# DSC 40B Theoretical Foundations II

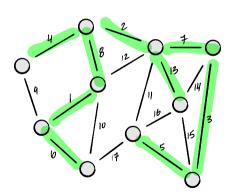
Lecture 17 | Part 1

**Kruskal's Algorithm** 

# **Last Time: Minimum Spanning Tree**

- The minimum spanning tree problem is as follows:
  - GIVEN: A weighted, undirected graph  $G = (V, E, \omega)$ .
  - ► COMPUTE: a spanning tree of *G* with minimum cost (i.e., minimum total edge weight).

# **Example**



## **Last Time: Building MSTs**

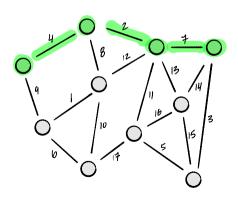
- How do we build a MST efficiently?
- We'll adopt a greedy approach.
  - Build a tree edge-by-edge.
  - At every step, doing what looks best at the moment.
- This strategy isn't guaranteed to work in all of life's situations, but it works for building MSTs.

# **Two Greedy Approaches**

- We'll look at two greedy algorithms:
  - Last Time: Prim's Algorithm
  - ► Today: Kruskal's Algorithm
- Differ in the order in which edges are added to tree.

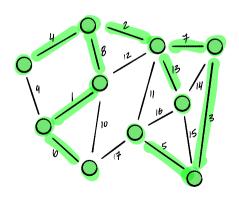
Also differ in time complexity.

# Prim's Algorithm, Informally



- Start by picking any node to add to "tree", T.
- While T is not a spanning tree, greedily add lightest edge from a node in T to a node not in T.
  - "lightest" = edge of smallest weight

# Kruskal's Algorithm, Informally



- Start with empty forest:  $T = (V, E_{mst})$ , where  $E_{mst} = \emptyset$ .
- Loop through edges in increasing order of weight.
  - If edge does not create a cycle in *T*, add it to *T*.
  - If T is a spanning tree, break.

# **Being Greedy**

- Prim: add the **node** with smallest estimated cost and update neighbors.
  - Works locally, "grows" a connected tree.

- Kruskal: add the edge with smallest weight.
  - As long as it doesn't make a cycle.
  - Edge can be anywhere in graph.

# Kruskal's Algorithm (Pseudocode)

```
def kruskal(graph, weights):
    mst = UndirectedGraph()
    # sort edges in ascending order by weight
    sorted edges = sorted(graph.edges, kev=weights)
    for (u, v) in sorted edges:
        # if u and v are not already connected
        if ...:
            mst.add edge(u. v)
            # (optional) if mst is now a spanning tree, break
            if len(mst.edges) == len(graph.nodes) - 1:
                break
```

return mst

# **Checking for Connectivity**

- Each iteration: check if u and v are connected in  $T = (V, E_{mst})$ .
- We could do a DFS/BFS on each iteration...
  - $\triangleright$   $\Theta(V + E_{mst}) = \Theta(V)$  each time.
  - Expensive!

- Remember:
  - If you're computing something once, use a fast algorithm.
  - If you're computing it repeatedly, consider a data structure.

# **Disjoint Set Forests**

Represent a collection of disjoint sets.

$$\{\{1, 5, 6\}, \{2, 3\}, \{0\}, \{4\}\}$$

- .union(x, y): Union the sets containing x and y.
- .in\_same\_set(x, y): Return True/False if x
  and y are in the same set.1

 $<sup>^{1}</sup>$ Usually implemented as a .find(x) method returning representative of set containing x.

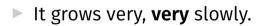
# **Example**

```
»> # create a DSF with {{0}, {1}, {2}, {3}, {4}, {5}}
»> dsf = DisjointSetForest([0, 1, 2, 3, 4, 5])
»> dsf.union(o. 3)
»> dsf.union(1, 4)
»> dsf.union(3. 1)
»> dsf.union(2, 5)
»> # dsf now represents {{0, 1, 3, 4}, {2, 5}}
»> dsf.in same set(0.3)
True
»> dsf.in same set(0. 2)
False
```

# **Disjoint Set Forests**

Properties of Operations take  $\Theta(\alpha(n))$  time, where n is number of objects in collection.

 $\triangleright$   $\alpha(n)$  is the inverse Ackermann function.



Essentially constant time.



# **Disjoint Set Forests**

- Can be used to keep track of CCs of a dynamic graph.
- Nodes of CCs are disjoint sets.
  - Add an edge (u, v): union(u, v)
  - ightharpoonup Check if u and v are connected:
    - .in\_same\_set(u, v)
- To check if u, v are already connected:
  - $\triangleright$  BFS/DFS:  $\Theta(V)$  each time.
  - ▶ DSF:  $\Theta(\alpha(V))$  each time (essentially  $\Theta(1)$ ).

