

Problem Set 8

4A-1

a) $\vec{F} = \langle a, b \rangle$ = constant vectors at each point in vector field

$$\frac{\partial \vec{F}}{\partial x} = \frac{\partial \vec{F}}{\partial y} = \langle 0, 0 \rangle, \text{ is continuous function}$$

$$\vec{F}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\lim_{(x_1, y_1) \rightarrow (x_0, y_0)} \vec{F}(x_1, y_1) = \langle a, b \rangle = \vec{F}(x_0, y_0) \Rightarrow \vec{F} \text{ continuous.}$$

$$\lim_{(x_1, y_1) \rightarrow (x_0, y_0)} \vec{F}'(x_1, y_1) = \langle 0, 0 \rangle = \vec{F}'(x_0, y_0) \Rightarrow \vec{F}' \text{ is continuous.}$$

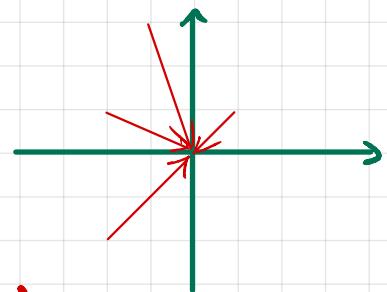
$\Rightarrow \vec{F}$ cont. differentiable in \mathbb{R}^2 .

b) $\vec{F}(x, y) = \langle -x, -y \rangle = -(x, y)$

$$F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$D\vec{F} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \quad \begin{array}{l} \text{continuous partial derivatives} \\ \text{everywhere} \end{array}$$

\Rightarrow continuously differentiable vector field



* Derivative of $\vec{F}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ using limits

$$\vec{p} = \langle x, y \rangle \quad \vec{k} = \langle k_1, k_2 \rangle$$

$$\lim_{\vec{k} \rightarrow \vec{0}} \frac{\vec{F}(\vec{p} + \vec{k}) - \vec{F}(\vec{p}) - D\vec{F}(\vec{p}) \vec{k}}{\|\vec{k}\|} = \lim_{\vec{k} \rightarrow \vec{0}} \frac{\begin{bmatrix} -x+k_1 \\ -y+k_2 \end{bmatrix} - \begin{bmatrix} -x \\ -y \end{bmatrix} - \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \end{bmatrix}}{\sqrt{k_1^2 + k_2^2}}$$

$$\lim_{\vec{k} \rightarrow \vec{0}} \frac{\begin{bmatrix} k_1 + k_1 \\ k_2 + k_2 \end{bmatrix}}{\sqrt{k_1^2 + k_2^2}} = \lim_{\vec{k} \rightarrow \vec{0}} \begin{bmatrix} \frac{zk_1}{\sqrt{k_1^2 + k_2^2}} \\ \frac{zk_2}{\sqrt{k_1^2 + k_2^2}} \end{bmatrix} = \lim_{\vec{k} \rightarrow \vec{0}} \begin{bmatrix} \frac{z}{\sqrt{1 + (k_2/k_1)^2}} \\ \frac{z}{\sqrt{1 + (k_1/k_2)^2}} \end{bmatrix} = \begin{bmatrix} z \\ z \end{bmatrix}$$

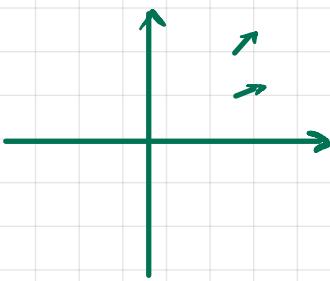
↑
differentiable
for any point (x, y)

$$c) \vec{F} = \left\langle \frac{x}{r}, \frac{y}{r} \right\rangle \cdot \langle g(x,y), h(x,y) \rangle$$

unit vectors pointing outwards radially

$$g(x,y) = \frac{x}{\sqrt{x^2+y^2}}$$

$$g_x = \frac{\sqrt{x^2+y^2} - x \cdot 2x}{2\sqrt{x^2+y^2}} = \frac{x^2+y^2 - x^2}{(x^2+y^2)^{3/2}} = \frac{y^2}{(x^2+y^2)^{3/2}}$$



near $(0,0)$ $\lim_{\vec{r} \rightarrow 0} \frac{y^2}{(x^2+y^2)^{3/2}}$ does not exist. We can check by using two different paths to $(0,0)$ and getting two different results for the limit. With $y=0$, $\lim_{(x,y) \rightarrow (0,0)} = 0$, with $x=0$ we have $\lim_{y \rightarrow 0} y^2/y^3 = \lim_{y \rightarrow 0} 1/y = \infty$

$\Rightarrow \vec{F}$ is not continuously differentiable at $(0,0)$.

Note the other partial derivatives:

$$g_y = \frac{-x \cdot 2y}{2\sqrt{x^2+y^2}} = \frac{-xy}{(x^2+y^2)^{3/2}} \quad h_x = \frac{x^2}{(x^2+y^2)^{3/2}} \quad h_y = \frac{-xy}{(x^2+y^2)^{3/2}}$$

g_x, g_y, h_x, h_y continuous everywhere except $(0,0)$

$\Rightarrow \vec{F}$ cont. diff. everywhere except $(0,0)$.

$$d) \vec{F}(x, y) = \langle y/r, -x/r \rangle = \langle g(x, y), h(x, y) \rangle = \left\langle \frac{y}{\sqrt{x^2+y^2}}, \frac{-x}{\sqrt{x^2+y^2}} \right\rangle$$

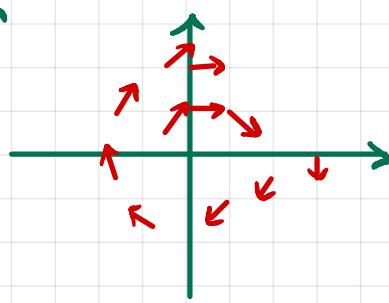
unit vectors tangent to the circle centered at origin passing through (x, y) , clockwise direction.

alternatively, unit position vector rotated 90° clockwise.

$$g_x = \frac{x}{\sqrt{x^2+y^2}} \quad g_y = \frac{-y}{\sqrt{x^2+y^2}}$$

$$h_x = \frac{x}{\sqrt{x^2+y^2}} \quad h_y = \frac{-y}{\sqrt{x^2+y^2}}$$

\Rightarrow cont. diff. \vec{F} except at $(0,0)$



4A-2

$$a) \omega(x, y) = ax + by \quad \vec{\nabla} \omega(x, y) = \langle a, b \rangle$$

$$b) \omega(x, y) = \ln(\sqrt{x^2+y^2}) \quad \vec{\nabla} \omega = \left\langle \frac{1}{\sqrt{x^2+y^2}} \cdot \frac{1}{\cancel{2}\sqrt{x^2+y^2}} \cdot \cancel{2}x, \frac{y}{x^2+y^2} \right\rangle$$

$$= \left\langle \frac{x}{r^2}, \frac{y}{r^2} \right\rangle$$

$$c) \omega(x, y) = f(r)$$

$$\omega_x = \frac{\partial f}{\partial r} \cdot \frac{\partial r}{\partial x} = f'(r) \cdot \frac{1}{2\sqrt{x^2+y^2}} \cdot 2x = f'(r) \cdot \frac{x}{\sqrt{x^2+y^2}}$$

$$\omega_y = f'(r) \cdot \frac{y}{r}$$

$$\vec{\nabla} \omega = \left\langle f'(r) \frac{x}{r}, f'(r) \frac{y}{r} \right\rangle$$

