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Projects on Recent Advances in Machine Learning **Neural Operators**

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Neural Operators

*Neural Operator: Learning Maps Between Function Spaces
With Applications to PDEs - Kovachki et al. (2022)*



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Neural networks try to learn mappings between functions.

They satisfy the property of being universal approximators.

Universal approximation: a model that can uniformly approximate any continuous operator.

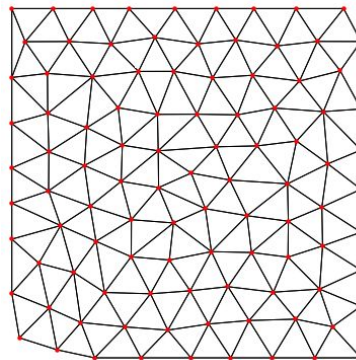
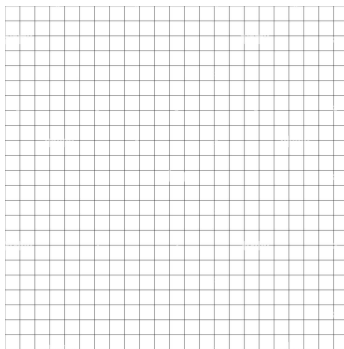
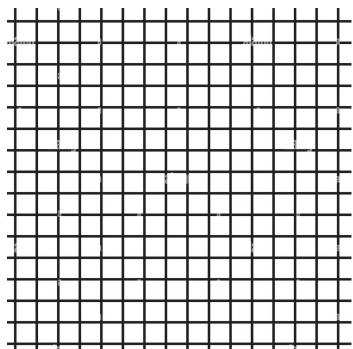
Caveat: Typical neural networks do so for finite dimensional spaces.

What if we wanted instead to learn an operator such as a PDE ?

Neural Operators: the only models that satisfy both universal approximation and discretization invariance.

A discretization invariant model satisfies:

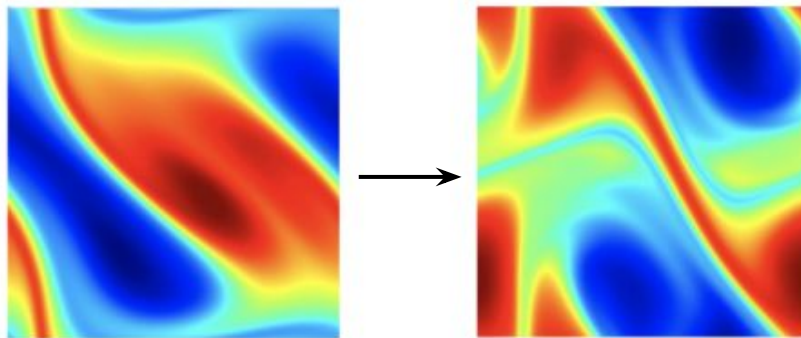
1. can act on any discretization of the input function, i.e. accepts any set of points in the input domain,
2. can be evaluated at any point of the output domain,
3. converges to a continuum operator as the discretization is refined.



Why is this important?

Burgers, Darcy subsurface flow, Navier-Stokes equations, etc.

Numerical solvers are expensive! This method allows to obtain solutions in a manner that is several orders of magnitude faster.



Navier-Stokes equation

We aim to estimate an operator (PDE), using a parametric map between infinite dimension spaces (Neural Network):

$$G_{\theta} : \mathcal{A} \rightarrow \mathcal{U}, \quad \theta \in \Theta$$

The inputs and outputs of the network are functions.

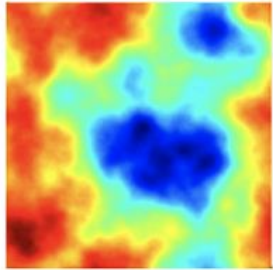
In practical terms they are equivalent to data points, or samplings of those functions.

Neural Operators

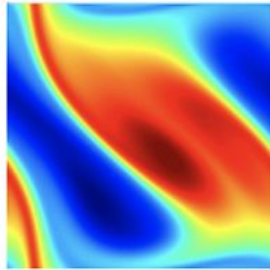
Example

8

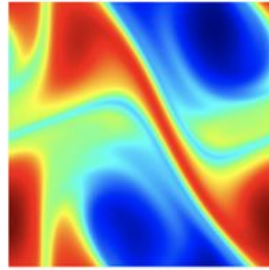
Initial Vorticity



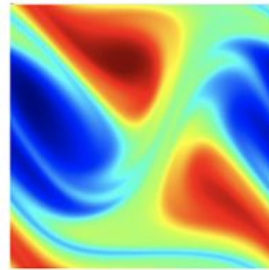
$t=15$



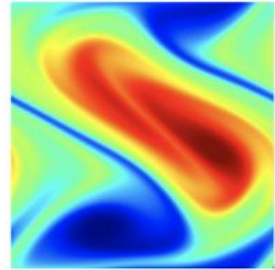
$t=20$



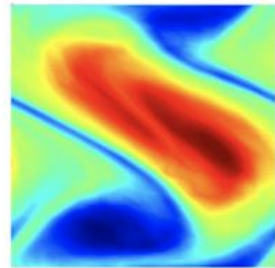
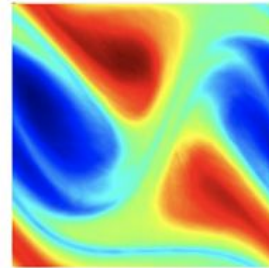
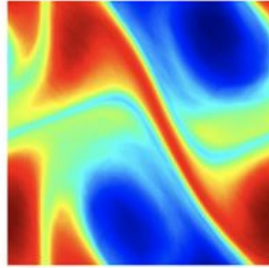
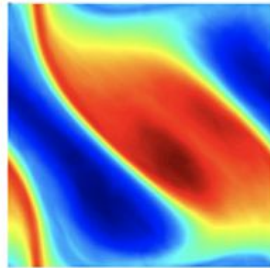
$t=25$



$t=30$



Prediction



There many variants of neural operators:

- graph-based operators
- low-rank operators
- multipole graph-based operators
- **Fourier operators**

