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# *Approximate Membership Queries (AMQs)*

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# Overview

- Motivation
- Hash Tables – A quick review
- Hash Functions – A quick review
- Bloom Filters
- Counting Bloom Filters
- More recent AMQ Filters

# MOTIVATION

# Set Membership

- Given an arbitrary sized **string**  $s$  and a **set**  $S$
- Does  $s$  **belong** to  $S$  ?
- Easy answer for **small sets** !
  - **Complexity** ?
- BUT “difficult” answer for **huge sets** !
  - E.g., Big-Data applications
- **Approximate** Membership Queries (**AMQ**)

# HASH TABLES

# Hash Tables

- Data structure for storing **key-value** pairs
- **No ordering !!**
- **BUT, fast access !!**
- **No duplicate keys !!**

# Hash Tables

- Two main operations :
- **Insert** (put) a key-value pair into the table
  - If key **already exists**, **update** the value
- **Search for** (get) the value associated with a given key

# Hash Tables

- **Additional** operations :
- `contains(key)`
- `delete(key)`
- `is_empty()`
- Keys iterator
- ...



# Hashing

- To reference key-value pairs stored in a table
- Perform arithmetic operations that transform **search keys** into **array indices**
  - FAST !!
- Ideally, different keys would map to different indices
- BUT, **collisions** do occur !!

# HashTables – Time complexity

- The time complexity of searches by hashing can be as low as  $O(1)$  or as high as  $O(N)$
- Worst-case ?
- Distinct keys  $K_i \neq K_j$  collide:  $h(K_i) = h(K_j)$
- The entire table must be searched to find the correct entry
- Or to conclude it is not there !

# Hash Tables – Toy Example

- Download the file `hash_table_V_1.py`
- Identify the available operations
- Create a table and insert several key-value pairs
- What kind of **keys** can be used ?
- How are **collisions** resolved ?
- What **operations** are missing ?

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# HASH FUNCTIONS

# Hash Functions

- **Pseudo-random** mathematical functions used to compute indices for table look-up
  - Keys are mapped to small integers
- Indices should be **evenly distributed**
  - Even if there are regularities in the data
- There are **many** hash functions
  - With different degrees of complexity
  - And with differences in performance
  - For different applications

# Simple Hash Functions

## ■ Division method

- ❑ Choose a **prime  $m$**  that isn't close to a power of 2
- ❑  **$h(k) = k \bmod m$**
- ❑ Works badly for many types of patterns in the input data

## ■ Knuth's variant

- ❑  **$h(k) = k(k+3) \bmod m$**
- ❑ Supposedly works much better than the raw division method

# Simple Hash Functions

```
def hash(astring, tablesize):  
    sum = 0  
    for pos in range(len(astring)):  
        sum = sum + ord(astring[pos])  
  
    return sum%tablesize
```

- **Anagrams** will be given the same values...

# Hash Functions – DJB31MA

```
uint hash(const uchar* s, int len, uint seed)
{
    uint h = seed;
    for (int i=0; i < len; ++i)
        h = 31 * h + s[i];
    return h;
}
```



# Non-cryptographic Hash Functions

- Suitable for hash table lookup but not for cryptography / secure uses
- Fast computation
- **FNV** – Fowler-Noll-Vo hash function
- **Murmur** Hash
  - **M**ultiply and **r**otate
- ...

# Universal Hashing

- Issue
  - There always exist **keys** that are mapped to the **same integer / index**
- Consider a **set** of hash functions  $H$
- $H$  is **universal** (good), if
  - For all keys  $0 \leq i \leq j < M$
  - **Probability**  $(h(i) = h(j)) \leq 1 / M$ , for  $h$  randomly selected from  $H$

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# **APPROXIMATE MEMBERSHIP QUERIES**

# Approximate Membership Queries

- Given a set  $S = \{x_1, x_2, \dots, x_n\}$
- Answer queries of the form: *Is  $y$  in  $S$ ?*
- Data structure should be **FAST** and **SMALL**
  - Faster than **searching** through  $S$
  - Smaller than **explicit representation**

# Approximate Membership Queries

- How to get **speed** and **size** improvements ?
- Allow some **probability of error** !!
- **False positives**
  - $y \notin S$  but reporting  $y \in S$
- **False negatives**
  - $y \in S$  but reporting  $y \notin S$

# BLOOM FILTERS

# Bloom Filters

- B. H. Bloom, 1970
- Use **hash functions** to determine **approximate set membership**
- Allow for **fast set membership tests** on very large data sets
- Applications
  - Spell-Checking / Text Analysis
  - Network monitoring
  - ...

