Large-scale visual recognition Novel patch aggregation mechanisms

Florent Perronnin, XRCE Hervé Jégou, INRIA

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For large-scale visual recognition, we need image signatures which contain **fine-grained information**:

- in retrieval: the larger the dataset size, the higher the probability to find another similar but irrelevant image to a given query
- in classification: the larger the number of other classes, the higher the probability to find a class which is similar to any given class

BOV answer to the problem: increase visual vocabulary size

→ see previous part on scaling visual vocabularies

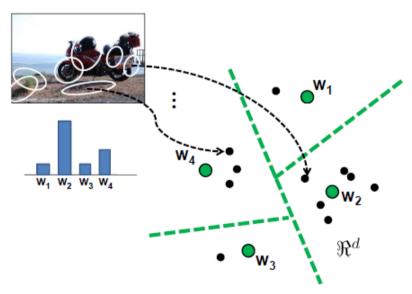
How to increase amount of information without increasing the visual vocabulary size?





BOV is only about **counting** the number of local descriptors assigned to each Voronoi region

Why not including **other statistics**?



http://www.cs.utexas.edu/~grauman/courses/fall2009/papers/bag_of_visual_words.pdf

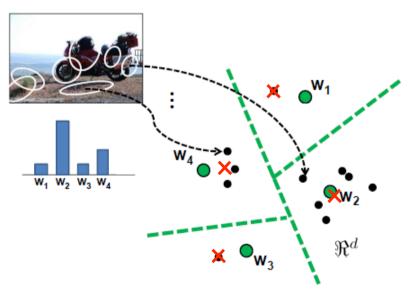




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Why not including **other statistics**? For instance:

mean of local descriptors ×





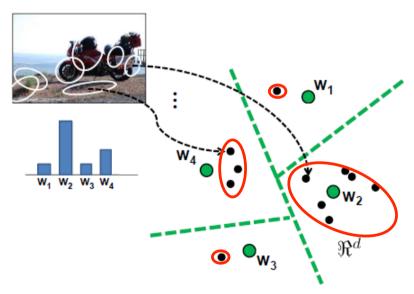




BOV is only about **counting** the number of local descriptors assigned to each Voronoi region

Why not including **other statistics**? For instance:

- mean of local descriptors
- (co)variance of local descriptors



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Outline

A first example: the VLAD

The Fisher Vector

Other higher-order representations

Example results





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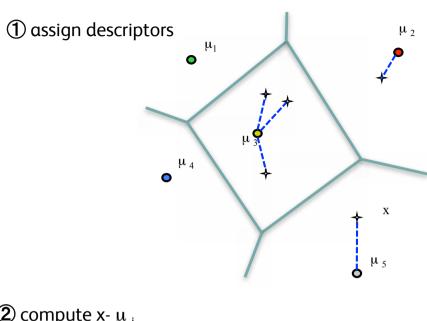


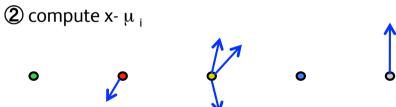


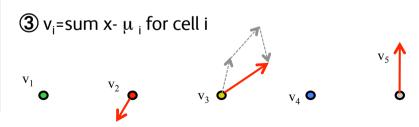
A first example: the VLAD

Given a codebook $\{\mu_i, i=1\dots N\}$, e.g. learned with K-means, and a set of local descriptors $X=\{x_t, t=1\dots T\}$:

- ① assign: $NN(x_t) = \arg\min_{\mu_i} ||x_t \mu_i||$
- ②③ compute: $v_i = \sum_{x_t: NN(x_t) = \mu_i} x_t \mu_i$
- concatenate $\mathbf{v_i}$'s + ℓ_2 normalize







Jégou, Douze, Schmid and Pérez, "Aggregating local descriptors into a compact image representation", CVPR'10.





A first example: the VLAD

A graphical representation of
$$v_i = \sum_{x_t: NN(x_t) = \mu_i} x_t - \mu_i$$



Jégou, Douze, Schmid and Pérez, "Aggregating local descriptors into a compact image representation", CVPR'10.