4A-3

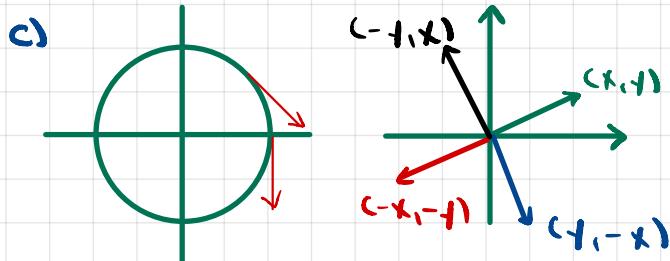
a) $\vec{v} = \langle 1, 2 \rangle \quad \vec{F}(x, y) = \langle 1, 2 \rangle$

b) At (x, y) direction is $\langle -x, -y \rangle$

$$\vec{v} = k \langle -x, -y \rangle$$

$$\Rightarrow \vec{F}(x, y) = \langle -x, -y \rangle$$

$$|\vec{v}| = k \sqrt{x^2 + y^2} = r \cdot \sqrt{x^2 + y^2} \Rightarrow k = \sqrt{x^2 + y^2} = r$$



rotation by 90° clockwise T

$$T(x, y) = \langle y, 0 \rangle = \langle y, -x \rangle$$

\Rightarrow At (x, y) the vector field vector is $\langle y, -x \rangle$

$$|k \langle y, -x \rangle| = \frac{1}{r^2}$$

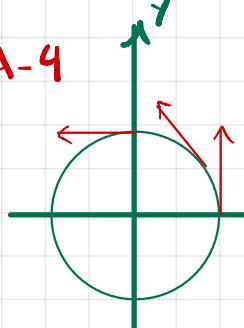
$$k \sqrt{y^2 + x^2} = \frac{1}{r^2} = kr \Rightarrow k = \frac{1}{r^3}$$

$$\Rightarrow \vec{F}(x, y) = \frac{\langle y, -x \rangle}{r^3}$$

d) $\vec{F} = \langle 1, 1 \rangle \cdot \vec{S}(x, y) = \langle S(x, y), S(x, y) \rangle$

$$|\vec{F}| = \sqrt{2} S(x, y)$$

4A-4



rotation counterclockwise 90° $T(\langle x, y \rangle) = \langle -y, x \rangle$

$$\vec{F} = c \langle -y, x \rangle$$

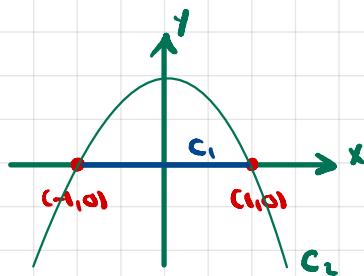
$$|\vec{F}| = cr = \frac{k}{r} \Rightarrow c = \frac{k}{r^2}$$

$$\vec{F} = \frac{k}{r^2} \langle -y, x \rangle$$

$$4B-1 \int_C \vec{F} \cdot d\vec{r} = \int_C \vec{F} \cdot \hat{T} ds$$

a) $\vec{F} = \langle x^2 - y, 2x \rangle$

interpretation



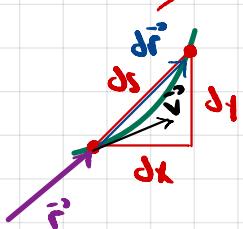
→ we want the work done by the force field \vec{F} on a particle moving from $(-1, 0)$ to $(1, 0)$ along two different paths C_1 and C_2 .
 $\vec{F}(x, y) = \langle F_x(x, y), F_y(x, y) \rangle$ specific point in the subinterval of $t \in [a, b]$

$$\int_C \vec{F} \cdot \hat{T} ds = \lim_{\Delta t \rightarrow 0} \sum_{i=1}^n \vec{F}(x(t_i^*), y(t_i^*)) \cdot \hat{T}(x(t_i^*), y(t_i^*)) \cdot \Delta s; \quad \begin{matrix} \text{force} \\ \text{velocity vector} \end{matrix} \quad \begin{matrix} \text{distance travelled} \\ = \lim_{\Delta t \rightarrow 0} \sum_{i=1}^n \Delta s; \end{matrix}$$

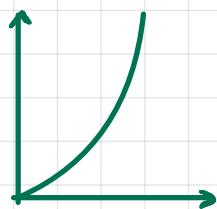
where we partitioned the range of parameter t that parametrizes C .

* what is $d\vec{r}$?

$$\hat{T} ds = \frac{\vec{v}}{\|\vec{v}\|} dt \cdot \frac{d\vec{r}}{dt} \cdot dt$$



$$ds = \sqrt{dx^2 + dy^2} = \sqrt{(\frac{dx}{dt})^2 + (\frac{dy}{dt})^2} \cdot dt = \|\vec{v}\| dt$$



$$\begin{aligned} \vec{r}(t) &= \langle t, t^2 \rangle \\ \vec{v}(t) &= \langle 1, 2t \rangle \\ \hat{T}(t) &= \frac{\langle 1, 2t \rangle}{\sqrt{1+4t^2}} \end{aligned}$$

when we think of ds, dx, dy as infinitesimals then the red ds is \parallel to \vec{v} and its length is distance travelled in dt .

$$d\vec{r} \cdot \hat{T} \cdot ds$$

$$= \frac{\langle 1, 2t \rangle}{\sqrt{1+4t^2}} \cdot \sqrt{1+4t^2} dt$$

$d\vec{r}$ is the change in position vector. Its magnitude ds and direction \hat{T} .

$$= \langle dt, 2t dt \rangle$$

$$\|d\vec{r}\| = \sqrt{dt^2 + 4t^2 dt^2} = \sqrt{1+4t^2} dt = \|\vec{v}(t)\| dt = ds$$

solution $\vec{F} = \langle x^2 - y, 2x \rangle \quad C_1: \vec{r}(t) = \langle -1 + 2t, 0 \rangle \quad \vec{v}(t) = \langle 2, 0 \rangle$

$$\begin{aligned} \int_{C_1} \langle x^2 - y, 2x \rangle \cdot \langle 2, 0 \rangle dt &= \int_0^1 2(-1+2t)^2 dt \cdot \int_0^1 2(4t^2 - 4t + 1) dt \cdot 2 \left[\frac{4t^3}{3} - 2t^2 + t \right] \Big|_0^1 \\ &= 2 \left[\frac{4}{3} - 2 + 1 \right] - 2 \frac{4-6+3}{3} = \frac{2}{3} \end{aligned}$$