# Application – Spell-Checkers

- Determine if **candidate words** are members of the **set of words** in a dictionary
- The Bloom filter should be large enough to allow the inclusion of additional words by the user



# Application – Web-Caching

- Bloom filters are used in WWW caching proxy servers
- Proxy servers intercept requests from clients and either fulfill the requests themselves or re-issue them to servers

# Application – Email Spam

- We know **1 billion** “good” email addresses
- If an email comes from one of these, it is **NOT** spam
- How check for spam in a **FAST** way ?

# Application – Text Analysis

- Find **related** passages in different reports
- Constructing a Bloom Filter of all the words in each passage
- Computing the **normalized dot product** of all Bloom filter pairs
- The result of every dot product is a **similarity measure**

# Bloom Filters

- *Is  $y$  in  $S$  ?*
- A Bloom filter
  - Provides an answer in **constant time**
    - Time to **hash**
- Uses a **small** amount of memory space
- **BUT**, with some **small probability of being wrong !**

# 1<sup>st</sup> – Register the elements of set $S$

Start with an  $m$  bit array, filled with 0s.

$B$	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
-----	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

Hash each item  $x_j$  in  $S$   $k$  times. If  $H_i(x_j) = a$ , set  $B[a] = 1$ .

$B$	0	1	0	0	1	0	1	0	0	1	1	1	0	1	1	0
-----	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

[Mitzenmacher]

## 2<sup>nd</sup> – Process the queries

To check if  $y$  is in  $S$ , check  $B$  at  $H_i(y)$ . All  $k$  values must be **1**.

$B$	0	1	0	0	1	0	1	0	0	1	1	1	0	1	1	0
-----	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

Possible to have a false positive; all  $k$  values are **1**, but  $y$  is not in  $S$ .

$B$	0	1	0	0	1	0	1	0	0	1	1	1	0	1	1	0
-----	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

[Mitzenmacher]

# Basic operations

## ■ Initialization

- ❑ Clear all cells

## ■ Insertion

- ❑ Compute the values of **k hash functions**
- ❑ **Set** the corresponding **cells**, if needed
- ❑ It takes constant time, but proportional to  $k$

# Basic operations

- Membership test
  - Compute the values of **k hash functions**
  - Check if the corresponding **cells** have been set
  - If **any** such cell is **not set**, the searched element is **not a member** of the set
- **Worst-case ?**
- Checking all **k cells** !
  - Set **elements** and **false positives**



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# Bloom Filter – Simple Demos

- Bloom Filters by Example

- <http://billmill.org/bloomfilter-tutorial/>

- Bloom Filters

- <https://www.jasondavies.com/bloomfilter/>

# Bloom Filters – Toy Example

- Download the file `bloom_filter_V_1.py`
- Identify the available operations
- Create a Bloom filter and insert several items
- Perform membership tests for various items
  - Belonging and `not belonging` to the set

# Bloom Filters – Behaviour

- **Deterministic** hash functions !
- No attempt to solve hashing collisions !
- Can we get **false negatives** ?
- Probability of **false positives** ?
- How to **minimize** ?

# Bloom Filter – Parameters

- The **behaviour** of a Bloom filter is determined by four parameters
- **n** set elements registered in B
- **m = c × n** cells in B (i.e., bits)
- **k** independent, random hash functions
- **f** is the fraction of cells set to 1

# Bloom Filter – Parameters

- How to choose  $m$ , the size of the filter ?
- How to choose  $k$ , the number of hash functions ?
- How do we choose the best  $k$  value ?

