

PSet 3

IE-2, IE-3, IF-S done in PSet 2

IE-4 line through $(0,1,2)$ and $(2,0,3)$, intersection with $x+4y+z=4$

strategy: find parametric eq. for line
insert into plane eq., find t

$$P_0 = (0,1,2) \quad P_1 = (2,0,3)$$

$$\vec{P_0 P_1} = \langle 2, -1, 1 \rangle$$

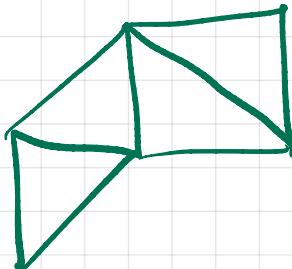
$$\langle x, y, z \rangle = \langle 0, 1, 2 \rangle + t \langle 2, -1, 1 \rangle$$

$$x(t) = 2t$$

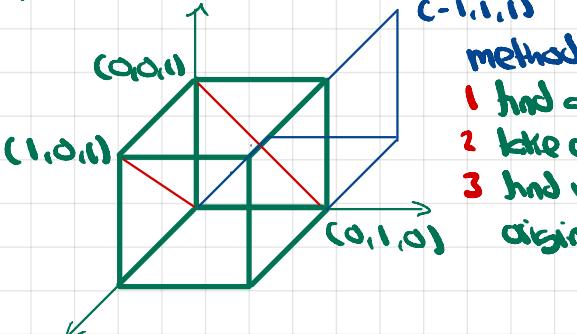
$$\begin{aligned} y(t) &= 1-t \\ z(t) &= 2+t \end{aligned} \Rightarrow \begin{aligned} 2t + 4(1-t) + 2+t &= 4 \\ 2t + 4 - 4t + 2 + t &= 4 \\ -t + 6 &= 4 \Rightarrow t = 2 \end{aligned}$$

$$\langle x(2), y(2), z(2) \rangle = \langle 4, -1, 4 \rangle$$

$$\text{check plane eq: } \cancel{4+4(-1)+4=4}$$



IE-7



$\langle -1, 1, 1 \rangle$

method

- 1 find a vector parallel to each line
- 2 take cross product to obtain vector \vec{v} pointing towards shortest path
- 3 find intersection of \vec{v} generated line and the line not passing through origin

1

$$\text{line 1, through origin: } \langle x(t), y(t), z(t) \rangle = \vec{r}_1(t) = t \langle 1, 0, 1 \rangle$$

$$\text{line 2: } \vec{r}_2(n) = \langle 0, 0, 1 \rangle + n \langle 0, 1, -1 \rangle = \langle 0, n, 1-n \rangle$$

$$2 \quad \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & 1 \\ 0 & 1 & -1 \end{vmatrix} = \langle -1, -(-1), 1 \rangle = \langle -1, 1, 1 \rangle$$

shortest path line is parallel to $\langle -1, 1, 1 \rangle$

$$\vec{r}_3(m) = \vec{r}_{3_0} + m \langle -1, 1, 1 \rangle = \langle t, 0, t \rangle + (-m, m, m) = \langle 0, n, 1-n \rangle$$

$$t-m=0 \Rightarrow t=m$$

$$m=n$$

$$t+m=1-n \Rightarrow m+m=1-m \Rightarrow 3m=1 \Rightarrow m=\frac{1}{3}, t=\frac{1}{3}, n=\frac{1}{3}$$

check

$$\vec{r}_3(\frac{1}{3}) = \langle \frac{1}{3}, 0, \frac{1}{3} \rangle = \vec{r}_{3_0}$$

$$\vec{r}_2(\frac{1}{3}) = \langle \frac{1}{3}, 0, \frac{1}{3} \rangle + \langle -\frac{1}{3}, \frac{1}{3}, \frac{1}{3} \rangle$$

$= \langle 0, \frac{1}{3}, \frac{2}{3} \rangle$, intersection point

$$\vec{r}_2(\frac{1}{3}) = \langle 0, \frac{1}{3}, \frac{2}{3} \rangle$$

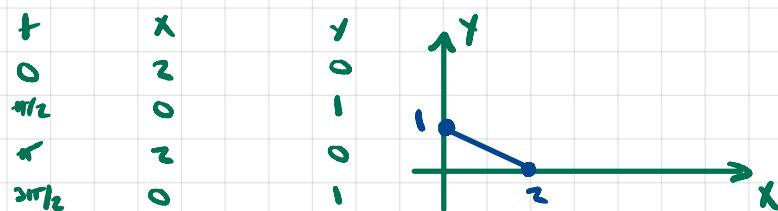
II-3

a) $\vec{r} = \langle 2\cos^2 t, \sin^2 t \rangle$

$$x(t) = 2\cos^2 t = 2 - 2\sin^2 t$$

$$y(t) = \sin^2 t$$

$$\frac{x(t)}{2} + y(t) - 1 = \frac{x(t)}{2} + \sin^2 t - 1 = \frac{x(t)}{2}$$



b) $\vec{r} = \langle \cos 2t, \cos t \rangle$

$$x(t) = \cos(2t)$$

$$= 2\cos^2 t - 1$$

$$2 \cdot y(t)^2 = 2\cos^2 t$$

$$\Rightarrow 2y(t)^2 - x(t) = 2\cos^2 t - 2\cos^2 t + 1$$

$$2y(t)^2 - x(t) = 1$$

$$\cos^2 t = \frac{1}{2}(1 + \cos 2t)$$

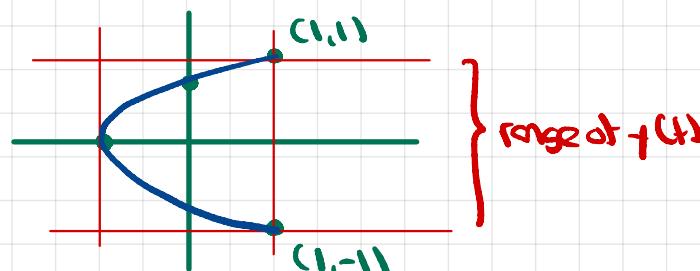
$$2\cos^2 t - 1 + \cos 2t = \cos 2t = 2\cos^2 t - 1$$

t	x	y
0	1	1
$\pi/4$	0	$\sqrt{2}/2$
$\pi/2$	-1	0
$3\pi/4$	0	-1
π	-1	-1
$5\pi/4$	0	0
2π	1	1