Alternatively,

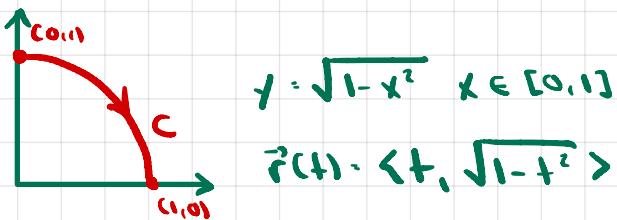
$$\int \langle x^2 - y, 2x \rangle \langle dx/dt, dy/dt \rangle dt = \int_{C_1} (x^2 - y) dx + 2x dy$$

$$y=0 \Rightarrow dy=0 \quad \int_{-1}^1 (x^2 dx + 2x \cdot 0) = \frac{x^3}{3} \Big|_{-1}^1 = \frac{1}{3} - \left(-\frac{1}{3}\right) = \frac{2}{3}$$

$$C_2: y = 1 - x^2 \quad \vec{r}(t) = \langle t, 1 - t^2 \rangle \quad t \in [-1, 1]$$

$$\int_{C_2} \vec{F} \cdot d\vec{r} = \int_{C_2} (x^2 - 1) dx + 2x dy = \int_{-1}^1 \left[[t^2 - 1 + t^2] dt + 2t(-2t) dt \right] = \int_{-1}^1 (-1 - 2t^2) dt \\ dx = dt \quad dy = -2t dt \\ = \left[-t - \frac{2}{3}t^3 \right]_{-1}^1 = \left(-1 - \frac{2}{3} \right) - \left(1 + \frac{2}{3} \right) = -2 - \frac{4}{3}$$

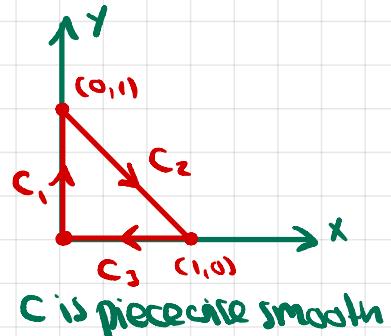
b) $\vec{F} = \langle xy, -x^2 \rangle$



$$r=1 \\ x = \cos \theta \quad dx = -\sin \theta d\theta \\ y = \sin \theta \quad dy = \cos \theta d\theta \\ \vec{r}(t) = \langle \cos \theta, \sin \theta \rangle \quad \theta \in [0, \pi/2]$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_C xy dx - x^2 dy = \int_0^{\pi/2} \cos \theta \sin \theta (-\sin \theta d\theta) + \cos^2 \theta \cos \theta d\theta \\ = \int_0^{\pi/2} (-\cos \theta \sin^2 \theta - \cos^3 \theta) d\theta = \int_0^{\pi/2} [-\cos \theta + \cancel{\cos^2 \theta} - \cancel{\cos^3 \theta}] d\theta = - \int_0^{\pi/2} \cos \theta d\theta \\ = - \sin \theta \Big|_{0}^{\pi/2} = -(-1) = 1$$

c) $\vec{F} = \langle y, -x \rangle$



$$\int_C \vec{F} \cdot d\vec{r} = \int_{C_1} \vec{F} \cdot d\vec{r} + \int_{C_2} \vec{F} \cdot d\vec{r} + \int_{C_3} \vec{F} \cdot d\vec{r}$$

$$\int_{C_1} \vec{F} \cdot d\vec{r} = \int_0^1 y \cdot 0 - 0 \cdot dy = 0$$

$$\int_{C_2} \vec{F} \cdot d\vec{r} = \int_{C_2} y dx - x dy, \quad \begin{matrix} y = 1 - x \\ dy = -dx \end{matrix} \Rightarrow \int_{C_2} (1 - x) dx + x dx = \int_0^1 dx = 1$$

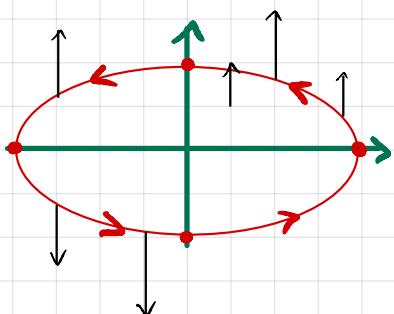
$$\int_{C_3} \vec{F} \cdot d\vec{r} = 0$$

$$\int_C \vec{F} \cdot d\vec{r} = 1$$

a) $\vec{F} \cdot \langle 1, 0 \rangle$

C: $x = 2\cos t$
 $y = \sin t$

$dx = -2\sin t dt$

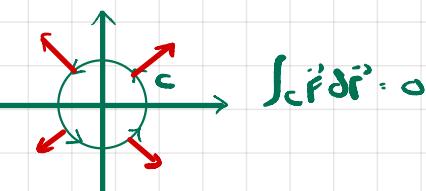


t	x	y
0	2	0
$\pi/2$	0	1
π	-2	0
$3\pi/2$	0	-1
2π	2	0

$$\int_C \vec{F} d\vec{r} = \int_0^{2\pi} \sin t (-2\sin t) dt = \int_0^{2\pi} -2\sin^2 t dt = -(t - \sin t \cos t) \Big|_0^{2\pi} = -[2\pi - 0] - [0 - 0] = -2\pi$$

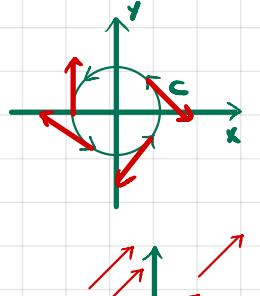
4B-2

a) $\vec{F} = \langle x, y \rangle$ radially outward vectors



$$\int_C \vec{F} d\vec{r} = 0$$

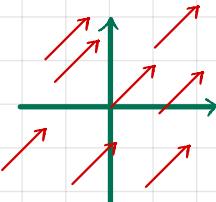
b) $\vec{F} = \langle y, -x \rangle$



$$\begin{aligned} \int_C \vec{F} d\vec{r} &= \int_C y dx - x dy = \int_0^{2\pi} c \sin \theta \cdot (-c \sin \theta d\theta) - c \cos \theta (c \cos \theta d\theta) \\ &= \int_0^{2\pi} (-c^2 \sin^2 \theta - c^2 \cos^2 \theta) d\theta = \int_0^{2\pi} -c^2 d\theta = -c^2 (2\pi) \end{aligned}$$