# Probabilities – After 1 insertion

- Initially all bits are set to zero
- Inserting one element
- What is the probability of  $b_i = 1$ , after using the **first hash function** ?
  - Equal probability for any cell

$$P(b_i = 1) = \frac{1}{m}$$

$$P(b_i = 0) = 1 - \frac{1}{m}$$

# Probabilities – After 1 insertion

- After computing the  $k$  hash functions and setting  $k$  cells

$$P(b_i = 0) = \left(1 - \frac{1}{m}\right)^k$$

# Probabilities – After $n$ insertions

- After inserting all  $n$  set elements, by computing each time  $k$  hash values
  - Assuming independence

$$P(b_i = 0) = \left(1 - \frac{1}{m}\right)^{k \times n}$$



# Probabilities – After $n$ insertions

$$P(b_i = 0) = \left(1 - \frac{1}{m}\right)^{k \times n}$$

$$P(b_i = 1) = 1 - a^k, \quad a = \left(1 - \frac{1}{m}\right)^n$$

# Probability of a false positive

- Testing the membership of an item not in  $S$  entails a positive answer
  - Corresponding  $k$  bits are set to 1
- The probability of that happening is

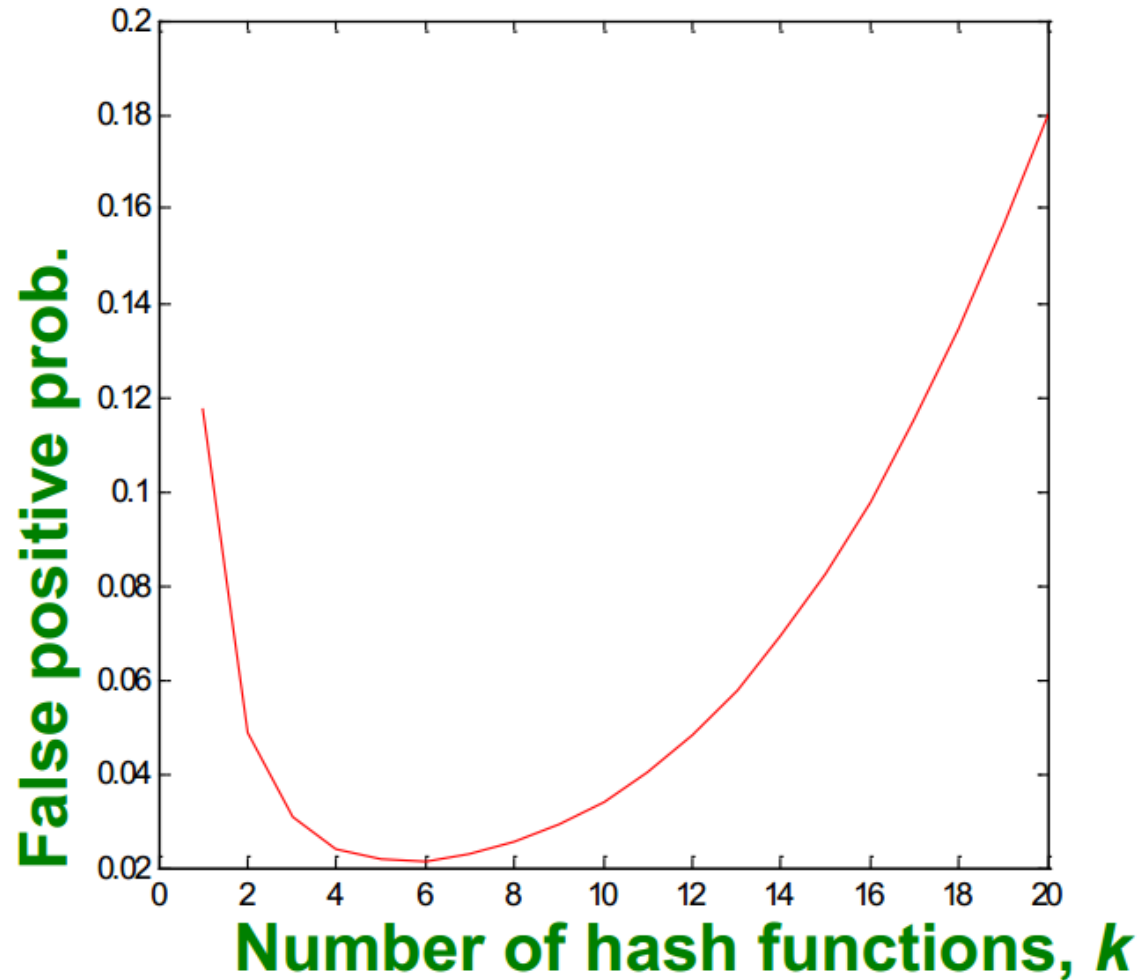
$$p = (1 - a^k)^k$$

$$p \approx (1 - e^{-kn/m})^k$$

# Example

- $n = 1$  billion items,  $m = 8$  billion bits
- $k = 1$  :  $p \approx (1 - e^{-1/8}) = 0.1175$
- $k = 2$  :  $p \approx (1 - e^{-2/8})^2 = 0.0493$
- What happens as we keep increasing  $k$  ?

