

COMP7065 Innovative Laboratory

Spatial Control with ControlNet

After completion of this lab, students will be able to

1. Construct workflows with ControlNet nodes;
2. Apply various spatial control to output image by ControlNet, including:
 - a) Human Pose,
 - b) CannyEdge Maps,
 - c) M-LSD Line Maps,
 - d) HED Boundary Maps,
 - e) Scribbles;
3. Integrate spatial control to their AI artworks;

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1. Pose control with ControlNet

Preparations: In this part, you will learn how to build a basic workflow that applies human pose control through **ControlNet** and **OpenPose**. Before we build up the workflow, you should download the model weights of ControlNet first. It is recommended to download the **pruned** versions on HuggingFace through the following link:

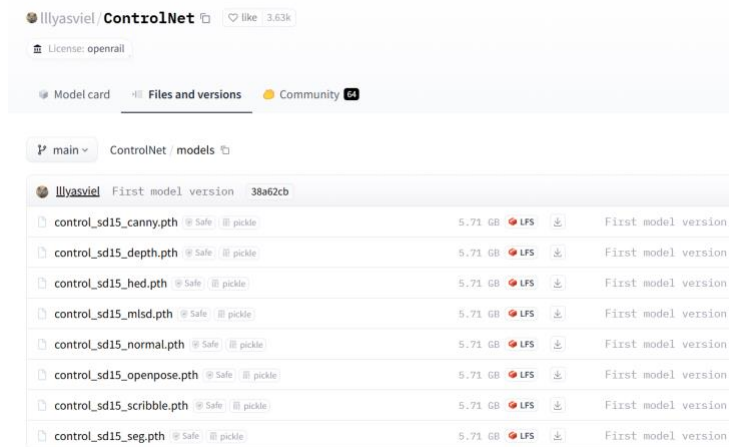
<https://huggingface.co/webui/ControlNet-modules-safetensors/tree/main>

File Name	Size	Upload Action	Commit Message	Time
ClashSAN	Upload 2 files	8148814		almost 2 years ago
.gitattributes	1.48 kB	initial commit		almost 2 years ago
README.md	582 Bytes	Create README.md		almost 2 years ago
cldm_v15.yaml	1.95 kB	Upload 9 files		almost 2 years ago
cldm_v21.yaml	2.22 kB	Create cldm_v21.yaml (#3)		almost 2 years ago
control_canny-fp16.safetensors	723 MB	Upload 9 files		almost 2 years ago
control_depth-fp16.safetensors	723 MB	Upload 9 files		almost 2 years ago
control_hed-fp16.safetensors	723 MB	Upload 9 files		almost 2 years ago
control_mlsd-fp16.safetensors	723 MB	Upload 9 files		almost 2 years ago
control_normal-fp16.safetensors	723 MB	Upload 9 files		almost 2 years ago
control_openpose-fp16.safetensors	723 MB	Upload 9 files		almost 2 years ago
control_scribble-fp16.safetensors	723 MB	Upload 9 files		almost 2 years ago
control_seg-fp16.safetensors	723 MB	Upload 9 files		almost 2 years ago
t2iadapter_canny-fp16.safetensors	154 MB	Upload 2 files		almost 2 years ago
t2iadapter_color-fp16.safetensors	37.4 MB	Upload 2 files		almost 2 years ago
t2iadapter_depth-fp16.safetensors	155 MB	Upload t2iadapter_depth-fp16.safetensors		almost 2 years ago
t2iadapter_keypose-fp16.safetensors	155 MB	Upload 3 files		almost 2 years ago
t2iadapter_openpose-fp16.safetensors	155 MB	Upload 2 files		almost 2 years ago
t2iadapter_seg-fp16.safetensors	155 MB	Upload 3 files		almost 2 years ago
t2iadapter_sketch-fp16.safetensors	154 MB	Upload 3 files		almost 2 years ago
t2iadapter_style-fp16.safetensors	77.2 MB	Upload 2 files		almost 2 years ago

Please download the weights named **'control_canny-fp16.safetensors'**, **'control_hed-fp16.safetensors'**, **'control_mlsd-fp16.safetensors'**, **'control_openpose-fp16.safetensors'** and **'control_scribble-fp16.safetensors'**, and place all of them into this folder: **'ComfyUI\models\controlnet'**. Note that the postfix of the filename specifies the usage of the weights. For example, **'_scribbles'** means that the ControlNet is trained to recognize spatial control from a scribble.

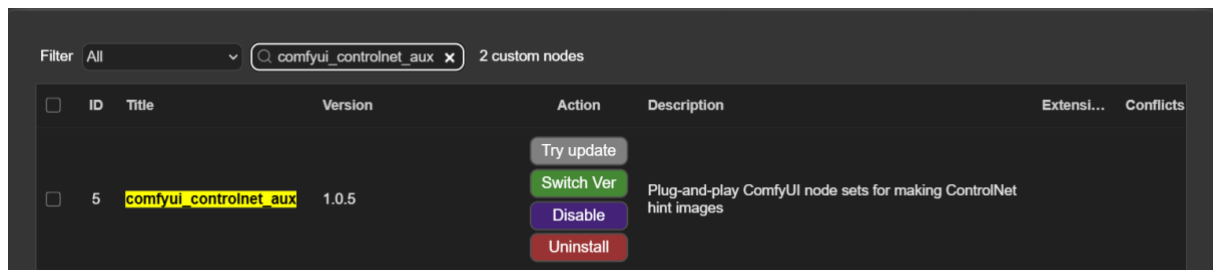
Alternatively, you can download the **full** model weights of ControlNet from its developer's model repository on HuggingFace:

<https://huggingface.co/lllyasviel/ControlNet/tree/main/models>



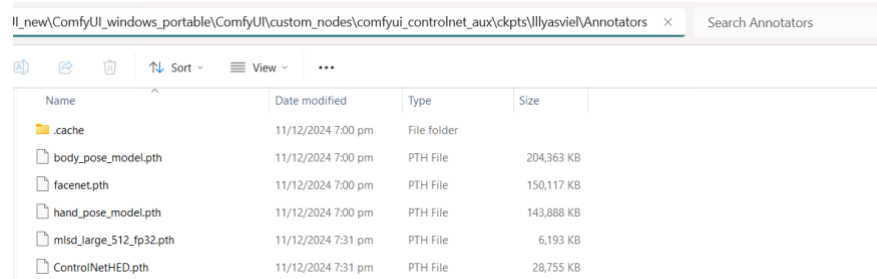
However, the full model weights occupy a considerable amount of disk storage (5.71GB for each type), and may potentially cause 'Cuda: out of memory' error during generation process. Meanwhile based on my own experience, the output quality doesn't have a significant improvement when replacing the pruned ControlNet with the full weights one. So it is more recommended that you directly use the pruned version of ControlNet.