Position vector travels from $(1,1)$

at $t=0$ to $(1,-1)$ at $t=\pi$ and

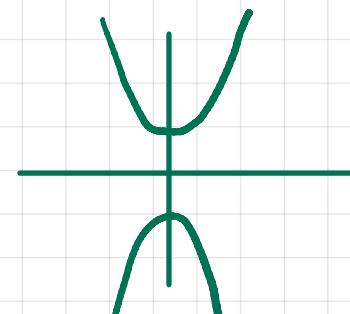
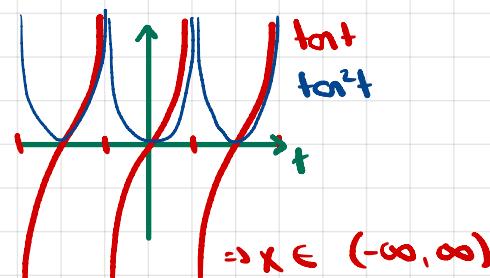
back to $(1,1)$ at $t=2\pi$.



d) $\vec{r}(t) = \langle \tan t, \sec t \rangle = \left\langle \frac{\sin t}{\cos t}, \frac{1}{\cos t} \right\rangle = \frac{1}{\cos t} \langle \sin t, 1 \rangle$

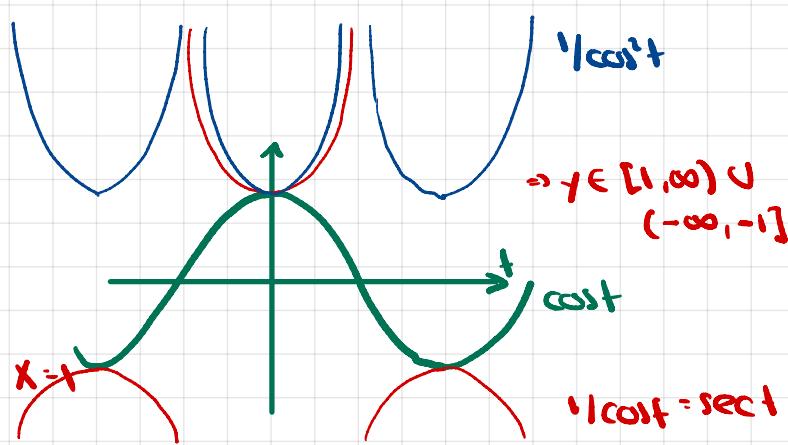
$$y(t) = 1 + x(t)$$

$$\sec^2 t = 1 + \tan^2 t$$



$$y^2 = 1 + x^2 \Rightarrow y = \pm \sqrt{1+x^2}$$

t	x	y
0	0	1
$\pi/4$	1	$\sqrt{2}$
$\pi/2$	∞	∞
$3\pi/4$	-1	$-\sqrt{2}$
$-\pi/4$	-1	$-\sqrt{2}$
$-\pi/2$	$-\infty$	$-\infty$

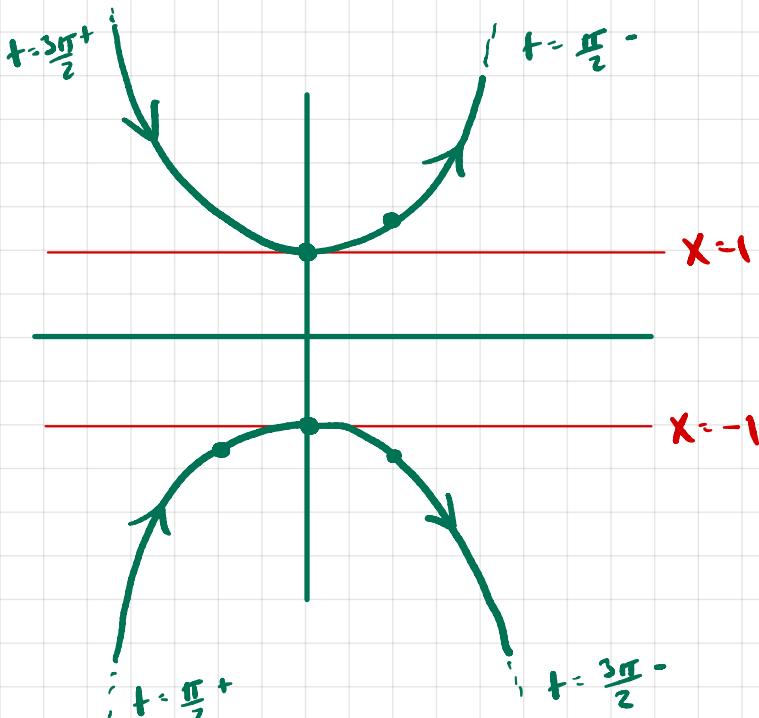


$$1/\cos t = \sec t$$

$$\vec{r}(t) = \langle \tan t, \sec t \rangle$$

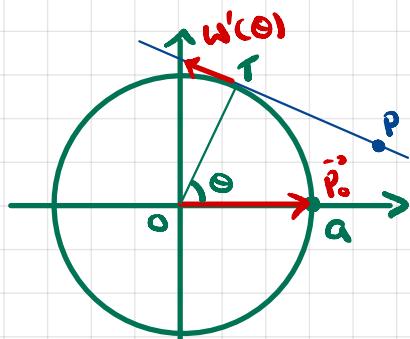
$$y'(t) = 1 + \dot{x}(t)$$

$$\sec^2 t = 1 + \tan^2 t$$



	x	y
0	0	1
$\pi/4$	-1	$\sqrt{2}$
$\pi/2^-$	∞	∞
$\pi/2^+$	$-\infty$	$-\infty$
$3\pi/4$	-1	$-\sqrt{2}$
π	0	-1
$5\pi/4$	1	$-\sqrt{2}$
$6\pi/4^-$	∞	$-\infty$
$6\pi/4^+$	$-\infty$	∞

II-S



$$\vec{OP} \cdot \vec{OT} = \vec{T}\vec{P}$$

$$|\vec{T}\vec{P}| = a\theta$$

$$\vec{OT} \cdot \vec{w}'(\theta) = \langle \cos \theta, \sin \theta \rangle$$

$$w'(\theta) = \langle -\sin \theta, \cos \theta \rangle \text{ - tangent vector}$$

$$\vec{T}\vec{P} = \frac{\vec{w}'(\theta)}{|w'(\theta)|} \cdot |\vec{P}(\theta)| = -\frac{\langle -\sin \theta, \cos \theta \rangle}{a} \cdot a\theta = \langle a\theta \sin \theta, -a\theta \cos \theta \rangle$$

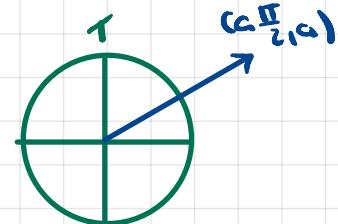
$$\vec{OP} = \vec{P}(\theta) = \langle a \cos \theta + a\theta \sin \theta, a \sin \theta - a\theta \cos \theta \rangle$$

$$= a \cdot \langle \cos \theta + \theta \sin \theta, \sin \theta - \theta \cos \theta \rangle$$

