

PSet 16 - Frequency Response - Part I

$$1. \ddot{x} + 6\dot{x} + 4x = 50 \cos \omega t$$

$$\ddot{z} + 6\dot{z} + 4z = 50e^{j\omega t}$$

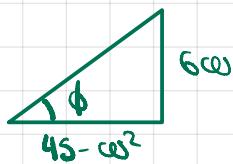
$$p(r) = r^2 + 6r + 45$$

$$p(i\omega) = -\omega^2 + 6i\omega + 45$$

$$\text{response: } x_p(t) = \frac{50}{|p(i\omega)|} \cdot \cos(\omega t - \phi)$$

$$|p(i\omega)| = \sqrt{(45 - \omega^2)^2 + 36\omega^2}$$

$$\phi = \text{Arg}(p(i\omega)) = \tan^{-1}\left(\frac{6\omega}{45 - \omega^2}\right)$$



$$\text{gain}(\omega) = \frac{1}{\sqrt{(45 - \omega^2)^2 + 36\omega^2}}$$

$$\max \text{ gain when } \min (45 - \omega^2)^2 + 36\omega^2$$

$$2(45 - \omega^2)(-2\omega) + 72\omega = 0$$

$$-4\omega(45 - \omega^2) + 72\omega = -180\omega + 4\omega^3 + 72\omega = 0$$

$$\omega(4\omega^2 - 108) = 0$$

$$\Rightarrow \omega^2 = 27 \Rightarrow \omega = \sqrt{27}$$

Part II

$$1. \ddot{x} + \frac{1}{2}\dot{x} + 4x = \cos 2t$$

$$\ddot{z} + \frac{\dot{z}}{2} + 4z = e^{2it}$$

$$p(z) = z^2 + \frac{1}{2}z + 4$$

$$p(z_i) = -4 + i + 4 - i$$

$$|p(z_i)| = 1$$

a) gain = 1

phase = $\pi/2$

$$b) z_p = \frac{1}{p(\omega i)} \cdot e^{i\omega t}$$

$$\text{complex gain} = \frac{1}{p(\omega i)} = \frac{1}{4 - \omega^2 + \frac{\omega i}{2}}$$

$$= \frac{4 - \omega^2 - \omega i/2}{(4 - \omega^2)^2 + (\omega/2)^2}$$

$$p(\omega i) = -\omega^2 + \frac{\omega i}{2} + 4$$

$$\text{gain} = \frac{1}{|p(\omega i)|} = \frac{1}{\sqrt{(4 - \omega^2)^2 + (\omega/2)^2}}$$

$$\phi = \arg(p(\omega i))$$

$$\tan \phi = \frac{\omega/2}{4 - \omega^2}$$

$$2. a) \max \text{ gain} \Rightarrow z(4 - \omega^2)(-2\omega) + \frac{\omega}{2} = 0$$

$$\Rightarrow -16\omega + 4\omega^3 + \frac{\omega}{2} = 0 \Rightarrow 8\omega^3 - 31\omega = 0$$

$$\Rightarrow \omega(8\omega^2 - 31) = 0$$

$$\Rightarrow \omega_r = \sqrt{\frac{31}{8}} < 2$$

$$g(\omega_r) = 1.0079\dots$$

$$b) \phi = \pi/4 \Rightarrow \frac{\omega}{8 - 2\omega^2} = 1 \Rightarrow 2\omega^2 + \omega - 8 = 0$$

$$\Delta = 1 - 4 \cdot 2 \cdot (-8) = 65 \Rightarrow \omega = \frac{-1 + \sqrt{65}}{4} = 1.76\dots$$

c) Nyquist Plot

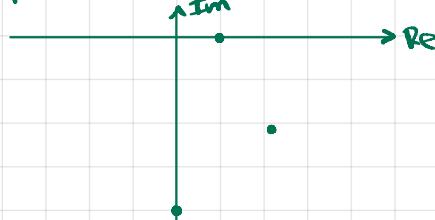
$$\tilde{g}(\omega) = \frac{1}{p(\omega i)} = \frac{1}{4 - \omega^2 + \frac{\omega i}{2}} = \frac{4 - \omega^2 - \frac{\omega i}{2}}{(4 - \omega^2)^2 + (\omega/2)^2}$$

$$\text{on complex plane } \left\langle \frac{4 - \omega^2}{(4 - \omega^2)^2 + (\omega/2)^2}, \frac{-\omega/2}{(4 - \omega^2)^2 + (\omega/2)^2} \right\rangle$$

