Data Shapley: Equitable Valuation of Data for Machine Learning

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Overview

- Data generated by individuals is a key component of the market place
 - E.g. health care, advertising
- 3 ingredients in case of supervised machine learning
 - A fixed training dataset : $D = \{(x_i, y_i)\}_{i=1}^n$
 - A learning algorithm : \mathcal{A} , which solves $\theta^* = \arg\min_{\theta} \sum_{i=1}^{n} l(f(x_i; \theta), y_i)$
 - A performance metric : V, test performance of f
 - Mean Squared Error in regression
 - Accuracy in classification

- 1. What is an equitable measure of the value of each (x_i, y_i) to \mathcal{A} w.r.t. V
- 2. How do we efficiently compute this data value in practical settings

Equitable data valuation

Notation

- $\phi_i(V)$: value of *i*-th train datum in terms of V
- V(S): test performance of f trained on $S \subseteq D$ c.f. $V(S = \Phi)$ indicates test performance of randomly initialized classifier
- What properties make ϕ_i "equitable"
 - 1. Null player: $\forall S \subseteq D \{i\}, \ V(S \cup \{i\}) = V(S), \ then \ \phi_i = 0$
 - 2. Symmetry : $\forall S \subseteq D \{i, j\}, \ V(S \cup \{i\}) = V(S \cup \{j\}), \ then \ \phi_i = \phi_j$
 - 3. Linearity $\forall \alpha_1, \alpha_2 \in \mathbb{R}$, $\phi_i(\alpha_1 V_1 + \alpha_2 V_2) = \alpha_1 \phi_i(V_1) + \alpha_2 \phi_i(V_2)$
 - 4. Efficiency : $V(D) = \sum_{i} \phi_{i}(V)$

Shapely is a <u>unique</u> measure satisfying the above four properties

Shapely formulation

Formulation

(Shapely)
$$\phi_i \coloneqq \frac{1}{n} \sum_{S \subseteq D - \{i\}} {n-1 \choose |S|}^{-1} \left(V(S \cup \{i\}) - V(S) \right)$$

- Sum of marginal gains divided by # of subsets with cardinality |S|
 - assign <u>uniform weights</u> to different subset size |S|
 - note that such normalization is derived from the efficiency property

- 1. Traversing all the possible $S \subseteq D \{i\}$ is computationally infeasible for large dataset
- 2. Every computation of V requires a separate model training

Approximating ϕ

Monte-Carlo method

$$\phi_{i} := \frac{1}{n} \sum_{S \subseteq D - \{i\}} {n - 1 \choose |S|}^{-1} \left(V(S \cup \{i\}) - V(S) \right)$$

$$= \frac{1}{n} \sum_{j=0}^{n-1} {n - 1 \choose j}^{-1} \sum_{S \subseteq D - \{i\}} V(S \cup \{i\}) - V(S)$$

$$= \mathbb{E}_{i \sim U(0, n-1)} \mathbb{E}_{S \subseteq D - \{i\}} \left[V(S \cup \{i\}) - V(S) \right] = \mathbb{E}_{\pi \sim \Pi} \left[V(S_{\pi}^{i} \cup \{i\}) - V(S_{\pi}^{i}) \right]$$

 $\begin{array}{l} \mathsf{t=1},\pi = [2,1,5,3,4] \\ \phi_2^1 = V(\{2\}) \\ \phi_1^1 = V(\{2,1\}) - V(\{2\}) \\ \dots \\ \phi_4^1 = V(\{2,1,5,3,4\}) - V(\{2,1,5,3\}) \\ \dots \\ \mathsf{t=T},\pi = [5,3,1,2,4] \\ \phi_5^T = V(\{5\}) \\ \phi_3^T = V(\{5,3\}) - V(\{5\}) \\ \dots \\ \phi_4^T = V(\{5,3,1,2,4\}) - V(\{5,3,1,2\}) \end{array} \qquad \phi_i = \frac{1}{T} \sum_{t=1}^T \phi_i^t \quad \forall i \in [5]$