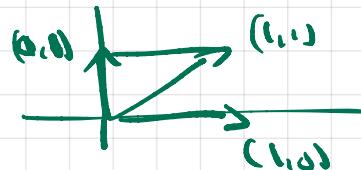
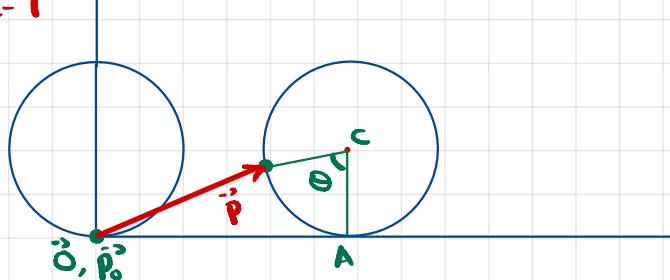
check if $\vec{P}(\theta)$ makes sense

$$\vec{P}(0) = a \langle 1, 0 \rangle$$

$$\vec{P}(\pi/2) = a \langle 0 + \frac{\pi}{2}, 1 - \frac{\pi}{2} \cdot 0 \rangle = a \langle \frac{\pi}{2}, 1 \rangle = \langle \frac{a\pi}{2}, a \rangle$$



II-7



$$\vec{OP} = \vec{OA} + \vec{AC} + \vec{CP}$$

$$\vec{OA} = \langle a\cos\theta, 0 \rangle$$

$$\vec{AC} = \langle 0, a \rangle$$



$$\vec{CP} = \langle -a\sin\theta, -a\cos\theta \rangle$$

$$\Rightarrow \vec{OP} = \vec{P}(\theta) = \langle a\cos\theta - a\sin\theta, a - a\cos\theta \rangle$$

check: does result make sense?

$$\vec{P}(0) = \langle 0, 0 \rangle$$

$$\vec{P}\left(\frac{\pi}{2}\right) = \langle a\left(\frac{\pi}{2} - 0\right), a - a \cdot 0 \rangle = \langle a\left(\frac{\pi}{2} - 0\right), a \rangle$$

II-1

$$\text{a) } \vec{r}(t) = \langle e^t, e^{-t} \rangle$$

$$\vec{v}(t) = \vec{r}'(t) = \langle e^t, -e^{-t} \rangle$$

$$\text{speed} = \sqrt{v(t)} = \sqrt{v'(t)} = \sqrt{x'(t)^2 + y'(t)^2}$$

$$v(t) = \sqrt{e^{2t} + e^{-2t}} = \frac{ds}{dt} \quad \text{- time rate of change of arc length}$$

$$\text{unit tangent vector} = \frac{\vec{v}(t)}{\| \vec{v}(t) \|} = \frac{\langle e^t, -e^{-t} \rangle}{\sqrt{e^{2t} + e^{-2t}}}$$

$$\vec{a}(t) = v'(t) = \langle e^t, e^{-t} \rangle$$

$$\text{b) } \vec{r}(t) = \langle t^2, t^3 \rangle \quad \vec{v}(t) = \langle 2t, 3t^2 \rangle$$

$$v(t) = \frac{ds(t)}{dt} = \sqrt{v'(t)} = \sqrt{4t^2 + 9t^4}$$

$$\text{unit tangent velocity} = \frac{\langle 2t, 3t^2 \rangle}{\sqrt{4t^2 + 9t^4}}$$

* arc length along curve with position vector $\vec{r}(t)$, from $\vec{r}(a)$ to $\vec{r}(b)$ is defined

$$\int_a^b (\sqrt{x'(t)^2 + y'(t)^2 + z'(t)^2})^2 dt$$

$$= \int_a^b \sqrt{v(t)} dt \quad \text{where } v(t) = \sqrt{v'(t)}$$

* arc length function

$$s(t) = \int_a^t \sqrt{v(t)} dt$$

$$\vec{a}(t) = \langle 2, 6t \rangle$$

$$c) \vec{r}(t) = \langle 1 - 2t^2, t^2, -2 + 2t^2 \rangle$$

$$\vec{v}(t) = \langle -4t, 2t, 4t \rangle$$

$$a(t) = \langle -4, 2, 4 \rangle$$

$$|\vec{v}(t)| = \sqrt{16t^2 + 4t^2 + 16t^2} = 6t$$

$$\text{unit tangent velocity: } \frac{\langle -4t, 2t, 4t \rangle}{6t}$$

$$1J-2 \quad \vec{OP} = \left\langle \frac{1}{1+t^2}, \frac{t}{1+t^2} \right\rangle = \vec{r}(t)$$

$$a) \vec{v}(t) = \left\langle \frac{-2t}{(1+t^2)^2}, \frac{1+t^2-t \cdot 2t}{(1+t^2)^2} \right\rangle = \left\langle \frac{-2t}{(1+t^2)^2}, \frac{1-t^2}{(1+t^2)^2} \right\rangle$$

$$s(t) = \int_0^t \left[\frac{4t^2}{(1+t^2)^4} + \frac{(1-t^2)^2}{(1+t^2)^4} \right]^{1/2} dt$$

$$\frac{ds}{dt} = \sqrt{s(t)} = \frac{4t^2 + 1 - 2t^2 + t^4}{(1+t^2)^4} = \frac{t^4 + 2t^2 + 1}{(1+t^2)^4} = \frac{(1+t^2)^2}{(1+t^2)^4} = \frac{1}{(1+t^2)^2}$$

$$\vec{r} = \frac{\vec{v}(t)}{\sqrt{s(t)}} = \left\langle \frac{-2t}{t^4 + 2t^2 + 1}, \frac{(1-t^2)(1+t^2)^2}{t^4 + 2t^2 + 1} \right\rangle$$

$$b) \quad s(t) = (1+t^2)^2$$

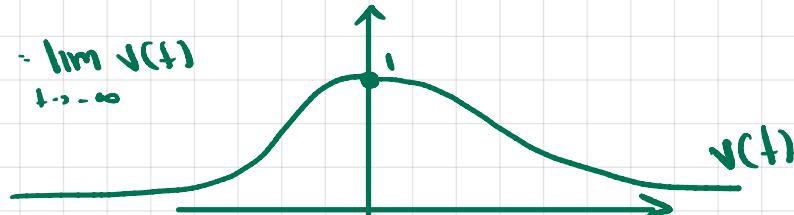
$$s'(t) = -2(1+t^2)^3 \cdot (2t) = \frac{-4t}{(1+t^2)^3}$$

$$s'(t) \cdot 0 \Rightarrow -4t \cdot 0 \Rightarrow t \cdot 0$$

$$\begin{array}{c} \oplus \\ 0 \\ \ominus \end{array} \quad s'(t) = c(t)$$

$$\lim_{t \rightarrow \infty} s(t) = 0 = \lim_{t \rightarrow -\infty} s(t)$$

$$s(0) = 1$$



t	x	y
0	1	0
1	$\frac{1}{2}$	$\frac{1}{4}$
2	$\frac{1}{5}$	$\frac{2}{25}$
3	$\frac{1}{10}$	$\frac{3}{100}$

