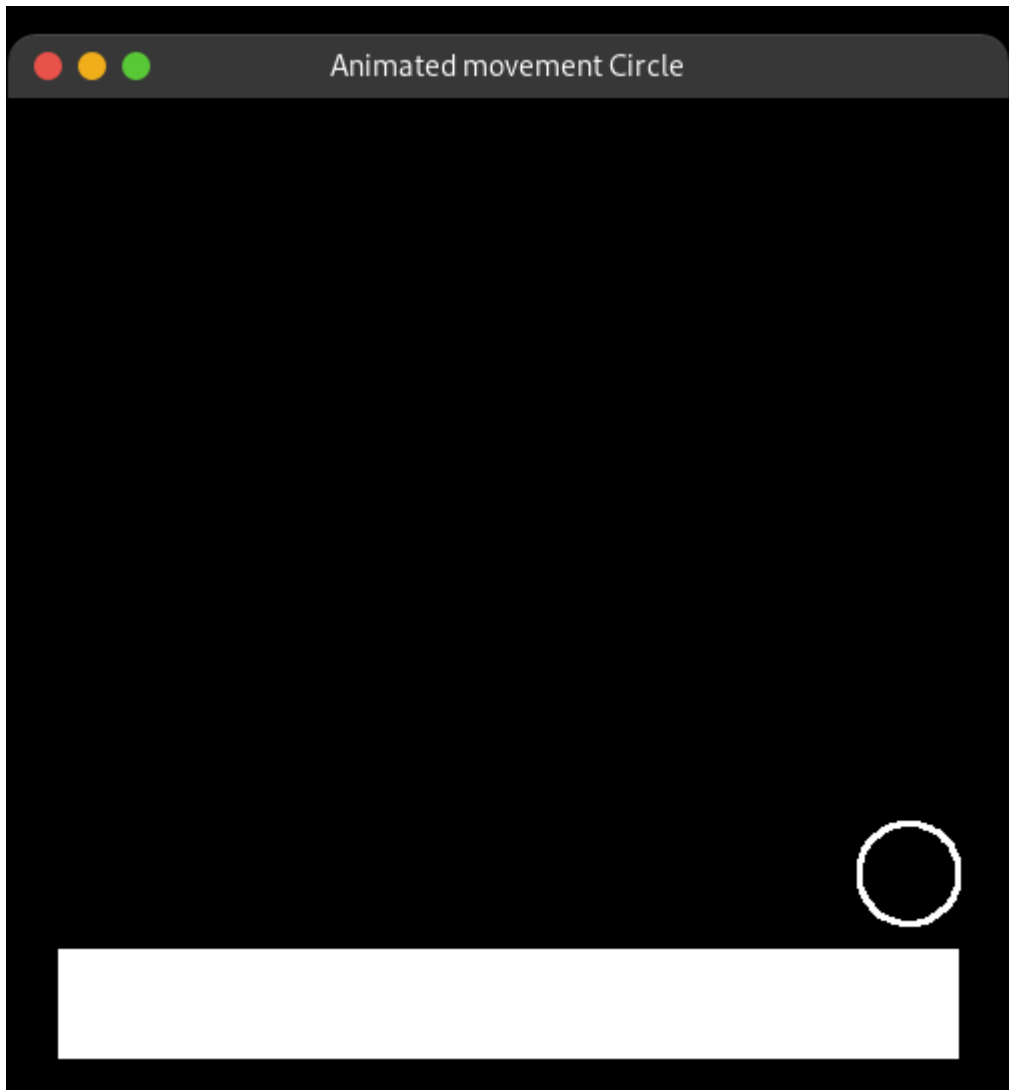
    glutInit(&argc, argv);
    glutInitWindowPosition(200, 100);
    glutInitWindowSize(500, 500);
    glutInitDisplayMode(GLUT_RGB);

    glutCreateWindow("Animated movement Circle");
    init();
    glutDisplayFunc(display);
}

```



```
glutReshapeFunc(reshape);  
glutMainLoop();  
}
```



2. Write a menu driven program to implement set of composite transformations on 3D polygon. Program should include:
- a. Rotation (about arbitrary point, arbitrary axis, arbitrary plane)
  - b. Scaling (fixed point)
  - c. Shearing
  - d. Reflection

Also show all the principle axis and other relevant point and lines necessary in each choice.