# Optimal value of $k$



# Optimal value of $k$

- To determine the value of  $k$  that minimizes  $p$  we minimize  $\log p$ , which is more tractable

- And get

$$k_{opt} \approx \frac{m}{n} \times \ln 2 \approx 0.693 \times \frac{m}{n}$$

- Use the closest integer to  $k_{opt}$

- For the previous example :  $k_{opt} \approx 5,54 \approx 6$

# Which Hash Functions ?

- No need to use **cryptographic** hash functions !
- You can **simulate k** hash functions by simply combining **two hash functions**
  - Kirsch and Mitzenmacher (2006)
- Compute one base hash function on **unsigned 64-bit** numbers
- Take the upper half and the lower half of that value and return them as **two 32 bit numbers**

# Bloom Filters – Toy Example – Tasks

- Carry out computational experiments with different filter parameters ( $m$ ,  $n$ ,  $k$ )
- Generate a random set of keys and insert pairs key-value
- Perform membership tests
- Analyze the percentage of false positives

# Bloom Filters – Wrap-up

- **No false negatives** and **limited memory** usage
  - Great for pre-processing before more expensive checks
- Suitable for hardware implementation
  - Hash computations can be **parallelized**
- **Error rate** can be decreased by increasing the number of hash functions and allocated memory space



# Bloom Filters – Wrap-up

- Useful for applications where an imperfect set membership test can be helpfully applied to a **large data set of unknown composition**
- Advantage over hash tables is Bloom filter **speed** and **error rate**

# Bloom Filters – Pending Issues

- Cannot represent **multi-sets**
  - I.e., sets with repeated elements
- Cannot query the **multiplicity** of an item
- **Deleting** an item is not possible !

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# **COUNTING** **BLOOM FILTERS**

# Counting Bloom Filters

- Multi-set representation
- Now, each filter cell is a **w-bit counter**
  - **w = 4** seems to be enough for most applications

# Counting Bloom Filters

- To **insert** an element, **increase** the value of each corresponding **cell**
- **Test membership** checks if each of the required **cells** is **non-zero**

# Counting Bloom Filters

- To **delete** an element, **decrease** the value of each corresponding **cell**
- **Deletions** necessarily introduce **false negative errors !!**
  - How ?

# Counting Bloom Filters

- To retrieve the **count** of an element :
- **Compute** its set of counters
- And return the **minimum value** as a **frequency estimate**

# Counting Bloom Filters

Start with an  $m$  bit array, filled with 0s.

$B$

0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

Hash each item  $x_j$  in  $S$   $k$  times. If  $H_i(x_j) = a$ , add 1 to  $B[a]$ .

$B$

0	3	0	0	1	0	2	0	0	3	2	1	0	2	1	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

[Mitzenmacher]



# Counting Bloom Filters

To delete  $x_j$  decrement the corresponding counters.

*B*

0	2	0	0	0	0	2	0	0	3	2	1	0	1	1	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

Can obtain a corresponding Bloom filter by reducing to 0/1.

*B*

0	1	0	0	1	0	1	0	0	1	1	1	0	0	1	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

[Mitzenmacher]

# Counting Bloom Filters – Issues

- Counter **overflow**
  - **No more increments** after reaching  $2^w - 1$
  - BUT, now we have **undercounts** !!
- Choice of **counter width**  $w$ 
  - A **large**  $w$  diminishes space savings and introduces unused space (many zeros)
  - A **small**  $w$  quickly leads to maximum values
  - Trade-off...

# Counting Bloom Filters in Practice

- If insertions/deletions are **rare** compared to look-ups
  - Keep a CBF in “off-chip memory”
  - Keep a BF in “on-chip memory”
  - Update the BF when the CBF changes
- Keep space savings of a Bloom filter
- But can deal with deletions
- Popular design for network devices

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# REFERENCES

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# References

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- A. Broder and M. Mitzenmacher, Network Applications of Bloom Filters: A Survey, *Internet Mathematics*, Vol. 1, N. 4, 2004

# THE QUOTIENT FILTER

# Bloom Filters – Main limitation

- What happens if the filter is **too big to fit in main memory** ?
- Store some parts of the filter in **HDD** or **SSD**
- **BUT** random accesses are **slower** in disk...
- Significantly **bad performance** !