4B-3 $\vec{F} = \langle 1, 1 \rangle$

a) $\int \vec{F} \cdot d\vec{r}$



$$\lim_{n \rightarrow \infty} \sum_i \vec{F}(t_i^*) \cdot \vec{v}(t_i^*) \cdot \Delta s_i = \lim_{n \rightarrow \infty} \sum_i \vec{F}(t_i^*) \cdot \hat{t} \cdot dt = \lim_{n \rightarrow \infty} \| \vec{F}(t_i^*) \| \cdot \cos \theta dt$$

note when $\theta = 0 \Rightarrow \hat{t}$ and \vec{F} have same direction: $\text{dir}(\hat{t}) \cdot \text{dir}(\vec{F}) = 1$

$$\Rightarrow \vec{v}(t) = h(t) \langle 1, 1 \rangle, h(t) > 0 \Rightarrow \vec{r}(t) = H(t) \langle 1, 1 \rangle \quad H(t) = \int h(t) dt$$

b) $\cos \theta = -1 \Rightarrow \theta = \pi, \text{dir}(\hat{t}) = -\text{dir}(\vec{F})$

$$\vec{v}(t) = h(t) \langle -1, -1 \rangle, h(t) > 0 \Rightarrow \vec{r}(t) = H(t) \langle -1, -1 \rangle \quad H(t) = \int h(t) dt$$

c) $\cos \theta = 0 \Rightarrow \theta = \pi/2$

$$\langle 1, 1 \rangle \cdot \vec{v}(t) = 0, \text{dir}(\vec{v}(t)) = \langle v_1(t), v_2(t) \rangle \text{ this means } v_1(t) + v_2(t) = 0$$

$$\Rightarrow v_1(t) = -v_2(t) \Rightarrow \vec{v}(t) = \langle v_1(t), -v_1(t) \rangle = h(t) \langle 1, -1 \rangle$$

d) C has length l , parallel to $\langle 1, 1 \rangle$, can be parametrized

$$\vec{r}(t) = \langle r_x(t), r_y(t) \rangle + t \in [0, t_f]$$

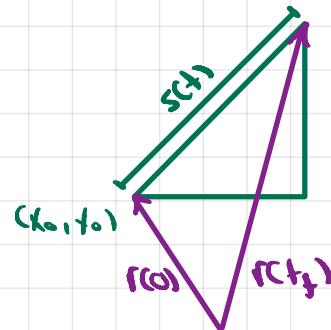
$$\vec{v}(t) = h(t) \langle 1, 1 \rangle$$

$$\max \int_C \vec{F} \cdot d\vec{r} = \int_C \vec{F} \cdot \vec{v} ds = \int_C \vec{F} \cdot \frac{\vec{v}}{\|v\|} \cdot \sqrt{ds}$$

$$= \int_C \vec{F} \cdot \vec{v} dt = \int_0^{t_f} \vec{z} \cdot h(t) dt = \frac{2}{\sqrt{2}} \int_0^{t_f} \sqrt{2} h(t) dt$$

$$= \frac{2}{\sqrt{2}} S(t) \Big|_0^{t_f} = \frac{2}{\sqrt{2}} (1-0) = \sqrt{2}$$

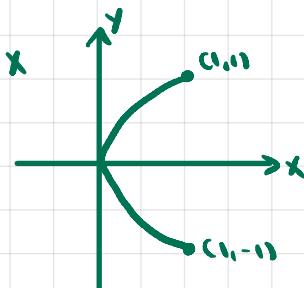
$$\min \int_C \vec{F} \cdot d\vec{r} = \int_0^{t_f} \vec{z} \cdot h(t) dt = \frac{2}{\sqrt{2}} (0-1) = -\sqrt{2}$$



$$\|\vec{v}(t)\| = \sqrt{2} h(t) = \sqrt{2} h(t)$$

$$S(t) = \int_0^t \sqrt{2} h(u) du$$

$$4C-1 \quad S(x, y) = x^3 y + y^3 \quad C: y^2 = x$$



$$a) \vec{F} \cdot \nabla f = \langle 3x^2 y, x^3 + 3y^2 \rangle$$

$$b) ii) \int_C \vec{F} \cdot d\vec{r} = \int_C 3x^2 y dx + (x^3 + 3y^2) dy$$

$$\vec{r}(t) = \langle t^2, t \rangle \quad dx = 2t dt \quad dy = dt$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_1^1 3t^2 \cdot 2t dt + (t^6 + 3t^2) dt = \int_1^1 (7t^6 + 3t^2) dt = t^7 + t^3 \Big|_1^1 = (1+1) - (-1-1) = 4$$

* Alternatively:

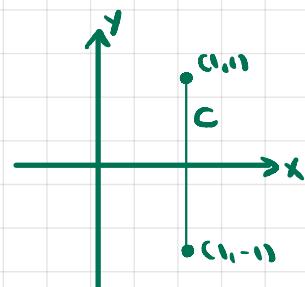
$$\int_{-1}^1$$

$$\begin{aligned} & \int_0^1 3x^2 \sqrt{x} - \int_0^1 3x^2 \sqrt{x} dx + \int_0^1 (1^6 + 3t^2) dt = \int_0^1 3x^{5/2} dx - \int_0^1 3x^{5/2} dx + \int_0^1 (1^6 + 3t^2) dt \\ &= 3 \cdot \frac{2}{7} x^{7/2} \Big|_0^1 - 3 \cdot \frac{2}{7} x^{7/2} \Big|_0^1 + \left(\frac{1}{7} + t^3 \right) \Big|_0^1 = \frac{6}{7} - \left[-\frac{6}{7} \right] + \left[\frac{1}{7} + 1 - (-\frac{1}{7} - 1) \right] \\ &= \frac{12}{7} + \frac{3}{7} + 2 = 4 \end{aligned}$$

iii) Independence of Path theorem $\int_C \vec{F} \cdot d\vec{r}$ of continuous vector field \vec{F} is indep. of path in plane or space region $D \iff \vec{F} = \nabla f$ for some f defined on D

In this problem, $\vec{F} = \nabla f$ by definition over \mathbb{R}^2 , so specifically $\int_C \vec{F} \cdot d\vec{r}$ is path independent. Let's choose a simpler C :

$$\begin{aligned} x = 1, dx = 0 \quad \int_C 3y \cdot 0 + (1+3y^2) dy &= \int_1^1 (1+3y^2) dy = (y + y^3) \Big|_1^1 \\ &= 1+1 - (-1-1) = 4 \end{aligned}$$



iii) fundamental theorem for line integrals: $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ C is smooth, parameterized by $\vec{r}(t) = \langle t^2, t \rangle$,

$t \in [-1, 1]$. $\nabla f = \langle 3x^2 + 1, x^3 + 3x^2 \rangle$, \leftarrow continuous vector-valued function everywhere in domain.

