

Directional Derivatives

Given $z = f(x, y)$, its first-order partial derivatives are:

$$f_x(\vec{x}) = \lim_{h \rightarrow 0} \frac{f(\vec{x} + h\hat{i}) - f(\vec{x})}{h} \quad f_y(\vec{x}) = \lim_{h \rightarrow 0} \frac{f(\vec{x} + h\hat{j}) - f(\vec{x})}{h}$$

$$\vec{x} = \langle x, y \rangle, \hat{i} = \langle 1, 0 \rangle, \hat{j} = \langle 0, 1 \rangle$$

If we replace \hat{i} or \hat{j} with another unit vector \hat{u} we obtain a directional derivative

$$D_{\hat{u}} f(\vec{x}) = \lim_{h \rightarrow 0} \frac{f(\vec{x} + h\hat{u}) - f(\vec{x})}{h} \quad \text{provided the limit exists.}$$

Note

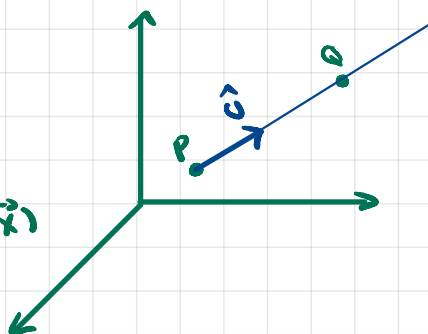
$$\vec{P} = \vec{x}$$

$$\vec{Q} = \vec{x} + h\hat{u}$$

$$\Delta w = f(Q) - f(P) = f(\vec{x} + h\hat{u}) - f(\vec{x})$$

$$\Delta s = |\vec{PQ}| = h = \text{distance}$$

$$\frac{\Delta w}{\Delta s} = \frac{f(\vec{x} + h\hat{u}) - f(\vec{x})}{h} = \text{average rate of change of } f \text{ w/ respect to distance}$$



If we take the limit as $h \rightarrow 0$ we obtain the instantaneous rate of change of w at P with respect to distance in the direction of \hat{u} (ie dir. \vec{P} to \vec{Q})

$$\frac{dw}{ds} = \lim_{\Delta s \rightarrow 0} \frac{\Delta w}{\Delta s} = D_{\hat{u}} f(\vec{x})$$

Theorem

Real-valued function f diff $\rightarrow \vec{x}$

$$\Rightarrow D_{\hat{u}} f(\vec{x}) \text{ exists and } = \nabla f(\vec{x}) \cdot \hat{u}$$

\hat{u} a unit vector

Chain Rule

$$\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$$

$$\Rightarrow f(x(t), y(t), z(t)) \text{ diff fn of } t$$

$f(x, y, z)$ differentiable function

$$D_t [f(\vec{r}(t))] = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} = \nabla f(\vec{r}(t)) \cdot \vec{r}'(t)$$

velocity vector

$$r(t) \text{ smooth parametric curve w/ nonzero velocity vector } \Rightarrow \vec{v} = v \cdot \hat{u}, v = |\vec{v}|$$

$$\Rightarrow D_t [f(\vec{r}(t))] = v \cdot \nabla f(\vec{r}(t)) \cdot \hat{u} = v D_{\hat{u}} f(\vec{r}(t)) = \frac{dw}{ds} \cdot \frac{ds}{dt}$$

where $w = f(\vec{r}(t))$

Gradient Vector as a Normal Vector

$$F(x, y, z) = 0$$

implicit function theorem \Rightarrow near any point P where $\frac{\partial F}{\partial z} \neq 0$, F defines z implicitly, in terms of x and y , continuously, diff.

\Rightarrow near P , graph $F(x, y, z) = 0$ coincides with the surface $z = f(x, y)$

Similarly, $\frac{\partial F}{\partial x} \neq 0 \stackrel{\text{near } P}{\Rightarrow} x = g(y, z)$, defined implicitly, coincides with F near P

Analogous result for $y = h(x, z)$ if $\frac{\partial F}{\partial y} \neq 0$ near P

$\Rightarrow \nabla F(P) \neq \vec{0}$, i.e. any of $F_x, F_y, F_z \neq 0$ near P , $\Rightarrow F(x, y, z)$ looks like a surface near P

Theorem

$F(x, y, z)$ cont. diff

$P(x_0, y_0, z_0)$ point where $\nabla F(P_0) \neq \vec{0}$

$$\Rightarrow \nabla F(P_0) \cdot r'(t_0) = 0$$

$\vec{r}(t)$ diff curve on this surface, $r(t_0) = (x_0, y_0, z_0)$,

$$r'(t_0) \neq 0$$