



Secure Connectivity Determination Under the Risk of Adversarial Model

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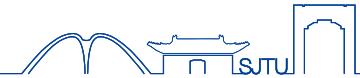
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Introduction

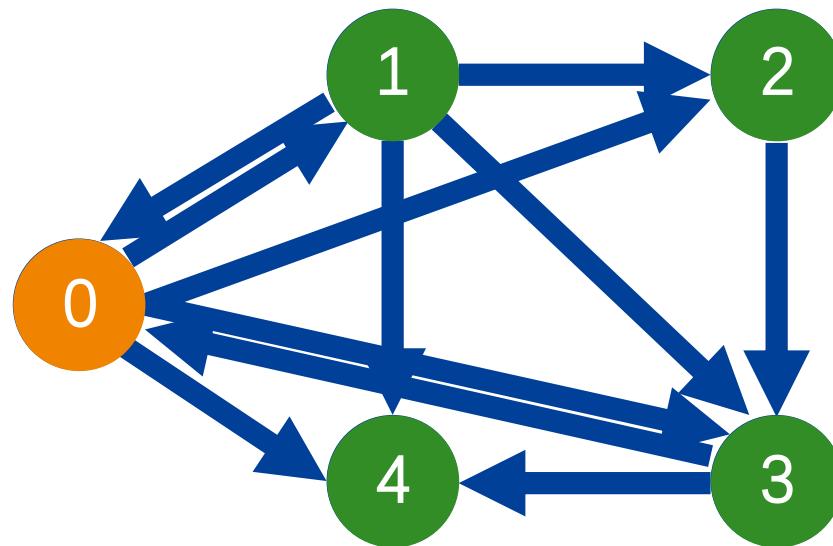


- We consider the scene that in a network $G = (V, E)$:
 - Define **Connectivity** as the number of points **reachable by the source point** divided by the total number of points other than the source.
 - $\text{Connectivity} \stackrel{\text{def}}{=} \sum_{v \in V, v \neq \text{src}} \frac{1_{\text{connected}(\text{src}, v)}}{|V|-1}$
 - **The attacker** is trying to reduce the connectivity by deleting K edges.
 - **The defender** can choose K edges and protect them from attacks.
 - The attack on the edge that has been protected will fail.
 - We design a framework based on reinforcement learning, in which we simultaneously train an attacker model and a defender model. Our work is inspired by **GAN**.
 - Our experiments show that the RL-based model performs better than a rule-based algorithm and the stochastic algorithm.

Introduction



- First the network is represented by a directed graph G with $N(=5)$ vertices and $M(=11)$ edges. The source point is v_0 by default.

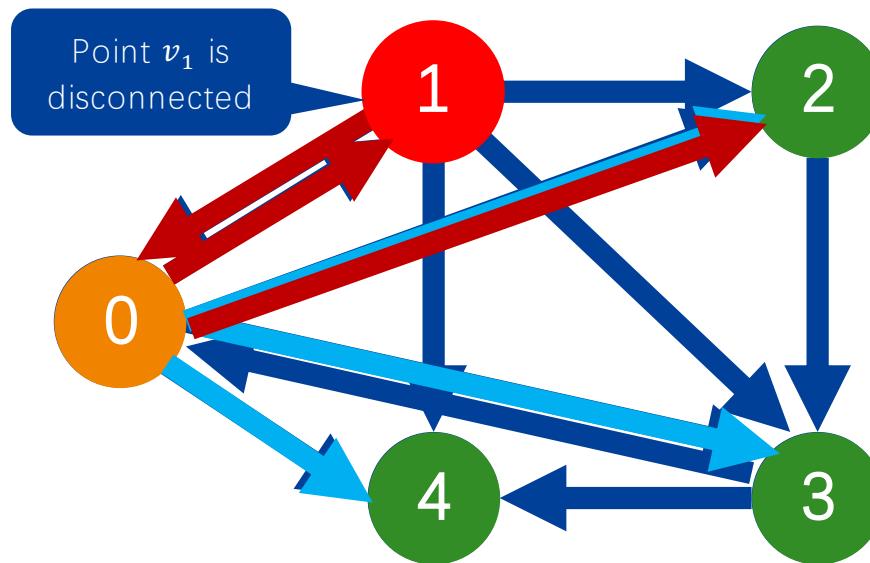


- Note that in this original graph, the source point is connected to all other four vertices.