Secondly, please install the custom node '**comfyUI controlnet aux**' by using **ComfyUI node manager**. This custom node provides you with a convenient method to apply image preprocessing, such as pose estimation and straight line detection, so as to cooperate with ControlNet spatial control.



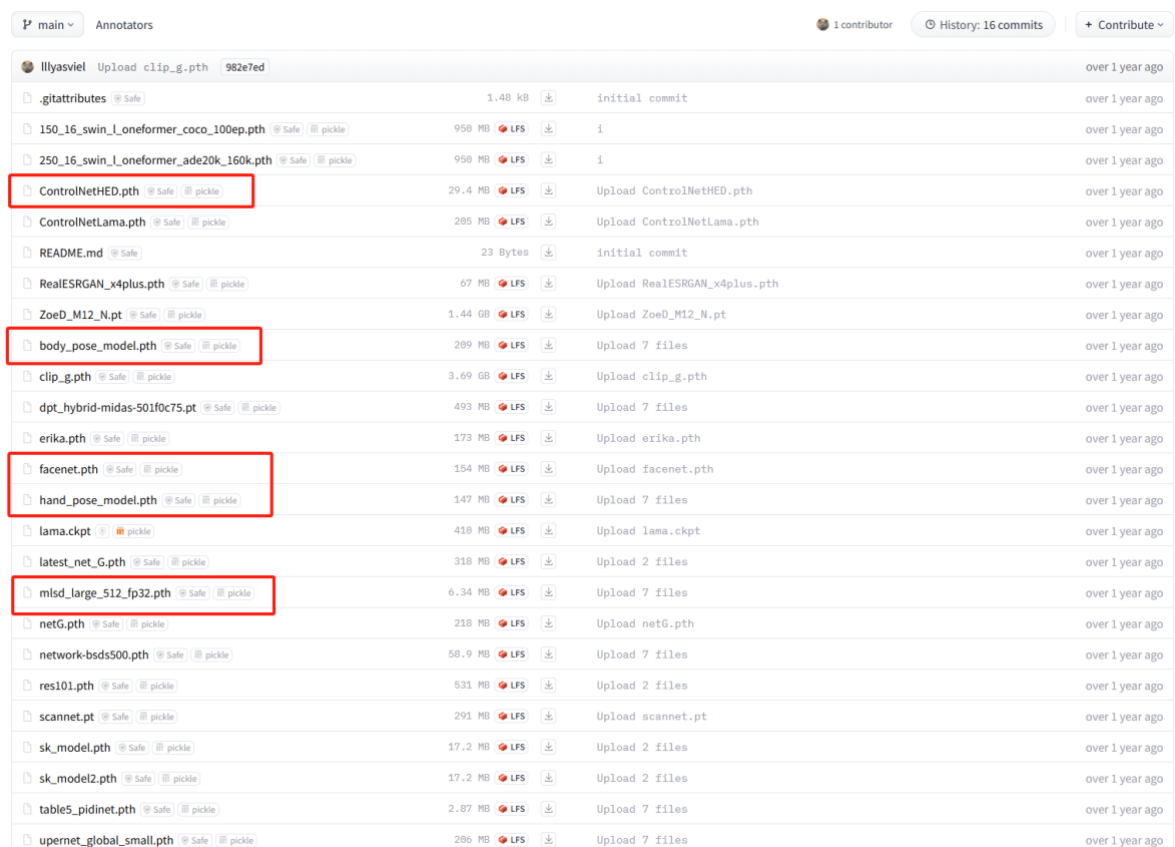
[Optional] During testing the showcases on our Lab's computer, I found that this custom node may not work smoothly in the latest ComfyUI. It sometimes may fail to automatically download the required model weights of the preprocessing network. To avoid this issue, you may need to manually download these weights from their [official HuggingFace website](https://huggingface.co/lllyasviel/annotators) by yourself, and place them into the folder:

'ComfyUI\custom_nodes\comfyui_controlnet_aux\ckpt\lllyasviel\Annotators'.



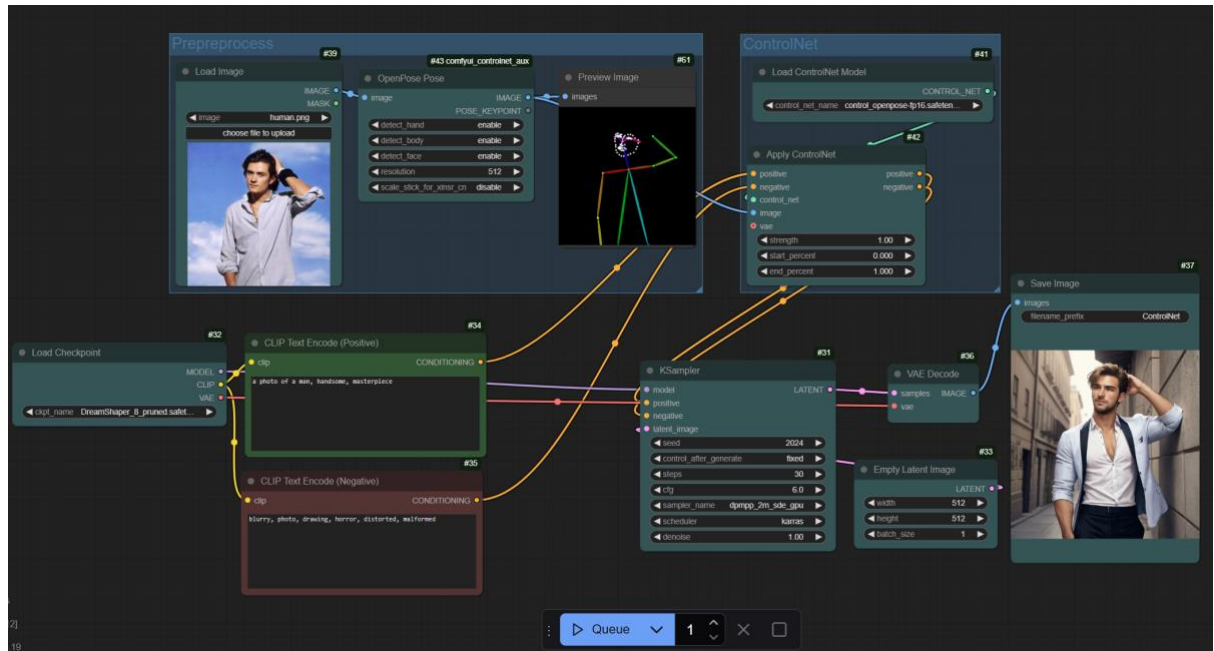
Name	Date modified	Type	Size
.cache	11/12/2024 7:00 pm	File folder	
body_pose_model.pth	11/12/2024 7:00 pm	PTH File	204,363 KB
facenet.pth	11/12/2024 7:00 pm	PTH File	150,117 KB
hand_pose_model.pth	11/12/2024 7:00 pm	PTH File	143,888 KB
mlsd_large_512_fp32.pth	11/12/2024 7:31 pm	PTH File	6,193 KB
ControlNetHED.pth	11/12/2024 7:31 pm	PTH File	28,755 KB

The required model weights for this lecture's showcases are marked in the figure below.