$\Rightarrow f$ continuously differentiable $\Rightarrow \int_C \nabla f \cdot d\vec{r} = f(\vec{r}(b)) - f(\vec{r}(a))$

In this problem: $\int_C \vec{F} \cdot d\vec{r} = f(\vec{r}(1)) - f(\vec{r}(-1)) = f(1, 1) - f(-1, -1) = 2 - (-2) = 4$

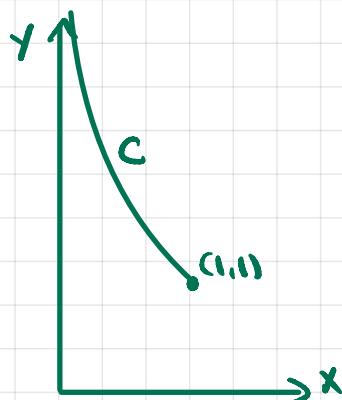
$$4C-2 \quad f(x, y) = xe^{xy}$$

$$\text{a) } \vec{F} = \nabla f = \langle e^{xy} + xe^{xy} \cdot y, xe^{xy} \cdot x \rangle \\ = \langle e^{xy}(1+x), x^2e^{xy} \rangle$$

$$\text{b) ii) } x(t) = t \quad dx = dt \quad y(t) = 1/t \quad dy = -dt/t^2$$

$$\nabla f(t) = \langle e^{(1+t)}, t^2 \cdot e \rangle = \langle 2e, t^2 e \rangle$$

$$\int_C \vec{F} \cdot d\vec{r} = \int_1^0 2e dt + \cancel{\int_1^0 e \left(\frac{-dt}{t^2}\right)} = \int_1^0 (2e - e) dt = \int_1^0 e dt = -e$$



$$\text{iii) } \int_{C_1} \vec{F} \cdot d\vec{r} = \int_1^0 (e^x(1+x) dx - (\cancel{e^x} + xe^x - \cancel{e^x})) \Big|_1^0 = -e$$

$$\begin{aligned} \int e^x x dx &= e^x x - \int e^x dx = e^x x - e^x \\ dv = e^x dx &\quad v = e^x \\ u = x &\quad du = dx \end{aligned}$$

$$\int_{C_2} \vec{F} \cdot d\vec{r} = \int_0^1 0 dy = 0$$

$$\Rightarrow \int_C \vec{F} \cdot d\vec{r} = -e + 0 = -e$$

$$4C-3 \quad f(x,y) = \sin x \cos y$$

a) $\vec{F} = \nabla f = \langle \cos x \cos y, -\sin x \sin y \rangle$

b) Vector field is \vec{F} of regular intervals in \mathbb{R}^2 .

$$\langle x, y \rangle = \left\langle k_1 \pi, \frac{\pi}{2} + k_2 \pi \right\rangle$$

or

$$\langle x, y \rangle = \left\langle \frac{\pi}{2} + k_1 \pi, k_2 \pi \right\rangle$$

$$f(k_1 \pi, \frac{\pi}{2} + k_2 \pi)$$

$$= \sin(k_1 \pi) \cos(\frac{\pi}{2} + k_2 \pi)$$

$$= 0 \cdot 0 = 0$$

$$f(\frac{\pi}{2} + k_1 \pi, k_2 \pi)$$

$$= \sin(\frac{\pi}{2} + k_1 \pi) \cos(k_2 \pi)$$

$$\pm 1 \cdot \pm 1 = \pm 1$$

$$f=1 \Rightarrow \left\langle \frac{\pi}{2} + k_1 \cdot 3\pi, k_2 \cdot 3\pi \right\rangle$$

or $\left\langle 3\pi/2 + k_1 \cdot 2\pi, \pi + k_2 \cdot 2\pi \right\rangle$

$$f=-1 \Rightarrow \left\langle 3\pi/2 + k_1 \cdot 3\pi, k_2 \cdot 3\pi \right\rangle$$

$$\left\langle \frac{\pi}{2} + k_1 \cdot 2\pi, \pi + k_2 \cdot 2\pi \right\rangle$$

\vec{F} is a continuous gradient field in \mathbb{R}^2

$\Rightarrow \int_C \vec{F} d\vec{r}$ is path independent

$= f(x_f, y_f) - f(x_0, y_0)$, where

C starts at (x_0, y_0) ends at (x_f, y_f) .

Max value occurs starting here

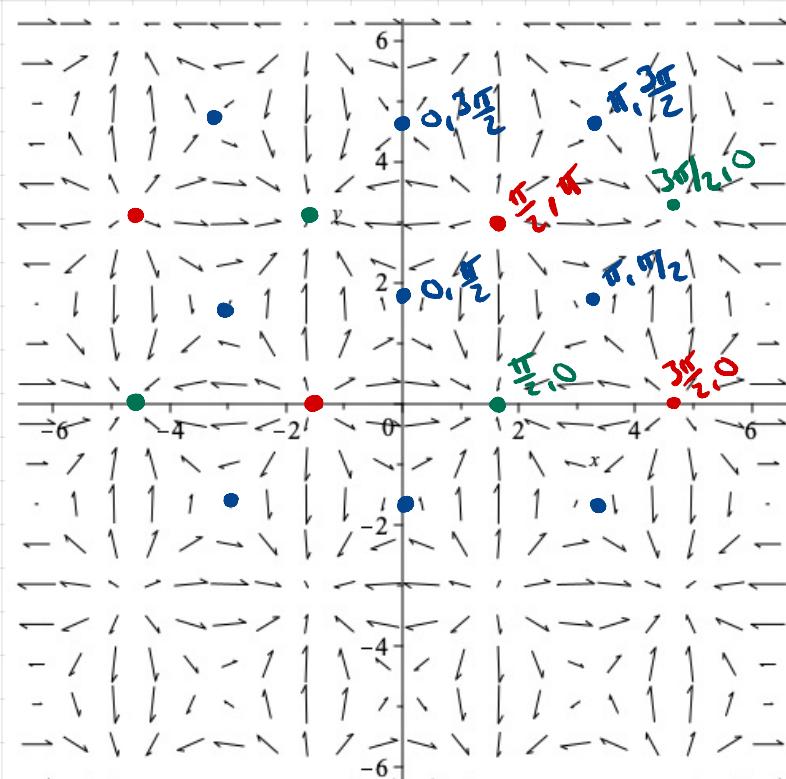
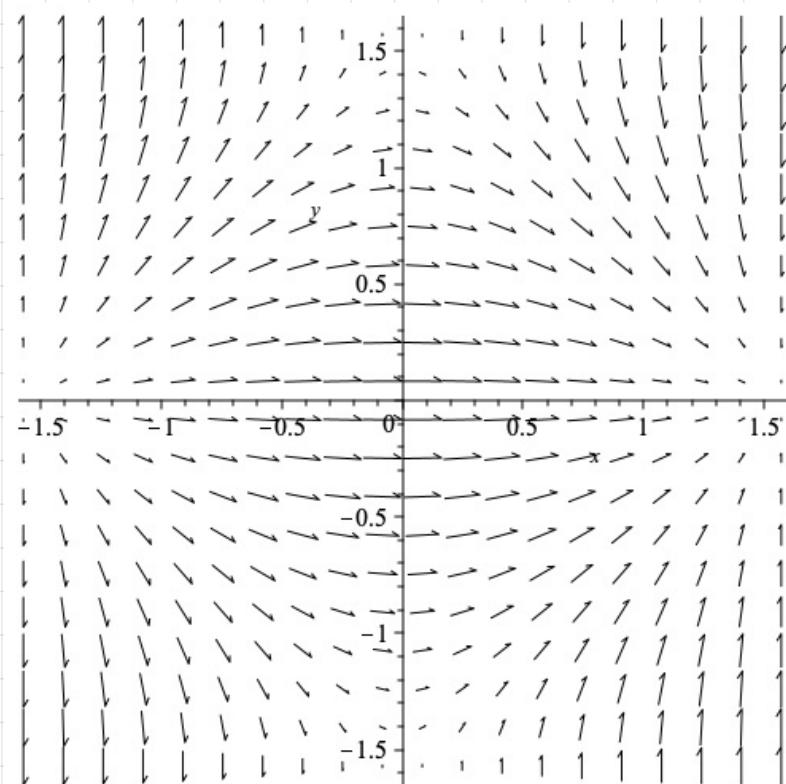
$f = -1$ and ending here $f = 1$.

