Introduction to Machine Learning

Lecture 11 Unsupervised Learning II

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Clustering

- Find subgroups (clusters) in data
 - What makes a cluster?
 - Within cluster similarity high
 - Across cluster similarity low
- Canonical application: market segmentation
 - Cluster customers into subgroups
 - Target each subgroup differently
- Many clustering techniques
 - We'll look at
 - K-means
 - Gaussian mixtures

- Partition data into K distinct (non-overlapping) clusters
 - Objective: minimize within cluster variation
- Given N training samples {x}_{n=1,2,...N}
 - K clusters
 - Each cluster has a prototype vector μ_k
 - Assign each sample to a cluster, $r_{nk}=1$ if x_n belongs to cluster k
 - Minimize

$$J = \sum_{n=1}^{N} \sum_{k=1}^{K} r_{nk} \|\mathbf{x}_n - \boldsymbol{\mu}_k\|^2$$

Solve

$$\min_{r,\boldsymbol{\mu}} \sum_{n} \sum_{k} r_{nk} ||\boldsymbol{x}_n - \boldsymbol{\mu}_k||^2$$

- Difficult
 - Too many possible partitions, $\sim K^N$
 - Find local minimum using an iterative procedure
 - 1) Fix r, optimize for μ
 - 2) Fix μ , optimize for r
 - 3) Repeat

Solving K-means

- Fix μ , optimize for r
 - Assign each sample to closest prototype's cluster

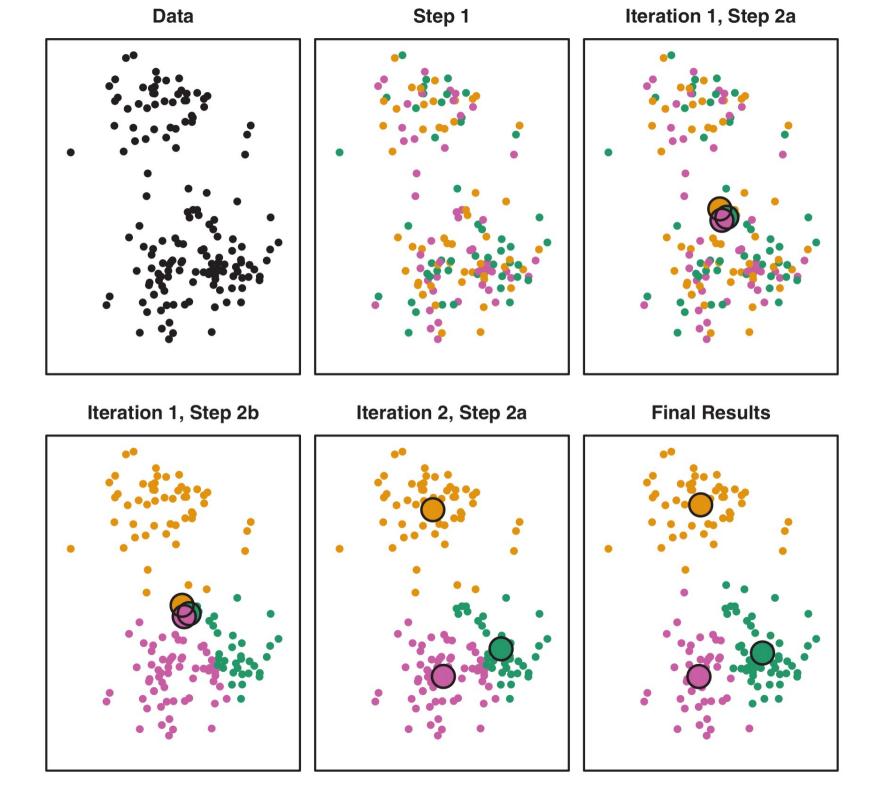
$$r_{nk} = \begin{cases} 1 & \text{if } k = \arg\min_{j} \|\mathbf{x}_n - \boldsymbol{\mu}_j\|^2 \\ 0 & \text{otherwise.} \end{cases}$$

- Fix r, optimize for μ
 - Set μ_k to the center of all samples in cluster k

$$\boldsymbol{\mu}_k = \frac{\sum_n r_{nk} \mathbf{x}_n}{\sum_n r_{nk}}.$$

Algorithm 10.1 K-Means Clustering

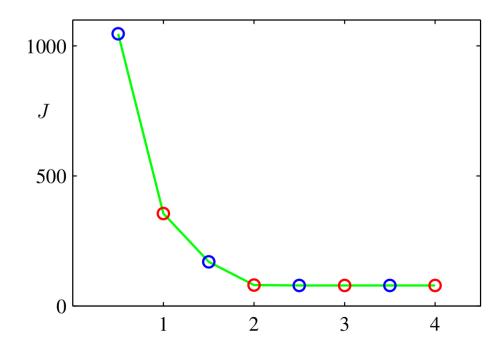
- 1. Randomly assign a number, from 1 to K, to each of the observations. These serve as initial cluster assignments for the observations.
- 2. Iterate until the cluster assignments stop changing:
 - (a) For each of the K clusters, compute the cluster *centroid*. The kth cluster centroid is the vector of the p feature means for the observations in the kth cluster.
 - (b) Assign each observation to the cluster whose centroid is closest (where *closest* is defined using Euclidean distance).