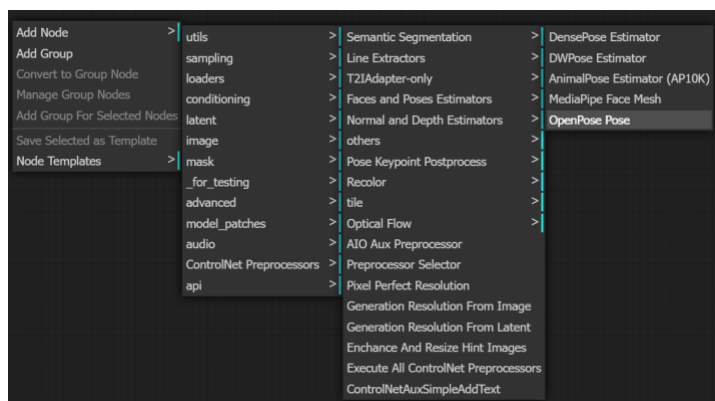
File Name	Size	Commit Info
Upload clip_g.pth	982e7ed	over 1 year ago
.gitattributes	1.48 kB	initial commit
150_16_swin_l_oneformer_coco_100ep.pth	958 MB	i
250_16_swin_l_oneformer_ade20k_160k.pth	958 MB	i
ControlNetHED.pth	29.4 MB	Upload ControlNetHED.pth
ControlNetLama.pth	285 MB	Upload ControlNetLama.pth
README.md	23 Bytes	initial commit
RealESRGAN_x4plus.pth	67 MB	Upload RealESRGAN_x4plus.pth
ZoeD_M12_N.pt	1.44 GB	Upload ZoeD_M12_N.pt
body_pose_model.pth	209 MB	Upload 7 files
clip_g.pth	3.69 GB	Upload clip_g.pth
dpt_hybrid-midas-501f0c75.pt	493 MB	Upload 7 files
erika.pth	173 MB	Upload erika.pth
facenet.pth	154 MB	Upload facenet.pth
hand_pose_model.pth	147 MB	Upload 7 files
lama.ckpt	418 MB	Upload lama.ckpt
latest_net_G.pth	318 MB	Upload 2 files
mlsd_large_512_fp32.pth	6.34 MB	Upload 7 files
netG.pth	218 MB	Upload netG.pth
network-bsd500.pth	58.9 MB	Upload 7 files
res101.pth	531 MB	Upload 2 files
scannet.pt	291 MB	Upload scannet.pt
sk_model.pth	17.2 MB	Upload 2 files
sk_model2.pth	17.2 MB	Upload 2 files
table5_pidinet.pth	2.87 MB	Upload 7 files
upernet_global_small.pth	286 MB	Upload 7 files

Showcase: Human pose control is a basic function of ControlNet. Below is a showcase workflow adapted from an [official example](#) provided by RunComfy. You can download the source image (human.png) from [this link](#).



Basically, this workflow in the showcase is equivalent to **adding two additional groups of nodes to the default image-to-text workflow**. The first group of nodes is responsible for **image preprocessing**, while the other group **configures the ControlNet**.

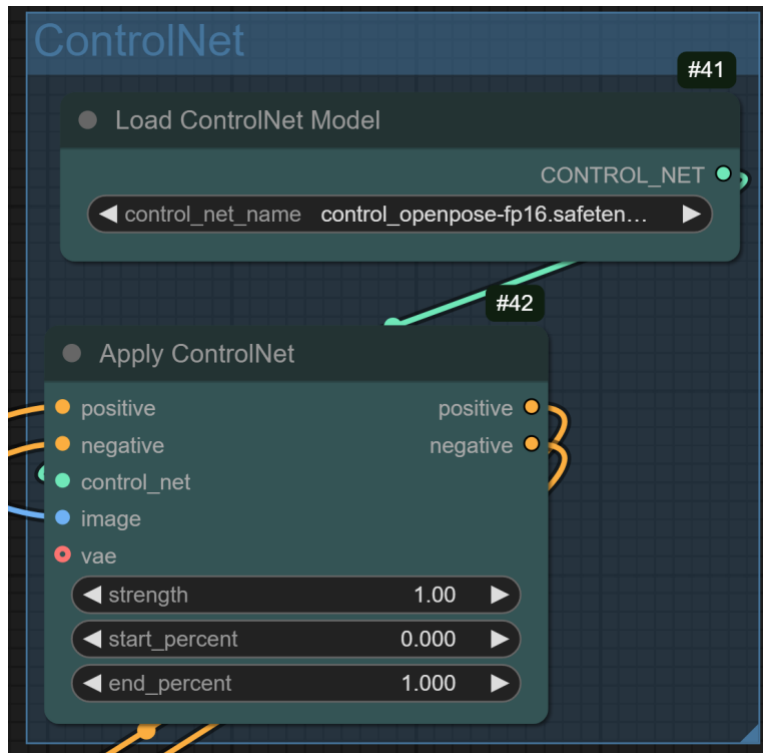
Image Preprocessing: In this showcase, the image preprocessing is to detect the keypoints of the human body such as face and joints using the OpenPose network. You should pay attention to the **‘OpenPose Pose’** node, which is the core during image preprocessing. You can add it into your workflow by left clicking your mouse first and sequentially select **‘Add Node -> ControlNet Preprocessors -> Faces and Poses Estimators -> OpenPose Pose’**.



