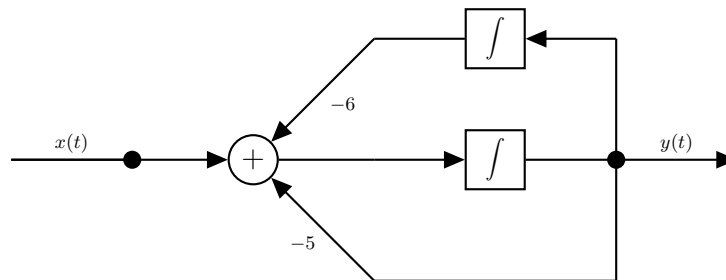




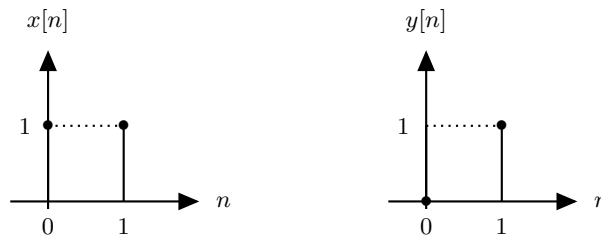
### Regulations:

- **Grouping:** You are allowed to work in pairs.
- **Submission:** We provide a latex template for your solutions. Use that template and create a hw2.tar.gz file that includes hw2.tex and all other related files. Tar.gz file should not contain any directories and should create a hw2.pdf file with the following commands, otherwise you will get zero;  
`tar xvzf hw2.tar.gz`  
`pdflatex hw2.tex`  
Submit hw2.tar.gz to the odtuclass page of the course.
- **Deadline:** 23:55, 27 April, 2021 (Tuesday).
- **Late Submission:** Not allowed.

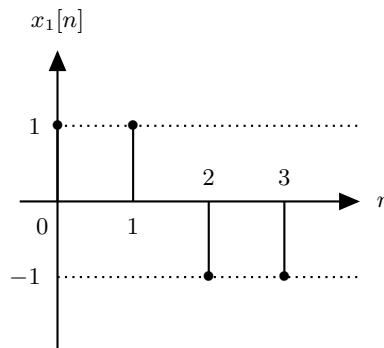
1. (15 pts) Consider an LTI system given by the following block diagram:



- (a) (5 pts) Find the differential equation which represents this system.
- (b) (10 pts) Find the output  $y(t)$ , when the input  $x(t) = (e^{-t} + e^{-4t})u(t)$ . Assume that the system is initially at rest.
2. (20 pts) Consider a discrete LTI system, initially at rest, given by the following input-output pair:



- (a) (5 pts) Find the output of this system for the following input: (Hint: Use superposition and time invariance property.)



- (b) (5 pts) Find and plot the impulse response of this system.
- (c) (5 pts) Find the difference equation which represents this system.
- (d) (5 pts) Find the block diagram representation of this system.
3. (10 pts) Evaluate the following convolutions.
- (a) (5 pts) Given  $x[n] = \delta[n-3] + 2\delta[n+1]$  and  $h[n] = \delta[n-1] + 3\delta[n+2]$ , compute and draw  $y[n] = x[n] * h[n]$ .
- (b) (5 pts) Given  $x[n] = u[n+3] - u[n]$  and  $h[n] = u[n-1] - u[n-3]$ , compute and draw  $y[n] = x[n] * h[n]$ .

4. (12 pts) Evaluate the following convolutions.

(a) (6 pts) Given  $h(t) = e^{-3t}u(t)$  and  $x(t) = e^{-2t}u(t)$ , find  $y(t) = x(t) * h(t)$ .

(b) (6 pts) Given  $h(t) = e^{2t}u(t)$  and  $x(t) = u(t) - u(t - 2)$ , find  $y(t) = x(t) * h(t)$ .

5. (18 pts) Consider a discrete-time LTI system represented by the unit step response:

$$s[n] = nu[n].$$

(a) (6 pts) Find the impulse response,  $h[n]$ , which represents this system.

(b) (6 pts) Find the input  $x[n]$ , when the output is  $y[n] = \delta[n] - \delta[n - 1]$ .

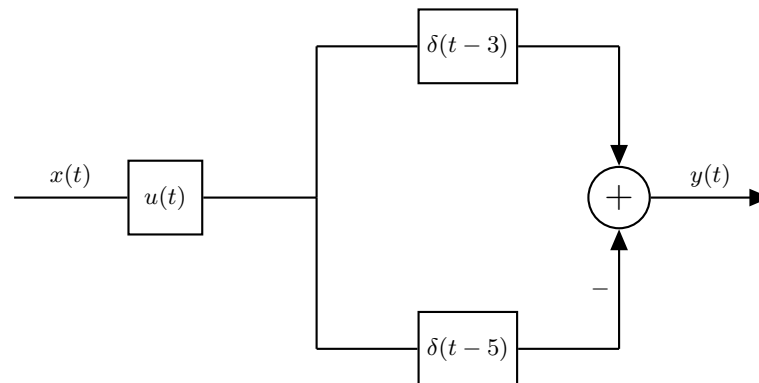
(c) (6 pts) Find the difference equation which represents this system.

6. (10 pts) Consider an LTI system represented by the following unit step response:

$$s(t) = \frac{1}{2}t^2u(t).$$

For the input  $x(t) = e^{-t}u(t)$ , find  $y(t)$ .

7. (15 pts) Consider an LTI system represented by the following block diagram:



(a) (5 pts) Find and plot the overall impulse response of this system.

(b) (5 pts) Find the output,  $y(t)$ , when the input is  $x(t) = e^{-3t}u(t)$ .

(c) (5 pts) Find  $g(t) = (\frac{dh(t)}{dt}) * x(t)$ .