# Bloom Filters – Main limitation

## ■ IDEAS:

- ❑ Random access **only once**
- ❑ Store each element's data **really close**

## ■ BUT

- ❑ When using just **1 hash function**
- ❑ Have to deal with **high collision probability**

## ■ HOW ? --- **The Quotient Filter**



# The Quotient Filter

- 2011 : Michael Bender et al.
- Space-efficient probabilistic data structure for AMQ
- Implements a **set** with 4 operations
  - **Add** element
  - **Delete** element
  - Test whether an element **is a member**
  - Test whether an element **is not a member**

# The Quotient Filter

- **BUT** do not actually store each element
- Just store a **p-bit fingerprint** for each element
- Using just **one hash function**
- Compact **open hash table** with  **$m = 2^q$**  buckets

# Quotienting

- The fingerprint  $f$  ( $p$  bits) is partitioned
- Division by  $2^r$ , i.e., shift to the right
  - The remainder  $f_r$  :  $r$  least significant bits
  - The quotient  $f_q$  :  $q$  most significant bits
- The quotient indexes a table bucket
- The remainder is stored in that bucket

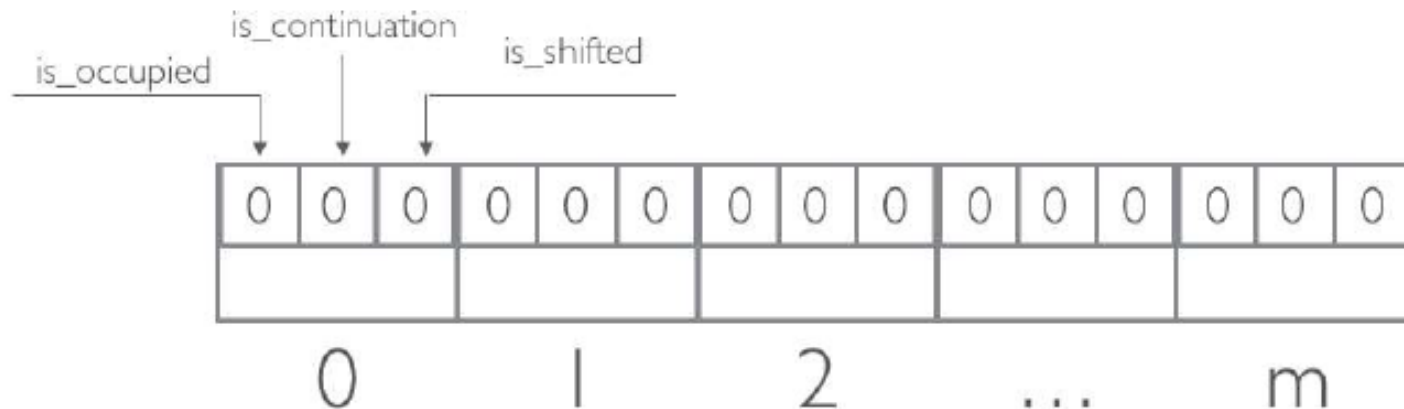
# Soft-collision handling

- Collisions do occur !!
- Different fingerprints have the same quotient :

$$f_q = f^*_q$$

- All remainders of fingerprints with the same quotient are stored contiguously in a run
- If necessary, a remainder is shifted forward from its original location
  - Stored in a subsequent bucket
  - Wrapping around at the end of the table

# 3 auxiliary bits per bucket



[Gakhov]

- Initially set to **zero**
- **is\_occupied** :  $f_q = j$  for some stored fingerprint
  - $j$  is the **canonical bucket**
- **is\_continuation** : occupied, but not by first remainder in a **run**
- **is\_shifted** : remainder in the bucket is not in its canonical bucket

# Membership testing

- Given the searched element
- Use hash function to compute its fingerprint
- Compute quotient  $f_q$  and remainder  $f_r$
- If bucket  $f_q$  is not occupied : item definitely not in the filter !!