```

#include <GL/glut.h>
#include <iostream>
#include <math.h>
#include <stdio.h>
#include <stdlib.h>
#include <unordered_set>
using namespace std;
typedef float Matrix4x4[4][4];
Matrix4x4 theMatrix;
float ptsIni[8][3] = {{80, 80, -100}, {180, 80, -100}, {180, 180,
-100},
                        {80, 180, -100}, {60, 60, 0}, {160, 60, 0},
                        {160, 160, 0}, {60, 160, 0}};
// Realign above line while execution
// Initial Co-ordinates of the Cube to be Transformed
int flag = 0;
float ptsFin[8][3];
float refptX, refptY, refptZ; // Reference points
float TransDistX, TransDistY, TransDistZ; // Translations along Axes
float ScaleX, ScaleY, ScaleZ; // Scaling Factors along Axes
float Alpha, Beta, Gamma, Theta; // Rotation angles about Axes
float A, B, C; // Arbitrary Line Attributes
float aa, bb, cc;
float shx, shy, shz; // Arbitrary Line Attributes
float x1, y1, z1, x2, y2, z2;
int choiceRot, choiceRef, choiceSh;
unordered_set<int> choice;
void matrixSetIdentity(Matrix4x4 m) // Initialises the matrix as Unit
Matrix
{
    int i, j;
    for (i = 0; i < 4; i++)
        for (j = 0; j < 4; j++)
            m[i][j] = (i == j);
}

void matrix_pre_multiply(
    Matrix4x4 a,
    Matrix4x4 b) { // Multiplies matrix a times b, putting result in b
    int i, j;
    Matrix4x4 tmp;
    for (i = 0; i < 4; i++) {
        for (j = 0; j < 4; j++) {
            tmp[i][j] = a[i][0] * b[0][j] + a[i][1] * b[1][j] + a[i][2] *
b[2][j] +
                        a[i][3] * b[3][j];

```

```

    }
}
for (i = 0; i < 4; i++) {
    for (j = 0; j < 4; j++) {
        theMatrix[i][j] = tmp[i][j];
    }
}
}

void translate(int tx, int ty, int tz) {
    Matrix4x4 m;
    matrixSetIdentity(m);
    m[0][3] = tx;
    m[1][3] = ty;
    m[2][3] = tz;
    matrix_pre_multiply(m, theMatrix);
}

void scale(float sx, float sy, float sz) {
    Matrix4x4 m;
    matrixSetIdentity(m);
    m[0][0] = sx;
    m[1][1] = sy;
    m[2][2] = sz;
    matrix_pre_multiply(m, theMatrix);
}

void shearx() {
    Matrix4x4 m;
    matrixSetIdentity(m);
    m[0][1] = shy;
    m[0][2] = shz;
    matrix_pre_multiply(m, theMatrix);
}

void sheary() {
    Matrix4x4 m;
    matrixSetIdentity(m);
    m[1][0] = shx;
    m[1][2] = shz;
    matrix_pre_multiply(m, theMatrix);
}

void shearz() {
    Matrix4x4 m;
    matrixSetIdentity(m);
    m[2][0] = shx;
    m[2][1] = shy;
    matrix_pre_multiply(m, theMatrix);
}

void RotateX(float angle) {

```

```

    Matrix4x4 m;
    matrixSetIdentity(m);
    angle = angle * 22 / 1260;
    m[1][1] = cos(angle);
    m[1][2] = -sin(angle);
    m[2][1] = sin(angle);
    m[2][2] = cos(angle);
    matrix_pre_multiply(m, theMatrix);
}

