Theory of Computation Assignment no. 11

Goktug Saatcioglu

- (1) a. If A ≤ B then there exists a truth preserving reduction from A to B. Furthermore, if B ≤ C then there exists a truth preserving reduction from B to C. Thus, we know that there is an algorithm M₁ (i.e. Turing machine) that takes an input word x and outputs a word y such that if x ∈ A then y ∈ B and if x ∉ A then y ∉ B. We also know that there is an algorithm M₂ (i.e. Turing Machine) that takes an input word y and outputs a word z such that if y ∈ B then z ∈ C and if y ∉ B then z ∉ C. Combining M₁ and M₂ together, we can create an algorithm M₃ (i.e. Turing machine) that takes an input x and first simulates M₁ to get an output y. Then M₃ will simulate M₂ on y to get z. Firstly, since M₁ and M₂ is computable we know that M₃ is computable. Secondly, we see that if x ∈ A then y ∈ B then z ∈ C (or if x ∉ A then y ∉ B then z ∉ C) which implies that x ∈ A then z ∈ C (or x ∉ A then z ∉ C) which proves that ≤ is transitive. Thus, we conclude if A ≤ B and B ≤ C then A ≤ C.
 - b. If $A \leq_p B$ then there exists a truth preserving polynomial time reduction from A to B. Furthermore, if $B \leq_p C$ then there exists a truth preserving polynomial time reduction from B to C. Thus, we know that there is an algorithm M_1 (i.e. Turing machine) that takes an input word x and outputs a word y such that if $x \in A$ then $y \in B$ and if $x \notin A$ then $y \notin B$ in some time polynomial in the length of the input x (where |x|=n). We also know that there is an algorithm M_2 (i.e. Turing Machine) that takes an input word y and outputs a word z such that if $y \in B$ then $z \in C$ and if $y \notin B$ then $z \notin C$ in some time polynomial in length of the input y (where |x|=o). Combining M_1 and M_2 together, we can create an algorithm M_3 (i.e. Turing machine) that takes an input x and first simulates M_1 to get an output y. Then M_3 will simulate M_2 on y to get z. Firstly, since M_1 and M_2 is computable we know that M_3 is computable. Secondly, we see that if $x \in A$ then $y \in B$ then $z \in C$ (or if $x \notin A$ then $y \notin B$ then $z \notin C$) which implies that $x \in A$ then $z \in C$ (or $x \notin A$ then $z \notin C$). Thirdly, since M_1 runs in polynomial time in the length of the input x (where |x|=n) and since M_2 runs in polynomial time in the length of input y where |y|=0) we know that M_3 also runs in polynomial time in the length of the input x. All three points combined proves that \leq_p is transitive and we conclude if $A \leq_p B$ and $B \leq_p C$ then $A \leq_p C$.
 - c. We can use the same reduction as the one for all $L \in RE$, $L \preceq ACCEPT$. Let M_f be a reduction algorithm from L to ACCEPT and M be a Turing machine such that L(M) = L. We know that M exists since we assume that $L \in RE$. Then, M_f , given an input w, creates the Turing machine M described above and then outputs the descriptions of M and w (i.e. $(\langle M \rangle, \langle w \rangle)$). We see that M_f is a truth-preserving reduction from L to ACCEPT since if a word $w \in L(M)$ then $\langle M, w \rangle \in ACCEPT$ and if $w \notin L(M)$ then $\langle M, w \rangle \notin ACCEPT$. Furthermore, M_f is computable since we can encode both M and w according to the encoding scheme discussed in class. Finally, we know that the runtime of M_f is polynomial in the length of w (where |w| = n) since M is given (i.e. a constant) meaning we can encode both M and w in polynomial time. Thus, we conclude that for all $L \in RE$, $L \preceq_P ACCEPT$.
 - d. Let $A \in R$ and $B \subseteq \Sigma^*$ such that $B \notin \{\emptyset, \Sigma^*\}$. Then there exists a Turing machine M that decides A because we assume that $A \in R$ and there exists two words $w_1, w_2 \in \Sigma^*$ such that $w_1 \in B$ and $w_2 \notin B$ because we assume that $B \notin \{\emptyset, \Sigma^*\}$. To get a truth preserving reduction from A to B consider the following algorithm M_f (i.e. Turing machine). M_f given an input w will simulate M on w where if M accepts then M_f outputs w_1 and if M rejects then M_f outputs w_2 . Firstly, M_f

is computable since by assumption we know that M is computable (because $A \in R$). Secondly, if $w \in A$ then M will accept and M_f outputs $w_1 \in B$ and if $w \notin A$ then M will reject and M_f outputs $w_2 \notin B$ which means that M_f is a truth-preserving reduction from A to B. Thus, we conclude that $A \leq B$ for every two languages $A, B \in R$, as long as B is not the empty language nor the language containing all words.