Introduction



- Some edges are defended by the Defender.
- And some are under attack of the Attacker.



- Our goal is to develop stronger defender that can protect the connectivity.

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Works on Connectivity Under Attack



- *Near Optimal Adaptive Shortest Path Routing with Stochastic Links States under Adversarial Attack (Pan Zhou, 2016)*
 - The shortest path routing of a network with stochastically time varying link metrics under potential adversarial attacks.
 - Formulating it as a multi-armed bandit (MAB) problem.
- *The adversarial stochastic shortest path problem with unknown transition probabilities (Gergely Neu, 2012)*
 - loop-free stochastic shortest path problems.
 - “follow the perturbed optimistic policy”

Works on Connectivity Under Attack



- *Adversarial resilience of matchings in bipartite random graphs (P. Balister, 2017)*
 - How to find the maximum matching in bipartite graphs after an adversary deleted some edges.
- *Adversarial Deletion in a Scale Free Random Graph Process (AD Flaxman, 2007)*
 - A property in a dynamically evolving random graph.

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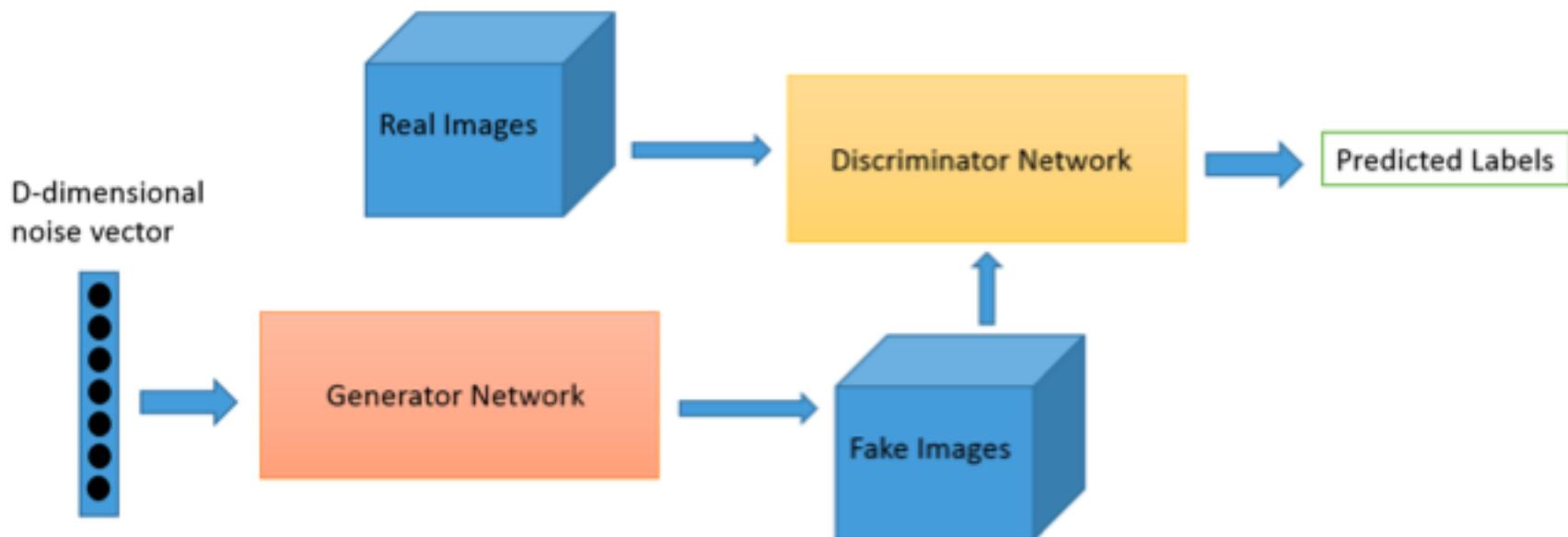