$$\Rightarrow \int_C \vec{F} d\vec{r} = 2$$

For example, C being the curve from $(\frac{\pi}{2}, \pi)$ to $(\frac{3\pi}{2}, \pi)$

In general any path from $\left\langle \frac{\pi}{2} + k_1 \cdot 2\pi, \pi + k_2 \cdot 2\pi \right\rangle$ or $\left\langle \frac{3\pi}{2} + k_1 \cdot 2\pi, k_2 \cdot 2\pi \right\rangle$

to $\left\langle \frac{\pi}{2} + k_1 \cdot 3\pi, k_2 \cdot 3\pi \right\rangle$ or $\left\langle 3\pi/2 + k_1 \cdot 2\pi, \pi + k_2 \cdot 2\pi \right\rangle$ has line integral $\int_C \vec{F} d\vec{r}$ equal to the max value of 2.



$$\bullet f=0 \quad \bullet f=1 \quad \bullet f=-1$$

4C-S

a) $\vec{F} = \langle y^2 + 2x, xy \rangle = \langle P(x,y), Q(x,y) \rangle$

If $\vec{F} = \nabla f$ then $P_y = Q_x$

$$P_y = 2y \quad Q_x = cy \Rightarrow c = 2$$

Two ways to find potential function f

1) line integral

$$\int_{C_1 + c_1} \vec{F} d\vec{r} = f(x,y) - f(0,0)$$

$$\int_{C_1} (y^2 + 2x) dx + 2xy dy, \text{ on } C_1, y=0 \Rightarrow dy=0$$

$$\Rightarrow \int_0^x 2x dx = x^2$$

$$\int_0^y 2xy dy = xy^2$$

$$\Rightarrow \int_C \vec{F} d\vec{r} = x^2 + xy^2 - \underbrace{f(0,0)}_{\text{constant, we can set this to zero}} \Rightarrow f(x,y) = x^2 + xy^2$$

∇f steps the same

2) antiderivatives

$$P(x,y) = f_x \Rightarrow \int P(x,y) dx = f$$

$$\int (y^2 + 2x) dx = xy^2 + x^2 + g(y)$$

$$f_y = 2xy + g'(y) \Rightarrow g'(y) = 0 \text{ choose compare with } Q(x,y) = f_y = 2xy$$

$$\Rightarrow f(x,y) = x^2 + xy^2$$

b) $\vec{F} = \langle e^{x+1}(x+c), e^{x+1}x \rangle$

$$P_y = e^{x+1}(x+c) \quad Q_x = e^{x+1}x + e^{x+1} \Rightarrow e^{x+1}(x+c) = e^{x+1}(x+1) \Rightarrow c=1$$

$$f = \int e^{x+1}(x+1) dx = e^{x+1} \cdot a + \int e^{x+1}x dx = e^{x+1}a + e^{x+1}x - e^{x+1} = e^{x+1}(a+x-1) + g(y)$$

$$f_y = e^{x+1}(a+x-1) + g'(y)$$

$$\cdot e^{x+1}x + [e^{x+1}(a-1) + g'(y)]$$

c must be 1 here

$$u = x \quad du = dx$$

$$dv = e^{x+1} dx$$

$$v = e^{x+1}$$

$$= e^{x+1}x - \int e^{x+1} dx$$

$$= e^{x+1}x - e^{x+1}$$

$$\Rightarrow g'(y) \cdot 0 \Rightarrow g(y) = C \Rightarrow f(x,y) = e^{x+1}x + C$$

4C-6

a) Exact differential form: \langle scalar function $Q(x, t, z)$, and the expression

$$dQ \equiv (\partial Q / \partial x)_{t,z} dx + (\partial Q / \partial y)_{x,z} dy + (\partial Q / \partial z)_{x,y} dz$$

Given \in differential form $A(x, t, z)dx + B(x, t, z)dy + C(x, t, z)dz$

we check that it is exact by determining if $\langle A, B, C \rangle$ is the gradient of some F .

Note $\int_C A dx + B dy + C dz = \int_C \vec{F} d\vec{r}$ so if $\vec{F} = \langle A, B, C \rangle = \nabla F$ then we know

F is conservative.

$$A(x, t) = y$$

$$A_y = 1$$

$\Rightarrow \langle A, B \rangle$ not \in gradient field.

$$B(x, t) = -x$$

$$B_x = -1$$

b) $y(2x+y)dx + x(2y+x)dy$

Is $\langle y(2x+y), x(2y+x) \rangle$ a gradient?

$$\int A dx = \int (2xy + y^2) dx = x^2y + xy^2 + g(y) \quad \frac{\partial}{\partial y} (x^2y + xy^2 + g(y)) = x^2 + 2xy + g'(y)$$

$$\text{compare with } B = x^2 + 2xy \Rightarrow g'(y) = 0 \Rightarrow g(y) = C$$

$\Rightarrow y(2x+y)dx + x(2y+x)dy$ is an exact differential

$\Rightarrow \int (x^2y + xy^2 + C) dx$ is a potential function for a conservative vector field $\vec{F} = \nabla f$

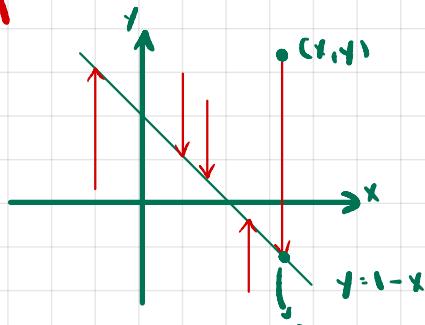
$= \langle y(2x+y), x(2y+x) \rangle$, and $y(2x+y)dx + x(2y+x)dy$ is an exact differential

$\Leftrightarrow \int_C \vec{F} d\vec{r} = \int_C y(2x+y)dx + x(2y+x)dy$ is path independent.