- π : random permutation of indices [n] ------ If π = [2,1,5,3,4], then S_{π}^{5} = {2,1} S_{π}^{i} : subset of indices coming before datum i ---
 - 1. Sample a random permutation
 - 2. Scan the permutation from the first to the last element and calculate the marginal gain (truncate the calculation of marginal gain whenever $|V(D) V(S_{\pi}^{i})| < tolerance$)
 - 3. Repeat 1 and 2, then obtain final estimation by average

Approximating V

- 1. Train the model with only one epoch and with mini-batch size of 1 \rightarrow Algorithm 2
 - marginal gain can be computed between iterations
 - require HPO to find the one resulting best performance by one epoch (high learning rate)
- 2. Estimate value by group of data points \rightarrow Algorithm 1
 - e.g. group the patients into discrete bins based on age, gender, ethnicity, etc.

Algorithm 1 Truncated Monte Carlo Shapley

```
Input: Train data D = \{1, \dots, n\}, learning algorithm
\mathcal{A}, performance score V
Output: Shapley value of training points: \phi_1, \ldots, \phi_n
Initialize \phi_i = 0 for i = 1, \dots, n and t = 0
while Convergence criteria not met do
    t \leftarrow t + 1
    \pi^t: Random permutation of train data points
   v_0^t \leftarrow V(\emptyset, \mathcal{A})
    for j \in \{1, ..., n\} do
        \begin{array}{c|c} \textbf{if} \; |V(D)-v_{j-1}^t| < \text{Performance Tolerance then} \\ v_j^t = v_{j-1}^t & \text{of the rest of } \\ \textbf{else} \end{array} 
           v_j^t \leftarrow V(\{\pi^t[1], \dots, \pi^t[j]\}, \mathcal{A})
        end if
       \phi_{\pi^t[j]} \leftarrow \frac{t-1}{t} \phi_{\pi^{t-1}[j]} + \frac{1}{t} (v_j^t - v_{j-1}^t)
    end for
                                               marqual gain
end for
```