void RotateY(float angle) {
    Matrix4x4 m;
    matrixSetIdentity(m);
    angle = angle * 22 / 1260;
    m[0][0] = cos(angle);
    m[0][2] = sin(angle);
    m[2][0] = -sin(angle);
    m[2][2] = cos(angle);
    matrix_pre_multiply(m, theMatrix);
}

void RotateZ(float angle) {
    Matrix4x4 m;
    matrixSetIdentity(m);
    angle = angle * 22 / 1260;
    m[0][0] = cos(angle);
    m[0][1] = -sin(angle);
    m[1][0] = sin(angle);
    m[1][1] = cos(angle);
    matrix_pre_multiply(m, theMatrix);
}

void Reflect(void) {
    Matrix4x4 m;
    matrixSetIdentity(m);
    switch (choiceRef) {
    case 1:
        m[2][2] = -1;
        break;
    case 2:
        m[0][0] = -1;
        break;
    case 3:
        m[1][1] = -1;
        break;
    }
    matrix_pre_multiply(m, theMatrix);
}

void DrawRotLine(void) {

```

```

switch (choiceRot) {
case 1:
    glBegin(GL_LINES);
    glVertex3s(-1000, B, C);
    glVertex3s(1000, B, C);
    glEnd();
    break;
case 2:
    glBegin(GL_LINES);
    glVertex3s(A, -1000, C);
    glVertex3s(A, 1000, C);
    glEnd();
    break;
case 3:
    glBegin(GL_LINES);
    glVertex3s(A, B, -1000);
    glVertex3s(A, B, 1000);
    glEnd();
    break;
case 4:
    glBegin(GL_LINES);
    glVertex3s(x1 - aa * 500, y11 - bb * 500, z1 - cc * 500);
    glVertex3s(x2 + aa * 500, y2 + bb * 500, z2 + cc * 500);
    glEnd();
    break;
}
}

void TransformPoints(void) {
    int i, k;
    float tmp;
    for (k = 0; k < 8; k++)
        for (i = 0; i < 3; i++)
            ptsFin[k][i] = theMatrix[i][0] * ptsIni[k][0] +
                           theMatrix[i][1] * ptsIni[k][1] +
                           theMatrix[i][2] * ptsIni[k][2] + theMatrix[i][3];
    // Realign above line while execution
}

void Axes(void) {
    glColor3f(0.0, 0.0, 0.0); // Set the color to BLACK
    glBegin(GL_LINES);      // Plotting X-Axis
    glVertex2s(-1000, 0);
    glVertex2s(1000, 0);
    glEnd();
    glBegin(GL_LINES); // Plotting Y-Axis
    glVertex2s(0, -1000);
    glVertex2s(0, 1000);
}

```

```

    glEnd();
}
void Draw(float a[8][3]) // Display the Figure
{
    int i;
    glColor3f(1.0, 0.5, 1.0);
    glBegin(GL_POLYGON);
    glVertex3f(a[0][0], a[0][1], a[0][2]);
    glVertex3f(a[1][0], a[1][1], a[1][2]);
    glVertex3f(a[2][0], a[2][1], a[2][2]);
    glVertex3f(a[3][0], a[3][1], a[3][2]);
    glEnd();
    i = 0;
    glColor3f(1.0, 0.6, 0.5);
    glBegin(GL_POLYGON);
    glVertex3s(a[0 + i][0], a[0 + i][1], a[0 + i][2]);
    glVertex3s(a[1 + i][0], a[1 + i][1], a[1 + i][2]);
    glVertex3s(a[5 + i][0], a[5 + i][1], a[5 + i][2]);
    glVertex3s(a[4 + i][0], a[4 + i][1], a[4 + i][2]);
    glEnd();
    glColor3f(0.2, 0.4, 1.0);
    glBegin(GL_POLYGON);
    glVertex3f(a[0][0], a[0][1], a[0][2]);
    glVertex3f(a[3][0], a[3][1], a[3][2]);
    glVertex3f(a[7][0], a[7][1], a[7][2]);
    glVertex3f(a[4][0], a[4][1], a[4][2]);
    glEnd();
    i = 1;
    glColor3f(0.5, 0.4, 0.3);
    glBegin(GL_POLYGON);
    glVertex3s(a[0 + i][0], a[0 + i][1], a[0 + i][2]);
    glVertex3s(a[1 + i][0], a[1 + i][1], a[1 + i][2]);
    glVertex3s(a[5 + i][0], a[5 + i][1], a[5 + i][2]);
    glVertex3s(a[4 + i][0], a[4 + i][1], a[4 + i][2]);
    glEnd();
    i = 2;
    glColor3f(0.5, 0.6, 0.2);
    glBegin(GL_POLYGON);
    glVertex3s(a[0 + i][0], a[0 + i][1], a[0 + i][2]);
    glVertex3s(a[1 + i][0], a[1 + i][1], a[1 + i][2]);
    glVertex3s(a[5 + i][0], a[5 + i][1], a[5 + i][2]);
    glVertex3s(a[4 + i][0], a[4 + i][1], a[4 + i][2]);
    glEnd();
    i = 4;
    glColor3f(1.0, 0.3, 0.4);
    glBegin(GL_POLYGON);

```

