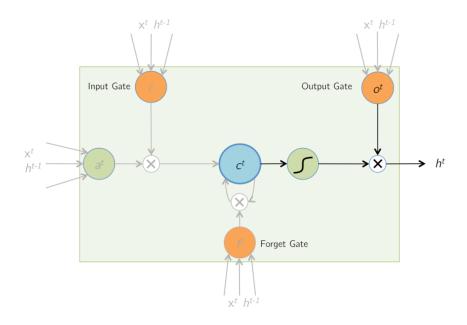
## LSTM

Many readers started learning LSTM from this blog post. But for those who want to dive deeper into its math derivations, this slide is a better choice.

### The LSTM Unit



# Forward Pass

- 1. an input:  $a^t = \tanh(\hat{a}^t) = \tanh(W_a x^t + U_a h^{t-1})$ 2. the input gate:  $i^t = \sigma(\hat{i}_t) = \sigma(W_i x^t + U_i h^{t-1})$
- 3. the forget gate:  $f^t = \sigma(\hat{f}^t) = \sigma(W_f x^t + U_f h^{t-1})$ 4. the memory cell:  $c^t = a^t \odot i^t + c^{t-1} \odot f^t$
- 5. the output gate:  $o^t = \sigma(\hat{o}^t) = \sigma(W_o x^t + U_o h^{t-1})$
- 6. the output:  $h^t = \tanh(c^t) \odot o^t$

### NOTE:

1. There is an implicit data flow  $c^{t+1}=c^t$  between LSTM units. This implies that  $c^t$  should accept gradients from not only  $h^t$ , but also  $h^{t+1}$ .

- 2. All gates uses the sigmoid function as their activations. This is because the gates' output must be in the range [0,1] so could they be used with  $\odot$  as the gate.
- 3. The non-linearity of an LSTM cell comes from the tanh activations of  $a^t$  and  $h_t$ . Compared with sigmoid, whose gradient closes to zero when the input is very negative and stucks the SGD process, tanh doesn't have this problem.

### **Backward Pass**

The backward pass updates  $W_o$ ,  $U_o$ ,  $W_f$ ,  $U_f$ ,  $W_i$ , and  $U_i$ .

Denoting the error of  $h^t$  by E, the derivation of the backpropagation algorithm tells that we will have  $\frac{\partial E}{\partial h^t}$  form the cost layer.

$$\frac{\partial E}{\partial o^t} = \frac{\partial E}{\partial h^t} \cdot \frac{\partial h^t}{\partial o^t} = \frac{\partial E}{\partial h^t} \odot \tanh(c^t)$$

$$\frac{\partial E}{\partial c^t} = \frac{\partial E}{\partial h^t} \frac{\partial h^t}{\partial c^t} = \frac{\partial E}{\partial h^t} \odot o^t \odot \left[ 1 - \tanh^2(c^t) \right]$$

Due to the implicit data flow, we introduce a variable  $\delta c^t$  to accumulate gradients from  $h^T$ :

$$\delta c^t + = \frac{\partial E}{\partial c^t}$$

Given  $\delta c^t$ , we can find

$$\begin{split} \frac{\partial E}{\partial i^t} &= \delta c^t \odot a^t \\ \frac{\partial E}{\partial a^t} &= \delta c^t \odot i^t \\ \frac{\partial E}{\partial f^t} &= \delta c^t \odot c^{t-1} \\ \frac{\partial E}{\partial c^{t-1}} &= \delta c^t \odot f^t \end{split}$$

**NOTE:** that the last equation sets the initial value of  $\delta c^{t-1}$ , which will be updated later by  $\frac{\partial E}{\partial c^{t-1}}$ .

$$\frac{\partial E}{\partial \hat{a}^t} = \frac{\partial E}{\partial a^t} \odot \left[ 1 - \tanh(\hat{a}^t) \right]$$

$$\frac{\partial E}{\partial \hat{i}^t} = \frac{\partial E}{\partial i^t} \odot \hat{a}^t \odot (1 - \hat{a}^t)$$

$$\frac{\partial E}{\partial \hat{f}^t} = \frac{\partial E}{\partial f^t} \odot \hat{f}^t \odot (1 - \hat{f}^t)$$

$$\frac{\partial E}{\partial \hat{o}^t} = \frac{\partial E}{\partial o^t} \odot \hat{o}^t \odot (1 - \hat{o}^t)$$

Because

$$\hat{I} = \Theta I$$

where

$$\begin{split} \hat{I}^t &= [\hat{a}^t \ \hat{i}^t \ \hat{f}^t \ \hat{o}^t]^T \\ \Theta &= [W \ U] \\ I^t &= [x^t \ h^{t-1}]^T \end{split}$$

we have

$$\delta\Theta^t = \frac{\partial E}{\partial \Theta}\mid_t = \frac{\partial E}{\partial \hat{I}^t} \cdot \frac{\partial \hat{I}^t}{\partial \Theta}\mid_t = \left[\frac{\partial E}{\partial \hat{a}^t} \; \frac{\partial E}{\partial \hat{i}^t} \; \frac{\partial E}{\partial \hat{f}^t} \; \frac{\partial E}{\partial \hat{o}^t}\right] \times I^t$$

According to the multivariate chain rule

$$\frac{\partial E}{\partial \Theta} = \sum_{t=1}^{T} \delta \Theta^{t}$$