Fourier Neural Operator

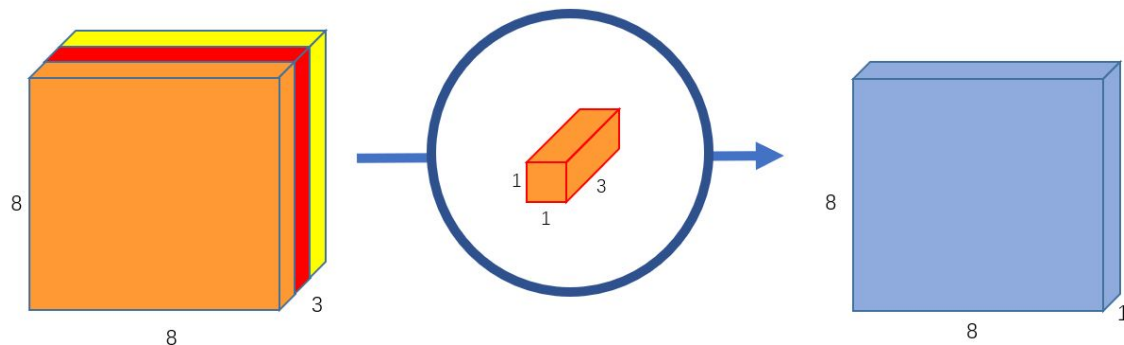
Fourier Neural Operator for parametric partial differential equations - Li et al.(2021)



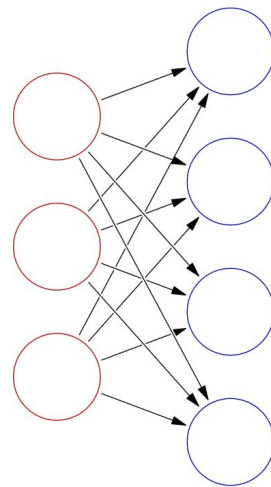
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What is a pixel-wise or 1×1 convolution?

Only pixels from different channels are combined.



The operation remains the same no matter the resolution.

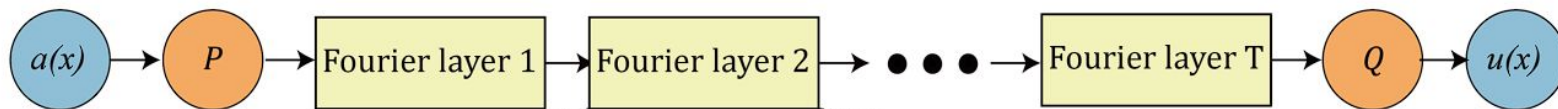


The Fourier Neural operator achieves this while also being *Resolution Invariant*.

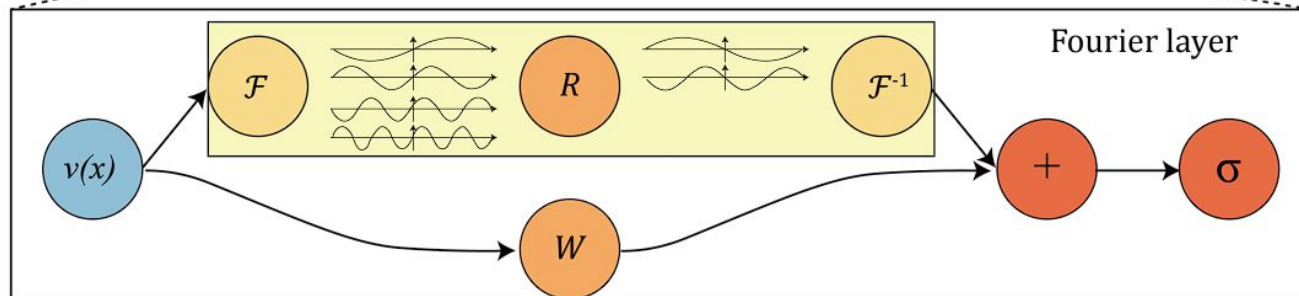


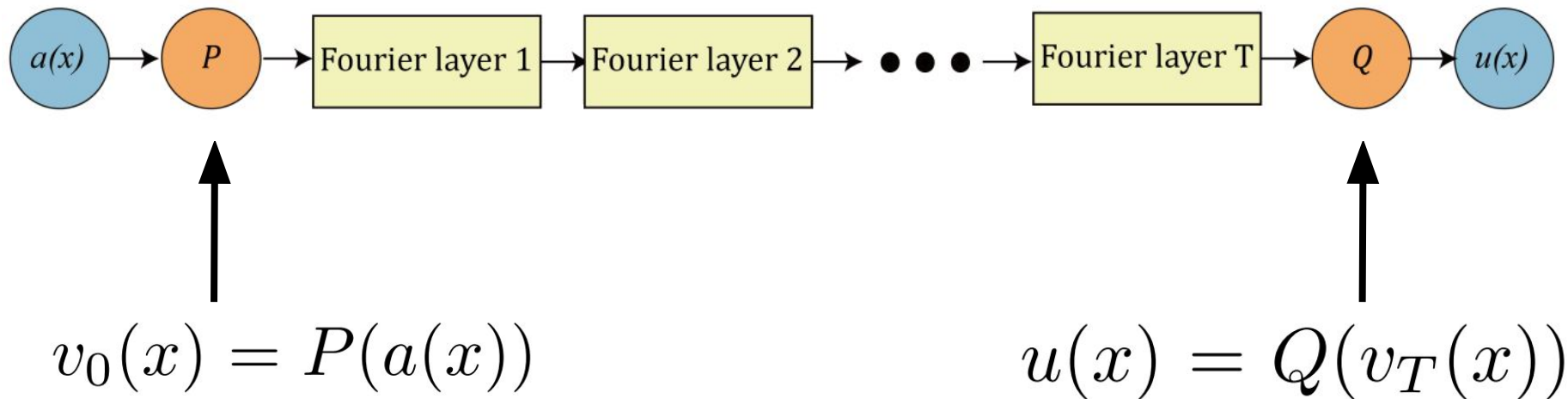
How?

(a)