# Membership testing

- If bucket  $f_q$  is occupied
  - Scan left to locate first bucket with  $\text{is\_shifted} = 0$
  - Scan right to identify the quotient's run
  - For each bucket in the run, compare the stored remainder with  $f_r$
  - If found, the searched element is (probably) in the filter
  - Else, it is definitely not in the filter

# Adding an element

- Given the searched element
- Use hash function to compute its **fingerprint**
- Compute quotient  $f_q$  and remainder  $f_r$
- Follow a path similar to the **testing** procedure, until certain that element **not in the filter**

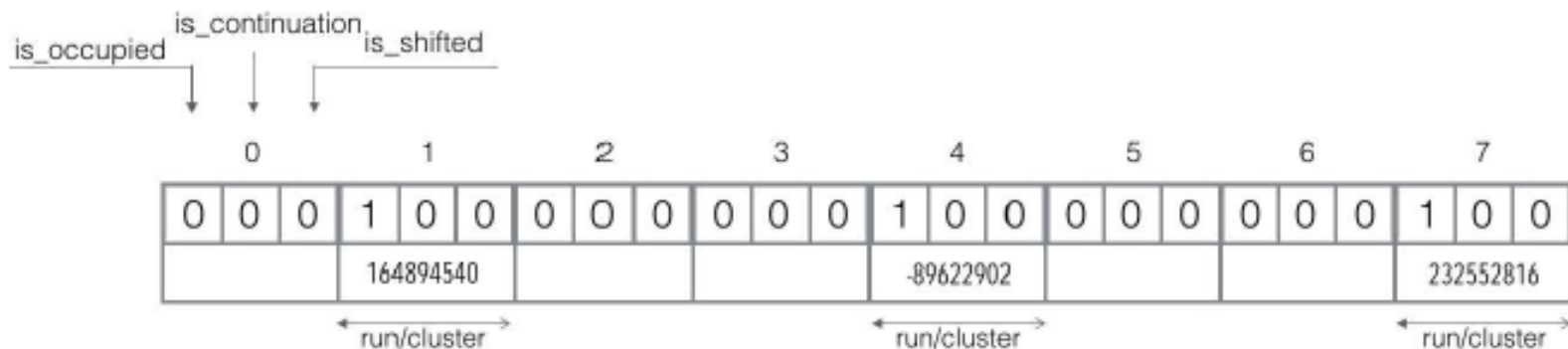


# Adding an element

- Choose bucket in the current run and insert the remainder  $f_r$ 
  - Keep the sorted order !!
- Shift forward all remainders at or after the chosen bucket
  - Update the buckets' bits

# Example – Adding elements

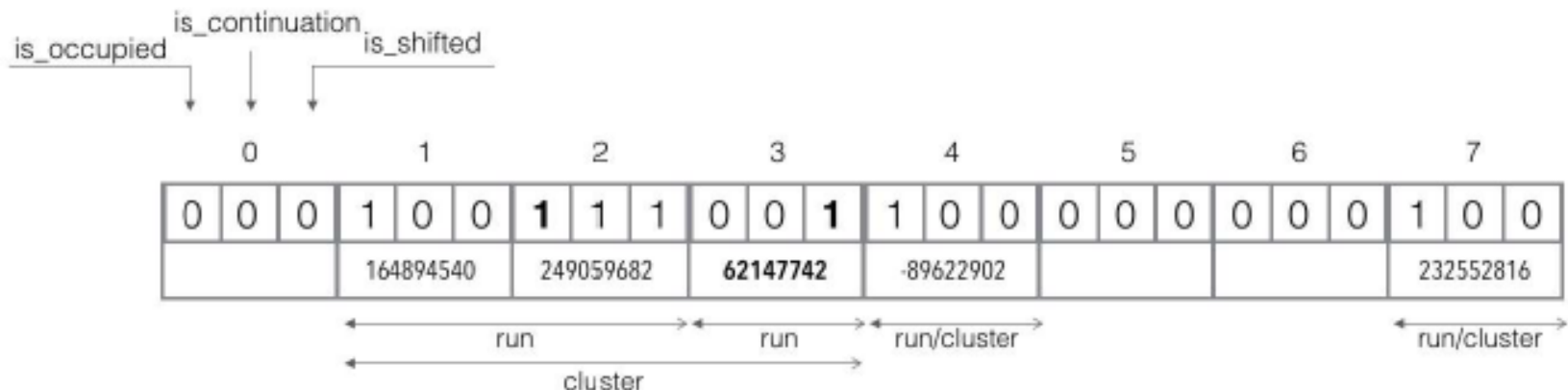
- Quotient size  **$q = 3$**
- 32-bit signed MurmurHash3
- Add
  - $f_q(\text{amsterdam}) = 1, f_r(\text{amsterdam}) = 164894540$
  - $f_q(\text{berlin}) = 4, f_r(\text{berlin}) = -89622902$
  - $f_q(\text{london}) = 7, f_r(\text{london}) = 232552816$