# Kruskal's Algorithm

```
def kruskal(graph, weights):
   mst = UndirectedGraph()
    # place each node in its own disjoint set
    components = DisjointSetForest(graph.nodes)
    # sort edges in ascending order by weight
    sorted edges = sorted(graph.edges, key=weights)
    for (u, v) in sorted edges:
        if not components in same set(u, v):
            mst.add edge(u, v)
            components.union(u, v)
            # (optional) if mst is now a spanning tree, break
            if len(mst.edges) == len(graph.nodes) - 1:
                break
```

# **Time Complexity**

```
def kruskal(graph, weights):
   mst = UndirectedGraph()
   # place each node in its own disjoint set
components = DisjointSetForest(graph.nodes)
  # (optional) if mst is now a spanning tree break
          if len(mst.edges) == len(graph.nodes) - 1:
             break
   return mst
```

# **Time Complexity**

- Assume graph is connected. Then  $E = \Omega(V)$ .
- ► Kruskal's takes  $\Theta(E \log E) = \Theta(E \log V)$  time.
  - Dominated by sorting the edges.
- Note: if graph disconnected, Kruskal's produces a minimum spanning forest.

# DSC 40B Theoretical Foundations II

Lecture 17 | Part 2

Kruskal v. Prim

#### Kruskal v. Prim

- Both algorithms for computing MSTs.
- ▶ Which is "better"?
- ► There's no clear winner.

# **Time Complexity**

- Prim:
  - ▶ Binary heap:  $\Theta(V \log V + E \log V)$
  - Fibonacci heap:  $\Theta(V \log V + E)$
- Kruskal: Θ(E log V)
- If the graph is dense,  $E = \Theta(V^2)$ , and Prim's with Fibonacci heap "wins".
  - $\triangleright$  Θ( $V^2$ ) versus Θ( $V^2$  log V).

#### Not so fast...

Fibonacci heaps are hard to implement, high overhead.

- Prim's will be faster for very large dense graphs.
- But Kruskal's may be faster for smaller dense graphs.
- The right choice depends on your application.

#### Main Idea

Asymptotic time complexity isn't everything. For small inputs, the "inefficient" algorithm may beat the "efficient" one. There's also ease of implementation to consider.

# DSC 40B Theoretical Foundations II

Lecture 17 | Part 3

**MSTs and Clustering** 

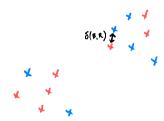
# Clustering

Goal: identify the groups in data. Example:



# Clustering, Formalized

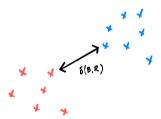
- We frame as an optimization problem.
  - GIVEN: n data points.
  - GOAL: assign color to each point (red or blue) to maximize the distance between the closest pair of red and blue points.



**Bad Clustering** 

# Clustering, Formalized

- We frame as an optimization problem.
  - GIVEN: n data points.
  - ► GOAL: assign color to each point (red or blue) to maximize the distance between the closest pair of red and blue points.



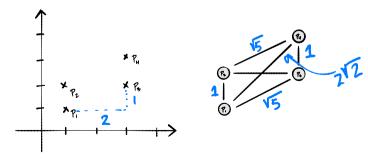
**Good Clustering** 

#### **Brute Force Solution**

- Try all possible assignments; return best.
- If there are n data points, there are  $\Theta(2^n)$  assignments.
- Exponential time; very slow. Practical only for ~ 50 data points.
- Instead, we will turn it into a graph problem.

# **Distance Graphs**

- Given n data points,  $p_1, p_2, ..., p_n$ , create complete graph with  $V = \{p_1, ..., p_n\}$ .
- ► Set weight of edge  $(p_i, p_j)$  = dist $(p_i, p_j)$ .
- The result is a weighted, undirected distance graph.



#### Main Idea

We can always think of a set of points in a (metric) space as a weighted distance graph. This is a **very** important idea, because it allows us to use our graph algorithms!

# **Clustering with MSTs**

- Given n data points and a number of clusters, k:
  - Create distance graph G.
  - Run Kruskal's Algorithm on G until there are only k components.



- ► The resulting connected components are the clusters.
- ► This is known as single-linkage clustering.



**Example** 

# **Single-Linkage Clustering**

- Time complexity of single-linkage is determined by Kruskal's Algorithm: Θ(E log E).
- Since distance graph is complete,  $E = \Theta(V^2)$ , and so

$$\Theta(E \log E) = \Theta(V^2 \log V) = \Theta(n^2 \log n)$$

Practically, can cluster ~ 10,000 points.

### **Summary**

- We started the quarter with a brute force solution.
  - ightharpoonup Took Θ(2<sup>n</sup>) time, only feasible for a few dozen points.
- We've now reframed the problem using graph theory.
  - Now only  $\Theta(n^2 \log n)$  time!
  - Feasible for tens of thousands of points.

# Why Algorithms?

- Data scientists use computers as tools.
- But solving a problem isn't just about coding it up.
- You need to know how to analyze your code and use the right algorithms and data structures to make your solution efficient.