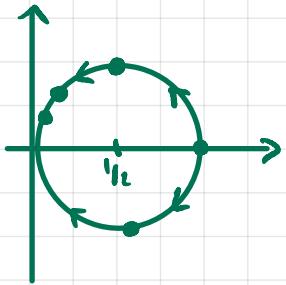
$$c) \quad x(t)^2 + y(t)^2 = \frac{1+t^2}{(1+t^2)^2} = \frac{1}{1+t^2} = x(t) \Rightarrow x^2 + y^2 = x$$

$$x^2 - x + \frac{1}{4} + y^2 - \frac{1}{4} \Rightarrow (x - \frac{1}{2})^2 + y^2 = \frac{1}{4}$$

$$\lim_{t \rightarrow \infty} x(t) = 0$$

$$\lim_{t \rightarrow \infty} y(t) = \lim_{t \rightarrow \infty} \frac{1}{2t} = 0$$

t	x	y
-1	$\frac{1}{2}$	$-\frac{1}{2}$
-2	$\frac{1}{5}$	$-\frac{2}{5}$



1J-3

$$\vec{r}(t) = \langle r_1(t), r_2(t) \rangle$$

$$\vec{s}(t) = \langle s_1(t), s_2(t) \rangle$$

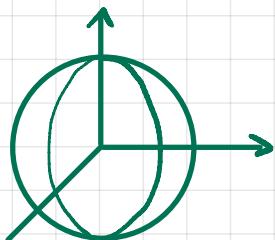
$$\vec{r} \cdot \vec{s} = r_1 s_1 + r_2 s_2$$

$$\begin{aligned}\frac{d}{dt} \vec{r} \cdot \vec{s} &= r'_1 s_1 + r_1 s'_1 + r'_2 s_2 + r_2 s'_2 \\ &= (r'_1 s_1 + r'_2 s_2) + (r_1 s'_1 + r_2 s'_2) \\ &= \langle r'_1, r'_2 \rangle \cdot \langle s_1, s_2 \rangle + \langle r_1, r_2 \rangle \langle s'_1, s'_2 \rangle \\ &= \vec{r}' \cdot \vec{s} + \vec{r} \cdot \vec{s}'\end{aligned}$$

1J-4

$$\vec{op} \cdot \vec{r}(t) = \langle x(t), y(t), z(t) \rangle$$

a) $|\vec{op}| = k \cdot \sqrt{x^2 + y^2 + z^2} = |\vec{r}(t)|$



$$\frac{2xx' + 2yy' + 2zz'}{2\sqrt{x^2 + y^2 + z^2}} = 0 \Rightarrow xx' + yy' + zz' = 0 \Rightarrow \vec{r}(t) \cdot \vec{r}'(t) = 0$$

b) sphere: $|\vec{r}| = k \Rightarrow |\vec{r}|^2 = \vec{r} \cdot \vec{r} = k^2$

$$\frac{d}{dt}(\vec{r} \cdot \vec{r}) = \vec{r}' \cdot \vec{r} + \vec{r} \cdot \vec{r}' = 0 + 2\vec{r}' \cdot \vec{r} \Rightarrow \vec{r}' \cdot \vec{r} = 0 \Rightarrow \vec{v} \cdot \vec{r} = 0$$

c) $\vec{r} \cdot \vec{v} = 0$

$$\vec{r} \cdot \vec{r} = |\vec{r}|^2$$

$$\frac{d}{dt}(\vec{r} \cdot \vec{r}) = 2\vec{r}' \cdot \vec{r} = 2\vec{v} \cdot \vec{r} = 0$$

$$\Rightarrow \int \left[\frac{d}{dt} (\vec{r} \cdot \vec{r}) \right] dt = k$$

$$\vec{r} \cdot \vec{r} = k$$

$$|\vec{r}|^2 = k \Rightarrow |\vec{r}| = \sqrt{k}$$

IJ-S

a) $\|\vec{v}(t)\| = k = \vec{v}(t) \cdot \vec{j}(t)$

$$\vec{v} \cdot \vec{v} = \vec{v} \cdot \vec{v} + \vec{v} \cdot \vec{v} = 0$$

$$2\vec{v} \cdot \vec{v} = 0 \Rightarrow \vec{v} \cdot \vec{v} = 0 \Rightarrow \vec{a}(t) \cdot \vec{v}(t) = 0$$

b) $\vec{v} \cdot \vec{v} = 0$

$$\|\vec{v}\|^2 = \vec{v} \cdot \vec{v}$$

$$\frac{d}{dt} \vec{v} \cdot \vec{v} = 2\vec{v} \cdot \vec{v} = 2\vec{v} \cdot \vec{v} = 0$$

$$\Rightarrow \vec{v} \cdot \vec{v} = \|\vec{v}\|^2 = k \Rightarrow \|\vec{v}\| = \sqrt{k}$$

IJ-6 $\vec{r}(t) = \langle a \cos t, a \sin t, bt \rangle$

a) $\vec{v}(t) = \langle -a \sin t, a \cos t, b \rangle$

$$\vec{a}(t) = \langle -a \cos t, -a \sin t, 0 \rangle$$

$$\vec{T} = \frac{\vec{v}(t)}{\|\vec{v}(t)\|}$$

$$\|\vec{v}(t)\| = \|\vec{v}(t)\| \cdot \sqrt{a^2 \sin^2 t + a^2 \cos^2 t + b^2} = \sqrt{a^2 + b^2} = k$$

$$\frac{ds}{dt} = \|\vec{v}(t)\|$$

b) $\vec{a}(t) = \langle -a \cos t, a \sin t, 0 \rangle$

$$= 2(t) \vec{v}(t) = a^2 \sin t \cos t - a^2 \sin t \cos t = 0$$

The point moves with constant speed, which means (b) FJ-S that $\vec{a}(t) \cdot \vec{v}(t) = 0$.