- e. Let $A \in P$ and $B \subseteq \Sigma^*$ such that $B \notin \{\emptyset, \Sigma^*\}$. Then there exists a Turing machine M that computes A in polynomial time in the length of some input w (where |w| = n) because we assume that $A \in P$. Furthermore, we know that there exists two words $w_1, w_2 \in \Sigma^*$ such that $w_1 \in B$ and $w_2 \notin B$ because we assume that $B \notin \{\emptyset, \Sigma^*\}$. To get a truth preserving reduction from A to B consider the following algorithm M_f (i.e. Turing machine). M_f given an input w will simulate M on w where if M accepts then M_f outputs w_1 and if M rejects then M_f outputs w_2 . Firstly, M_f is computable in polynomial time in the length of input w since by assumption we know that M is computable in polynomial time in the length of input w (because $A \in P$). Secondly, if $w \in A$ then M will accept and M_f outputs $w_1 \in B$ and if $w \notin A$ then M will reject and M_f outputs $w_2 \notin B$ which means that M_f is a truth-preserving polynomial time reduction from A to B. Thus, we conclude that $A \leq_p B$ for every two languages $A, B \in P$, as long as B is not the empty language nor the language containing all words.
- (2) a. We begin by defining a Turing machine N such that $L(N) = \Sigma^*$. We know that such a machine exists and is easy to create since we just need to accept regardless of input. Then consider the following algorithm M_f that takes as input descriptions of a Turing machine $\langle M' \rangle$ and a word $\langle w' \rangle$:

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M_f(\langle M' \rangle, \langle w' \rangle):
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- 1. Construct a TM M that ignores its input w and simulates M' on λ . M accepts if M halts on λ .
- 2. Construct a TM N that always accepts its input (i.e. $L(N) = \Sigma^*$).
- 3. Output $(\langle N \rangle, \langle M \rangle)$.

Now, if M' halts on λ then the language of M is given by Σ^* since M accepts all words w. In other words, if M' halts on λ then $L(M) = \Sigma^*$ which then means that $L(N) \subseteq L(M)$. Conversely, if M' does not halt on λ then M runs (implicitly) infinitely for all words w meaning $L(M) = \emptyset$ and $L(N) \not\subseteq L(M)$. Thus, M_f is a truth-preserving reduction from $HALT_{\lambda}$ to $CONTAINED_TM$ and we conclude $HALT_{\lambda} \preceq CONTAINED_TM$.

b. Again, we define the Turing machine N but this time we change L(N). Consider the algorithm M_f that takes as input descriptions of a Turing machine $\langle M' \rangle$ and a word $\langle w' \rangle$ of length n (i.e. |w'| = n):

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M_f(\langle M' \rangle, \langle w' \rangle):
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1. Compute n = |w'|.

Construct a TM M that ignores its input w and simulates M' on λ for n steps.

M enters an infinite loop if M' halts at any point during the simulation, otherwise M accepts.

- 2. Construct a TM N that accepts inputs with length greater than or equal to n (i.e. accept if $|w'| \ge n$).
- 3. Output $(\langle N \rangle, \langle M \rangle)$.

Similarly to a., if M' does not halt on λ in n steps then $L(N) \subseteq L(M)$ because M halts on all w with length greater than or equal to n. Conversely, if M' does halt on λ in n steps then it would enter an infinite loop for all w meaning $L(M) = \emptyset$ and $L(N) \not\subseteq L(M)$. Thus, M_f is a truth-preserving reduction from $(HALT_{\lambda})^c$ to $CONTAINED_TM$ and we conclude $(HALT_{\lambda})^c \preceq CONTAINED_TM$.