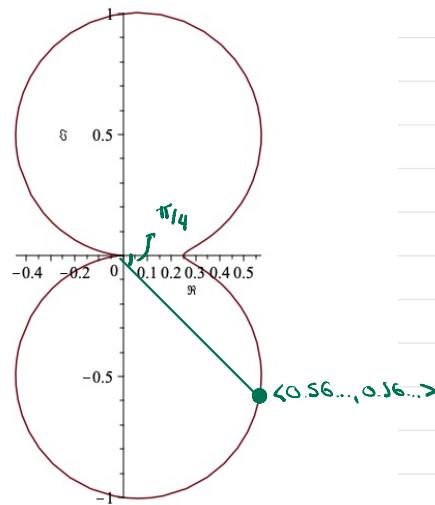
$$\omega = 0 \Rightarrow \langle 1/4, 0 \rangle$$

$$\omega = 2 \Rightarrow \langle 0, -1 \rangle$$

$$\phi = \frac{\pi}{4} \Rightarrow \omega = 1.76\dots \Rightarrow \langle 0.56\dots, -0.56\dots \rangle$$



$$\left\langle \frac{4 - \omega^2}{(4 - \omega^2)^2 + (\omega/2)^2}, \frac{-\omega/2}{(4 - \omega^2)^2 + (\omega/2)^2} \right\rangle =$$



$$d) p(r) = mr^2 + br + k$$

$$p(\omega) = -m\omega^2 + b\omega i + k = (k - \omega^2) + b\omega i$$

$$\tilde{g}(\omega) = \frac{1}{k - m\omega^2 + b\omega i} = \frac{(k - \omega^2) - b\omega i}{(k - \omega^2)^2 + b^2\omega^2}$$

\tilde{g} is purely imag. then $k = \omega^2 = 0$. This condition does not depend on b . The magnitude of the purely im. part does.

$$\tilde{g}(r) = \frac{-bi}{b^2 \cdot 4} = \frac{-i}{2b} \quad \uparrow b \Rightarrow \downarrow \max \text{ real gain} = \frac{1}{2b}$$

$$|\tilde{g}(\omega)| = \frac{1}{|p(\omega)|} = \sqrt{\frac{1}{(4 - \omega^2)^2 + b^2\omega^2}}$$

\Rightarrow real gain depends on b

As we reduce k we are reducing the spring constant.

Also,

$$m\ddot{x}'' + b\dot{x}' + kx = 0$$

$$p(r) = mr^2 + br + k$$

$$e^{rt} p(r) = 0$$

$$\Delta = b^2 - 4mk$$

$$r = \frac{-b \pm \sqrt{b^2 - 4mk}}{2m}, \text{ assume } b^2 - 4mk < 0$$

$$e^{\frac{-bt}{2m}} e^{\frac{\sqrt{4mk-b^2}}{2m}it}$$

$$\text{call } \frac{\sqrt{4mk-b^2}}{2m} = \omega_0$$

$$e^{\frac{\sqrt{4mk-b^2}}{2m}it} = e^{\omega_0 it} = \cos \omega_0 t + i \sin \omega_0 t$$

$$\Rightarrow e^{\frac{-bt}{2m}} \cos \omega_0 t, e^{\frac{-bt}{2m}} \sin \omega_0 t \text{ are solns}$$

$$\Rightarrow x_h = c_1 e^{\frac{-bt}{2m}} \cos \omega_0 t + c_2 e^{\frac{-bt}{2m}} \sin \omega_0 t \\ = e^{\frac{-bt}{2m}} (c_1 \cos \omega_0 t + c_2 \sin \omega_0 t)$$

So also input, ω_1 complex roots, orginal freq. (pseudo-freq.)
is $\frac{\sqrt{4mk-b^2}}{2m}$. Reducing spring constant (or increasing damping)
reduce this "natural" pseudo-freq.

$$\Rightarrow \tilde{g}(\omega) = \frac{(k-m\omega^2) - b\omega i}{(k-m\omega^2)^2 + b^2\omega^2} \Rightarrow \text{purely imag (ie } \phi = \pi/2\text{)} \text{ when}$$

$$\omega^2 = \frac{k}{m} \Rightarrow \omega = \sqrt{\frac{k}{m}}$$

$$\phi = \arg(p(i\omega)) = \arg(-m\omega^2 + bi\omega + k)$$

$$\Rightarrow \tan \phi = \frac{b\omega}{k-m\omega^2} \Rightarrow \tan \phi = \frac{b}{k} \Rightarrow \phi$$

$$\tilde{g}(\omega) = \frac{1}{k-m\omega^2 + b\omega i} = \frac{(k-m\omega^2) - b\omega i}{(k-m\omega^2)^2 + b^2\omega^2}$$

$$\phi = \frac{\pi}{2} \Rightarrow \frac{k-m\omega^2}{(k-m\omega^2)^2 + b^2\omega^2} = 0 \Rightarrow \omega = \sqrt{\frac{k}{m}}$$