Prediction Assignment Writeup

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Executive Summary

In this study, we conducted a machine learning(Random Forest) by using data from accelerometers on the belt, forearm, arm, and dumbell of 6 participants. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways.

We predict the manner in which they did the exercise. This is the "classe" variable in the training set.

Load Library

```
library(ggplot2)
library(dplyr)
library(caret)
library(randomForest)
```

Load Training / Test data and Data manipulation

```
temp <- tempfile()</pre>
download.file("https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv",temp)
train <- read.csv(temp, header=T, stringsAsFactors = FALSE, na.strings=(c("NA", "")))
train <- tbl df(train)</pre>
unlink(temp)
temp <- tempfile()</pre>
download.file("https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv",temp)
test <- read.csv(temp, header=T, stringsAsFactors = FALSE, na.strings=(c("NA", "")))
test <- tbl_df(test)
unlink(temp)
## Combine training & test data
full <- bind_rows(train, test) # bind training & test data
## Checking data size
dim(full)
## [1] 19642
               161
## Checking NA data
na_count_full <- sapply(full, function(y) sum(is.na(y)))</pre>
head(na_count_full[na_count_full>0],15)
##
     kurtosis_roll_belt kurtosis_picth_belt
                                                  kurtosis_yaw_belt
##
                  19236
                                                              19236
##
     skewness_roll_belt skewness_roll_belt.1
                                                  skewness_yaw_belt
##
                  19236
                                        19236
                                                              19236
##
                               max_picth_belt
          max_roll_belt
                                                       max_yaw_belt
```

```
##
                   19236
                                         19236
                                                                19236
##
          min_roll_belt
                                min_pitch_belt
                                                        min_yaw_belt
##
                   19236
                                         19236
                                                                19236
##
    amplitude_roll_belt amplitude_pitch_belt
                                                  amplitude_yaw_belt
                                                                19236
```

There are many variables containing too many NA data.

Since it is hard to impute those NA data, We decide to eliminate the variables.

(Also, eliminate "X"(it's just a serial number) and "cvtd_timestamp"(dupulicates with "raw_stamp"") for machine learning.)

```
##
               user_name raw_timestamp_part_1 raw_timestamp_part_2
##
                        0
                                               0
                                                                     0
##
              new_window
                                    num_window
                                                            roll_belt
##
                                       yaw_belt
##
              pitch_belt
                                                     total_accel_belt
##
##
            gyros_belt_x
                                   gyros_belt_y
                                                         gyros_belt_z
##
##
                                                         accel_belt_z
           accel_belt_x
                                  accel_belt_y
##
                        0
                                              0
##
          magnet_belt_x
                                 magnet_belt_y
                                                        magnet_belt_z
##
##
                roll_arm
                                                               yaw_arm
                                      pitch_arm
##
##
        total accel arm
                                    gyros_arm_x
                                                          gyros_arm_y
##
##
             gyros_arm_z
                                    accel_arm_x
                                                          accel_arm_y
                        0
##
##
             accel_arm_z
                                  magnet_arm_x
                                                         magnet_arm_y
##
##
                                 roll_dumbbell
                                                       pitch_dumbbell
           magnet_arm_z
##
                        0
                                                                     0
##
           yaw_dumbbell total_accel_dumbbell
                                                     gyros_dumbbell_x
##
                                              0
                              gyros_dumbbell_z
##
                                                     accel_dumbbell_x
       gyros_dumbbell_y
##
                                              0
##
       accel dumbbell y
                              accel dumbbell z
                                                    magnet dumbbell x
##
                                                                     0
##
      magnet_dumbbell_y
                             magnet dumbbell z
                                                         roll forearm
##
                       0
                                              0
                                                                     0
##
                                                  total_accel_forearm
          pitch_forearm
                                   yaw_forearm
##
                       0
                                              0
##
        gyros forearm x
                               gyros_forearm_y
                                                      gyros forearm z
##
                                                                     0
##
        accel_forearm_x
                               accel_forearm_y
                                                      accel_forearm_z
##
                        0
```

```
## magnet_forearm_x magnet_forearm_y magnet_forearm_z
## 0 0 0
## classe problem_id
## 20 19622
```

It seems much better.

We conducted Some data manipulations for Machine Learning.

```
## Factorize some variables
full$classe <- factor(full$classe)
full$user_name <- factor(full$user_name)
full$new_window <- factor(full$new_window)
full$user_name <- factor(full$user_name)

## Split the data back into a train set and a test set
train3 <- full[1:19622,]
test3 <- full[19623:19642,]
train3 <- train3 %>% select(-problem_id)
test3 <- test3 %>% select(-classe, -problem_id)
```

Machine Learning (Random Forest)

At first, we split training data into training_train/training_test for CV.

```
## Spllit training data
set.seed(62433)
inTrain <- createDataPartition(train3$classe, p=0.7, list=FALSE)
training_train <- train3[inTrain,]
training_test <- train3[-inTrain,]</pre>
```

We built Rondom Forest model by using training data set. Also, applied the model to training_test data set.

```
set.seed(62433)
mod_rf <- randomForest(classe ~., data=training_train, n.tree = 1000)
prediction_rf <- predict(mod_rf, training_test)
table(training_test$classe, prediction_rf)</pre>
```

```
##
      prediction_rf
##
                В
                      C
                                 Ε
          Α
                           D
##
     A 1674
                0
                      0
                           0
          1 1138
                      0
                           0
                                 0
##
     В
                2 1024
                           0
##
     C
##
     D
           0
                0
                      1
                        963
                      0
                           0 1082
```

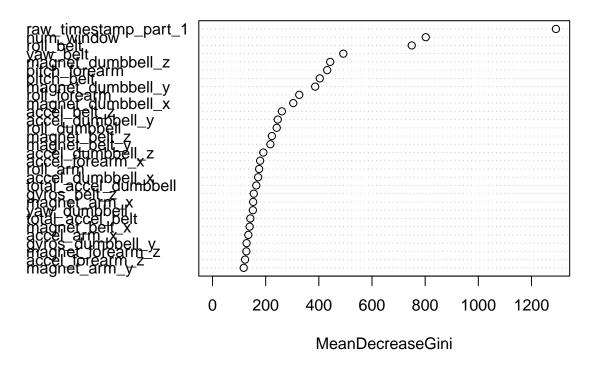
```
sum(diag(table(training_test$classe, prediction_rf)))/nrow(training_test)
```

```
## [1] 0.9993203
```

The accuracy is over 99%.

```
varImpPlot(mod_rf)
```

mod_rf



 $Looking \ the \ relative \ importance \ of \ variables, \ "raw_timestamp_part1", \ "num_window" \ and \ "roll_belt" \ are so \ high \ scores.$

Predict by using test data.

We finally predict 20 different test cases by using the Random Forest model.

```
prediction_rft <- predict(mod_rf, test3)
solution <- data.frame(Problem_ID = 1:20, classe = prediction_rft)
solution</pre>
```

```
##
      Problem_ID classe
## 1
                1
## 2
                2
                        Α
                3
## 3
                        В
## 4
                4
                        Α
                5
## 5
                        Α
                6
                        Ε
## 6
## 7
                7
                        D
## 8
                8
                        В
## 9
                9
                        Α
## 10
               10
                        Α
## 11
               11
                        В
                        С
               12
## 12
## 13
               13
                        В
## 14
               14
                        Α
```

##	15	15	Ε
##	16	16	Ε
##	17	17	Α
##	18	18	В
##	19	19	В
##	20	20	R