[Gakhov]

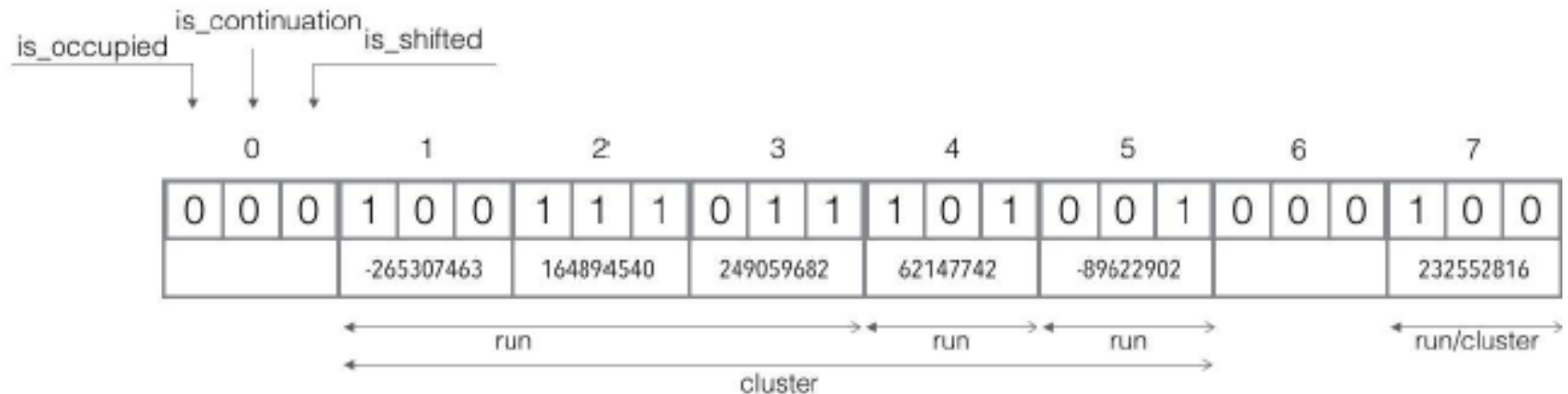
# Example – Adding elements

- Add  $f_q(\text{madrid}) = 1, f_r(\text{madrid}) = 249059682.$   
 $f_q(\text{ankara}) = 2, f_r(\text{ankara}) = 62147742.$



[Gakhov]

## Example – Testing membership



$$f_g(\text{ferret}) = 1, f_r(\text{ferret}) = 122150710.$$

$$f_g(\text{berlin}) = 4, f_r(\text{berlin}) = -89622902.$$

[Gakhov]

# Quotient Filter - Features

- **False positives** are possible, but with low probability

$$P(e \in S \mid e \notin S) \leq \frac{1}{2^r}$$

- False positive probability can be tuned
- **False negatives** are not possible

# Quotient Filter - Features

- Hash function should generate **uniformly distributed** fingerprints
- The length of most runs is  **$O(1)$**
- Probable that most runs have length  **$O(\log m)$**
- Efficient filter for large number of elements

# Quotient Filter vs Bloom Filter

- QFs are about **20% bigger**
- QFs **are faster** : evaluate single hash function
- Comparison results (M. Bender)
  - **inserts**. BF: 690 000 inserts per second, QF: 2 400 000 insert per second
  - **lookups**. BF: 1 900 000 lookups per second, QF: 2 000 000 lookups per second
- QFs support **deletion** !!

# MORE RECENT APPROACHES



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# 2014 – Cuckoo Filters

## Cuckoo Filter: Practically Better Than Bloom

Bin Fan, David G. Andersen, Michael Kaminsky<sup>†</sup>, Michael D. Mitzenmacher<sup>‡</sup>  
Carnegie Mellon University, <sup>†</sup>Intel Labs, <sup>‡</sup>Harvard University

### ABSTRACT

In many networking systems, Bloom filters are used for high-speed set membership tests. They permit a small fraction of false positive answers with very good space efficiency. However, they do not permit deletion of items from the set, and previous attempts to extend “standard” Bloom filters to support deletion all degrade either space or performance.

