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Abstract. Linear time-invariant discrete digital plant, with no restrictions on the form of the state equation and the number of controls, is considered.

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Digital control systems may include both continuous-time and discrete-time signals; here, the latter are in a numerically coded form. The sampled-data control systems and digital control systems are discrete-time any industrial control systems include continuous-time signals, sampled-data signals, and digital signals.

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The controller has been designed in two steps: the first step is to reach the sliding-mode regime

while ensuring inrush current limiting; and the second one is to move the system to the desired operating point. By imposing sliding-mode regime, the equivalent control and the discrete-time large-signal dynamic model of this system are derived.

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Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller (μP), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC) .

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