

Ordinary Differential Equation (ODE): let $n \in \mathbb{N}$ and let $f : \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ then $f(x, y(x), y'(x), \dots, y^{(n)}(x)) = 0$.

Solution of an Ordinary Differential Equation: let $n \in \mathbb{N}$ let $\mathcal{U} \subseteq \mathbb{R}$ and let $f : \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ then a function $y \in C^n(\mathcal{U})$ such that $f(x, y(x), \dots, y^{(n)}(x)) = 0$ for all $x \in \mathcal{U}$.

Notation: let $n \in \mathbb{N}$ let $\mathcal{U} \subseteq \mathbb{R}$ and let $f : \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ then

$\text{sols}(f(x, y(x), y'(x), \dots, y^{(n)}(x)) = 0) = \{y \in C^n(\mathcal{U}) \mid f(x, y(x), \dots, y^{(n)}(x)) = 0\}$.

First Order Ordinary Differential Equation: let $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ then $f(x, y, y') = 0$.

Separable Ordinary Differential Equation: let $f, g : \mathbb{R} \rightarrow \mathbb{R}$ then $y' = f(y)g(x)$.

Claim Separation of Variables: let $f, g : \mathbb{R} \rightarrow \mathbb{R}$ such that $f(x) \neq 0$ for all $x \in \mathbb{R}$ then

$\text{sols}(y' = f(y)g(x)) = \text{sols}\left(\int \frac{1}{f(y)} dy = \int g(x) dx\right)$.

Corollary: $\text{sols}(y = y') = \{Ce^x \mid C \in \mathbb{R}\}$.

Curves that foliate a domain: Let $\Omega \subseteq \mathbb{R}^2$ and let $I \subseteq \mathbb{R}$ then a set of curves $\{\gamma_\alpha\} \subseteq I \rightarrow \mathbb{R}$ such that $\bigsqcup \gamma_i = \Omega$.

Claim: $\text{sols}(y = y')$ foliate the plane.

Remark: let $f : \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ and let $g \in \text{sols}(f(x, y, \dots, y^{(n)}))$ such that g is piecewise continuous then each continuous branch of g is a solution of the ODE.

Initial Value Problem (IVP): let $f : \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ and let $p \in \mathbb{R}^2$ then $\left\{ \begin{matrix} f(x, y', \dots, y^{(n)}) = 0 \\ y(p_1) = p_2 \end{matrix} \right.$.

Theorem Cauchy-Peano: let $I, J \subseteq \mathbb{R}$ be closed intervals let $f \in C^1(I \times J)$ and let $p \in \text{int}(I \times J)$ then there exists $\varepsilon > 0$ such that $\left\{ \begin{matrix} y' = f(x, y) \\ y(p_1) = p_2 \end{matrix} \right.$ has a solution on the interval $(p_1 - \varepsilon, p_1 + \varepsilon)$.

Theorem of Existence and Uniqueness: let $I, J \subseteq \mathbb{R}$ be closed intervals let $f \in C^1(I \times J)$ and let $p \in \text{int}(I \times J)$ then there exists $\varepsilon > 0$ such that $\left\{ \begin{matrix} y' = f(x, y) \\ y(p_1) = p_2 \end{matrix} \right.$ has a unique solution on the interval $(p_1 - \varepsilon, p_1 + \varepsilon)$.

Corollary: let $I, J \subseteq \mathbb{R}$ be closed intervals and let $f \in C^1(I \times J)$ then $\text{sols}(y' = f(x, y))$ foliates $I \times J$.

Vector Field: let $\Omega \subseteq \mathbb{R}^2$ be a domain then $\nu \in C(\Omega, \mathbb{R}^2)$.

Integral curve: let $\nu : \Omega \rightarrow \mathbb{R}^2$ be a vector field then a curve $\gamma : [a, b] \rightarrow \Omega$ such that $\frac{d\gamma}{dt}(t) = \nu(g(t))$.

