[a4paper]article

[utf8]inputenc [T1]fontenc textcomp [dutch]babel amsmath, amssymb code pythonhighlight

import xifthen pdfpages transparent graphicx ./img/

document Path planning itemize

C omputing a route from starting point to a goal point

a ssumptions itemize

w here you are and where u need to go and map of environment(perception)

b ehaviour of robot for command (math model)

o bstacles and open space where robot can moveds