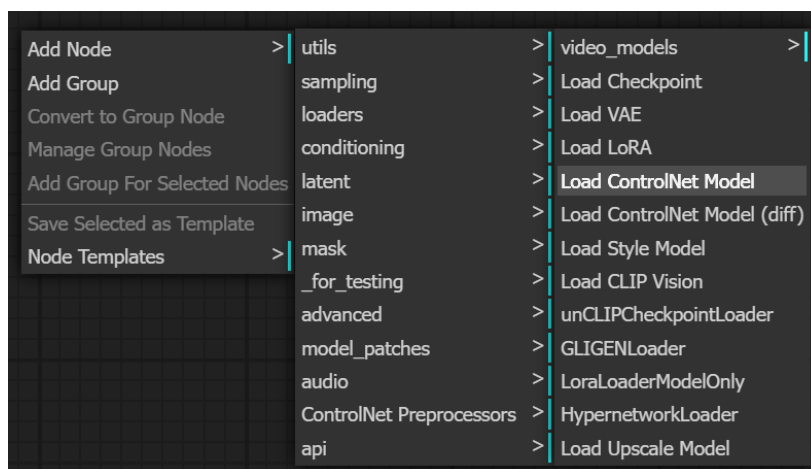
The functionality of this node is to apply pose estimation of a given figure photo or drawing. As illustrated by the Preview Image node, the output image consists of keypoints of the figure, and the keypoint image is then fed to ControlNet to apply spatial control to stable diffusion models. Description of each setting of the 'OpenPose Pose' node are presented in the table below. You may also refer to [this link](https://github.com/Fannovel16/comfyui_controlnet_aux/issues/447) for more detailed explanations.

Setting	Description
detect_hand	When enabled, the OpenPose Pose node will detect keypoints of hands.
detect_body	When enabled, the OpenPose Pose node will detect keypoints of body parts.
detect_face	When enabled, the OpenPose Pose node will detect keypoints on the faces.
resolution	This parameter determines the size of keypoint image, which will always be in a square shape. It doesn't affect the resolution of the final output.
scale_stick_for_xinsr_cn	When enabled, the body lines will be plotted thicker and the result becomes more stable. See this post for more details: https://github.com/Fannovel16/comfyui_controlnet_aux/issues/447





Configuring the ControlNet: The other group of nodes, including **'Load ControlNet Model'** and **'Apply ControlNet'**, are responsible for configuring the ControlNet model. The functionality of **'Load ControlNet Model'** is easy to understand. It just loads the weights of a ControlNet model that you've downloaded during the preparation stage. Note that you should match the model weights with the type of spatial prompts. For example, in this showcase we utilize the keypoint image estimated by **OpenPose** as the prompt image for ControlNet, so the corresponding weights should be **'control openpose-fp16.safetensors'**. One may not set the weights other than that, such as **'control scribble fp16.safetensors'**, which is intended for applying spatial prompts by scribbles. You may add the **'Load ControlNet Model'** node by sequentially selecting **'Add Node -> loaders -> Load ControlNet Model'**, or just type its name in the search bar popped after double clicking on the workspace.



The **'Apply ControlNet'** node configures the ControlNet previously loaded by **'Load ControlNet Model'** node. The description of each setting is presented in the table below. You can refer to [this link](#) for a detailed description on ComfyUI wiki.

Setting	Description
postive	Positive conditioning features, such as the output of a positive CLIP text encoder.
negative	Negative conditioning features, such as the output of a negative CLIP text encoder.
contrl_net	The ControlNet model weights previously loaded
image	The preprocessed image for spatial constraint.
vae	Optional, determines whether ControlNet should affect the VAE models.
strength	A scalar that determines the strength of ControlNet's effect on conditioning features.
start_percent	A float number between 0 and 1 that controls the start point of ControlNet's effect during denoising steps.
end_percent	A float number between 0 and 1 that controls the end point of ControlNet's effect during denoising steps.

It could be observed from the output image that the ControlNet is very effective. We didn't describe anything about pose in our text prompt. But in the result, the man actually shares a very similar posture as the one in input.

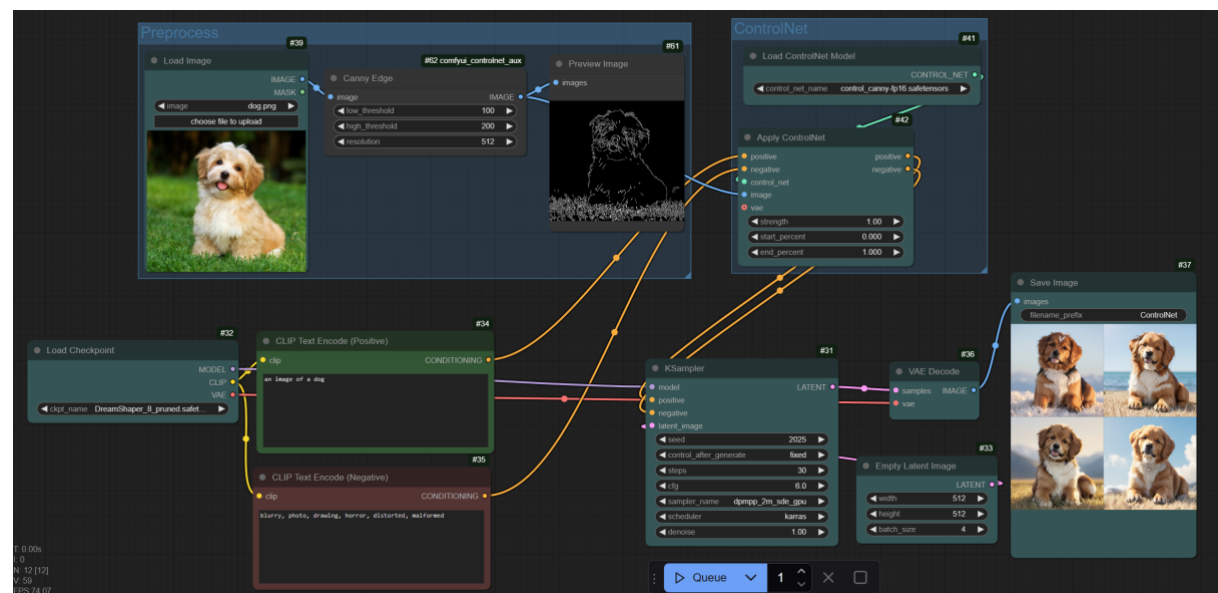
You are strongly encouraged to rebuild this showcase workflow on your own as an exercise. Also try to adjust different settings and observe the impact on output images. This helps you to strengthen the understanding of the functionalities ControlNet model in an intuitive manner.