$$1J-9 \quad \vec{r}(t) = \langle 3\cos t, 5\sin t, 4\cos t \rangle$$

$$a) \|\vec{r}(t)\| = \sqrt{9\cos^2 t + 25\sin^2 t + 16\cos^2 t} = \sqrt{25} = 5$$

$$b) \vec{r}'(t) = \langle -3\sin t, 5\cos t, -4\cos t \rangle$$

$$s(t) = \int \sqrt{9\sin^2 t + 25\cos^2 t + 16\sin^2 t} dt = \int \sqrt{5t} dt = \int 5dt$$

$$\frac{ds}{dt} = \sqrt{5} = 5$$

$$c) \vec{a}(t) = \vec{r}'(t) = \langle -3\cos t, 5\sin t, -4\cos t \rangle = -\vec{r}(t)$$

$$d) \vec{r} \cdot (\vec{i} \times \vec{j}) = \begin{vmatrix} 3\cos t & 5\sin t & 4\cos t \\ -3\sin t & 5\cos t & -4\sin t \\ -3\cos t & -5\sin t & -4\cos t \end{vmatrix}$$

$$= 3\cos t(-20\cos^2 t - 20\sin^2 t) - 5\sin t(12\sin t \cos t - 12\sin t \cos t) + 4\cos t(15\sin^2 t + 15\cos^2 t)$$

$$= -60\cos t + 60\cos t = 0$$

$\Rightarrow \vec{r}, \vec{i}, \vec{j}$ always lie on the same plane, but it always lies in the same plane?

$$\vec{r} \times \vec{j} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 3\cos t & 5\sin t & 4\cos t \\ -3\sin t & 5\cos t & -4\sin t \end{vmatrix}$$

$$= \langle -20\sin^2 t - 20\cos^2 t, -(-12\sin t \cos t + 12\sin t \cos t), 15\cos^2 t + 15\sin^2 t \rangle$$

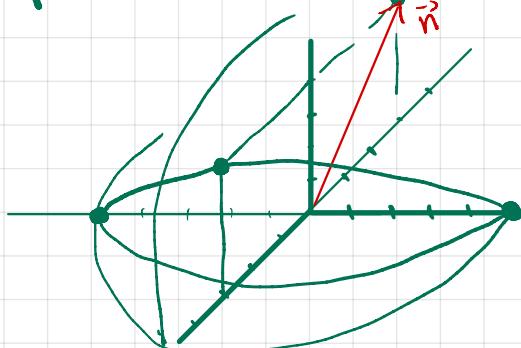
$$= \langle -20, 0, 15 \rangle = \vec{n}$$

$\Rightarrow \vec{r} \times \vec{j}$ gives a normal vector to the plane shared by \vec{r} and \vec{j} . Since this normal vector is always the same (ie doesn't depend on t), the plane of motion always lies in the same plane. The plane passes through the origin because the position vector starts at origin, and the direction is the same plane.

$$e) \vec{r}(0) = \langle 3, 0, 4 \rangle$$

$$\vec{r}(\pi/2) = \langle 0, 5, 0 \rangle$$

$$\vec{r}(-\pi/2) = \langle 0, -5, 0 \rangle$$



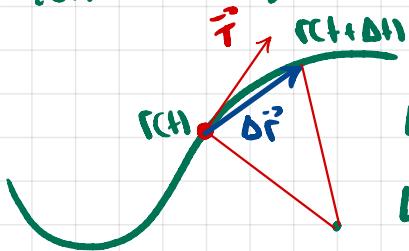
IK-2

$$\vec{s}(t) \text{ vector function, prove } \frac{d\vec{s}}{dt} \cdot \vec{\omega} \Rightarrow \vec{s}(t) \cdot \vec{\kappa}$$

$$\frac{d}{dt}(\vec{s}(t)) = \left\langle \frac{d}{dt}s_1(t), \frac{d}{dt}s_2(t) \right\rangle = \langle 0, 0 \rangle$$

$$\Rightarrow \vec{s}'(t) \cdot \vec{\omega} = \int \left\langle \frac{d}{dt}\vec{s}_1(t), \frac{d}{dt}\vec{s}_2(t) \right\rangle dt = \int \langle 0, 0 \rangle dt = \langle 0, 0 \rangle$$

IK-3



Area swept from $\vec{r}(t)$ to $\vec{r}(t+\Delta t)$ \approx approx. $\frac{1}{2}(\vec{r} \times \Delta \vec{r})$

$$\Delta \vec{r} \approx \vec{v}(t) \Delta t \Rightarrow \text{Area} \approx \frac{1}{2}(\vec{r} \times \vec{v}) \Delta t$$

We start with the assumption that $\vec{\omega} \parallel \vec{r}$

$\Leftrightarrow \vec{r} \times \vec{\omega} = 0$ & \vec{r} and $\vec{\omega}$ lie in the same plane through origin

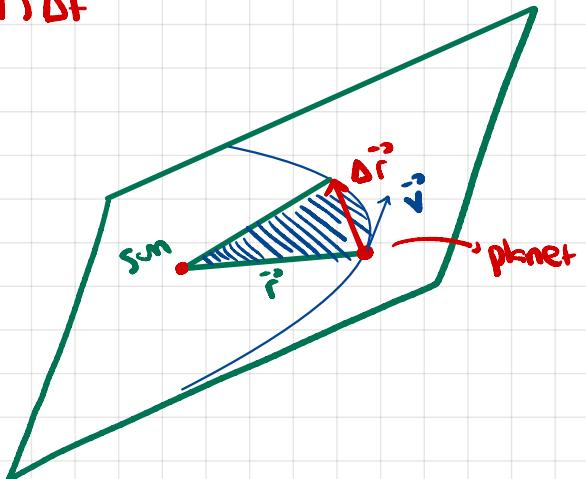
$$\Leftrightarrow \vec{r} \times \frac{d\vec{v}}{dt} = 0 \Leftrightarrow \vec{v} \times \vec{v} + \vec{r} \times \frac{d\vec{v}}{dt} = 0 \Leftrightarrow \frac{d\vec{r}}{dt} \times \vec{v} + \vec{r} \times \frac{d\vec{v}}{dt} = 0 \Leftrightarrow \frac{d}{dt}(\vec{r} \times \vec{v}) = 0$$

Use result from IK-2: $\frac{d\vec{s}}{dt} \cdot \vec{\omega} \Rightarrow \vec{s}(t) \cdot \vec{\kappa}$

$$\frac{d}{dt}(\vec{r} \times \vec{v}) = 0 \Rightarrow \vec{r} \times \vec{v} = \vec{\kappa}$$

But the area swept by the moving point is $\approx \frac{1}{2}(\vec{r} \times \vec{v}) \Delta t$

$$\Rightarrow \text{Area} \approx C \Delta t$$



Kepler's Law in terms of vectors

$$1) \text{ Area} \approx \frac{1}{2} |\vec{r} \times \Delta \vec{r}| \approx \frac{1}{2} |\vec{r} \times \vec{v}| \Delta t$$