A first example: the VLAD

But in which sense is the VLAD optimal?

Could we add other (higher-order) statistics?





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Score function

Given a likelihood function u_{λ} with parameters λ , the **score function** of a given sample X is given by:

$$G_{\lambda}^{X} = \nabla_{\lambda} \log u_{\lambda}(X)$$

→ Fixed-length vector whose dimensionality depends only on # parameters.

Intuition: direction in which the parameters λ of the model should we modified to better fit the data.





Fisher information matrix

Fisher information matrix (FIM) or negative Hessian:

$$F_{\lambda} = E_{x \sim u_{\lambda}} \left[\nabla_{\lambda} \log u_{\lambda}(x) \nabla_{\lambda} \log u_{\lambda}(x)' \right]$$

Measure similarity between using the Fisher Kernel (FK):

$$K(X,Y) = G_{\lambda}^{X'} F_{\lambda}^{-1} G_{\lambda}^{Y}$$

Jaakkola and Haussler, "Exploiting generative models in discriminative classifiers", NIPS'98.

→ can be interpreted as a score whitening

As the FIM, is PSD, it can be decomposed as: $F_{\lambda}^{-1} = L_{\lambda}' L_{\lambda}$

and the FK can be rewritten as a dot product between Fisher Vectors (FV):

$$\mathcal{G}_{\lambda}^{X} = L_{\lambda} G_{\lambda}^{X}$$





Application to images

 $X = \{x_t, t = 1 \dots T\}$ is the set of T i.i.d. D-dim local descriptors (e.g. SIFT) extracted from an image:

$$G_{\lambda}^{X} = \frac{1}{T} \sum_{t=1}^{T} \nabla_{\lambda} \log u_{\lambda}(x_{t})$$

→ average pooling is a direct consequence of independence assumption

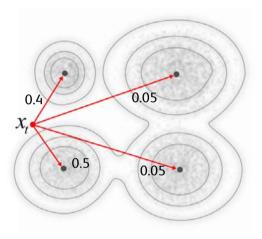
 $u_{\lambda}(x) = \sum_{i=1}^K w_i u_i(x)$ is a Gaussian Mixture Model (GMM) with parameters $\lambda = \{w_i, \mu_i, \Sigma_i, i=1\dots N\}$ trained on a large set of local descriptors \rightarrow a probabilistic **visual vocabulary**





Relationship with the BOV

FV formulas:







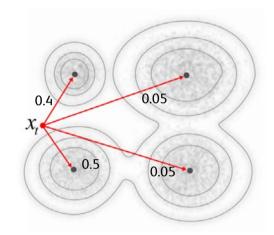
Relationship with the BOV

FV formulas:

gradient wrt to w

$$\approx \frac{1}{T} \sum_{t=1}^{T} \gamma_t(i)$$

→ soft BOV



 $\gamma_t(i)$ = soft-assignment of patch t to Gaussian i





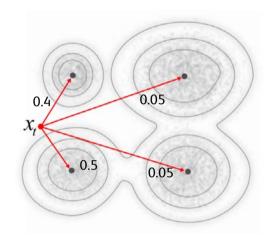
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• gradient wrt to μ and σ

$$\mathcal{G}_{\mu,i}^{X} = \frac{1}{T\sqrt{w_i}} \sum_{t=1}^{T} \gamma_t(i) \left(\frac{x_t - \mu_i}{\sigma_i}\right)$$

$$\mathcal{G}_{\sigma,i}^{X} = \frac{1}{T\sqrt{2w_i}} \sum_{t=1}^{T} \gamma_t(i) \left[\frac{(x_t - \mu_i)^2}{\sigma_i^2} - 1\right]$$

$$\gamma_t(i)$$
 = soft-assignment of patch t to Gaussian i

→ compared to BOV, include **higher-order statistics** (up to order 2)