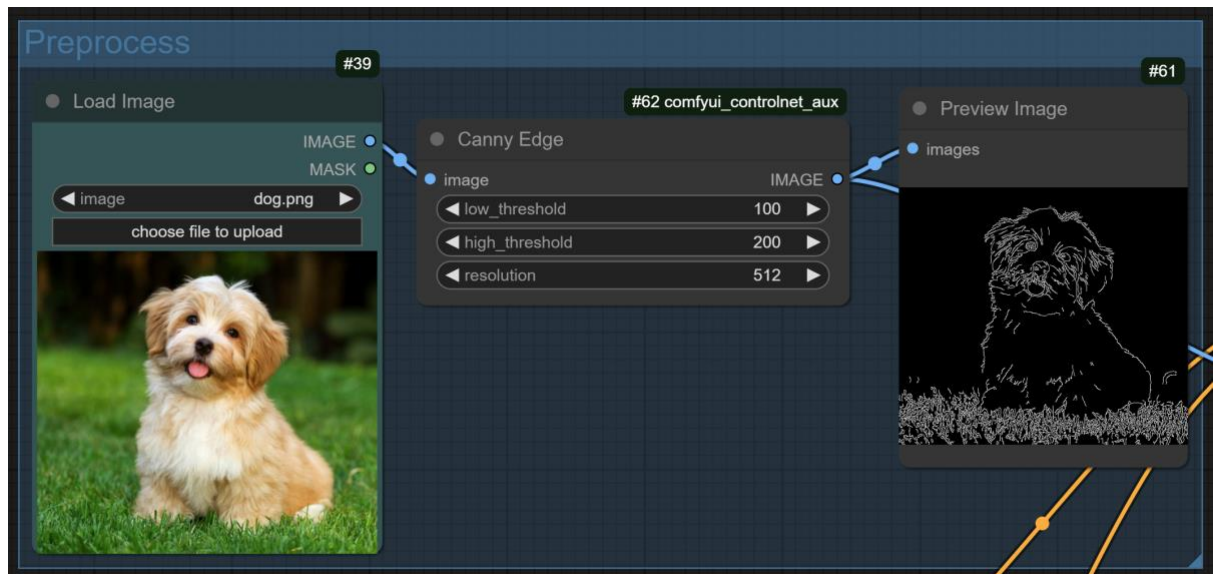
2. Explore different types of spatial control

Part 2 is just a simple showcase of how to apply spatial control of human pose through ControlNet. In Part 3, we will explore more types of spatial control by providing the ControlNet with different kinds of spatial prompts. Showcases in part 3 cover spatial prompts of Canny edge maps, Hough line maps, HED boundary maps and scibbles. It's also noteworthy that workflows in Part 3 are highly similar to the one in Part 2. The key differences lie in the **preprocessing node** and the corresponding **model weights** of ControlNet. They are adjusted according to the type of spatial prompts. Source images used in these showcases can be accessed through [this link](#) on Github.

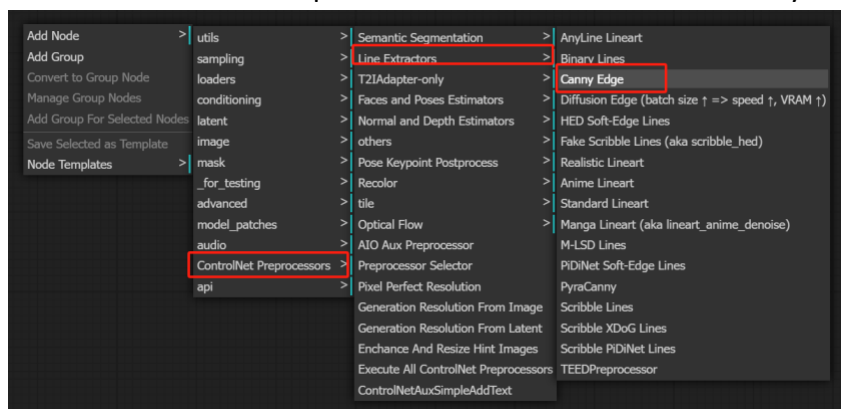
Canny edge maps

Below is a showcase workflow that uses a Canny edge map as spatial prompt for ControlNet. The Canny edge detection method is a classical approach in image processing. It detects the edges of a given image using convolutional operations with Canny operator. The Canny operator assigns each pixel with its gradient, and the absolute value of it is used to judge whether the pixel is an edge. The final output of Canny edge map is a binary image where the edges are highlighted, as shown in the figures below.





To apply Canny edge detection, you should modify the preprocess step by replacing 'OpenPose Pose' node with the 'Canny Edge' node, and set the model weights of ControlNet to 'control_canny-fp16.safetensors'. You can find the node by clicking 'Add Node -> ControlNet Preprocessors -> Line Extractors -> Canny Edge'.

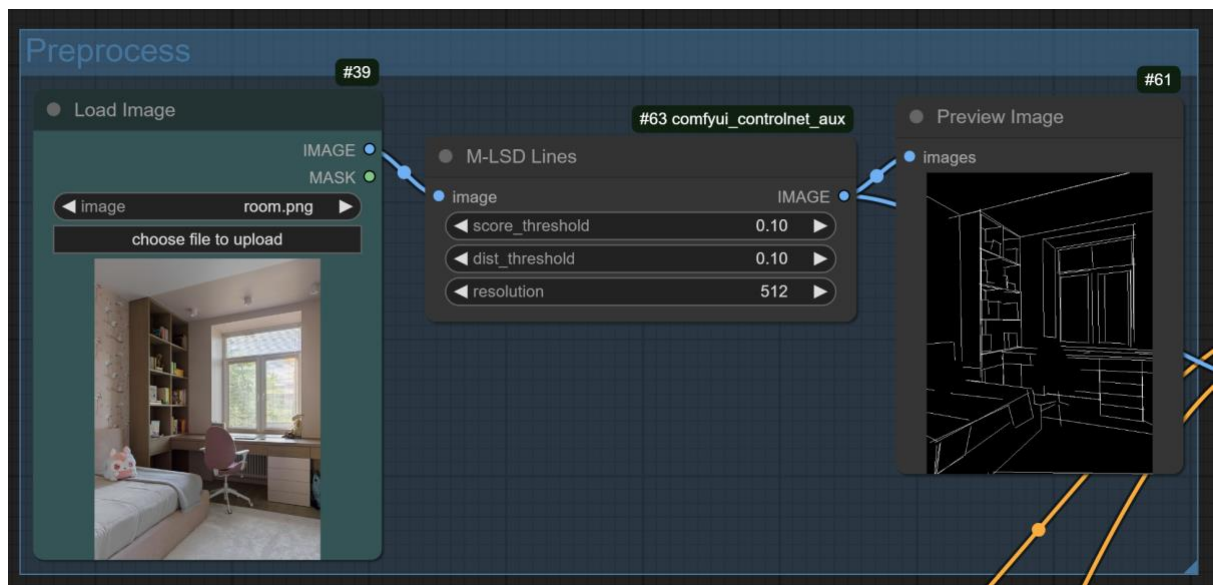
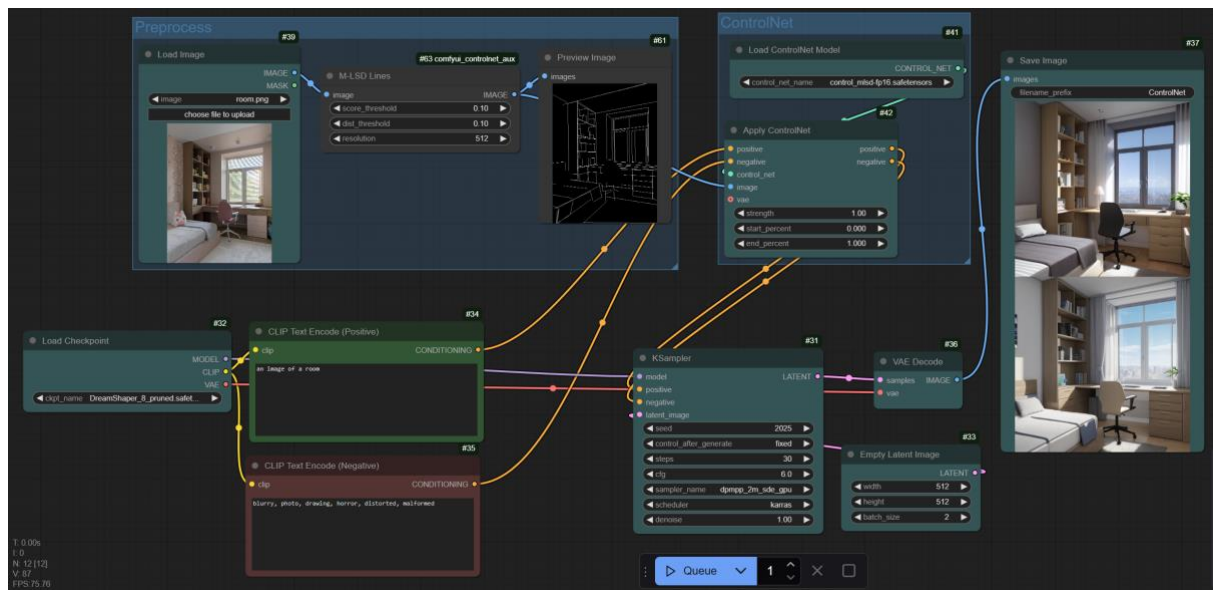