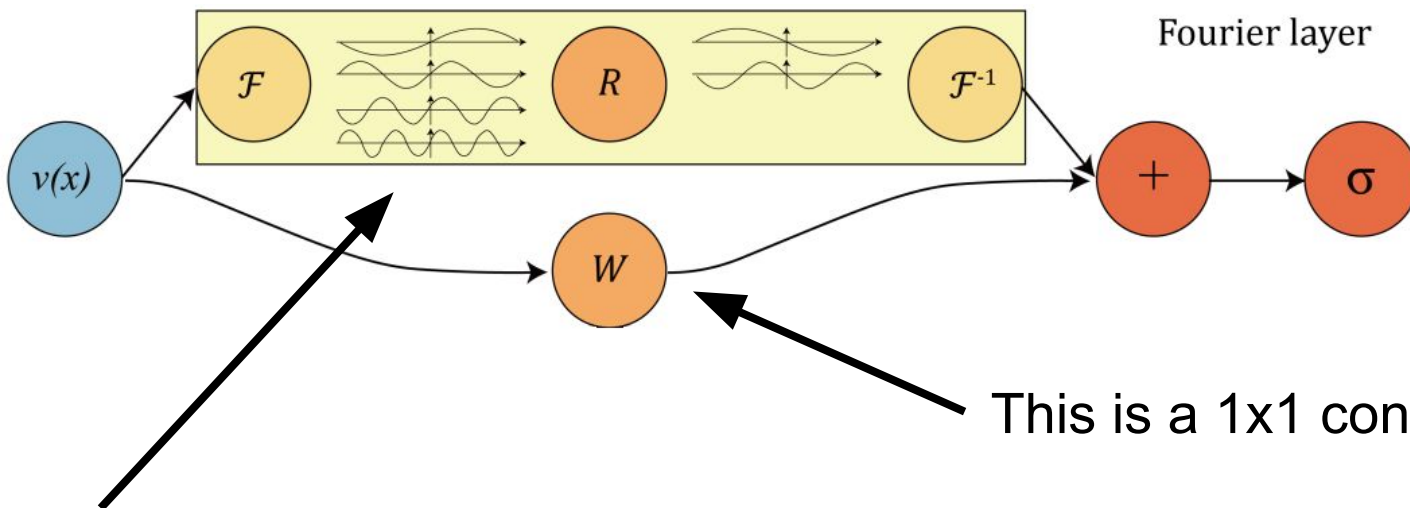
(b)





The input is translated into a latent space with a higher dimensionality

In this case they use 1x1 convolutions

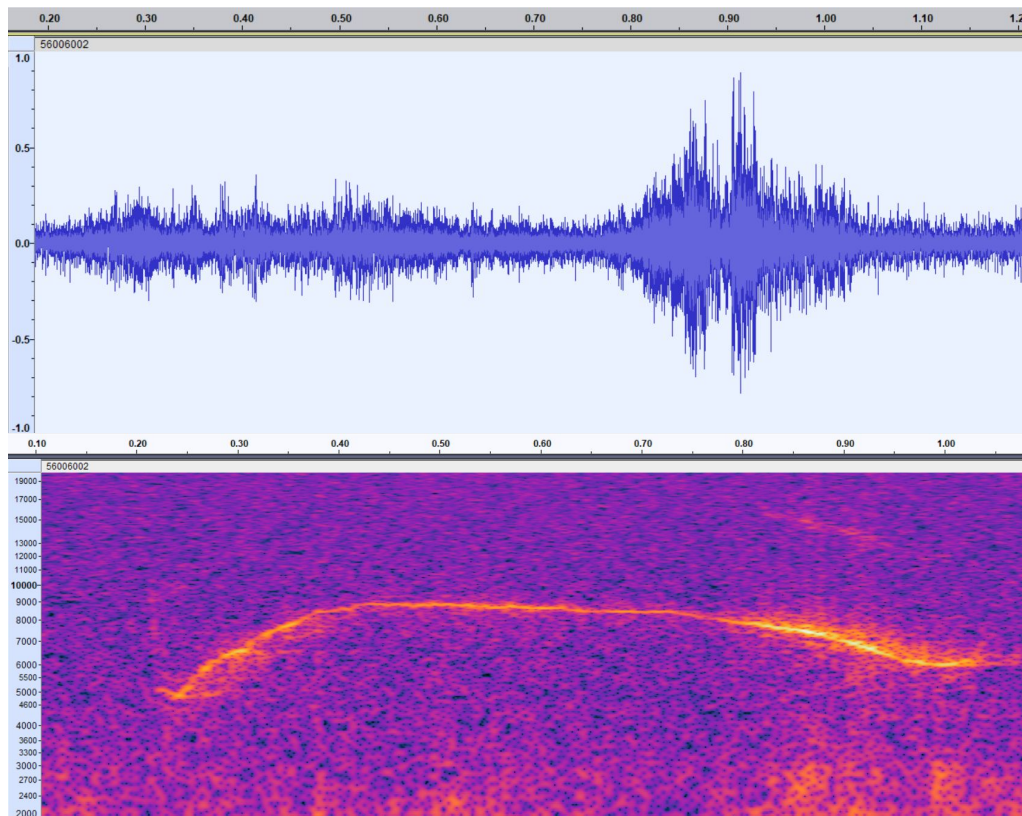


**How is this block
resolution invariant?**

This layer emulates
convolutions as matrix
products in the fourier space

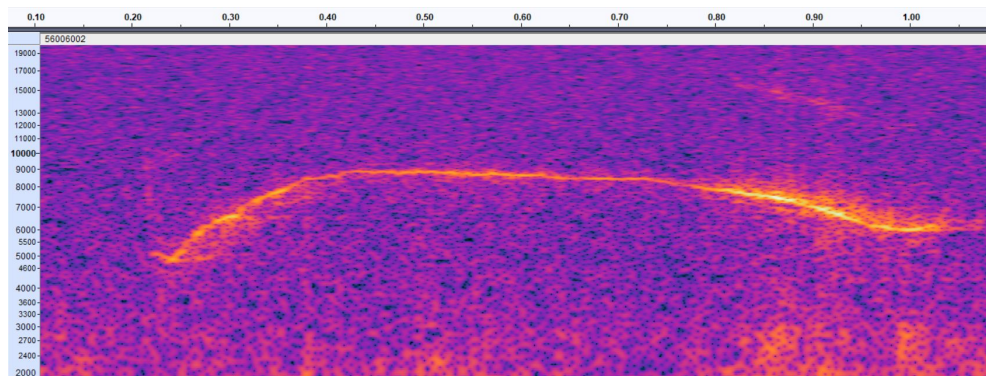
Signal sampled at 66 kHz

The maximum frequency obtained in the FFT is 33 kHz



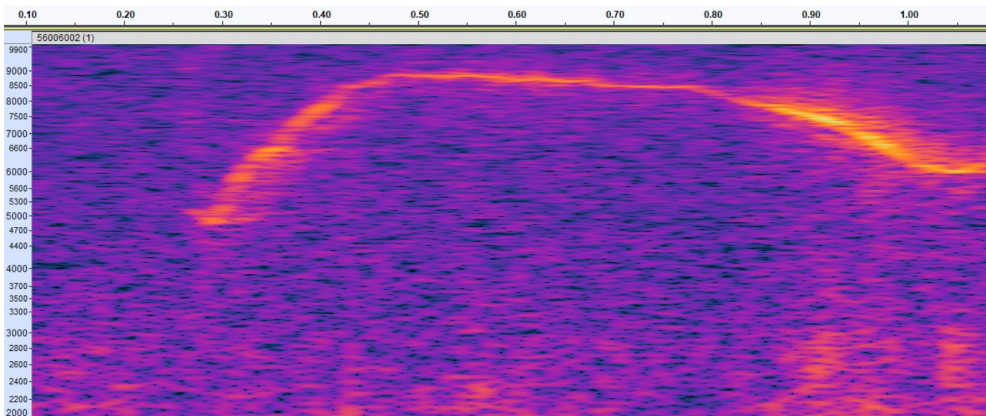
**Sample
Rates:**

66k



Lowering the SR
lowers the maximum
frequency...