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Review of GANs



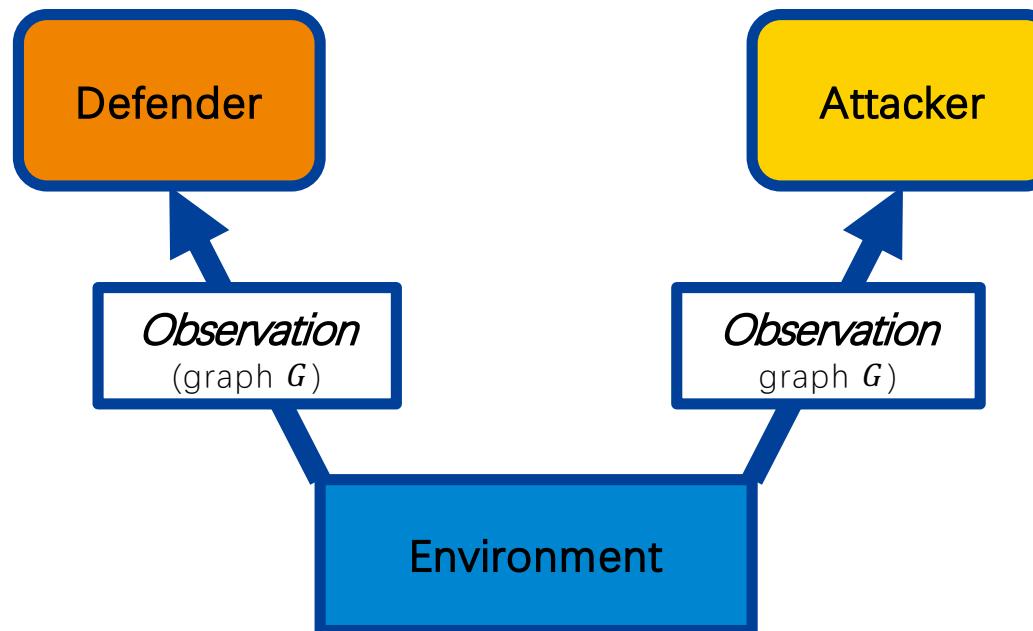
- First, let us quickly review Generative Adversarial Networks (GAN).



Proposed architecture



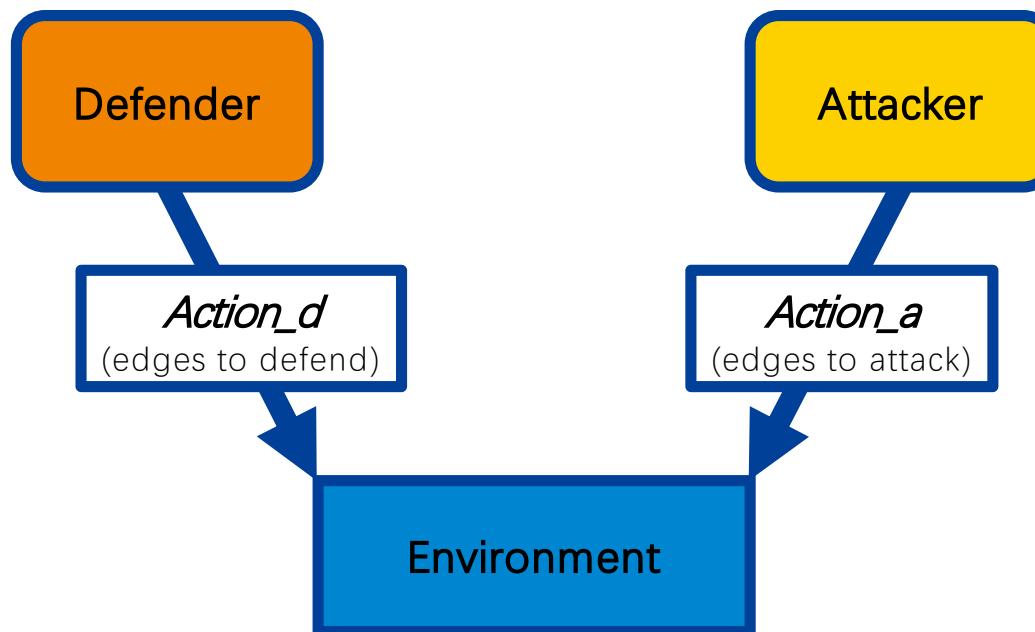
- We then propose our adversarial learning model.
- At the beginning of each time step:



Proposed architecture



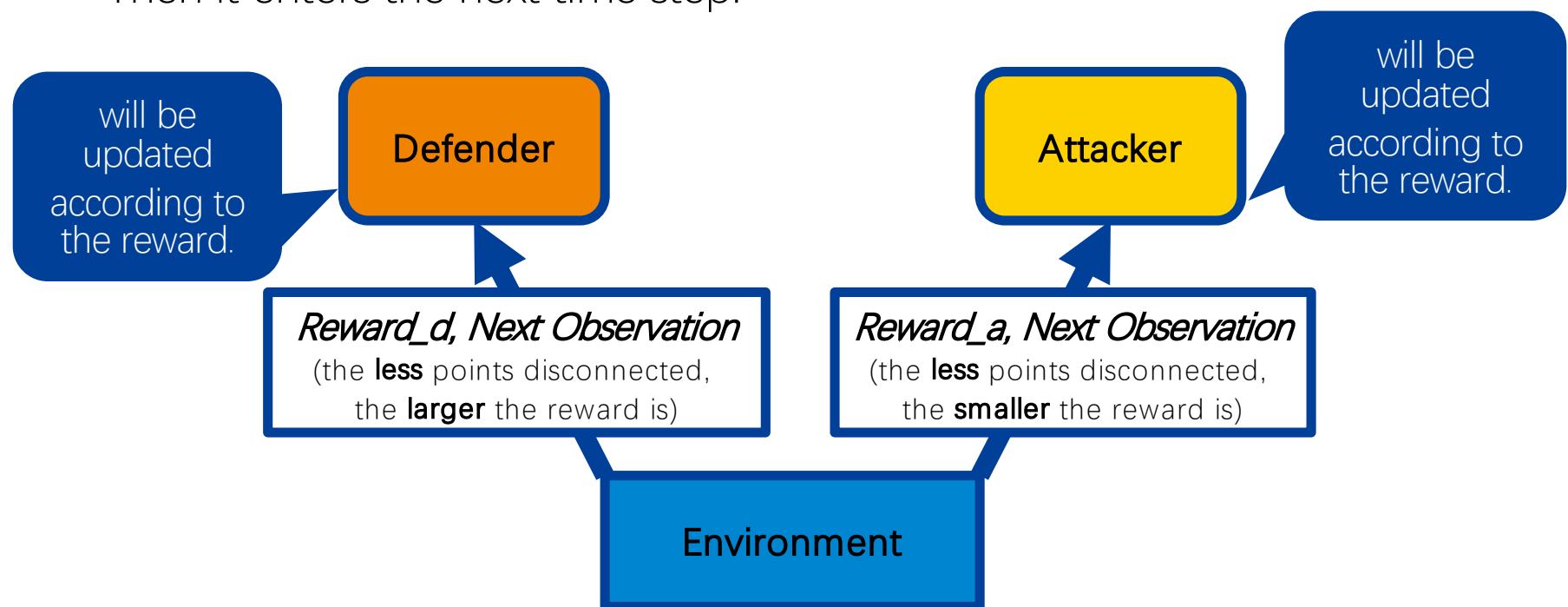
- We then propose our adversarial learning model.
- And then:



Proposed architecture



- We then propose our adversarial learning model.
- Then it enters the next time step:



- Assuming l points are disconnected from the source point after the attack, the defender gets $-\frac{l}{N-1}$ reward and the attacker gets $+\frac{l}{N-1}$ reward.