The settings of 'Canny Edge' node adjust the hyperparameter of the Canny edge detection algorithm. The description of each settings is presented in the table below. You can refer to [this link](#) for a more detailed explanation.

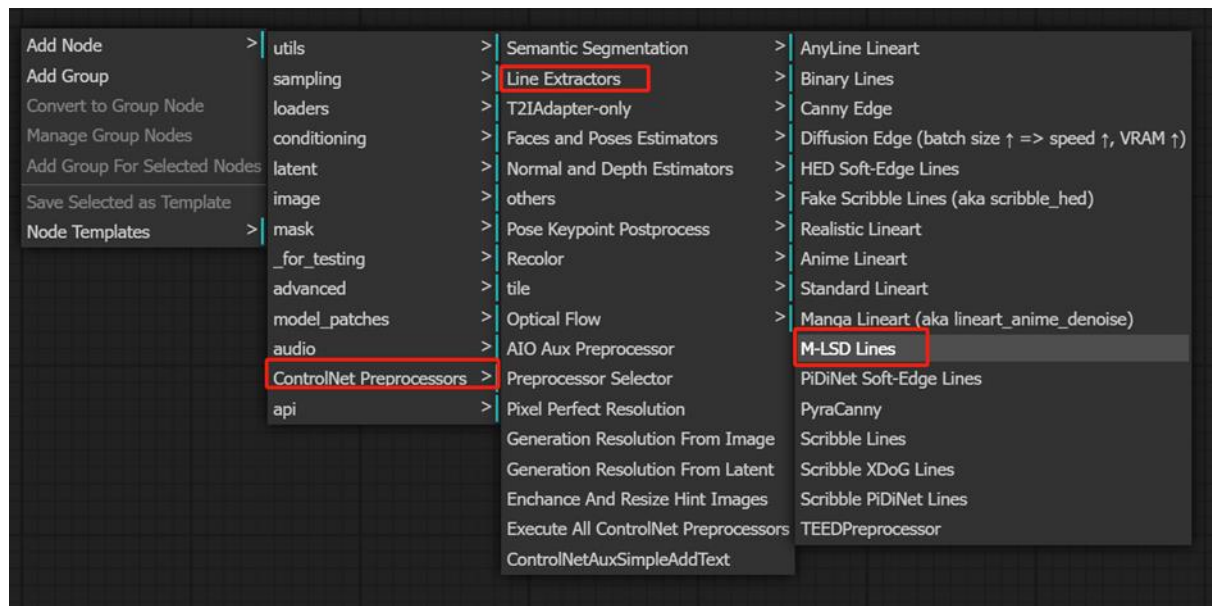
Setting	Description
low_threshold	An integer ranges from 0 to 255. Edge pixels whose gradient value is lower than this bound will be discarded. Decreasing this value result in more edge pixels.
high_threshold	An integer ranges from 0 to 255. Edge pixels whose gradient value is higher than this bound will be definitely preserved. Increasing this value result in less edge pixels.
resolution	This parameter determines the size of edge map, which will always be in a squared shape. It doesn't affect the resolution of the final output.

M-LSD line maps

M-LSD stands for mobile line segment detection. It is a deep learning-based, end-to-end line detection approach. In M-LSD, a light-weighted neural network model detects the straight line segments inside an image, and returns a binary image in which the estimated line segments are highlighted, as shown in the figures below. It's notable that M-LSD line maps are very powerful for scene designs because the output image maintains almost the same structures as the spatial prompt image. You can refer to the [original paper](#) for more details about M-LSD method.