We propose a new data structure called the *cuckoo filter* that can replace Bloom filters for approximate set membership tests. Cuckoo filters support adding and removing items dynamically while achieving even higher performance than Bloom filters. For applications that store many items and

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# 2017 – Counting Quotient Filters

## A General-Purpose Counting Filter: Making Every Bit Count

Prashant Pandey, Michael A. Bender, Rob Johnson, and Rob Patro  
Stony Brook University

### ABSTRACT

Approximate Membership Query (AMQ) data structures, such as the Bloom filter, quotient filter, and cuckoo filter, have found numerous applications in databases, storage systems, networks, computational biology, and other domains. However, many applications must work around limitations in the capabilities or performance of current AMQs, making these applications more complex and less performant. For example, many current AMQs cannot delete or count the number of occurrences of each input item, take up large amounts of space, are slow, cannot be resized or merged, or have poor locality of reference and hence perform poorly when stored on SSD or disk.

This paper proposes a new general-purpose AMQ, the counting quotient filter (CQF). The CQF supports approximate membership testing and counting the occurrences of items in a data set. This

# 2018 – Morton Filters

## Morton Filters: Faster, Space-Efficient Cuckoo Filters via Biasing, Compression, and Decoupled Logical Sparsity

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### ABSTRACT

Approximate set membership data structures (ASMDs) are ubiquitous in computing. They trade a tunable, often small, error rate ( $\epsilon$ ) for large space savings. The canonical ASMD is the Bloom filter, which supports lookups and insertions but not deletions in its simplest form. Cuckoo filters (CFs), a recently proposed class of ASMDs, add deletion support and often use fewer bits per item for equal  $\epsilon$ .

This work introduces the Morton filter (MF), a novel ASMD that introduces several key improvements to CFs. Like CFs, MFs support lookups, insertions, and deletions, but improve their respective throughputs by  $1.3\times$  to  $2.5\times$ ,  $0.9\times$  to  $15.5\times$ , and  $1.3\times$  to  $1.6\times$ . MFs achieve these improve-

# 2020 – Xor Filters

ACM Journal of Experimental Algorithmics, Vol. 25, No. 1, Article 1.5. Publication date: March 2020.

## Xor Filters: Faster and Smaller Than Bloom and Cuckoo Filters

THOMAS MUELLER GRAF and DANIEL LEMIRE, University of Quebec (TELUQ), Canada

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The Bloom filter provides fast approximate set membership while using little memory. Engineers often use these filters to avoid slow operations such as disk or network accesses. As an alternative, a cuckoo filter may need less space than a Bloom filter and it is faster. Chazelle et al. proposed a generalization of the Bloom filter called the Bloomier filter. Dietzfelbinger and Pagh described a variation on the Bloomier filter that can answer approximate membership queries over immutable sets. It has never been tested empirically, to our knowledge. We review an efficient implementation of their approach, which we call the xor filter. We find that xor filters can be faster than Bloom and cuckoo filters while using less memory. We further show that a more compact version of xor filters (xor+) can use even less space than highly compact alternatives (e.g., Golomb-compressed sequences) while providing speeds competitive with Bloom filters.

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# 2022 – Binary Fuse Filters

ACM Journal of Experimental Algorithmics, Vol. 27, No. 1, Article 1.5. Publication date: February 2022.

## Binary Fuse Filters: Fast and Smaller Than Xor Filters

THOMAS MUELLER GRAF and DANIEL LEMIRE, University of Quebec (TELUQ)

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Bloom and cuckoo filters provide fast approximate set membership while using little memory. Engineers use them to avoid expensive disk and network accesses. The recently introduced xor filters can be faster and smaller than Bloom and cuckoo filters. The xor filters are within 23% of the theoretical lower bound in storage as opposed to 44% for Bloom filters. Inspired by Dietzfelbinger and Walzer, we build probabilistic filters—called *binary fuse filters*—that are within 13% of the storage lower bound—without sacrificing query speed. As an additional benefit, the construction of the new binary fuse filters can be more than twice as fast as the construction of xor filters. By slightly sacrificing query speed, we further reduce storage to within 8% of the lower bound. We compare the performance against a wide range of competitive alternatives such as Bloom filters, blocked Bloom filters, vector quotient filters, cuckoo filters, and the recent ribbon filters. Our experiments suggest that binary fuse filters are superior to xor filters.

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