Let us denote: D = feature dim, N = # Gaussians

- BOV = N-dim
- FV = 2DN-dim





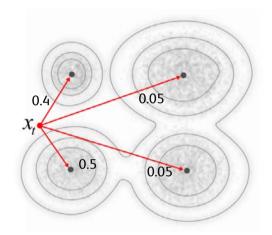
Relationship with the BOV

FV formulas:

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$$\approx \frac{\frac{1}{T} \sum_{t=1}^{T} \gamma_t(i)}{T}$$

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 $\gamma_t(i)$ = soft-assignment of patch t to Gaussian i

- → compared to BOV, include **higher-order statistics** (up to order 2)
- → FV much higher-dim than BOV for a given visual vocabulary size
- → FV much faster to compute than BOV for a given feature dim





Dimensionality reduction on local descriptors

Perform PCA on local descriptors:

- → uncorrelated features are more consistent with diagonal assumption of covariance matrices in GMM
- → FK performs whitening and enhances low-energy (possibly noisy) dimensions

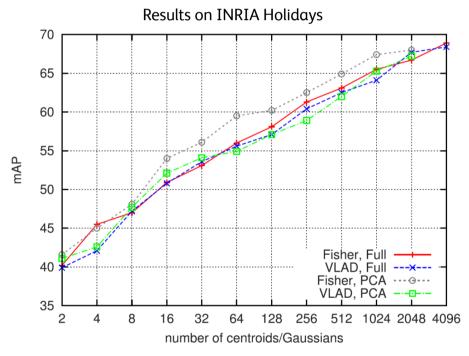




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Normalization: TF-IDF effect

Assuming that the x_t 's are iid drawn from a distribution p, we have:

$$G_{\lambda}^{X} = \frac{1}{T} \sum_{t=1}^{T} \nabla_{\lambda} \log u_{\lambda}(x_{t}) \approx \nabla_{\lambda} E_{x \sim p} \log u_{\lambda}(x) = \nabla_{\lambda} \int_{x} p(x) \log u_{\lambda}(x) dx.$$

If we assume that p is a mixture of image-dependent and image-independent information:

$$p(x) = \omega q(x) + (1 - \omega)u_{\lambda}(x)$$

Then we have:

$$G_{\lambda}^{X} \approx \omega \nabla_{\lambda} \int_{x} q(x) \log u_{\lambda}(x) dx + (1 - \omega) \underbrace{\nabla_{\lambda} \int_{x} u_{\lambda}(x) \log u_{\lambda}(x) dx}_{\approx 0 \text{ (MLE)}}$$

- →The FV depends only (approximately) on image-specific content (**TF-IDF**)
- $ightarrow \ell_2$ normalization removes dependence on ω

Perronnin, Sánchez and Mensink, "Improving the Fisher kernel for large-scale image classification", ECCV'10.





Normalization: variance stabilization

FVs can be (approximately) viewed as emissions of a compound Poisson: a sum of N iid random variables with N~Poisson.

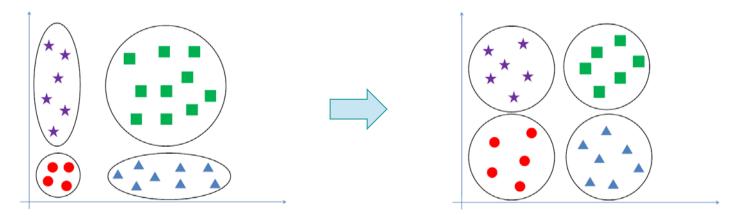
(8) variance depends on mean

Jégou, Perronnin, Douze, Sánchez, Pérez and Schmid, "Aggregating local descriptors into compact codes", TPAMI'11.

→ Variance stabilizing transforms of the form:

$$f(z) = \operatorname{sign}(z)|z|^{\alpha} \text{ with } 0 \le \alpha \le 1$$
 (with α =0.5 by default)

can be used on the FV (or the VLAD).



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→ Reduce impact of bursty visual elements

Jégou, Douze, Schmid, "On the burstiness of visual elements", ICCV'09.





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Other higher-order representations Revisiting the VLAD

But in which sense is the VLAD optimal?