21k

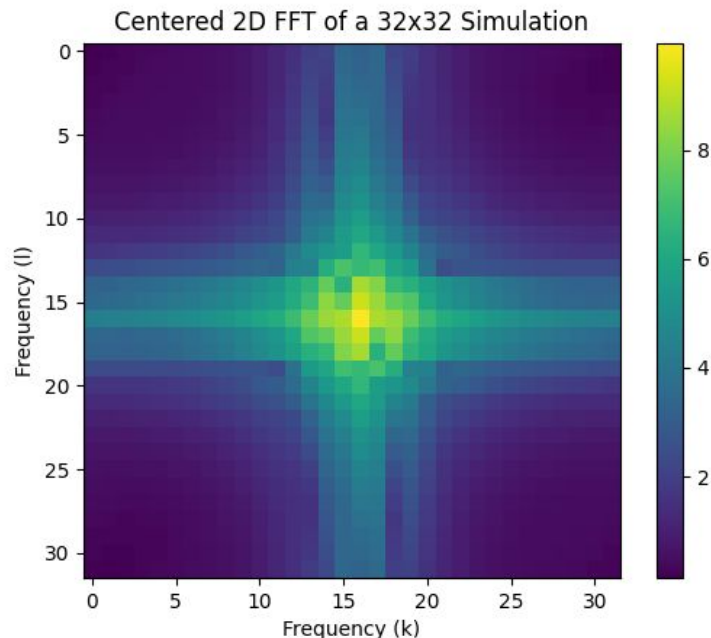
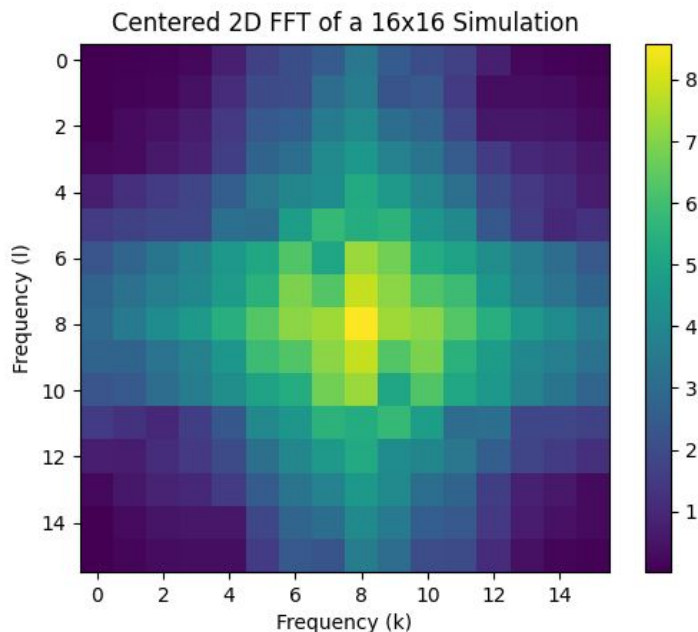


**But it will not change
the lower frequency
values of the FFT!**

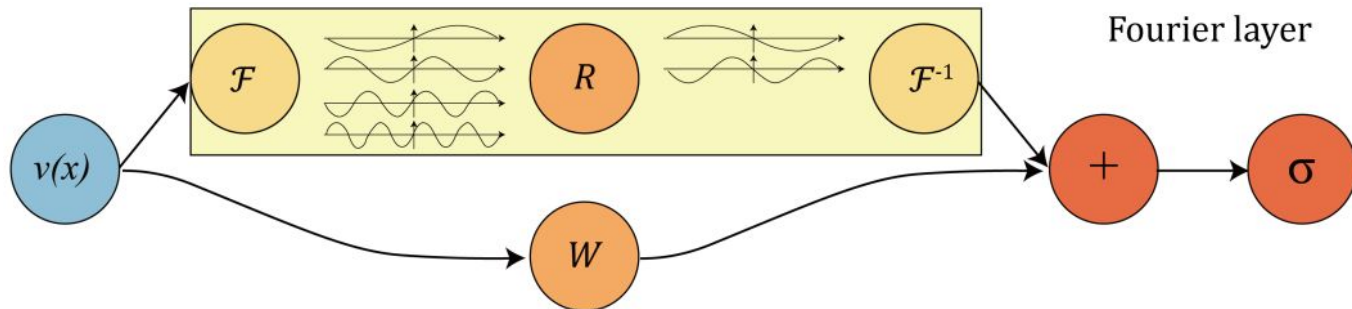
Resolution invariance in the Fourier Space



The FNO uses only the base modes of the input spectrum.

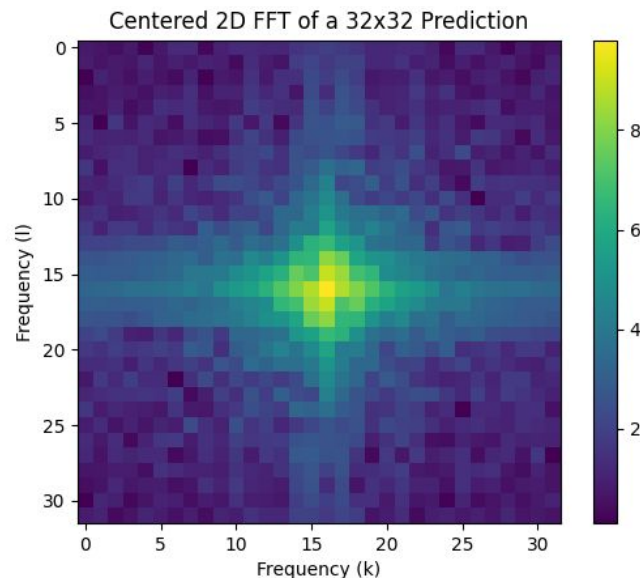


Doubling the spatial sampling frequency should yield the same values for the base frequencies.



From our perspective the main drawback of the FNO is:

Since the FNO discards higher frequency modes its output will only recreate the lower frequency components of the solution.



