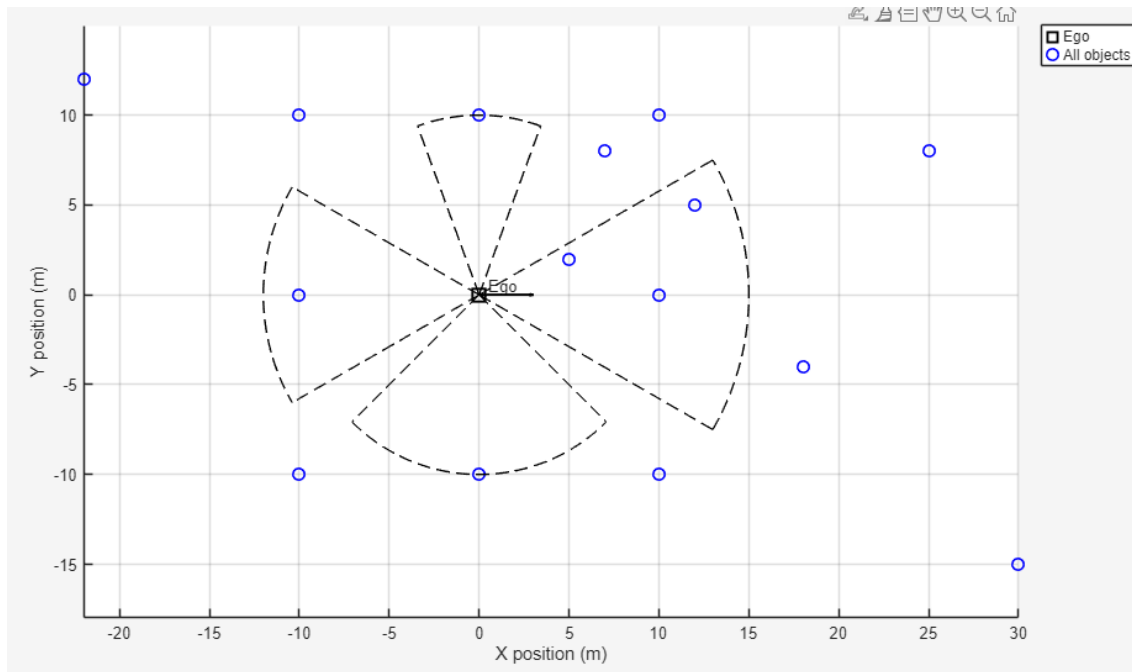## Multiple sensor object detection

When the ego-vehicle Yaw angle is 0 (i.e) the vehicle is travelling straight.

When the ego-vehicle turn left, Yaw angle 40. The detection angle should also change