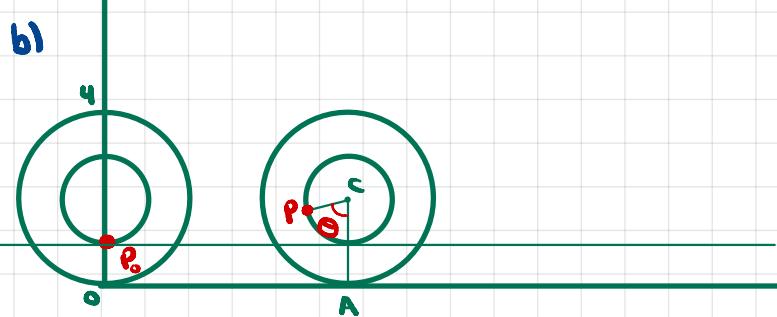
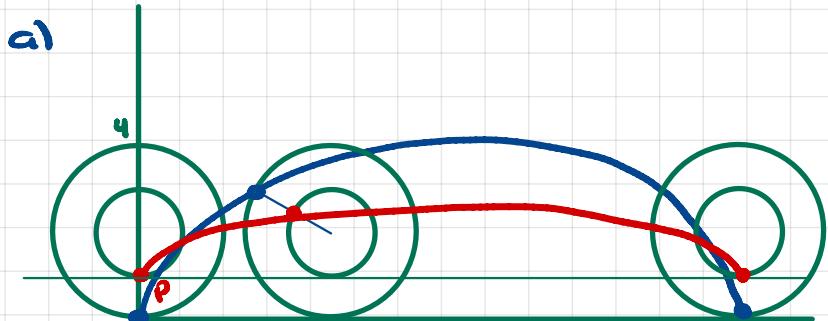
$$\text{Swept in time } \Delta t \quad \Delta r \approx \vec{v} \Delta t$$

Law says areas proportional to $\Delta t \Rightarrow |\vec{r} \times \vec{v}| - \text{constant}$

2) Plane of motion contains \vec{r} and \vec{v}

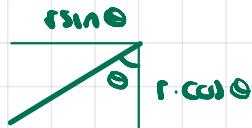
$\Rightarrow \vec{r} \times \vec{v}$ normal to plane of motion

Problem 1



$$\vec{OP} = \vec{OA} + \vec{AC} + \vec{CP}$$

$$\vec{OA} = \langle a\theta, 0 \rangle$$

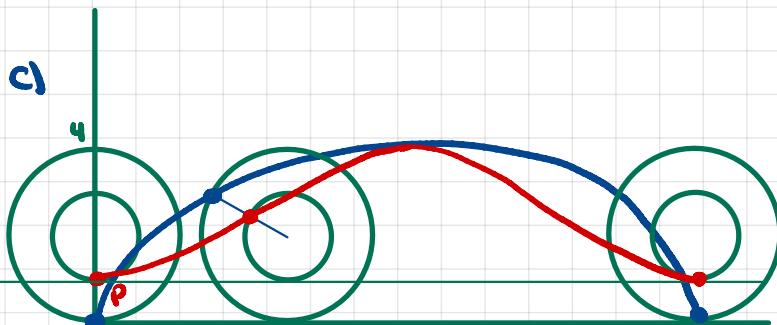


$$\vec{AC} = \langle 0, a \rangle$$

$$\vec{CP} = \langle -r\sin\theta, -r\cos\theta \rangle$$

$$\vec{OP} = \langle a\theta - r\sin\theta, a - r\cos\theta \rangle$$

$$\text{For } a=2, r=1 : \vec{OP} = \langle 2\theta - \sin\theta, 2 - \cos\theta \rangle$$



I thought the motion of P would be analogous to the motion on the outer rim of the wheel.

Problem 2

a) $\hat{u}, \hat{j}, \hat{v} \perp \hat{u}$

$$\vec{r}(t) = \cos t \hat{u} + \sin t \hat{v} = \langle u_1 \cos t + v_1 \sin t, u_2 \cos t + v_2 \sin t, \dots \rangle$$

$$|\vec{r}'(t)|^2 = \sqrt{(u_1 \cos t + v_1 \sin t)^2 + (u_2 \cos t + v_2 \sin t)^2 + (u_3 \cos t + v_3 \sin t)^2}$$

$$= \underbrace{\cos^2 t (u_1^2 + u_2^2 + u_3^2)}_{|\vec{u}|^2=1} + \underbrace{\sin^2 t (v_1^2 + v_2^2 + v_3^2)}_{|\vec{v}|^2=1} + \cancel{2 \sin t \cos t (u_1 v_1 + u_2 v_2 + u_3 v_3)}$$

$$= \vec{u} \cdot \vec{v} = 0$$

$$\sqrt{\cos^2 t + \sin^2 t} = 1$$

$\Rightarrow |\vec{r}(t)| = 1$, which by itself would be a sphere, however $\vec{r}'(t)$ is a lin. comb. of \hat{u} and \hat{v} . $\vec{u} \times \vec{v}$ is normal to the plane spanned by \hat{u} and \hat{v} and

$$\vec{u} \times \vec{v} \cdot \vec{r} = \vec{u} \times \vec{v} \cdot (\cos t \hat{u} + \sin t \hat{v}) = \vec{u} \times \vec{v} \cdot \hat{u} \cos t + \vec{u} \times \vec{v} \cdot \hat{v} \sin t = 0$$

\Rightarrow for all t , $\vec{r}'(t)$ is always \perp to the same normal vector $\vec{u} \times \vec{v} \Rightarrow \vec{r}'(t)$ is always on the same plane. $\Rightarrow \vec{r}(t)$ on a plane, $|\vec{r}'| = 1 \Rightarrow \vec{r}(t)$ is a circle

b) $P: x+2y+z=0 \quad \vec{n} = \langle 1, 2, 1 \rangle \quad \vec{r}(t)$ is \perp to \vec{n} (it is on P) and $|\vec{r}'(t)| = 1$

we can use any two vectors on P , make them unit vectors, and parametrize the circle

c) in a).