$$df = y(2x+y)dx + x(2y+x)dy$$

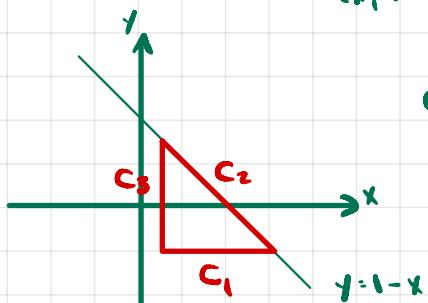
Problem 1

a)



$$\vec{F}(x,y) = \langle x-y, 1-x-y \rangle = \langle 0, 1-x-y \rangle$$

b)



C is a closed path.

$$\vec{F} \text{ is conservative } (\Leftrightarrow \vec{F} \cdot \nabla f) \Leftrightarrow \int_C \nabla f \cdot d\vec{r} = f(A) - f(A) = 0,$$

for all closed paths C .

$$\int_{C_1} \vec{F} \cdot d\vec{r} = 0 \text{ because } \vec{F} \cdot \hat{T} = 0 \text{ on } C_1.$$

so, if $\int_C \nabla f \cdot d\vec{r} + 0$ for C closed path then
 \vec{F} not conservative ($\vec{F} \neq \nabla f$).

$$\text{Also, } \vec{F} \neq \nabla f \Rightarrow \int_C \nabla f \cdot d\vec{r} \text{ is not } = 0 \\ \text{for all } C.$$

$$\int_{C_3} \vec{F} \cdot d\vec{r} + 0 \text{ because } \vec{F} \parallel \hat{T} \Rightarrow \vec{F} \cdot \hat{T} + 0 \text{ on } C_3.$$

$$\int_{C_1+C_2} \vec{F} \cdot d\vec{r} = \int_{C_1} \vec{F} \cdot d\vec{r} = 0 \text{ because on } C_2 \vec{F} = 0.$$

$$P_y = 0 \quad Q_x = -1$$

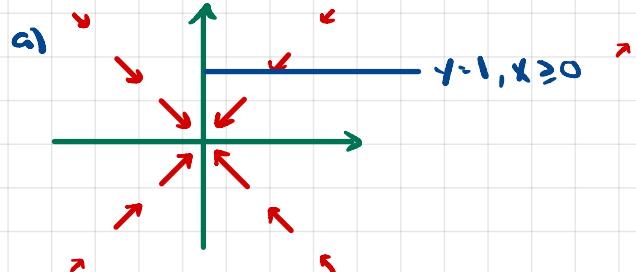
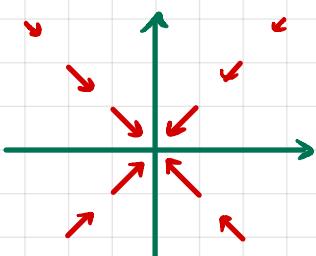
$\Rightarrow \vec{F}$ not conservative, $\vec{F} \neq \nabla f$

$$\Rightarrow \int_C \vec{F} \cdot d\vec{r} = \int_{C_1+C_2} \vec{F} \cdot d\vec{r} + \int_{C_3} \vec{F} \cdot d\vec{r} \neq 0$$

Note: starting at P_0 , it is possible to get to $y=1-x$ by moving horizontally with zero work from \vec{F} . Moving along $y=1-x$ is also done with zero work from \vec{F} . Note to return vertically down P_0 on $1-x$. Now, to get back to P_0 move down vertically, with $W < 0$ from \vec{F} .

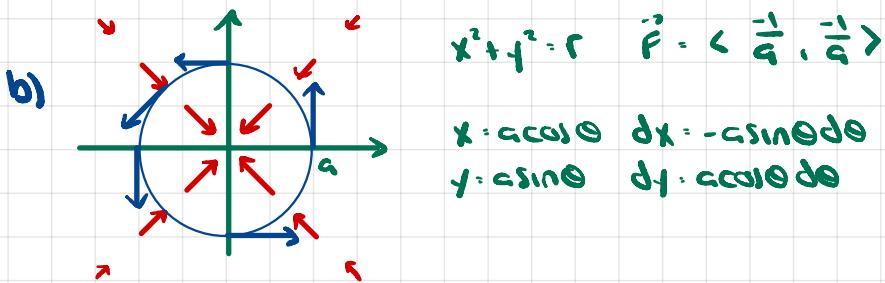
Problem 2

$$\vec{F} = \left\langle -\frac{x}{x^2+y^2}, \frac{y}{x^2+y^2} \right\rangle$$



$$\vec{F} = \left\langle \frac{-1}{x^2+y^2}, \frac{y}{x^2+y^2} \right\rangle \quad C: \quad y=1, x \geq 0$$

$$\int_C \vec{F} \cdot \vec{T} ds = \int_0^\infty \left(\frac{-t}{1+t^2} \right) dt = \lim_{n \rightarrow \infty} \int_0^n \frac{-t}{1+t^2} dt = \lim_{n \rightarrow \infty} \left[-\frac{\ln(1+t^2)}{2} \right]_0^n = \lim_{n \rightarrow \infty} -\frac{\ln(1+n^2)}{2} = -\infty$$



$$\begin{aligned} \int_C \vec{F} \cdot \vec{dr} &= \int_C \frac{-1}{r^2} (-r \sin \theta) d\theta - \frac{1}{r^2} r \cos \theta d\theta = \int_0^{2\pi} (\sin \theta - \cos \theta) d\theta \\ &= -\cos \theta - \sin \theta \Big|_0^{2\pi} = (-\cos 2\pi - \sin 2\pi) - (-\cos 0 - \sin 0) = (-1 - 0) - (-1 - 0) = 0 \end{aligned}$$

c)

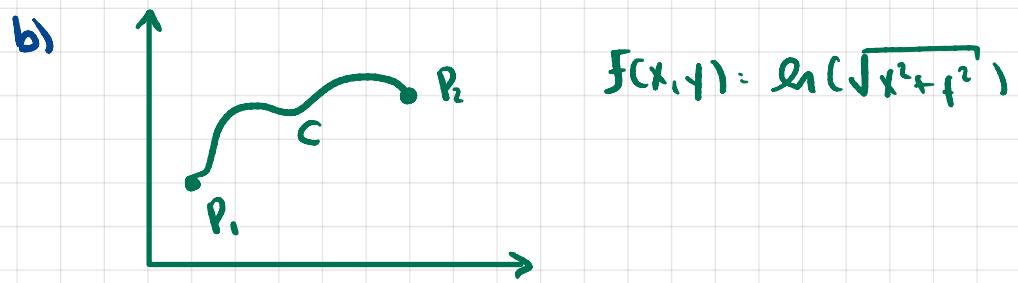
$$\int_C \vec{F} \cdot \vec{dr} = \int_0^1 \frac{-t}{2t^2-2t+1} dt - \frac{(1-t)}{2t^2-2t+1} (-dt) = \int_0^1 \frac{-t+1-t}{2t^2-2t+1} dt = \int_0^1 \frac{-2t+1}{2t^2-2t+1} dt$$

$$C: \quad y = 1 - x, \text{ parameterized } x = t, y = 1 - t$$

$$x^2 + y^2 = t^2 + 1 - 2t + t^2 = 2t^2 - 2t + 1$$

Problem 3

a) $\vec{F} = -\nabla \ln r = -\ln \sqrt{x^2 + y^2} \cdot \left\langle -\frac{x}{\sqrt{x^2 + y^2}}, -\frac{y}{\sqrt{x^2 + y^2}} \right\rangle$