Cost is guaranteed to decrease (or stay the same)

$$J = \sum_{n=1}^{N} \sum_{k=1}^{K} r_{nk} \|\mathbf{x}_n - \boldsymbol{\mu}_k\|^2$$

- Watch J and stop when it doesn't improve anymore
 - Cluster assignments don't change
- Or after a maximum number of iterations



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- Watch J and stop when it doesn't improve anymore
 - Cluster assignments don't change
- Or after a maximum number of iterations
- Sensitive to initial cluster assignments
 - Finds local minima
 - Run k-means multiple times with different random initializations
 - Pick the best

Potential issues

- Can be slow if N is large
 - Techniques to speed it up are available
- Hard to pick number of clusters K
 - Run it on a separate dataset and see if you get the same clusters
 - Can use bootstrap to sample datasets
- Not robust to outliers
 - Because of squared Euclidean distances
- K-means makes hard cluster assignments
 - A sample belongs to a cluster or not
 - Soft assignments may make more sense

K-medoids algorithm

- Use a different distance (dissimilarity) function
 - e.g., I_1 norm (absolute value)

$$\widetilde{J} = \sum_{n=1}^{N} \sum_{k=1}^{K} r_{nk} \mathcal{V}(\mathbf{x}_n, \boldsymbol{\mu}_k)$$

- Can be hard to optimize wrt to μ
- Constrain: prototype μ_k must be one of x_n in the cluster
 - Makes it easier to optimize
 - Look at each x_n in the cluster one by one

The probabilistic perspective

- Assume a latent variable z for cluster membership
 - $z_{nk} = 1$ if x_n belongs to cluster k
 - z has a multinomial distribution

$$z \sim \operatorname{Mult}(\pi_1, \pi_2, \dots, \pi_k)$$

$$0 \leqslant \pi_k \leqslant 1 \qquad \sum_{k=1}^K \pi_k = 1$$



Assume x|z has a Gaussian distribution

$$x|z_k = 1 \sim \mathcal{N}(\mu_k, \Sigma_k)$$

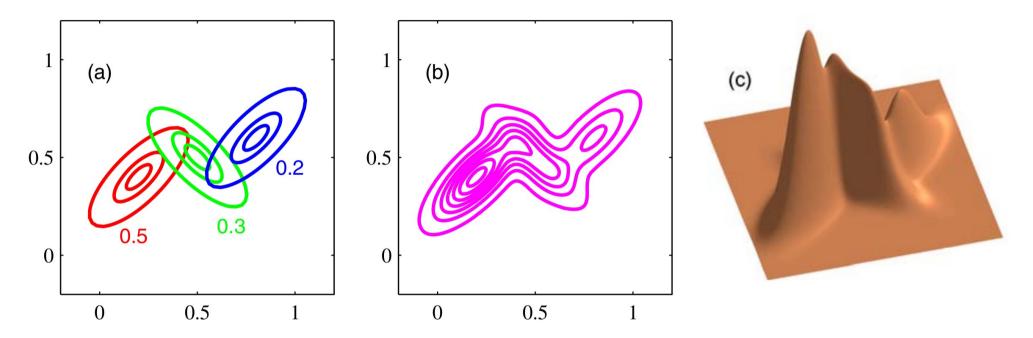


Figure 2.23 Illustration of a mixture of 3 Gaussians in a two-dimensional space. (a) Contours of constant density for each of the mixture components, in which the 3 components are denoted red, blue and green, and the values of the mixing coefficients are shown below each component. (b) Contours of the marginal probability density $p(\mathbf{x})$ of the mixture distribution. (c) A surface plot of the distribution $p(\mathbf{x})$.

Mixture of Gaussians

- Given a dataset of N samples {x}_{n=1,2,...N}
 - Find parameters π, μ, Σ
- Write the likelihood of parameters given data
 - Maximize it (maximum likelihood)

$$p(\mathbf{z}) = \prod_{k=1}^{K} \pi_k^{z_k}.$$

$$p(\mathbf{x}|\mathbf{z}) = \prod_{k=1}^K \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)^{z_k}.$$

Mixture of Gaussians model

$$p(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{z}) p(\mathbf{x}|\mathbf{z}) = \sum_{k=1}^{K} \pi_k \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)$$

Maximum likelihood for MoG

Log likelihood of parameters given data

$$\ln p(\mathbf{X}|\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \sum_{n=1}^{N} \ln \left\{ \sum_{k=1}^{K} \pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \right\}.$$

- Maximize using an iterative procedure
 - Fix μ, Σ optimize for π
 - Fix $oldsymbol{\pi}$ optimize for $oldsymbol{\mu}, oldsymbol{\Sigma}$
- This is expectation-maximization (EM) applied to mixture of Gaussians

EM for Gaussian Mixtures

Given a Gaussian mixture model, the goal is to maximize the likelihood function with respect to the parameters (comprising the means and covariances of the components and the mixing coefficients).