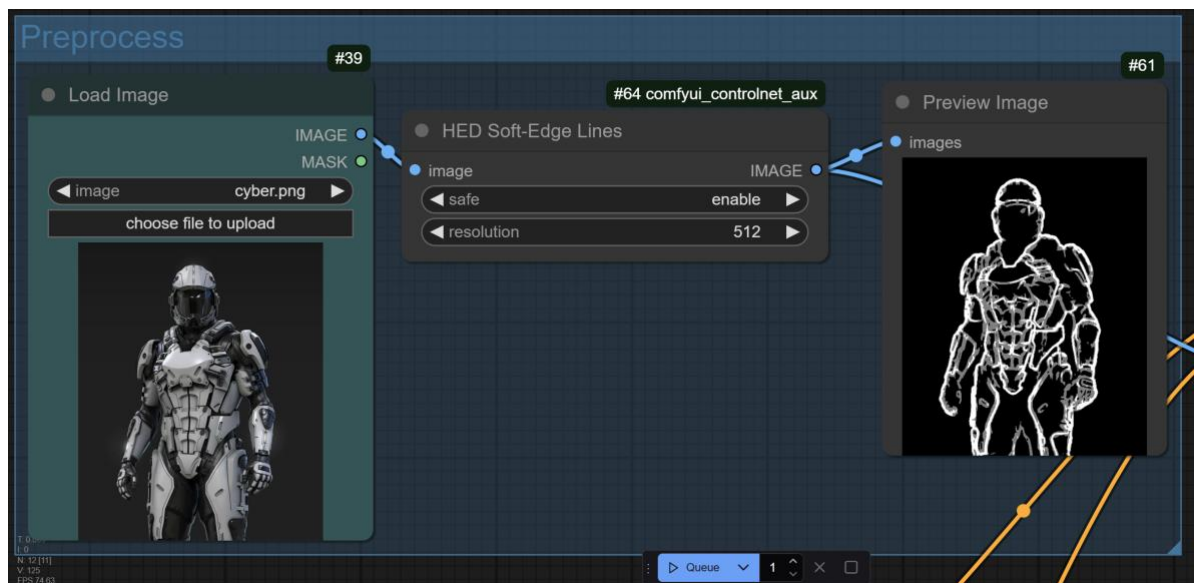
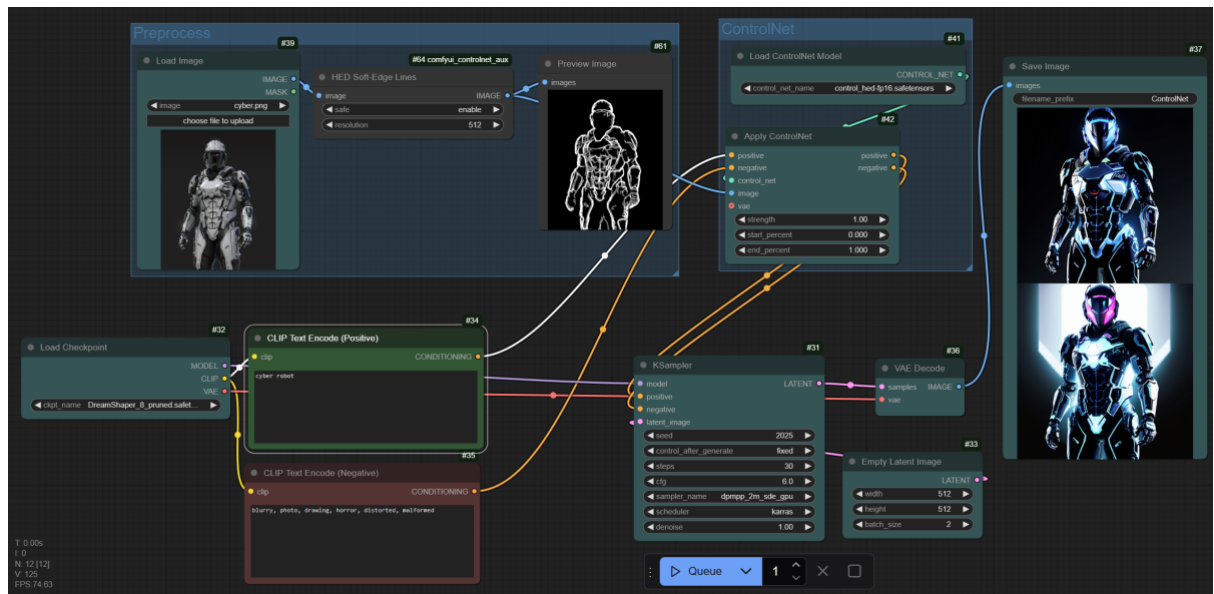
To apply M-LSD method, you should use the '**M-LSD Lines**' in preprocess stage, and change the weights of ControlNet to '**control_mlsd-fp16.safetensors**'. The figure below shows how to find the node, and the table below explains the settings of it. You can read the descriptions provided by [this link](#) for more details.



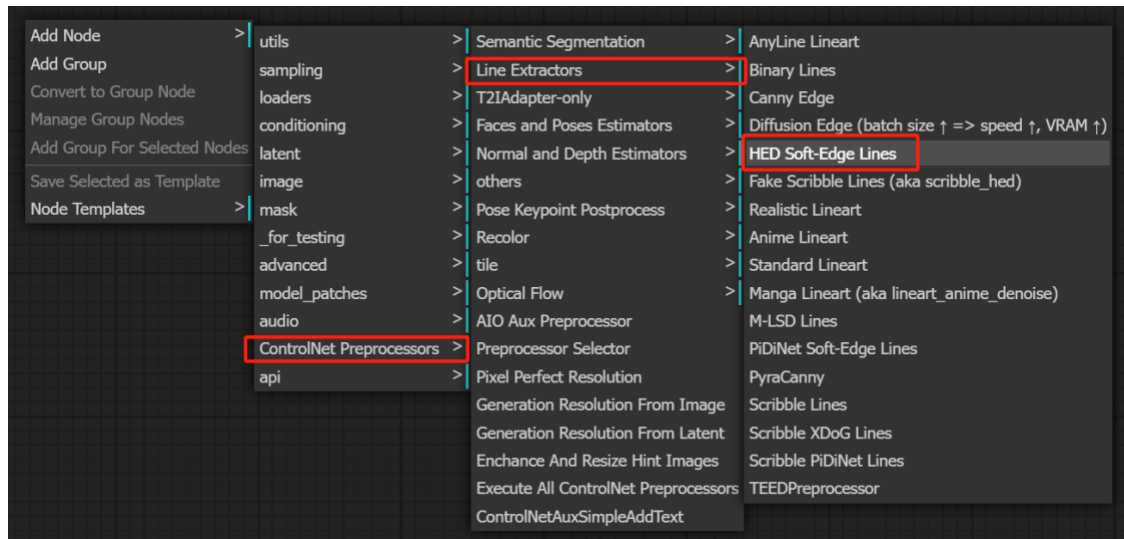
Setting	Description
score_threshold	A float number ranges from 0.01 to 2.0. It determines the minimum confidence score for a line to be valid. Decreasing this value result in more lines, but will potentially add noises.
dist_threshold	A float number ranges from 0.01 to 20.0. It determines the maximum allowable distance between points for them to be considered part of the same line.
resolution	This parameter determines the size of line map, which will always be in a squared shape. It doesn't affect the resolution of the final output.