Algorithm 2 Gradient Shapley

```
Input: Parametrized and differentiable loss function \mathcal{L}(.;\theta), train data D=\{1,\ldots,n\}, performance score function V(\theta)

Output: Shapley value of training points: \phi_1,\ldots,\phi_n

Initialize \phi_i=0 for i=1,\ldots,n and t=0

while Convergence criteria not met do

t\leftarrow t+1

\pi^t: Random permutation of train data points

\theta_0^t\leftarrow \text{Random parameters}

v_0^t\leftarrow V(\theta_0^t)

for j\in\{1,\ldots,n\} do

\theta_j^t\leftarrow \theta_{j-1}^t-\alpha\nabla_\theta\mathcal{L}(\pi^t[j];\theta_{j-1})

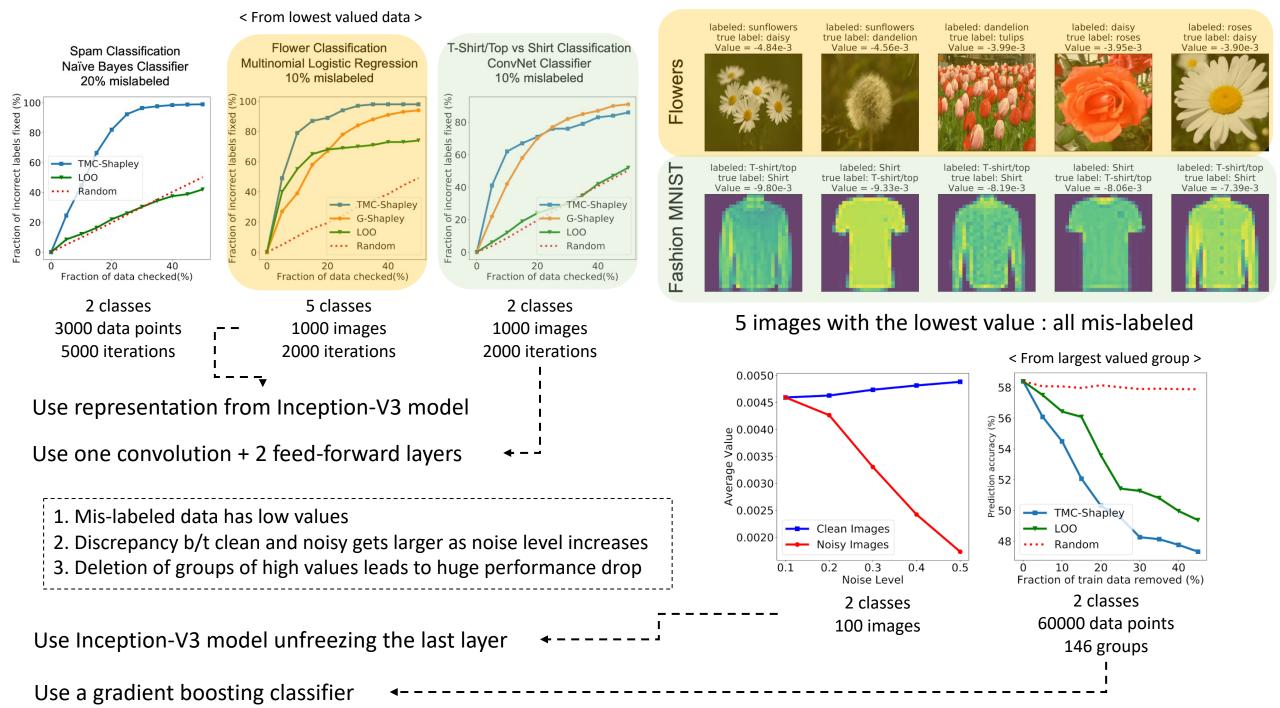
v_j^t\leftarrow V(\theta_j^t)

\phi_{\pi^t[j]}\leftarrow \frac{t-1}{t}\phi_{\pi^{t-1}[j]}+\frac{1}{t}(v_j^t-v_{j-1}^t)

end for
```

Convergence criteria (for generating random permutation)

$$\Rightarrow \frac{1}{n} \sum_{i=1}^{n} \frac{\left| \phi_i^t - \phi_i^{t-100} \right|}{|\phi_i^t|} < 0.05$$



Distributional Shapely

- Data Shapely assumed a fixed dataset D
 - no guarantee on consistency between the different, but similar datasets
 - it may be very sensitive to the exact choice of D and not transferrable across datasets
- Idea: Suggest an unbiased estimator for the size of D

$$v_i = \mathbb{E}_{B \subseteq D}[\phi_i] = \mathbb{E}_{B \subseteq D} \mathbb{E}_{j \sim U(0, |B| - 1)} \mathbb{E}_{S \subseteq B - \{i\}} [V(S \cup \{i\}) - V(S)]$$

$$|S| = i$$

- more stable under perturbations to inputs as well as the underlying data distribution
- Thm. under Lipschitz Stable performance metric V, the following holds (c.f. $|V(S \cup \{i\}) V(S \cup \{j\})| \le \beta(|S|) \cdot d(i,j)$)
 - 1. Similar distributions yield similar value functions $\Rightarrow |v_i(D_s) v_i(D_t)| \le C \cdot W(D_s, D_t)$
 - 2. Similar points receive similar values $\Rightarrow |v_i v_j| \le C \cdot d(i, j)$