```

glVertex3f(a[0 + i][0], a[0 + i][1], a[0 + i][2]);
glVertex3f(a[1 + i][0], a[1 + i][1], a[1 + i][2]);
glVertex3f(a[2 + i][0], a[2 + i][1], a[2 + i][2]);
glVertex3f(a[3 + i][0], a[3 + i][1], a[3 + i][2]);
glEnd();
}

void display(void) {
    glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
    Axes();
    glColor3f(1.0, 0.0, 0.0); // Set the color to RED
    Draw(ptsIni);
    matrixSetIdentity(theMatrix);
    if (choice.find(1) != choice.end()) {
        translate(TransDistX, TransDistY, TransDistZ);
    }
    if (choice.find(2) != choice.end()) {
        scale(ScaleX, ScaleY, ScaleZ);
    }
    if (choice.find(3) != choice.end()) {
        switch (choiceRot) {
            case 1:
                DrawRotLine();
                translate(0, -B, -C);
                RotateX(Alpha);
                translate(0, B, C);
                break;
            case 2:
                DrawRotLine();
                translate(-A, 0, -C);
                RotateY(Beta);
                translate(A, 0, C);
                break;
            case 3:
                DrawRotLine();
                translate(-A, -B, 0);
                RotateZ(Gamma);
                translate(A, B, 0);
                break;
            case 4:
                DrawRotLine();
                float MOD = sqrt((x2 - x1) * (x2 - x1) + (y2 - y1) * (y2 - y1) +
                                   (z2 - z1) * (z2 - z1));
                aa = (x2 - x1) / MOD;
                bb = (y2 - y1) / MOD;
                cc = (z2 - z1) / MOD;

```

```

        translate(-x1, -y11, -z1);
        float ThetaDash;
        ThetaDash = 1260 * atan(bb / cc) / 22;
        RotateX(ThetaDash);
        RotateY(1260 * asin(-aa) / 22);
        RotateZ(Theta);
        RotateY(1260 * asin(aa) / 22);
        RotateX(-ThetaDash);
        translate(x1, y11, z1);
        break;
    }
}
if (choice.find(4) != choice.end()) {
    Reflect();
}
if (choice.find(5) != choice.end()) {

    if (choiceSh == 1) {
        shearx();
    } else if (choiceSh == 2) {
        sheary();
    } else {
        shearz();
    }
}
TransformPoints();
Draw(ptsFin);
glFlush();
}
void init(void) {
    glClearColor(0.0, 0.0, 0.0, 0.0);
    // Set the Background color to WHITE
    glOrtho(-454.0, 454.0, -250.0, 250.0, -250.0, 250.0);
    // Set the no. of Co-ordinates along X & Y axes and their gappings
    glEnable(GL_DEPTH_TEST);
    // To Render the surfaces Properly according to their depths
}

int main(int argc, char **argv) {
    while (true) {
        printf("Enter your choice "