Dataset definition

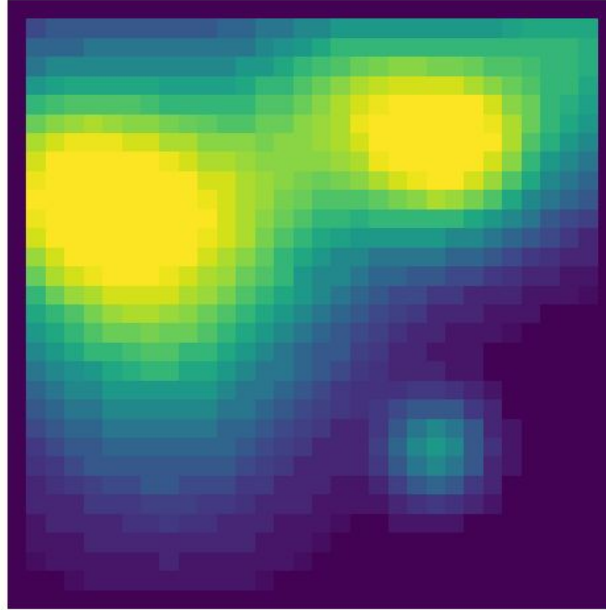
for the heat equation



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Time evolution

Iteration 1

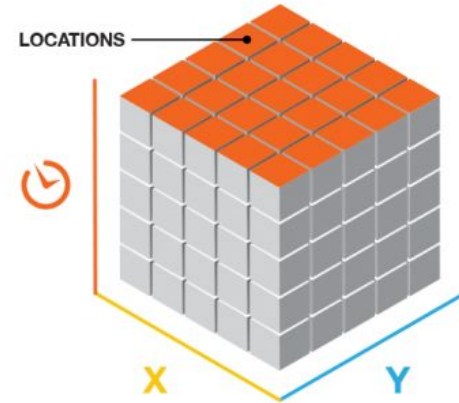


Boundary condition:
 $T = 0$ for borders

$$\frac{\partial u}{\partial t} = \Delta u$$

Differential equation relating time and spatial variables

Spatial and temporal discretization



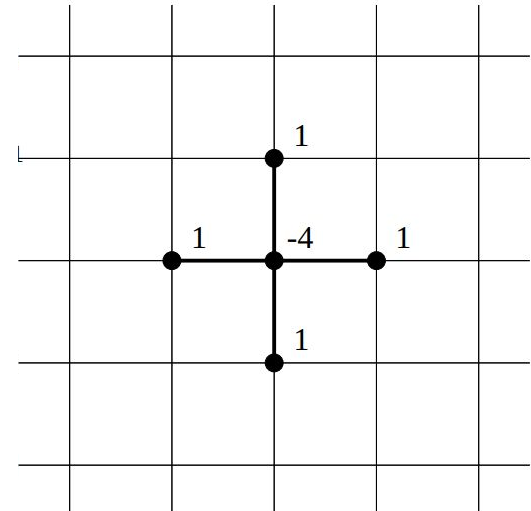
Discretization of the problem

$$\frac{\partial u}{\partial t} = \Delta u \quad \longrightarrow \quad \frac{u_{i,j}^{k+1} - u_{i,j}^k}{\Delta t} - \alpha \left(\frac{u_{i+1,j}^k - 2u_{i,j}^k + u_{i-1,j}^k}{\Delta x^2} + \frac{u_{i,j+1}^k - 2u_{i,j}^k + u_{i,j-1}^k}{\Delta y^2} \right) = 0$$

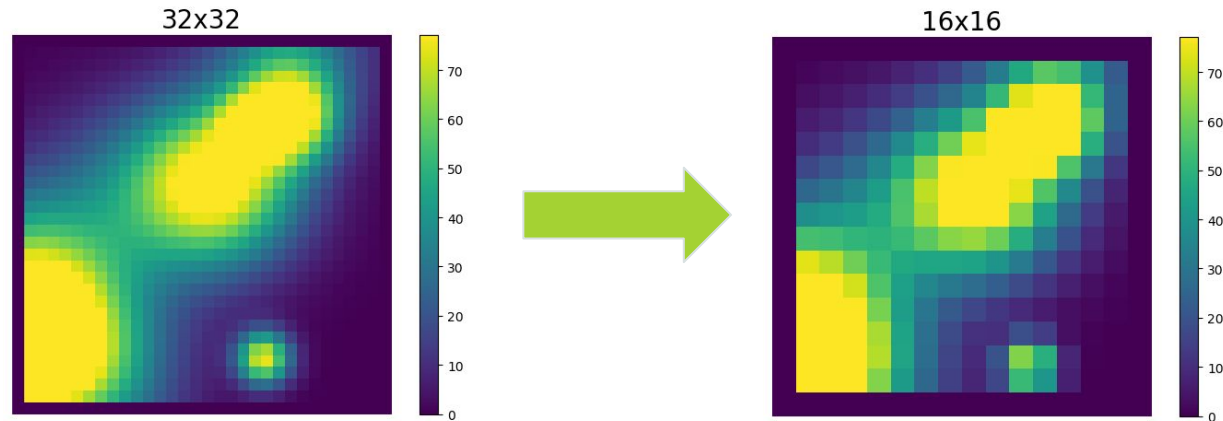
$$u_{i,j}^{k+1} = \gamma (u_{i+1,j}^k + u_{i-1,j}^k + u_{i,j+1}^k + u_{i,j-1}^k - 4u_{i,j}^k) + u_{i,j}^k$$