Could we add other (higher-order) statistics?

Jégou, Douze, Schmid and Pérez, "Aggregating local descriptors into a compact image representation", CVPR'10.





Other higher-order representations

Revisiting the VLAD

But in which sense is the VLAD optimal?

- → The VLAD can be viewed as a non-probabilistic version of the FV:
 - gradient with respect to mean only
 - replace GMM clustering by k-means

$$\mathcal{G}_{\mu,i}^{X} = \frac{1}{T\sqrt{w_i}} \sum_{t=1}^{T} \gamma_t(i) \left(\frac{x_t - \mu_i}{\sigma_i} \right) \qquad \Rightarrow \qquad v_i = \sum_{x_t : NN(x_t) = \mu_i} x_t - \mu_i$$

Could we add other (higher-order) statistics?

→ extension of the VLAD to include 2nd order statistics: VLAT

Picard and Gosselin, "Improving image similarity with vectors of locally aggregated tensors", ICIP '11.





Other higher-order representations

Super-Vector (SV) coding

 $f:\mathbb{R}^D o \mathbb{R}$ is Lipschitz smooth if $\forall (x,y) \in \mathbb{R}^D imes \mathbb{R}^D$:

$$|f(x) - f(y) - \nabla f(y)'(x - y)| \le \frac{\beta}{2}||x - y||^2$$

Given a codebook $\{\mu_i, i = 1 \dots N\}$ and a patch x_t we have:

$$f(x_t) \approx f(\mu_i) + \nabla f(\mu_i)'(x_t - \mu_i) = w'\varphi_{SV}(x_t)$$

with
$$\varphi_{SV}(x_t) = \begin{bmatrix} 0, \dots, 0, & \overbrace{s, (x_t - \mu_i)}^{(D+1) \text{ non-zero dim}}, 0, \dots, 0 \end{bmatrix}$$

and
$$w = \left[0, \dots, 0, \frac{f(\mu_i)}{s}, \nabla f(\mu_i), 0, \dots, 0\right]$$
 (to be learned)

Zhou, Yu, Zhang and Huang, "Image classification using super-vector coding of local image descriptors", ECCV'10.





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Average pooling → SV ≈ BOV + VLAD

Bound in Lipschitz smooth inequality provides argument for k-means.

Zhou, Yu, Zhang and Huang, "Image classification using super-vector coding of local image descriptors", ECCV'10. See also: Ladický and Torr, "Locally linear support vector machines", ICML'11.





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Example on Holidays:

Descriptor	K	D	Holidays (mAP)					
			D' = D	ightarrow D'=2048	ightarrow D' =512	ightarrow D'=128	ightarrow D'=64	ightarrow D'=32
BOW	1 000	1 000	40.1		43.5	44.4	43.4	40.8
	20 000	20 000	43.7	41.8	44.9	45.2	44.4	41.8
Fisher (μ)	16	1 024	54.0		54.6	52.3	49.9	46.6
	64	4096	59.5	60.7	61.0	56.5	52.0	48.0
	256	16 384	62.5	62.6	57.0	53.8	50.6	48.6
VLAD	16	1 024	52.0		52.7	52.6	50.5	47.7
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- → second order statistics are not essential for retrieval
- → even for the same feature dim, the FV/VLAD can beat the BOV
- → soft assignment + whitening of FV helps when number of Gaussians ↑
- → after dim-reduction however, the FV and VLAD perform similarly





ExamplesClassification

Example on PASCAL VOC 2007:

From: Chatfield, Lempitsky, Vedaldi and Zisserman, "The devil is in the details: an evaluation of recent feature encoding methods", BMVC'11.

	Feature dim	mAP
VQ	25K	55.30
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 - VQ: plain vanilla BOV
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 - LLC: BOV with sparse coding
- → including 2nd order information is important for classification





Packages

The INRIA package:

http://lear.inrialpes.fr/src/inria_fisher/

The Oxford package (soon to be released):

http://www.robots.ox.ac.uk/~vgg/research/encoding_eval/





Questions?



