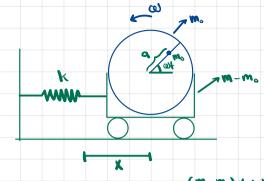
## 2.6 Forces Oscillations and Resonance

Example of selep that produces mass-spring system with sinusoidal input:



gibbecount of controls =  $\underline{X} = \frac{m}{(m-m^o)X + m^o(X + crossof)} = X + \frac{m}{m^o c}$  cosof

2nd law: mx = - kx

sib in X: mx"- mo a coscoscot - - KX

mx"+kx = moacosot

This is a mass-spring sthem cally estendingut

call Fo = moa w2 = mx"+kx = Fo cos wt

To show I such equations, short all mx" + kx = Fo coscot

b(1) = m(2+K=0 = 12= - m = 1= + (KIm)15!

 $X_{c_i} = e^{\left(\frac{k}{m}\right)^{1/c_i}} = \cos t \sqrt{\frac{k}{m}} + i \sin t \sqrt{\frac{k}{m}}$ 

 $X_c(t) = c_1 \cos t \int_{m}^{k} + c_2 \sin t \int_{m}^{k} = c_1 \cos \omega_0 t + c_2 \sin \omega_0 t$ 

000 = natural steapency

TI + Xp = Account, is a sinuscial cillin angula they out ou.

 $= \chi_{\theta}(t) = \frac{\omega_{o}^{o} - \omega_{r}}{V_{o}^{o} - \omega_{r}} cos \omega t$ 

=  $\chi(t)$  =  $C_1(co)\omega_0 t + C_2(in\omega_0 t) + \frac{F_0(m)}{\omega_0^2 - \omega^2} = co(\omega t)$ 

-  $C(\omega)(\omega) + \frac{1}{\omega^2 - \omega^2} = Cos(\omega) + cos(\omega) + cos(\omega)$