$$\gamma = \alpha \frac{\Delta t}{\Delta x^2}$$

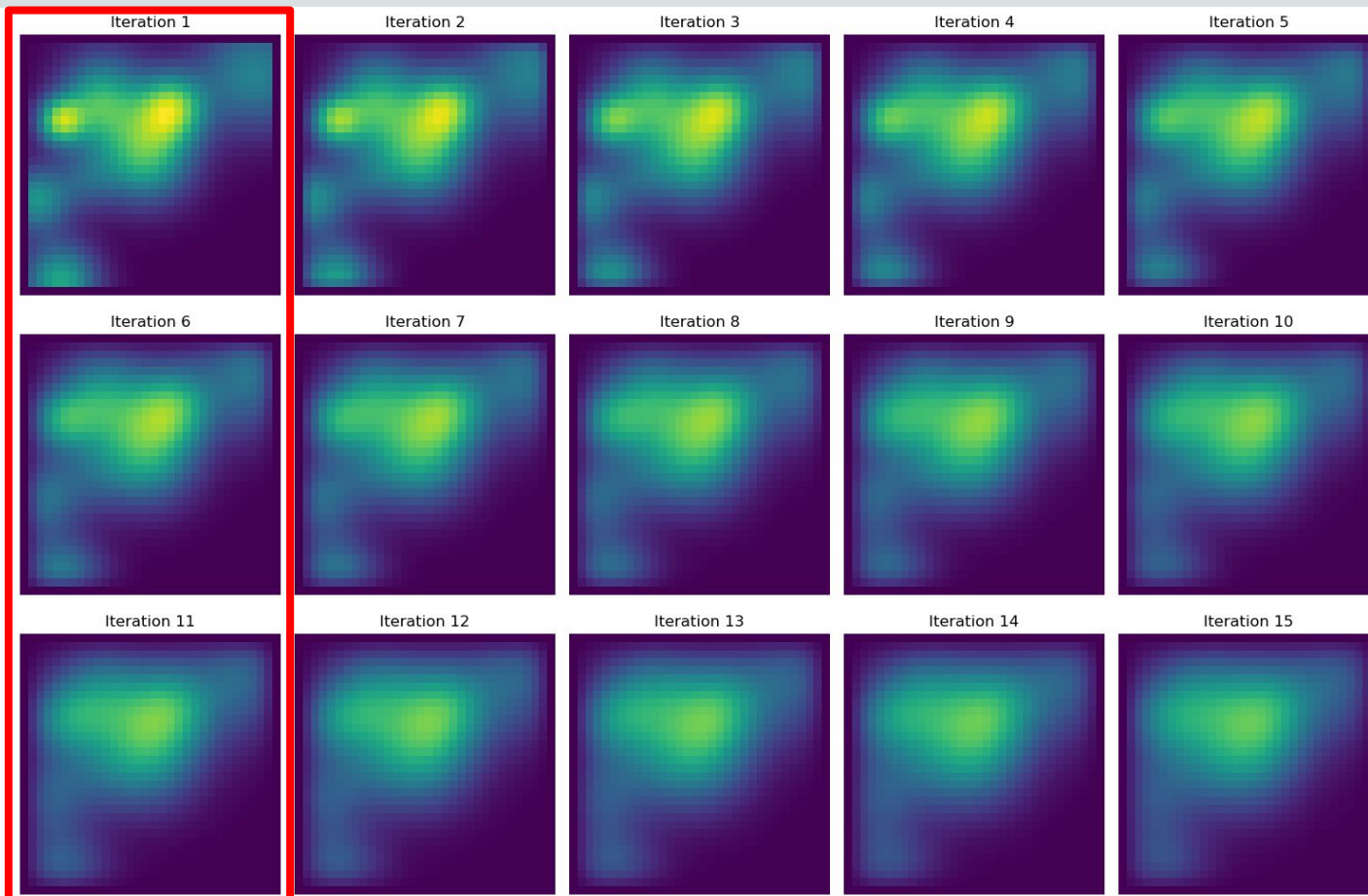
Convergence condition: $\gamma \leq \frac{1}{4}$

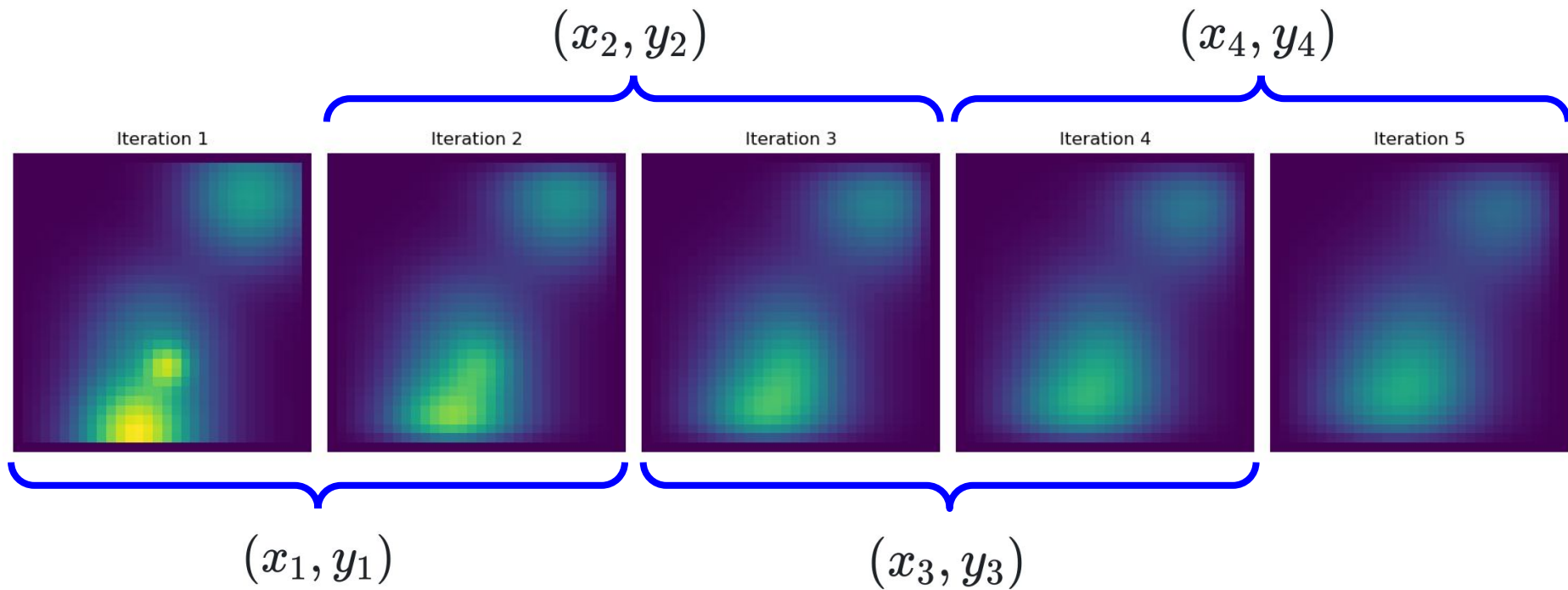


- Boundary conditions: All grid borders are set to a fixed value (0°)
- Random gaussian shaped heat areas are set in the first iteration
- To simulate lower resolutions, a subsampling is performed