Distributional Shapely

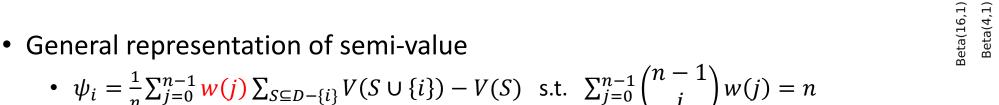
• Distributional Shapely assigns relatively <u>larger weights to small sized subsets</u> (note: (i) $S \subseteq B - \{i\}$, $B \subseteq D$, (ii) Data shapely: B = D)

			l				l .
	weight	/S/=0	/S/=1	•••	/S/=n-2	/S/=n-1	sum
Data shapely →	/B/=n	1/n	1/n	•••	1/n	1/n	1
	/B/=n-1	1/(n-1)	1/(n-1)		1/(n-1)	0	1
	/B/=1	1/2	1/2		0	0	1
	/B/=0	1	0	•••	0	0	1
	•	larger	ı			smaller	

- no more equal weights to subset size → no more satisfy the efficiency property := semi-values
- It is controversial whether it is beneficial to satisfy the efficiency in machine learning
 the value itself doesn't matter, but the rank matters

Beta Shapely

- Data Shapely assumed a uniform weight over the subset size |S|
 - Thm. When |S| is large enough, the marginal gain becomes negligible signal-to-noise ratio $(= \mu/\sigma)$ increases as the cardinality increases) more likely to be perturbed by noise)

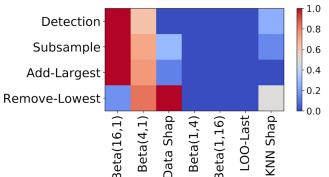


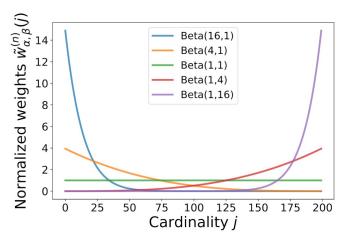
(c.f.
$$\phi_i = \frac{1}{n} \sum_{j=0}^{n-1} {n-1 \choose j}^{-1} \sum_{S \subseteq D - \{i\}} V(S \cup \{i\}) - V(S)$$
)





- $w_{\alpha,\beta}(j) = n \frac{Beta(j+\beta,n-j-1+\alpha)}{Beta(\alpha,\beta)} \Rightarrow (\alpha,\beta) = (1,1)$ suffices to Data Shapely
- $\alpha \geq \beta = 1$ assigns large weights on the small cardinality and remove noise from large cardinality





Data Banzhaf

- Stochastic training methods (e.g. SGD) make the performance metric unreliable
 - noise is shown to be substantial to make different runs produce inconsistent value rankings
- Idea 1 : Suggest to use Banzhaf value as a robust data value notion

•
$$\psi_i = \frac{1}{n} \sum_{j=0}^{n-1} \frac{n}{2^{n-1}} \sum_{S \subseteq D - \{i\}} V(S \cup \{i\}) - V(S) = \mathbb{E}_{S \subseteq D - \{i\}} [V(S \cup \{i\}) - V(S)]$$

$$|S| = i$$

- Note that it is also the semi-value s.t. $\sum_{j=0}^{n-1} {n-1 \choose j} \frac{n}{2^{n-1}} = n$
- $\frac{n}{2^{n-1}}$ is not a function of cardinality, which leads <u>large weights to subsets of large cardinality</u>
- Thm. Banzhaf value achieves the largest safety margin among the semi-values
 - ullet Safety margin: the largest tolerable perturbation on V that keeps the value order unchanged
- Idea 2 : Maximum Sample Reuse (MSR) Monte Carlo
 - Sample a number of subsets with various cardinalities $S = \{S_1, ..., S_m\} = S_{\ni i} \cup S_{\not\ni i}$
 - $\psi_i = \frac{1}{|S_{\ni i}|} \sum_{S \in S_{\ni i}} V(S) \frac{1}{|S_{\ni i}|} \sum_{S \in S_{\not\ni i}} V(S) \Rightarrow \text{enable faster estimation}$

E.O.D