"number:\n1.Translation\n2.Scaling\n3.Rotation\n4.Reflection\n5."
        "Shearing\n: ");
        int code;
        cin >> code;

```



```

choice.insert(code);
if (code == 1) {
    printf("Enter Translation along X, Y & Z\n: ");
    scanf("%f%f%f", &TransDistX, &TransDistY, &TransDistZ);
} else if (code == 2) {
    printf("Enter Scaling ratios along X, Y & Z\n: ");
    scanf("%f%f%f", &ScaleX, &ScaleY, &ScaleZ);
} else if (code == 3) {
    printf("Enter your choice for Rotation about axis:\n1.parallel to
"
        "X-axis.(y=B & z=C)\n2.parallel to Y-axis.(x=A &
z=C)\n3.parallel "
        "to Z-axis.(x=A & y=B)\n4.Arbitrary line passing through "
        "(x1,y1,z1) & (x2,y2,z2)\n: ");
    // Realign above line while execution
    scanf("%d", &choiceRot);

    if (choiceRot == 1) {
        printf("Enter B & C: ");
        scanf("%f %f", &B, &C);
        printf("Enter Rot. Angle Alpha: ");
        scanf("%f", &Alpha);
    } else if (choiceRot == 2) {
        printf("Enter A & C: ");
        scanf("%f %f", &A, &C);
        printf("Enter Rot. Angle Beta: ");
        scanf("%f", &Beta);
    } else if (choiceRot == 3) {
        printf("Enter A & B: ");
        scanf("%f %f", &A, &B);
        printf("Enter Rot. Angle Gamma: ");
        scanf("%f", &Gamma);
    } else if (choiceRot == 4) {
        printf("Enter values of x1 ,y1 & z1:\n");
        scanf("%f %f %f", &x1, &y1, &z1);
        printf("Enter values of x2 ,y2 & z2:\n");
        scanf("%f %f %f", &x2, &y2, &z2);
        printf("Enter Rot. Angle Theta: ");
        scanf("%f", &Theta);
    } else {
        cout << "Invalid option opted.";
    }
}

} else if (code == 4) {
    printf("Enter your choice for reflection about "
        "plane:\n1.X-Y\n2.Y-Z\n3.X-Z\n: ");

```

```

    scanf("%d", &choiceRef);
} else if (code == 5) {
    cout << "Enter your choice\n1.Shear X \n 2.Shear Y\n3.ShearZ\n";
    cin >> choiceSh;
    if (choiceSh == 1) {
        cout << "Enter shy and shz:";
        cin >> shy >> shz;
    } else if (choiceSh == 2) {
        cout << "Enter shx and shz:";
        cin >> shx >> shz;
    } else if (choiceSh == 3) {
        cout << "Enter shx and shy:";
        cin >> shx >> shy;
    } else {
        cout << "Invalid option opted";
    }
} else {
    break;
}
}
glutInit(&argc, argv);
glutInitDisplayMode(GLUT_SINGLE | GLUT_RGB | GLUT_DEPTH);
glutInitWindowSize(1362, 750);
glutInitWindowPosition(0, 0);
glutCreateWindow(" Composite Transformations ");
init();
glutDisplayFunc(display);
glutMainLoop();
return 0;
}

```

```
→ lab-07 git:(master) X ./a.out
Enter your choice number:
1.Translation
2.Scaling
3.Rotation
4.Reflection
5.Shearing
: 1
Enter Translation along X, Y & Z
: 100 10 10
Enter your choice number:
1.Translation
2.Scaling
3.Rotation
4.Reflection
5.Shearing
: 3
Enter your choice for Rotation about axis:
1.parallel to X-axis.(y=B & z=C)
2.parallel to Y-axis.(x=A & z=C)
3.parallel to Z-axis.(x=A & y=B)
4.Arbitrary line passing through (x1,y1,z1) & (x2,y2,z2)
: 1
Enter B & C: 0 0
Enter Rot. Angle Alpha: 78
Enter your choice number:
1.Translation
2.Scaling
3.Rotation
4.Reflection
5.Shearing
: q
```

make n2

Composite Transformations