Idea: jump every
5 iterations to
accelerate
diffusion

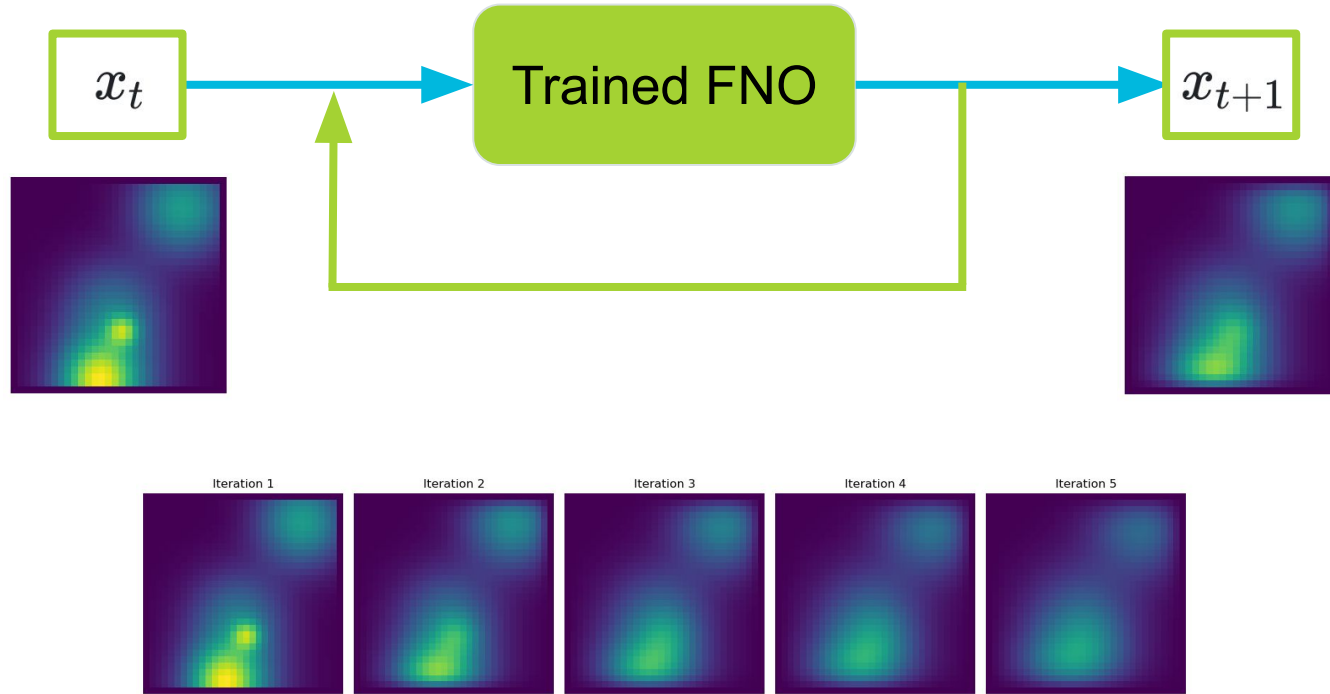


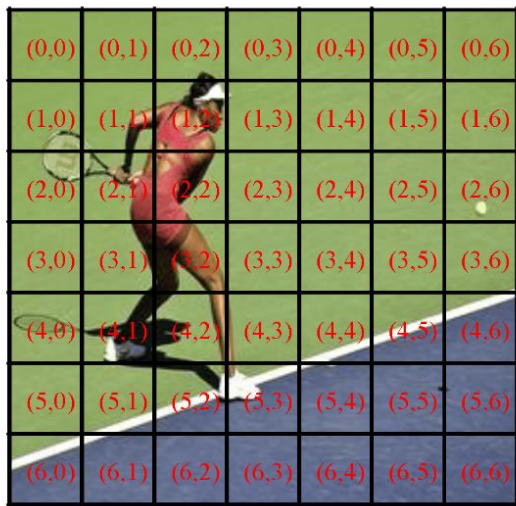


Parametric Encoding



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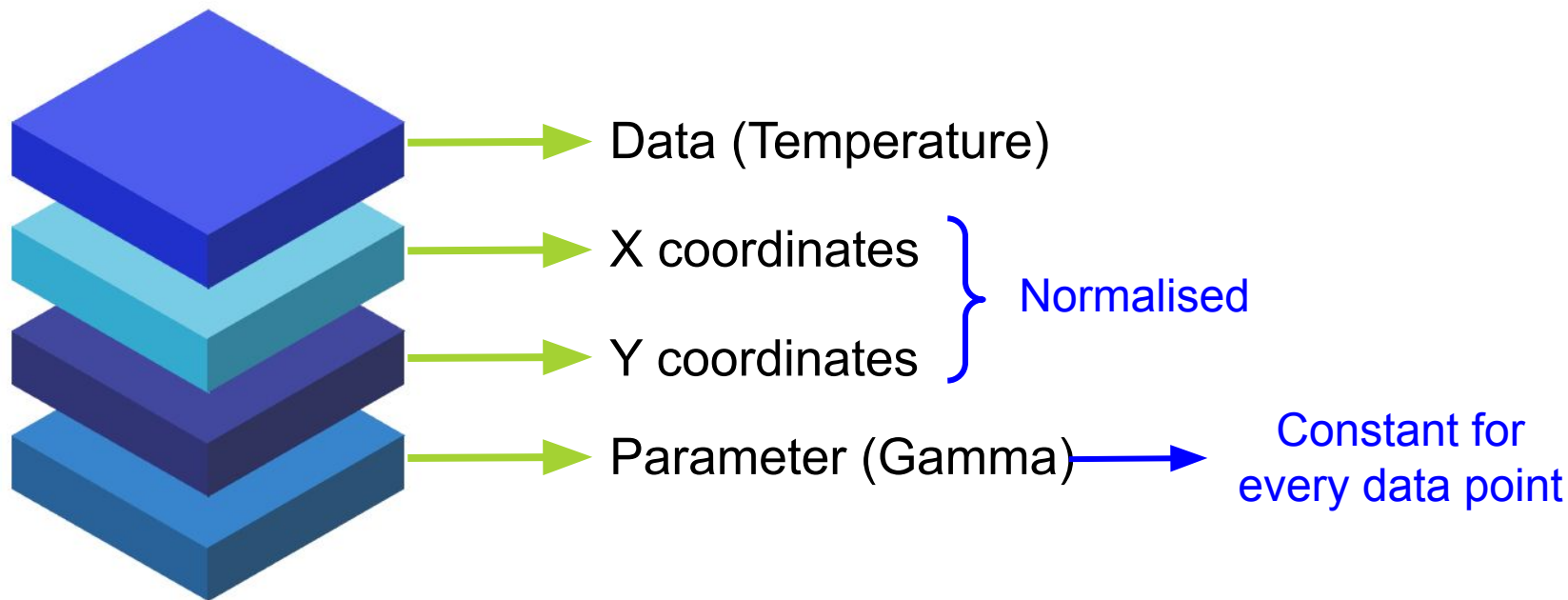