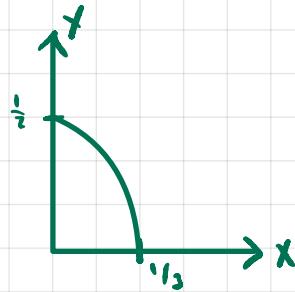
$$\int_C \vec{F} d\vec{r} = f(P_2) - f(P_1) \text{ since } \vec{F} \text{ is path independent.}$$

$$= \ln(\sqrt{x_2^2 + y_2^2}) - \ln(\sqrt{x_1^2 + y_1^2}) = \ln(r_2) - \ln(r_1) = \ln(r_2/r_1)$$

Problem 4

$$\vec{F} = \nabla(x^2y + 2xy^2) = \langle 2xy + 2y^2, x^2 + 4xy \rangle$$

$$C: 9x^2 + 4y^2 = 1$$



a) $\int_C \vec{F} \cdot d\vec{r} = \int_C (2xy + 2y^2) dx + (x^2 + 4xy) dy$

b) $x = \frac{1}{3} \cos t \quad y = \frac{1}{2} \sin t \quad dx = -\frac{\sin t}{3} dt \quad dy = \frac{\cos t}{2} dt$

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_0^{\pi/2} \left(\frac{\sin t \cos t}{3} + \frac{\sin^2 t}{2} \right) \left(-\frac{\sin t}{3} \right) dt + \left(\frac{\cos^2 t}{9} + 4 \cdot \frac{1}{3} \cdot \frac{1}{2} \cos t \sin t \right) \frac{\cos t}{2} dt \\ &= \int_0^{\pi/2} \left[-\frac{\sin^2 t \cos t}{9} - \frac{\sin^3 t}{6} + \frac{\cos^3 t}{18} + \frac{1}{3} \cos^2 t \sin t \right] dt \end{aligned}$$

c) $f(x, y) = x^2y + 2xy^2$

$$\int_C \vec{F} \cdot d\vec{r} = \int_A^B \nabla f \cdot d\vec{r} = f(B) - f(A) \text{ where } B = (0, 1/2), A = (1/3, 0)$$

$$f(B) = f(0, 1/2) = 0$$

$$f(A) = f(1/3, 0) = 0$$

d) f is continuously diff. in $\mathbb{R}^2 \Rightarrow \int_C \nabla f \cdot d\vec{r} = \int_C \vec{F} \cdot d\vec{r} = f(B) - f(A)$

i.e. $\vec{F} = \nabla f$ is path independent.

$$\Rightarrow \text{between } A = (1/3, 0) \text{ and } B = (0, 1/2), \int_C \vec{F} \cdot d\vec{r} = 0$$

Problem 5

$$\vec{F} = \langle x_1, x^3 \rangle$$

a) How to show \vec{F} not conservative?

We know that: \vec{F} conservative $\Leftrightarrow \vec{F} = \nabla f$

Using the \Rightarrow portion, if \vec{F} is not gradient then \vec{F} is not conservative.

Assume $\vec{F} = \nabla f = \langle f_x, f_y \rangle$

$$\Rightarrow f_x = x_1 \quad f_y = x^3$$

$$f_{x_1} = x \quad f_{xx} = 3x^2$$

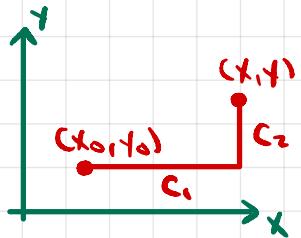
But $f_{x_1} + f_{xx} \Rightarrow \vec{F} \neq \nabla f$ for some f . $\Rightarrow \vec{F}$ not conservative.

b)

$$\int_{(x_0, y_0)}^{(x_1, y_1)} \vec{F} \cdot d\vec{r} =$$

$$\int_0^{x_1} x f_0 dx - f_0 x_1^2 = 0$$

$$\int_0^{y_1} x_1^3 - x_1^3 y_1$$



$$\int_{C_1} \vec{F} \cdot d\vec{r} = \int_C x_1 dx - \int_{x_0}^{x_1} x_1 y_0 dx = \frac{x^2}{2} y_0 \Big|_{x_0}^{x_1} = \frac{y_0}{2} (x_1^2 - x_0^2)$$

$$\int_{C_2} \vec{F} \cdot d\vec{r} = \int_0^{y_1} x_1^3 dy = x_1^3 (y_1 - y_0)$$

$$\int_C \vec{F} \cdot d\vec{r} = \frac{y_0 x^2}{2} + x_1^3 y - \frac{y_0 x_0^2}{2} - x_0^3 y_0 = f(x_1, y_1)$$

$$\text{But } f_x = x_1 + 3x^2 y - 3x^2 y_0 + x_1 \Rightarrow \vec{F} \neq \nabla f \text{ as we already knew}$$

$$f_y = x^3$$

Failed to see choosing simpler paths starting from $(x_0, y_0) = (0, 0)$

$$\Rightarrow f(x_1, y_1) = x_1^3 y, f_x = 3x^2 y + P(x_1, y_1), f_y = x^3 = Q(x_1, y_1)$$

The line integral results in a function that is not a potential for \vec{F} .

$$c) \vec{F} = \langle xy, x^3 \rangle$$

we know $\vec{F} = \nabla f$ for some $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ because $P_1 \neq Q_2$, ie $\operatorname{curl} \vec{F} = Q_2 - P_1 \neq 0$

if we try to find potential function despite this using method 2:

$$\int P dx = \int xy dx = \frac{x^2}{2}y + g(y)$$

$$\frac{d}{dy} \left[\int P dx \right] = \frac{x^2}{2} + g'(y), \text{ which should be equal to } x^3$$

$$\frac{x^2}{2} + g'(y) = x^3 \Rightarrow g'(y) = x^3 - \frac{x^2}{2}, \text{ but this is a function of } x, \text{ and we claimed it}$$

was not, contradiction. It means $g(y)$ is a function of y , which contradicts

our initial integration of $P(x, y)$:

$$\int g'(y) dy \Rightarrow g(y) = y(x^3 - x^2/2)$$

$$\Rightarrow J(x, y) = \frac{x^2}{y} + yx^3 - \frac{yx^2}{2}$$

$$J_x = \frac{2x}{y} + 3x^2 - yx + xy = P(x, y)$$