



Gokulakrishnan D P

SOFTWARE ENGINEER

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Summary

A curious developer seeking to learn more on robotics. Experienced in networking, motion planning, and control algorithms. Super nerd who loves Vim, Linux and enjoys to customize all of the development environment. Active participation and contribution to open-source community. Interested in devising a better problem-solving method for challenging tasks, and learning new technologies and tools if the need arises.

Education

Bannariamman Institute of Technology

BACHELOR OF ENGINEERING IN MECHATRONICS, CGPA: 8.71/10.0

Sathy, Tamil Nadu

May 2023

The Optimus Public School

SENIOR SCHOOL, PERCENTAGE: 80.4/100.0

Erode, Tamil Nadu

March 2019

The Optimus Public School

SECONDARY SCHOOL, PERCENTAGE: 9.2/10.0

Erode, Tamil Nadu

March 2017

Skills

Languages Python, JavaScript, C, C++

Frameworks ESP-IDF, ROS, Angular, RTOS

Documentation Latex, Markdown, HTML

Projects

Vantage

C++

- A terminal user interface for Lenovo laptops
- uses acpi interface to control lenova's battery operations
- 🐙 [Vantage](#)

Solar monitoring

FLUTTER AND RTOS

- Real time data monitoring of solar inverters
- Public communication over mqtt
- App to display all the parameters sent over mqtt
- 🐙 [Solar app](#)
- 🐙 [Solar embedded](#)

Scan unifier

C++

- ROS package to unify two laser scans into one
- Ripped from cob_navigation and maintained separately
- 🐙 [scan_unifier](#)

CalloverUSB

PYTHON

- attends and declines call through adb
- Supports both USB and wireless communication
- 🐙 [CalloverUSB](#)

Other repos

- 🐙 [Linux dotfiles](#) | 🐙 [esp wifi handler](#) | 🐙 [farmprice-webscrap](#) | 🐙 [tyre pressure](#)

Events

Flipkart Grid 3.0

Finalist

- Multi agent system with centralised navigation using camera in grid based task space
- Implemented collision detection and recovery behaviour
- Omnidirectional agents with no sensor

Smart India Hackathon

Winner

- Winner in Hardware edition
- ARIS-Accident rescue and investigation system
- Ad-hoc based accident message relay system
- Centralised monitoring and processing accident cause

L & T techgrium

semiFinalist

- Multi agent system with centralised navigation using camera in grid based task space
- Implemented collision detection and recovery behaviour
- Omnidirectional agents with no sensor

Eyantra

cleared 5 tasks

- mobile manipulator simulation for autonomous agriculture application
- Implemented collision detection and recovery behaviour
- Autonomous navigation with lidar and perception with depth cameras

Daksh 2020

Finalist

- Multi agent system with centralised navigation using camera in grid based task space
- Implemented collision detection and recovery behaviour
- Omnidirectional agents with no sensor