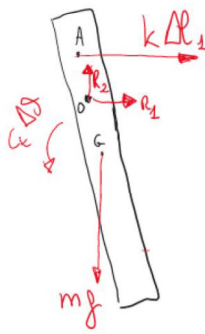


1. FBD



2. Newton's law

$$I_o \ddot{\theta} = -mgd \sin \theta - k \Delta l_1 a \cos \theta + C_t \dot{\theta}$$

3. Reaction forces: N/A

4. Kinematics: $\Delta l_1 = a \sin \theta$

$$\Delta \dot{\theta} = -\dot{\theta}$$

$$I_o \ddot{\theta} = -mgd \sin \theta - ka^2 \cos \theta \sin \theta - C_t \dot{\theta}$$

$$I_o \ddot{\theta} + C_t \dot{\theta} + ka^2 \cos \theta \sin \theta + mgd \sin \theta = 0$$

$$\dots \ddot{\theta} + \dots \dot{\theta} + \dots \cos \theta \sin \theta + \dots \sin \theta = 0$$

(part a)

5. Equilibrium: setting $\dot{\theta} = 0, \ddot{\theta} = 0 \rightarrow -mgd \sin \theta_{eq} - ka^2 \cos \theta_{eq} \sin \theta_{eq} = 0$

$$\text{so: } \sin \theta_{eq} [mgd + ka^2 \cos \theta_{eq}] = 0$$

for $\theta_{eq} = 0, \sin \theta_{eq} = 0$ so the equation above is satisfied and $\theta_{eq} = 0$ is a position of equilibrium

6. Stability: $V = mgh_c + \frac{1}{2} k \Delta l_1^2 = -mgd \cos \theta + \frac{1}{2} k a^2 \sin^2 \theta$

$$\frac{dV}{d\theta} = mgd \sin \theta + ka^2 \sin \theta \cos \theta$$

$$\frac{d^2V}{d\theta^2} = mgd \cos \theta + ka^2 [\cos^2 \theta - \sin^2 \theta]$$

substituting $\theta_{eq} = 0$

$$\left. \frac{d^2V}{d\theta^2} \right|_{\theta_{eq}=0} = mgd + ka^2 = \dots \frac{J}{\text{rad}^2} > 0$$

So $\theta_{eq} = 0$ is a STABLE EQUILIBRIUM POSITION (part b)

7. Linearization: $\sin \theta = \sin(0) + \cos(0) \tilde{\theta} = \tilde{\theta}$
 $\cos \theta \sin \theta = \cos(0) \sin(0) + [\cos^2(0) - \sin^2(0)] \tilde{\theta} = \tilde{\theta}$

$$I_o \ddot{\tilde{\theta}} = -mgd \tilde{\theta} - ka^2 \tilde{\theta} - C_t \dot{\tilde{\theta}}$$

8. Rearranging: $I_o \ddot{\tilde{\theta}} + C_t \dot{\tilde{\theta}} + (mgd + ka^2) \tilde{\theta} = 0$

$$I^* = I_o = \dots \text{kgm}^2$$

$$C_t^* = C_t = \dots \frac{\text{Nm s}}{\text{rad}}$$

$$k_t^* = ka^2 + mgd = \dots \frac{\text{Nm}}{\text{rad}}$$

(part c)

$$\omega_n = \sqrt{\frac{k_t^*}{I^*}} = \dots \frac{\text{rad}}{\text{s}}$$

$$\zeta = \frac{C_t^*}{2I^* \omega_n} = \dots = \dots \cdot 100\%$$

(part d)