Claim: let $\nu : \Omega \rightarrow \mathbb{R}^2$ be a vector field such that $\nu(x) \neq 0$ for all $x \in \Omega$ and let $\gamma : [a, b] \rightarrow \Omega$ be a curve such that $\nu(\gamma(t)) \in T_{\gamma(t)}(\text{Im}(\gamma))$ for all $t \in [a, b]$ then there exists a curve $\eta : [\alpha, \beta] \rightarrow [a, b]$ such that $\gamma \circ \eta$ is an integral curve.

C^n Vector Field: let $\Omega \subseteq \mathbb{R}^2$ be a domain then $\nu \in C^n(\Omega, \mathbb{R}^2)$.

Claim: let $\nu : \Omega \rightarrow \mathbb{R}^2$ be a C^1 vector field then $\{\gamma : [a, b] \rightarrow \Omega \mid (a, b \in \mathbb{R}) \wedge (\gamma \text{ is an integral curve of } \nu)\}$ foliates Ω .

Theorem Peano: let $\nu : \Omega \rightarrow \mathbb{R}^2$ be a vector field then $\{\gamma : [a, b] \rightarrow \Omega \mid (a, b \in \mathbb{R}) \wedge (\gamma \text{ is an integral curve of } \nu)\}$ covers Ω .

Lemma: let $\Omega \subseteq \mathbb{R}^2$ be a domain and let $f \in C^1(\Omega)$ then $\left(\frac{1}{f}\right)$ is a vector field.

Theorem of Existence and Uniqueness: let $\Omega \subseteq \mathbb{R}^2$ be a domain let $f \in C^1(\Omega)$ and let $g \in C^1(\mathbb{R})$ then $(g' = f(x, g)) \iff \left(\left(\frac{x}{g}\right) \text{ is an integral curve of } \left(\frac{1}{f}\right)\right)$.

Autonomous Ordinary Differential Equations: let $f : \mathbb{R} \rightarrow \mathbb{R}$ then $y' = f(y)$.

Logistic Equation: let $L > 0$ then $\dot{P}(t) = P(t)(L - P(t))$.

Equilibrium Solution: let $f : \mathbb{R} \rightarrow \mathbb{R}$ then a function $g \in \text{sols}(y' = f(y))$ such that $f(g(x)) = 0$ for all $x \in \mathbb{R}$.

Corollary: let $f \in C(\mathbb{R})$ and let $g : \mathbb{R} \rightarrow \mathbb{R}$ be an equilibrium solution then g is constant.

Corollary: let $L > 0$ then $\{0, L\}$ are the equilibrium solutions of the logistic equation.

Logistic Equation With Harvesting: let $L, k > 0$ then $\dot{P}(t) = P(t)(L - P(t)) - k$.

Stable Equilibrium Solution: let $f : \mathbb{R} \rightarrow \mathbb{R}$ then an equilibrium solution $g : \mathbb{R} \rightarrow \mathbb{R}$ such that for all $y \in \text{sols}(y' = f(y))$ and for all $\varepsilon > 0$ if there exists $\delta > 0$ and $p \in \mathbb{R}$ for which $|y(p) - g(p)| < \delta$ then $|y(t) - g(t)| < \varepsilon$ for all $t > p$.

Notation: let X be a set and let $\gamma : \mathbb{R} \rightarrow X$ then $\dot{\gamma} = \frac{d\gamma}{dt}$.

Notation: let X be a set and let $\gamma : \mathbb{R} \rightarrow X$ then $\ddot{\gamma} = \frac{d^2\gamma}{dt^2}$.

Remark: the notation $\dot{\gamma}, \ddot{\gamma}$ is often used when γ is a function of time.

System of Ordinary Differential Equation (ODE): let $n \in \mathbb{N}$ let $m \in \mathbb{N}_+$ and let $f : \mathbb{R} \times (\mathbb{R}^m)^n \rightarrow \mathbb{R}^m$ then

$f(t, y(t), y'(t), \dots, y^{(n)}(t)) = 0$.

Remark: all the theory of first order ODEs also applies to vectors of first order ODEs.

Lotka-Volterra equations: let $\alpha > 0$ then $\begin{cases} \dot{x}(t) = x(t) \cdot (1 - y(t)) \\ \dot{y}(t) = \alpha \cdot y(t) \cdot (x(t) - 1) \end{cases}$.