HED boundary maps

HED stands for holistically-nested edge detection. Similar to M-LSD, it is also a deep-learning based, end-to-end method. HED performs fast prediction on the edges of an given image using a fully convolutional neural network. HED boundaries are different with the Canny edges, because they are 'soft' edge maps instead of binary. This means that HED boundaries are more detailed. If you are interested in technical details of this method, you can refer to its [original paper](#) on arxiv.

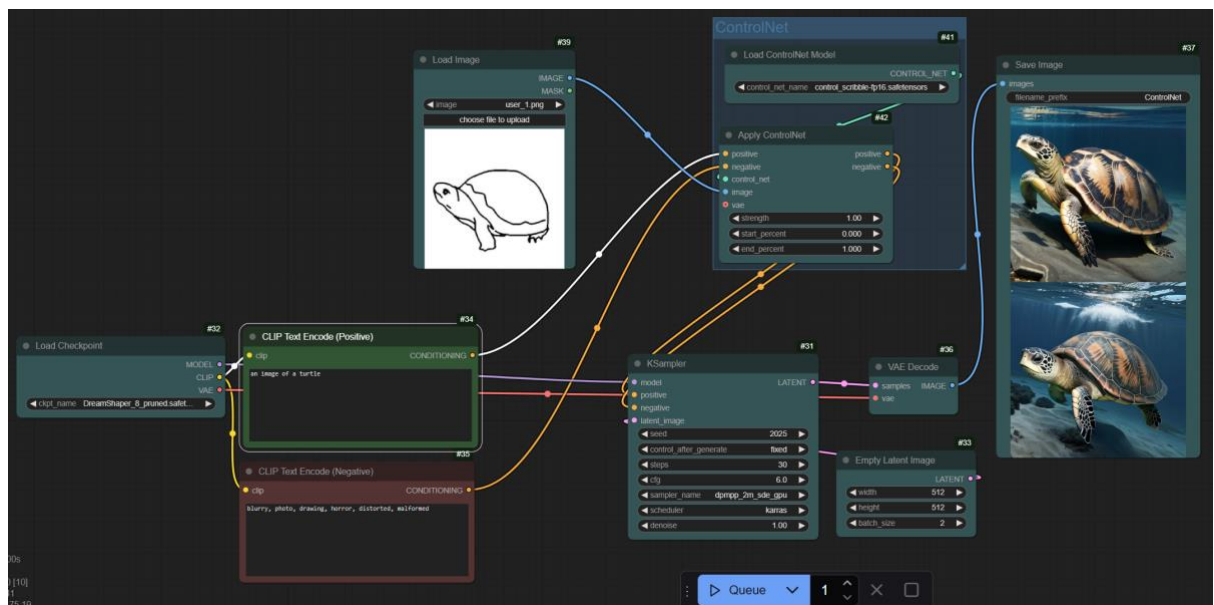


To apply the HED method to ControlNet spatial constraint, you should use the **'HED Soft-Edge Lines'** node in the preprocess stage, and select the **'control_hed_fp16.safetensors'** as weights for ControlNet. To find the node, you should sequentially click on 'Add Node -> ControlNet Preprocessors -> Line Extractors -> HED Soft-Edge Maps', as shown in the figure below. The setting 'safe' determines if the additional safety checks should be toggled. You can read the detailed explanation provided by [this link](#) for more instructions.



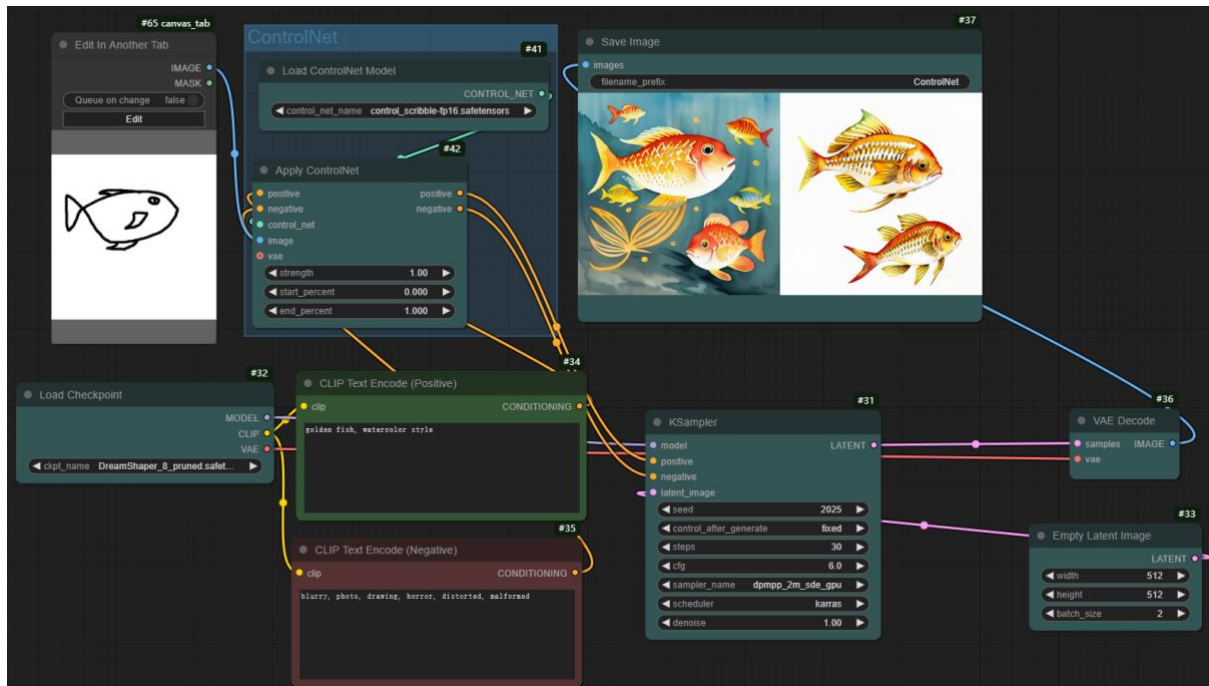
Scribbles

The last showcase is to provide a scribble as spatial prompt. Compared with others, this may be the simplest one since no preprocess is required, and you only need change the model wights of ControlNet to **'controlnet_scribble-fp16.safetensors'** and feed it with a scribble or sketch.



3. Exercise

Draw a scribble by yourself using the 'Canvas Tab' node and feed it as a spatial prompt to ControlNet. Feel free to design anything you like! If you forgot what is a 'Canvas Tab' node, please check Exercise (2) in Lab 7 for more details.



Final Submission: Please submit the workflow and 10 images generated from your drawings (along with the manual drawings), as a single zip file.