(3) a. Let Σ be the alphabet of at least two letters such that it is the alphabet for an instance of PCP, say P. We know that the strings of P are in the form $((s_1, t_1), \ldots, (s_n, t_n))$ and we seek to create two context free grammars G and H which respectively generate the s strings and t strings along with the information about the indices of the strings used. For our grammars we use the alphabet Σ along with n words that are not in Σ (so that we can avoid conflicts) to denote indices of strings. Let these n words be in the form l_1, \ldots, l_n and assume that they are not in Σ . Now, we need G to create the s strings in the form s_iGl_i so that we can generate a s string along with its corresponding index (given by l). Thus, the CFG G is given by

$$G \rightarrow s_1Gl_1 \mid \ldots \mid s_nGl_n \mid s_1n_1 \mid \ldots \mid s_nl_n.$$

Similarly, for H we need to create the t strings in the form t_iHl_i so that we can generate a t string along with its corresponding index (given by l). Thus, the CFG H is given by

$$H \rightarrow t_1 H l_1 \mid \ldots \mid t_n H l_n \mid t_1 n_1 \mid \ldots \mid t_n l_n.$$

Now let w be a word that describes $((s_1, t_1), \ldots, (s_n, t_n))$. We notice that if w is in P (i.e. $w \in P$) then there also exists an intersection of the grammars G and H which is not empty (i.e. $G \cap H \neq \emptyset$). Conversely, if $w \notin P$ then $G \cap H = \emptyset$. Thus, given an instance of PCP, the algorithm that generates the grammars G and H as described above is a truth-preserving reduction from PCP to $INTERSECT_CFL$ and we conclude $PCP \prec INTERSECT_CFL$.

- b. We know that if $A \leq B$ and $A \notin R$, then $B \notin R$ (which has been shown in class). Furthermore, from a. (above) we know that $PCP \leq INTERSECT_CFL$ which means that if $PCP \notin R$, then $INTERSECT_CFL \notin R$. In fact, since we know that $PCP \notin R$ (as given by the question) and $PCP \leq INTERSECT_CFL$, we know that $INTERSECT_CFL \notin R$.
- (4) a. We need to give an algorithm that takes a graph G and gives a new graph G' such that if G ∈ 3COL then G' ∈ 4COL and if G ∉ 3COL then G' ∉ 4COL. Furthermore, this algorithm must run in polynomial time in length of the input G. Let R be an algorithm that takes as input a graph G = (V, E) with V vertices and E edges (where the edges are described as sets of 2 vertices). Then R creates a new graph G' = (V', E') where V' = V ∪ {w} and w is a new vertex (i.e. w ∉ V) and E' = E ∪ {{w,v} | v ∈ V}. In other words, R takes the graph G and creates a new vertex w which is then connected to all vertices in G by edges which gives us the output graph G'. Now, if G has some three coloring then G' has the same exact three coloring by using the coloring of G and then G' is four colorable by coloring the introduced vertex w the fourth color. Conversely, if G does not have a three coloring then G' will not have a four coloring since the addition of the introduced vertex w can not lead to a four coloring. The algorithm R runs takes linear time in length of the input G since it creates a new vertex w and then goes over all vertices of G to create the new edges for G'. Thus, R (as described above) is a polynomial time truth-preserving reduction from 3COL to 4COL and we conclude 3COL ≤p 4COL.
 - b. We know that $3COL \leq_p 4COL$ as this was shown above in a. and the algorithm that performs the reduction R runs in linear time. Now, if $4COL \in P$ then there is exists some Turing machine B that computes 4COL in polynomial time. To compute 3COL in polynomial time we can take an input graph G = (V, E) with V vertices and E edges and first run it through our reduction algorithm R. This will give a resulting graph G' = (V', E') which is in 4COL if G was in 3COL and which is not in 4COL if G was not in 3COL. We then use B to check if G' is in 4COL where if $G' \in 4COL$ then we can conclude that $G \in 3COL$ and if $G' \notin 4COL$ then we can conclude that $G \notin 3COL$. We know that R runs in linear time in input G, where |G| = n, and B runs in polynomial time in input G' which means that our new algorithm runs in n^k which is polynomial time. Thus, we conclude that if $4COL \in P$ then $3COL \in P$ since $3COL \preceq_p 4COL$. (Note: It is also generally true that if $B \in P$ and $A \preceq_p B$ then $A \in P$.)
- (5) a. We need to give an algorithm that takes an undirected graph G and gives a new directed graph G' such that if $G \in HAM_CYCLE$ then $G' \in D_HAM_CYCLE$ and if $G \notin HAM_CYCLE$ then