Claim: let $\alpha > 0$ then $\left\{\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix}\right\}$ are the equilibrium solutions of the lotka-volterra equation.

Conserved Quantity: let $\mathcal{U} \subseteq \mathbb{R}^n$ and let $f : \mathcal{U} \rightarrow \mathbb{R}$ then a function $g \in C^1(\mathcal{U})$ such that $g \circ y$ is constant for all $y \in \text{sols}(y' = f(y))$.

Claim: let $\alpha > 0$ and let $\begin{pmatrix} x \\ y \end{pmatrix} \in C^1(\mathbb{R}^2)$ be a solution to the lotka-volterra equation then

$$\frac{d}{dt}((y(t) - 1 - \log(y(t))) + \alpha(x(t) - 1 - \log(x(t)))) = 0.$$

Corollary: let $\alpha > 0$ let $p \in \mathbb{R}^2$ and let $\begin{pmatrix} x \\ y \end{pmatrix} \in C^1(\mathbb{R}^2)$ be a solution to $\begin{cases} \dot{x}(t) = x(t) \cdot (1 - y(t)) \\ \dot{y}(t) = \alpha \cdot y(t) \cdot (x(t) - 1) \\ \begin{pmatrix} x \\ y \end{pmatrix}(0) = p \end{cases}$ then $\begin{pmatrix} x \\ y \end{pmatrix}$ is periodic.

Lemma: let $\alpha > 0$ let $p \in \mathbb{R}^2$ and let $\begin{pmatrix} x \\ y \end{pmatrix} \in C^1(\mathbb{R}^2)$ be a solution to $\begin{cases} \dot{x}(t) = x(t) \cdot (1 - y(t)) \\ \dot{y}(t) = \alpha \cdot y(t) \cdot (x(t) - 1) \\ \begin{pmatrix} x \\ y \end{pmatrix}(0) = p \end{cases}$ with period T then $\frac{1}{T} \int_0^T x dt = 1$

$$\text{and } \frac{1}{T} \int_0^T y dt = 1.$$

Claim Linear Substitution: let $a, b, c \in \mathbb{R}$ let $f : \mathbb{R} \rightarrow \mathbb{R}$ and let $y \in \text{sols}(y' = f(ax + by + c))$ then the function $z : \mathbb{R} \rightarrow \mathbb{R}$ which defined by $z(x) = ax + by + c$ satisfies $z' = a + bf(z)$.

Notation: let $\Omega \subseteq \mathbb{R}^2$ be a domain let $f : \Omega \rightarrow \mathbb{R}$ and let $p \in \mathbb{R}^2$ then (α_-, α_+) is the maximal interval where a solution to $\begin{cases} y' = f(x, y) \\ y(p_1) = p_2 \end{cases}$ is defined.

Corollary: let $\Omega \subseteq \mathbb{R}^2$ be a domain let $f \in C^1(\Omega)$ and let $p \in \mathbb{R}^2$ then $\alpha_- < p_1 < \alpha_+$.

Theorem: let $f \in C^1(\mathbb{R}^2)$ and let $p \in \mathbb{R}^2$ then

- $(\alpha_+ < \infty) \iff \left(\lim_{x \rightarrow \alpha_+^-} |y(x)| = \infty\right).$
- $(-\infty < \alpha_-) \iff \left(\lim_{x \rightarrow \alpha_-^+} |y(x)| = \infty\right).$

Theorem Extensibility of Solutions: let $D \subseteq \mathbb{R}^{n+1}$ be a closed set let $f \in C^1(D, \mathbb{R}^n)$ and let $y \in \text{sols}(y' = f(x, y))$ such that $\Gamma_y \cap D \neq \emptyset$ then there exists $\psi : [a, b] \rightarrow \mathbb{R}^n$ such that $\psi \in \text{sols}(y' = f(x, y))$ and $\psi(x) = y(x)$ for all $x \in \text{Dom}(y)$ and $\begin{pmatrix} \psi(a) \\ \psi(b) \end{pmatrix} \in \partial D$.