Models

RL(Reinforcement Learning)-based Model

- Based on **Advanced Actor Critic (A2C)**, one of the policy-based methods.
- Will be introduced later.

Stochastic Model

- Stochastically sample K edges among all.
- Do not update itself.
- Used as opponent when training single Attacker/Defender model.

Rule-based Model

- Stochastically sample K edges from edges outgoing from the source.
- Do not update itself.
- Used as baseline.

RL-based model



- *Observation:* s_t
 - The randomly generated directed graph G , as a flattened adjacent matrix.
- *Action:* a_t^1, \dots, a_t^K
 - The action space of **A2C** is $1..N(N - 1)$, representing each potential edge. The A2C algorithm we use will compute the policy (probability of taking each action). We take K actions with the largest K probabilities.
- *Reward*
 - $R_t^{Defender} = Connectivity_{t+1} - Connectivity_t$
 - $R_t^{Attacker} = -R_t^{defender}$
- *How to update*
 - The original update process of A2C is: $\nabla_\theta \log \pi(a_t | s_t; \theta) A(s_t, a_t; \theta)$
 - Our update process is: $\frac{1}{K} \sum_{k=1}^K \nabla_\theta \log \pi(a_t^k | s_t; \theta) A(s_t, a_t^k; \theta)$

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Experiment 1



- Train an **RL-based attacker** against a **stochastic-regime defender**.
 - Under setting: $N = 5, M = 16, K = 3$