- 1. Initialize the means μ_k , covariances Σ_k and mixing coefficients π_k , and evaluate the initial value of the log likelihood.
- 2. **E step**. Evaluate the responsibilities using the current parameter values

$$\gamma(z_{nk}) = \frac{\pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}.$$
 (9.23)

3. **M step**. Re-estimate the parameters using the current responsibilities

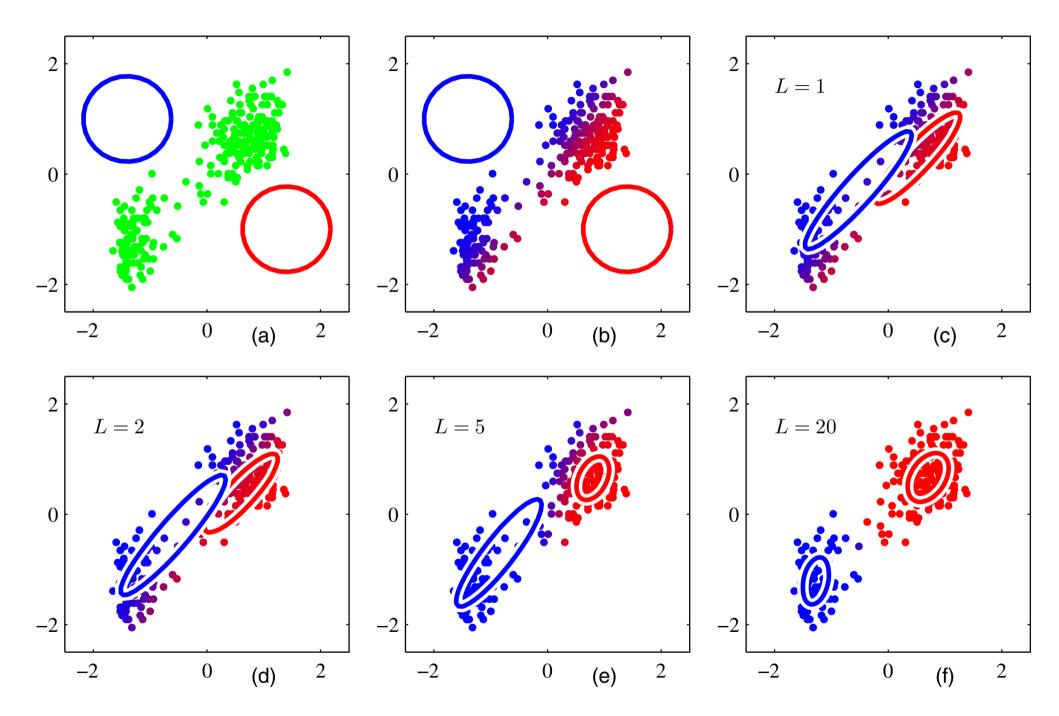
$$\boldsymbol{\mu}_k^{\text{new}} = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) \mathbf{x}_n \tag{9.24}$$

$$\Sigma_k^{\text{new}} = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) \left(\mathbf{x}_n - \boldsymbol{\mu}_k^{\text{new}} \right) \left(\mathbf{x}_n - \boldsymbol{\mu}_k^{\text{new}} \right)^{\text{T}}$$
(9.25)

$$\pi_k^{\text{new}} = \frac{N_k}{N} \tag{9.26}$$

where

$$N_k = \sum_{n=1}^{N} \gamma(z_{nk}). {(9.27)}$$



Why do all of this?

- Allows you to use any distribution
 - K-means: spherical clusters
 - Mixture of Bernoullis
- A principled approach to pick K (number of clusters)
 - Find the K that maximizes posterior
 - Better: Marginalize out K (average over all possible K)
- Allows you to generalize it
 - Dirichlet mixture models
 - Infinite mixture of Gaussian models
 - No need to specify K
 - Adjusted based on data

Summary

- Clustering
- K-means
 - Algorithm
 - K-medoids
- Probabilistic perspective
 - Mixture of Gaussians
 - Maximum likelihood for MoG

Exercises

- Show that for the K-means algorithm, the cost J never increases from one iteration to next
- Do lab 10.5.1 in ISLR

References

- [1] James, Witten, Hastie, and Tibshirani. An Introduction to Statistical Learning with Applications in R. Chapter 10.
- [2] Hastie, Tibshirani, and Friedman. The Elements of Statistical Learning. Chapter 14.
- [3] Bishop, C. Pattern Recognition and Machine Learning. Chapter 9.