Corollary: let $D \subseteq \mathbb{R}^{n+1}$ such that for all $\alpha, \beta \in \mathbb{R}$ the set $D \cap \{\alpha \leq x_1 \leq \beta\}$ is bounded let $f \in C^1(D, \mathbb{R}^n)$ and let $y \in \text{sols}(y' = f(x, y))$ such that $\Gamma_y \cap D \neq \emptyset$ then one of the next statements is true

- there exists $\psi : [a, b] \rightarrow \mathbb{R}^n$ such that $\psi \in \text{sols}(y' = f(x, y))$ and $\psi(x) = y(x)$ for all $x \in \text{Dom}(y)$ and $\begin{pmatrix} \psi(a) \\ \psi(b) \end{pmatrix} \in \partial D$.
- there exists $\psi : \mathbb{R} \rightarrow \mathbb{R}^n$ such that $\psi \in \text{sols}(y' = f(x, y))$ and $\psi(x) = y(x)$ for all $x \in \text{Dom}(y)$.

Corollary: let $I \subseteq \mathbb{R}$ be an open interval let $D \subseteq \mathbb{R}^n$ let $f \in C^1(I \times D, \mathbb{R}^n)$ and let $p, q : \mathbb{R} \rightarrow \mathbb{R}$ such that

$\|f(x, y)\| \leq p(x)\|y\| + q(x)$ then for all $y \in \text{sols}(y' = f(x, y))$ such that $\Gamma_y \cap (I \times D) \neq \emptyset$ there exists $\psi : I \rightarrow \mathbb{R}^n$ such that $\psi \in \text{sols}(y' = f(x, y))$ and $\psi(x) = y(x)$ for all $x \in \text{Dom}(y)$.

Theorem Continuous Dependence on Initial Conditions: let $\Omega \subseteq \mathbb{R}^2$ let $f \in C^1(\Omega)$ let $a, b, p \in \mathbb{R}$ and let y_p be a solution to $\begin{cases} y' = f(x, y) \\ y(a) = p \end{cases}$ such that y_p is defined on $[a, b]$ then for all $\varepsilon > 0$ there exists $\delta > 0$ such that for all $q \in \mathbb{R}$ for which $|p - q| < \delta$

if y_q is a solution to $\begin{cases} y' = f(x, y) \\ y(a) = q \end{cases}$ then y_q is defined on $[a, b]$ and $|y_p - y_q| < \varepsilon$.

Theorem: let $\Omega \subseteq \mathbb{R}^2$ let $f \in C^1(\Omega)$ let $a, b \in \mathbb{R}$ let $g \in C^1([a, b])$ and let $\{g_n\}_{n=0}^\infty \subseteq \text{sols}(y' = f(x, y))$ such that g_n is defined on $[a, b]$ for all $n \in \mathbb{N}$ and $g_n \xrightarrow{p.w.} g$ then $g \in \text{sols}(y' = f(x, y))$.

n-th Order Ordinary Differential Equation: let $f : \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ then $f(x, y \dots y^{(n)}) = 0$.

Claim: let $n \in \mathbb{N}_+$ let $f : \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ and let $g : \mathbb{R} \rightarrow \mathbb{R}$ then

$$(g \in \text{sols}(f(t, x(t) \dots x^{(n)}(t)) = 0)) \iff \left(\begin{pmatrix} g \\ \vdots \\ g^{(n)} \end{pmatrix} \in \text{sols} \left(\begin{cases} y_1 = \dot{x} \\ \vdots \\ y_{n-1} = y_{n-2} \\ y_{n-1} = f(t, x, y_1, \dots, y_{n-1}) \end{cases} \right) \right)$$

Harmonic Oscillator/Spring Position Equation: $\ddot{x} = -x$.

Claim: the function $E(x, y) = \frac{1}{2}x^2 + \frac{1}{2}y^2$ is a conserved quantity of $\begin{cases} \dot{x} = y \\ \dot{y} = -x \end{cases}$.

Spring with Friction Position Equation: $\ddot{x} = -x - \dot{x}$.

Constant Tension Spring Position Equation: $\ddot{x} = -1$.