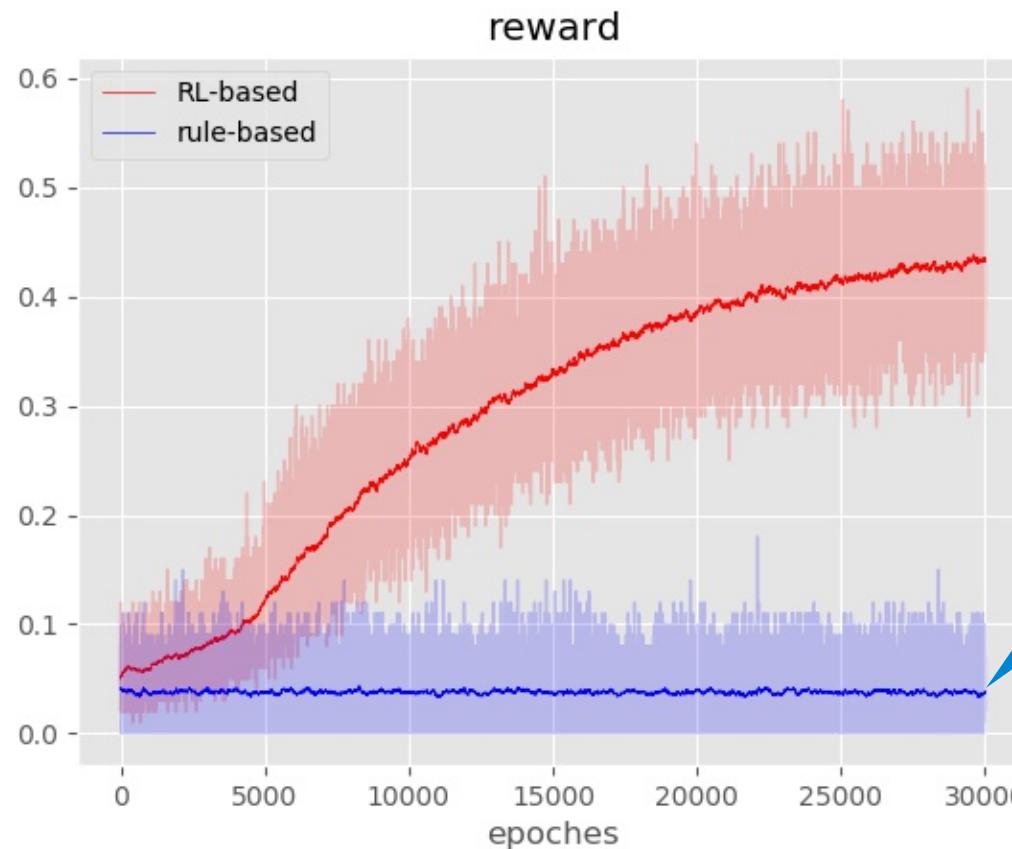


The baseline **attacker** model randomly choose edges connecting the **source point** to others to defend.

Experiment 2



- Train an **RL-based attacker** against a **rule-based defender**.
 - The rule-based defender is exploited.



The baseline **attacker** model randomly choose edges connecting the **source point** to others to defend.

Experiment 3



- Then, we train an **RL-based defender** against the just trained RL-based attacker.

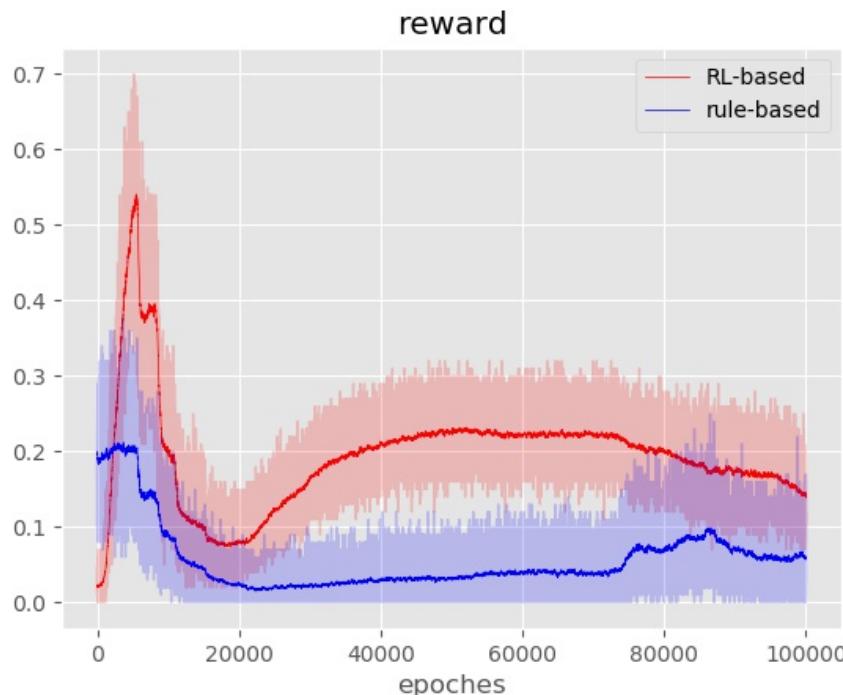


The baseline **defender** model randomly choose edges connecting the **source point** to others to defend.

Experiment 4



- What about training attacker and defender together, like **GAN**?



(a) RL-based Attacker



(b) RL-based Defender

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Discussion



- *Contribution*

- An adversarial learning architecture
- RL-based model, together with stochastic model, rule-based model
- Experiments

- *To be improved:*

- Better representation of the graph?
- Better designation of reward?
- Stronger baseline model to compare?
- Generalization?
- Multiple attackers?

- *Maybe useful:*

- GANs?
- Adversarial Machine Learning?
 - <https://aaai18adversarial.github.io/>



Thank you!

Q&A



Group No.2

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