$$x=0, y=1 \Rightarrow z=-2 \quad \langle 0, 1, -2 \rangle \sim \hat{u} \quad |\vec{u}| = \sqrt{5} \quad \hat{u} = \frac{\langle 0, 1, -2 \rangle}{\sqrt{5}}$$

$$\hat{u} \times \vec{n} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 1/\sqrt{5} & -2/\sqrt{5} \\ 1 & 2 & 1 \end{vmatrix} = \hat{i} \left(\frac{1}{\sqrt{5}} + \frac{4}{\sqrt{5}} \right) - \hat{j} \left(\frac{2}{\sqrt{5}} \right) + \hat{k} \left(-\frac{1}{\sqrt{5}} \right)$$

$$= \left\langle \frac{5}{\sqrt{5}}, -\frac{2}{\sqrt{5}}, -\frac{1}{\sqrt{5}} \right\rangle = \left\langle \sqrt{5}, -\frac{2\sqrt{5}}{5}, -\frac{\sqrt{5}}{5} \right\rangle$$

$$\hat{v} = \left\langle \frac{\sqrt{30}}{6}, -\frac{\sqrt{30}}{15}, -\frac{\sqrt{30}}{30} \right\rangle \Rightarrow \hat{u} \cdot \hat{v} = 0$$

$$\vec{r}(t) = \cos(t) \cdot \hat{u} + \sin(t) \cdot \hat{v}$$

c) Maple plot:

```
with(VectorCalculus)
n := <1, 2, 1>
u := <0, 1, -2>
uhat := u / Norm(u)
v := CrossProduct(uhat, n)
vhat := v / Norm(v)
```

$r := \cos(t) \cdot uhat + \sin(t) \cdot vhat$

plot3d(r, t=0..2π)

Problem 3

a) $x+2y+z=0$ is plane P

All lines passing through P are perpendicular to $\langle 1, 2, 1 \rangle$.

For $\langle x, y, z \rangle$ on a line:

$$\langle x, y, z \rangle \cdot \langle 0, 0, 0 \rangle + \langle a, b, c \rangle t \quad \text{where } \langle a, b, c \rangle \cdot \langle 1, 2, 1 \rangle = 0$$

$$\langle x, y, z \rangle \cdot \langle a, b, c \rangle t = \langle a, b, -a-2b \rangle t$$

$$a+2b+c=0$$

$$\Rightarrow c=-a-2b$$

$$\Rightarrow x(t) = ct$$

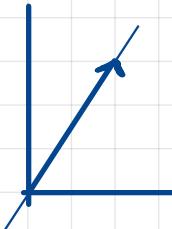
$$y(t) = bt$$

$$z(t) = (-a-2b)t$$

$$\frac{x(t)}{y(t)} = \frac{c}{b} = \text{constant} \rightarrow \text{we can scale}$$

$\langle a, b, -a-2b \rangle$ such that the coeff. on x is the ratio between a and b. If the ratio is α parameters then all we need to specify is the ratio to get the $\langle \frac{z}{\alpha}, 1 \rangle$ gives the same line after const. based on their relationship with the param.

$$* \vec{r} \cdot \langle 2t, 3t \rangle = t \langle 2, 3 \rangle$$

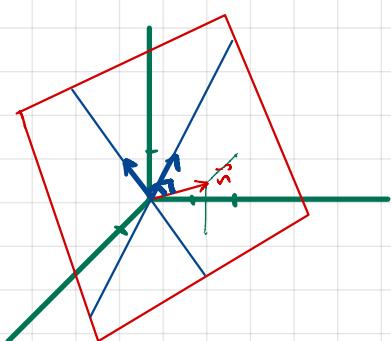


x and y maintain the same proportion. They are scaled up or down based on $\langle 2, 3 \rangle$. We can scale the vector up or down in size.

$$\langle x, y, z \rangle = \left\langle \frac{a}{b}, 1, -\frac{a}{b}-2 \right\rangle$$

$$= \langle \alpha, 1, -\alpha-2 \rangle$$

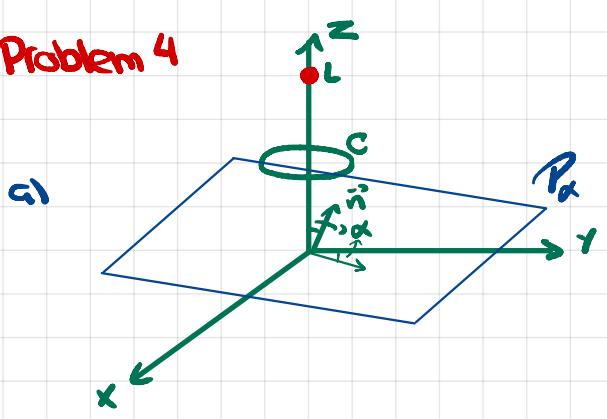
b)



This family of lines contains lines that are perpendicular to $\langle 1, 2, 1 \rangle$. Given one line we can get all the others by rotating the first line around the axis formed by the normal vector $\langle 1, 2, 1 \rangle$.

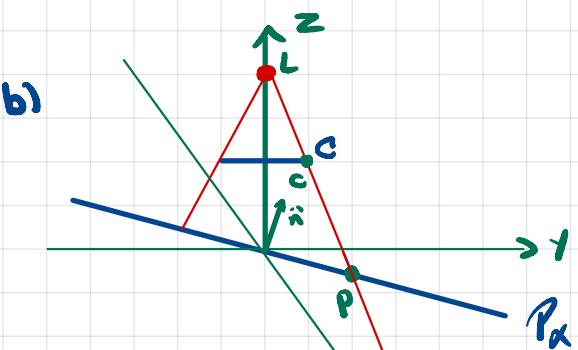
We need one parameter only to identify one particular direction perpendicular to $\langle 1, 2, 1 \rangle$, and that is α . The direction will then be that of the vector $\langle \alpha, 1, -\alpha-2 \rangle$.