- $G' \notin D_HAM_CYCLE$. Furthermore, this algorithm must run in polynomial time in length of the input G. Let R be an algorithm that takes as input an undirected graph G = (V, E) with V vertices and E edges (where the edges are described as sets of 2 vertices). Then R creates a new directed graph G' = (V', E') where V' = V and $E' = \{\{u, v\} \mid \{u, v\} \in E\}$. In other words, R takes the graph G and creates a new directed graph G' where for each undirected edge between u and v in G there are two directed edges $u \to v$ and $v \to u$ in G'. Now, if the undirected graph G has a Hamiltonian cycle $u_1 \ldots u_n$ then we know that V has n vertices where $\{u_1, \ldots, u_n\} = V$ and there exists at least an edge between each vertex in V such that for each $1 \le i < n : \{u_i, u_{i+1}\} \in E$ and $\{u_n, u_1\} \in E$. This then implies that for each $1 \le i < n : \{u_i, u_{i+1}\} \in E'$ and $\{u_n, u_1\} \in E'$ (by construction of R) meaning $u_1 \ldots u_n$ is also an Hamiltonian cycle of the directed graph G'. Conversely, if G does not have an Hamiltonian cycle then G' cannot have an Hamiltonian cycle since G' is essentially G with bi-directional edges. The algorithm G takes polynomial time in length of the input G since we traverse over all edges once and create two new edge pairs for G' for each edge we see. Thus, G (as described above) is a polynomial time truth-preserving reduction from G the G' cannot have G' be a polynomial time truth-preserving reduction from G the G' takes G' in G' to G' for each edge we see. Thus, G (as described above) is a polynomial time truth-preserving reduction from G' the G' takes G' to G' to G' the G' takes G' takes G' to G' takes G' to G' the G' takes G' to G' the G' takes G' takes
- b. We need to give an algorithm that takes a directed graph G and gives a new undirected graph G' such that if $G \in D_HAM_CYCLE$ then $G' \in HAM_CYCLE$ and if $G \notin D_HAM_CYCLE$ then $G' \notin HAM_CYCLE$. Furthermore, this algorithm must run in polynomial time in length of the input G. Let R be an algorithm that takes as input a directed graph G = (V, E) with V vertices and E edges (where the edges are described as sets of 2 vertices). Then R creates a new undirected directed graph G' = (V', E') where $V' = \{\{v_{in}\}, \{v\}, \{v_{out}\} \mid \{v\} \in V\}$ and $E' = \{\{u_{out}, v_{in}\}, \{v_{in}, v\}, \{v, v_{out}\} \mid \{u, v\} \in E\}$. In other words, R takes the graph the directed graph G and creates a new undirected graph G' where for each directed edge between u and v in G there is now an undirected edge that goes from the newly created u_{out} vertex into v_{in} , v_{in} goes into v and v goes to v_{out} . Now, if the directed graph G has a Hamiltonian cycle $u_1 \ldots u_n$ then we know that V has n vertices where $\{u_1, \ldots, u_n\} = V$ and there exists at least an edge between each vertex in V such that for each $1 \le i < n$: $\{u_i, u_{i+1}\} \in E$ and $\{u_n, u_1\} \in E$. This then implies that for each $1 \le i < n : \{(u_i), u_{i+1}\} \in E'$ and $\{u_n, u_1\} \in E'$ (by construction of R) since we now have the Hamiltonian cycle $(u_1)_{in}(u_1)(u_1)_{out}\dots(u_n)_{in}(u_n)(u_n)_{out}$ in G'. Conversely, if G does not have an Hamiltonian cycle then G' cannot have an Hamiltonian cycle since G' is essentially Gwith 3n vertices that has the same "structure" as G. The algorithm R takes polynomial time in length of the input G since we traverse over all vertices once to create the three new vertices and then traverse over all edges once to create the relevant edges in G' for each edge we see. Thus, R (as described above) is a polynomial time truth-preserving reduction from D₋HAM₋CYCLE to HAM_CYCLE and we conclude $D_HAM_CYCLE \leq_p HAM_CYCLE$.