Claim: the function $E(x, y) = x + \frac{1}{2}y^2$ is a conserved quantity of $\begin{cases} \dot{x} = y \\ \dot{y} = -1 \end{cases}$.

Gravity in One Dimension Equation: $\ddot{x} = -\frac{1}{x^2}$.

Claim: the function $E(x, y) = \frac{1}{x} + \frac{1}{2}y^2$ is a conserved quantity of $\begin{cases} \dot{x}=y \\ \dot{y}=-\frac{1}{x^2} \end{cases}$.

Pendulum Equation: $\ddot{x} = -\sin(x)$.

Claim: the function $E(x, y) = \frac{1}{2}y^2 - \cos(x)$ is a conserved quantity of $\begin{cases} \dot{x}=y \\ \dot{y}=-\sin(x) \end{cases}$.

Differential 1-form: let $P, Q : \mathbb{R}^2 \rightarrow \mathbb{R}$ then $P(x, y) dx + Q(x, y) dy$.

Remark: in this course we won't explain the formal definition of a differential 1-form so we will use it as an object with certain properties.

Integral: let $\gamma : [a, b] \rightarrow \mathbb{R}^2$ be a curve and let $P, Q : \mathbb{R}^2 \rightarrow \mathbb{R}$ then

$$\int_{\gamma} (P(x, y) dx + Q(x, y) dy) = \lim_{\Delta \rightarrow 0} \sum_{i=0}^{n-1} (P(x_i, y_i) (x_{i+1} - x_i) + Q(x_i, y_i) (y_{i+1} - y_i)).$$

Remark: in the definition above $\lim_{\Delta \rightarrow 0}$ is the limit of all partitions of γ to horizontal and vertical segments.

Claim: let $\gamma : [a, b] \rightarrow \mathbb{R}^n$ be a curve let $\nu : [\alpha, \beta] \rightarrow [a, b]$ such that $\gamma \circ \nu$ is a reparameterization of γ and let ω be a differential 1-form then $\int_{\gamma} \omega = \int_{\gamma \circ \nu} \omega$.

Claim: let $\gamma : [a, b] \rightarrow \mathbb{R}^n$ be a curve and let ω be a differential 1-form then $\int_{\gamma} \omega = -\int_{-\gamma} \omega$.

Integral: let $\gamma : [a, b] \rightarrow \mathbb{R}^2$ be a curve and let $f, g : \mathbb{R}^2 \rightarrow \mathbb{R}$ then $\int_{\gamma} f dg = \lim_{\Delta \rightarrow 0} \sum_{i=0}^{n-1} (f(x_i, y_i) (g(x_{i+1}, y_{i+1}) - g(x_i, y_i)))$.

Claim: let $g \in C^1(\mathbb{R}^2)$ then $dg = \frac{\partial g}{\partial x} dx + \frac{\partial g}{\partial y} dy$.

Corollary: let $\gamma : [a, b] \rightarrow \mathbb{R}^2$ be a curve let $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ and let $g \in C^1(\mathbb{R}^2)$ then $\int_{\gamma} f dg = \int_{\gamma} \left(f \cdot \frac{\partial g}{\partial x} dx + f \cdot \frac{\partial g}{\partial y} dy \right)$.

Exact Differential 1-form: a differential 1-form ω such that there exists $g \in C^1(\mathbb{R}^2)$ for which $\omega = dg$.

Theorem: let ω be a differential 1-form then TFAE

- ω is exact.
- there exists $f : \mathbb{R} \rightarrow \mathbb{R}$ such that for all curves $\gamma : [a, b] \rightarrow \mathbb{R}^2$ we have $\int_{\gamma} \omega = f(\gamma(b)) - f(\gamma(a))$.
- for all closed curves $\gamma : [a, b] \rightarrow \mathbb{R}^2$ we have $\int_{\gamma} \omega = 0$.

Primitive/Potential: let ω be an exact differential 1-form then $g \in C^1(\mathbb{R}^2)$ such that $\omega = dg$.

Claim: let $X : \mathbb{R} \rightarrow \mathbb{R}^3$ and let $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ then $\frac{d}{dt} (f \circ X) = (\nabla f) \cdot \dot{X}$.