Problem 4

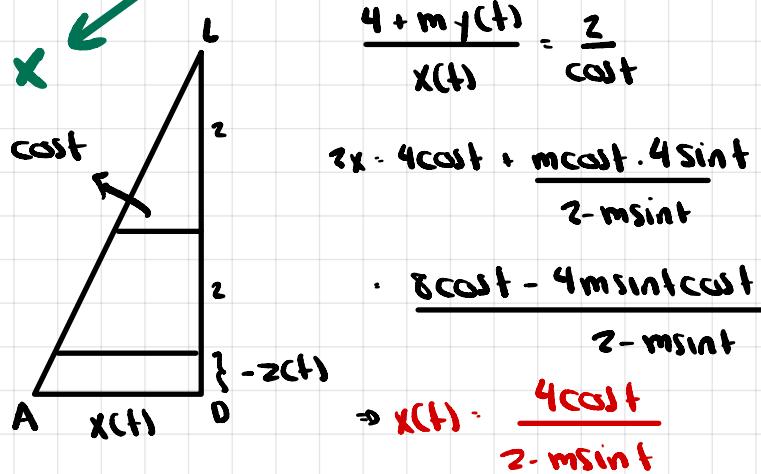
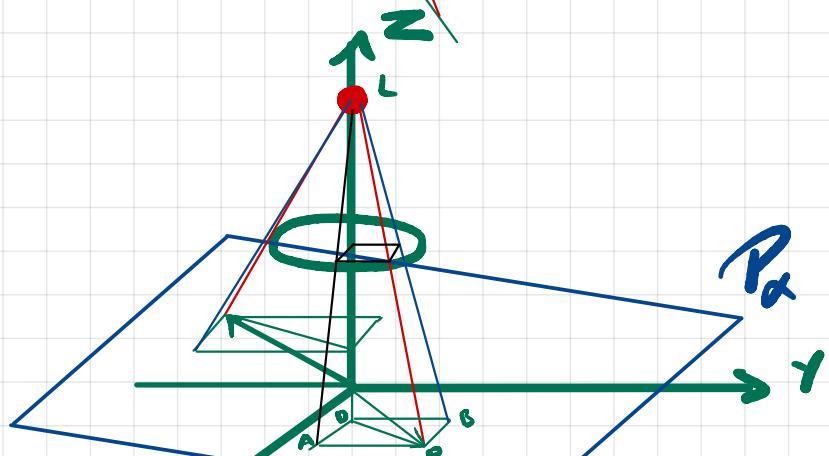


$$C(t) = \langle \cos t, \sin t, 2 \rangle$$

$$\vec{C}(t) = \langle \cos t, \sin t, 2 \rangle$$



$$\vec{OP} = \vec{OC} + \vec{CP}$$



$$P_x: m_y + z = 0 \quad m = \tan \alpha$$

$$\Rightarrow \frac{\sin \alpha}{\cos \alpha} y + z = 0$$

$$\Rightarrow \sin \alpha \cdot y + \cos \alpha z = 0$$

normal vector to P_x

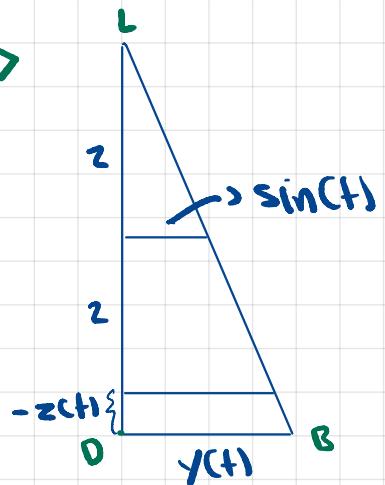
$$\langle 0, \sin \alpha, \cos \alpha \rangle \quad \text{proportion } \frac{y}{z}$$

$$\langle 0, \tan \alpha, 1 \rangle = \langle 0, m, 1 \rangle = \vec{n}$$

vectors on P_x

$$z = -my$$

$$\langle x, y, -my \rangle$$



$$\frac{z}{\sin t} = \frac{4 - z(t)}{y(t)}, \quad z(t) = -my(t)$$

$$2y = 4 \sin t + m \sin t$$

$$y(2 - m \sin t) = 4 \sin t$$

$$\Rightarrow y(t) = \frac{4 \sin t}{2 - m \sin t}$$

$$\Rightarrow z(t) = \frac{-4m \sin t}{2 - m \sin t}$$

$$\vec{r}(t) = \left\langle \frac{4 \cos t}{2 - m \sin t}, \frac{4 \sin t}{2 - m \sin t}, \frac{-4m \sin t}{2 - m \sin t} \right\rangle$$

$$c) \vec{r}_\alpha(t) = \left\langle \frac{4\cos t}{2-m\sin t}, \frac{4\sin t}{2-m\sin t}, \frac{-4m\sin t}{2-m\sin t} \right\rangle$$

$$\alpha=0 \Rightarrow m=0 \Rightarrow \vec{r}(t) = \langle 2\cos t, 2\sin t, 0 \rangle$$

$$\Rightarrow x^2 + y^2 = 4, \text{ circle radius } 2$$

$$|\vec{r}_\alpha(t) - \vec{r}_0(t)|$$

$$\vec{r}_\alpha(t)$$

$$t=0 \quad \left\langle \frac{4}{2} - 2, 0, 0 \right\rangle \\ \left\langle 2, 0, 0 \right\rangle$$

$$\vec{r}_0(t)$$

$$\left\langle 2, 0, 0 \right\rangle$$

$$\vec{r}_\alpha(t) - \vec{r}_0(t)$$

$$|\vec{r}_\alpha(t) - \vec{r}_0(t)|$$

$$0$$

$$t=\pi/2 \quad \left\langle 0, \frac{4}{2-m}, \frac{-4m}{2-m} \right\rangle$$

$$\left\langle 0, 2, 0 \right\rangle \quad \left\langle 0, \frac{4-(4-2m)}{2-m}, \frac{4m}{2-m} \right\rangle$$

$$\left\langle 0, \frac{3m}{2-m}, \frac{4m}{2-m} \right\rangle$$

$$\sqrt{\frac{4m^2 + 16m^2}{(2-m)^2}} \\ - \sqrt{\frac{20m^2}{(2-m)^2}}$$

$$t=\pi \quad \left\langle \frac{-4}{2}, 0, 0 \right\rangle \\ \left\langle -2, 0, 0 \right\rangle$$

$$\left\langle -2, 0, 0 \right\rangle$$

$$\left\langle 0, 0, 0 \right\rangle$$

$$0$$

$$t=\frac{3\pi}{2} \quad \left\langle 0, \frac{-4}{2+m}, \frac{4m}{2+m} \right\rangle$$

$$\left\langle 0, -2, 0 \right\rangle$$

$$\left\langle 0, \underbrace{\frac{-4}{2+m} + 2}_{\frac{-4+4+2m}{2+m}}, \frac{4m}{2+m} \right\rangle$$

$$\sqrt{\frac{4m^2 + 16m^2}{(2+m)^2}}$$

$$\frac{-4+4+2m}{2+m}$$

$$= \frac{2m}{2+m}$$

$$\left\langle 0, \frac{2m}{2+m}, \frac{4m}{2+m} \right\rangle$$

$$= \sqrt{\frac{20m^2}{(2+m)^2}}$$

The largest distortion, as estimated using the distance

$|\vec{r}_\alpha(t) - \vec{r}_0(t)|$, has largest value at

$\sqrt{\frac{20m^2}{(2+m)^2}}$. When $m > 0$ ($\alpha > 0$), $\sqrt{20m^2/(2-m)^2}$ is largest and for $m < 0$

($\alpha < 0$) $\sqrt{20m^2/(2+m)^2}$ is largest. The part of the plane furthest from the light source is most distorted, i.e. the portion tilted below the xy -plane.