

Improved Algorithms for Linear Stochastic Bandits (Abbasi-Yadkori, Pál, and Szepesvári 2011)

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- θ_* is an unknown vector in \mathbb{R}^d , which the player needs to estimate.

Reward and Regret

reward at time t	$E[\sum_{s \leq t} Y_s] = \sum_{s \leq t} \langle X_s, \theta_* \rangle$
optimal strategy	$x_t^* = \arg \max_{x \in D_t} \langle x, \theta_* \rangle$
max possible reward at time t	$\sum_{s \leq t} \langle x_s^*, \theta_* \rangle$
(pseudo-)regret at time t	$R_t = \sum_{s \leq t} \langle x_s^* - X_s, \theta_* \rangle$

Optimism in the Face of Uncertainty (Linearized)

input: decision sets D_t , initial confidence set C_0

loop

$t = 1, 2, 3, \dots$

$(X_t, \tilde{\theta}_t) = \arg \max_{(x, \theta) \in D_t \times C_{t-1}} \langle x, \theta \rangle$

play X_t , **observe** Y_t

update C_t

end loop

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- then

$$C_t = \{\theta \in \mathbb{R}^d \mid \|\theta - \hat{\theta}_t\|_{\bar{V}_t} \leq \epsilon_t\}$$

where

$$\epsilon_t = \sqrt{2 \log\left(\frac{\det(\bar{V}_t)^{\frac{1}{2}} \det(\lambda I)^{-\frac{1}{2}}}{\delta}\right)} + \lambda^{\frac{1}{2}} S$$

Regret bound of the OFUL algorithm

Theorem (Abbasi-Yadkori, Pál, and Szepesvári 2011)

Assume that $\|X_t\| \leq L$ and $\|\theta_\| \leq S$, for some constants $L, S > 0$, and that $\langle x, \theta_* \rangle \in [-1, 1]$ for all $x \in D_t$. Suppose $\lambda \geq 1$. Then with probability at least $1 - \delta$ the OFUL algorithm achieves*

$$R_t \leq 4\sqrt{td \log(\lambda + \frac{tL}{d})}(\sqrt{\lambda}S + \sqrt{2 \log(\frac{1}{\delta}) + d \log(1 + \frac{tL}{\lambda d})})$$

Comparison of Regret Bounds

	Dani et al. 08 ¹	This Work
Linear Bandits	$O\left(d \log(t) \sqrt{t \log(\frac{t}{\delta})}\right)$	$O\left(d \log(t) \sqrt{t} + \sqrt{dt \log(\frac{t}{\delta})}\right)$
d -armed	$O(d \log(t)/\Delta)$	$O(d \log(\frac{1}{\delta})/\Delta)$
Problem Dependent	$O(\frac{d^2}{\Delta} \log(\frac{t}{\delta}) \log^2(t))$	$O(\frac{\log(1/\delta)}{\Delta} (\log(t) + d \log \log(t))^2)$

¹(Dani, Hayes, and Kakade 2008)

A Self-Normalized Bound for Vector-Valued Martingales

Theorem (Abbasi-Yadkori, Pál, and Szepesvári 2011)

Let

- $F_t = \sigma(X_1, \dots, X_{t+1}, \eta_1, \dots, \eta_t)$, so $\{F_t\}_{t=0}^\infty$ is a filtration of σ -algebras
- η_t be 1-sub-Gaussian conditioned on F_{t-1} , with $\mathbb{E}[\eta_t | F_{t-1}] = 0$
- $\bar{V}_t = V_t + \lambda I$, $V_t = \sum_{s=1}^t X_s X_s^\top$ $S_t = \sum_{s=1}^t \eta_s X_s$.

Then, for any $\delta > 0$, with probability at least $1 - \delta$

$$\|S_t\|_{\bar{V}_t^{-1}}^2 \leq 2 \log \left(\frac{\det(\bar{V}_t)^{1/2} \det(\lambda I)^{-1/2}}{\delta} \right)$$

for all $t \geq 0$.

Lemma

In the setting of the theorem, let τ be any stopping time w.r.t $\{F_t\}_{t=0}^\infty$, then for any $\delta > 0$, with probability $1 - \delta$

$$\|S_t\|_{\bar{V}_\tau^{-1}}^2 \leq 2 \log \left(\frac{\det(\bar{V}_\tau)^{1/2} \det(\lambda I)^{-1/2}}{\delta} \right)$$

- $B_t(\delta) = \left\{ w \in \Omega : \|S_t\|_{\bar{V}_t^{-1}}^2 > 2 \log \left(\frac{\det(\bar{V}_t)^{1/2} \det(\lambda I)^{-1/2}}{\delta} \right) \right\}$
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$$\begin{aligned}
 \Pr \left(\bigcup_{t \geq 0} B_t(\delta) \right) &= \Pr(\tau < \infty) \\
 &\leq \Pr \left(\|S_\tau\|_{\bar{V}_\tau^{-1}}^2 > 2 \log \left(\frac{\det(\bar{V}_\tau)^{1/2} \det(\lambda I)^{-1/2}}{\delta} \right) \right) \\
 &\leq \delta
 \end{aligned}$$

Conclusion

- OFUL is a UCB-type algorithm for **linear** bandits, with an $\mathcal{O}(d \log(t) \sqrt{t} + \sqrt{dt \log(\frac{t}{\delta})})$ regret bound.
- Self-normalized martingale bound has many further applications, e.g. to finite-time identification of linear dynamical systems (Sarkar and Rakhlin 2018).

References

- Abbasi-Yadkori, Yasin, Dávid Pál, and Csaba Szepesvári (2011). “Improved Algorithms for Linear Stochastic Bandits”. In: *NIPS*.
- Dani, Varsha, Thomas P. Hayes, and Sham M. Kakade (2008). “Stochastic Linear Optimization under Bandit Feedback”. In: *COLT*.
- Sarkar, Tuhin and Alexander Rakhlin (2018). *Near optimal finite time identification of arbitrary linear dynamical systems*. [arXiv:1812.01251v7 \[cs.LG\]](#).