3.4: a) X= B+ B, E+ WE

E[x.]= B.+ B.t

We can see that the expected value depends on time, so it is non-shationary.

b) Xt = Bo+ B, ++ w,

VX(=X6-X6-1

= Bo+B1++W4-Bo-B, (t-1) - W+1

= Bo+ B. t + W+ - Bo - B. t + B1 - W+-1

= β,+ω,-ω<sub>t-1</sub>

EEVX+]=BI

Since  $EZVX_{\ell}J$  does not dopen on 6 so it does mean the mean requirement of Stationary.

Cov[dX++h, dX+]= Cov[ B,+W++h-W++h-1, B,+W+-W+-1]

= Cov[w<sub>e+h</sub>, w<sub>t</sub>] - Cov[w<sub>e+h</sub>, w<sub>t-1</sub>] - (ov[w<sub>e+h-1</sub>, w<sub>t</sub>] + Cov[w<sub>e+h-1</sub>, w<sub>t-1</sub>]

 $Cov\left[\nabla X_{e+h}, \nabla X_{t}\right] = \begin{cases} 26\% & h=0\\ -6\% & |h|=1\\ 0 & |h|=2 \end{cases}$ 

This show that the covariance for stationarity is met.

Thus VX t is Stationary

 $\nabla X_t = X_t - X_{t-1}$ 

= Bo+B1+4+-B0-B14-1)-Y+-1

= B, +y, -y,-1

[[] X+] = [[] + /+ - /+-1]

= B,+My +My

= 13, +2my

Since expected value does not depend on time, it does satisfy the mean requirement for stationary.

(ov(VX+h, VX+) = (ov(B1+Y+h-Y+h-1, B1+Y+-Y+-1))
= (ov(Yx+h, Y+) - (ov(Y++h, Y+-1) - (ov(Y+h-1, Y+)) + (ov(Y+h-1, Y+-1))
= 2(Y(h)) - (Y(h+1) - (Y(h-1)))

We can see that the covariance is independent of time and y+ is stated to be stationary.

Therefore VX with Yt instead of Wt is stationary