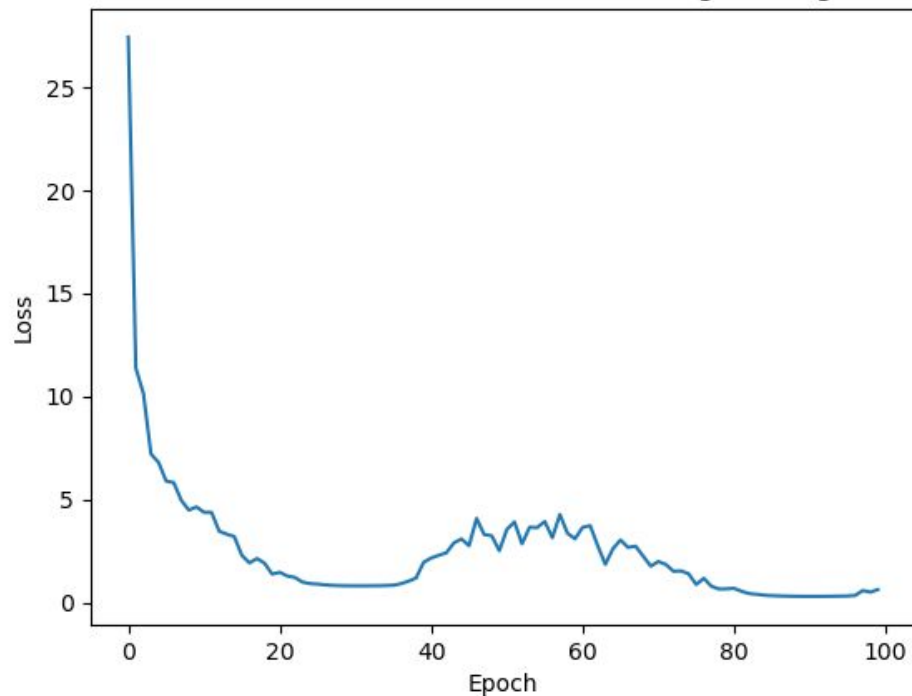
Coordinate-based Spatial Position
Encoding

Spatial Understanding: Spatial positional embedding aids deep learning models in comprehending the spatial relationships between elements in input data.

<https://www.mdpi.com/2227-7390/11/21/4550>

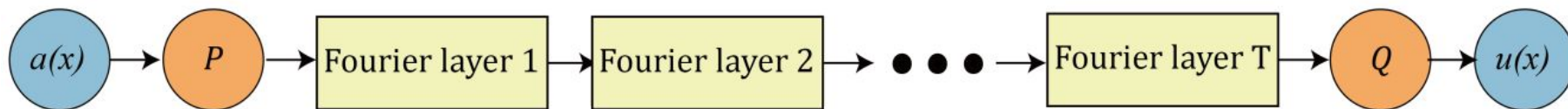


Loss Evolution for Parametric Encoding Training



- Training γ values: 5 values between 0.01 and 0.25
- Training duration: 2 min. on GPU
- Training size: 2386 input-output pairs
- Batch size: 32
- Number of epochs: 100

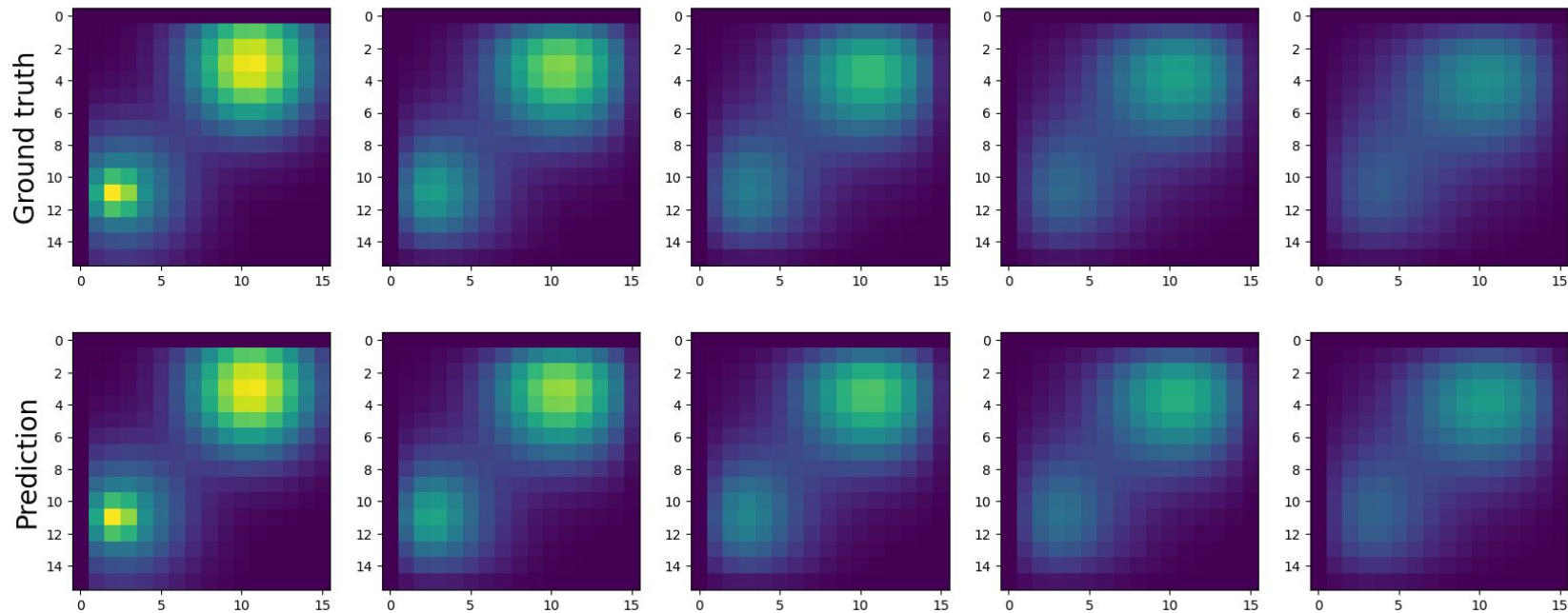
- 8 Fourier layers
- 32 hidden channels
- 64 projection channels
- 4 input channels
- Initial learning rate: 0.008
- Adam optimizer



Results

16x16

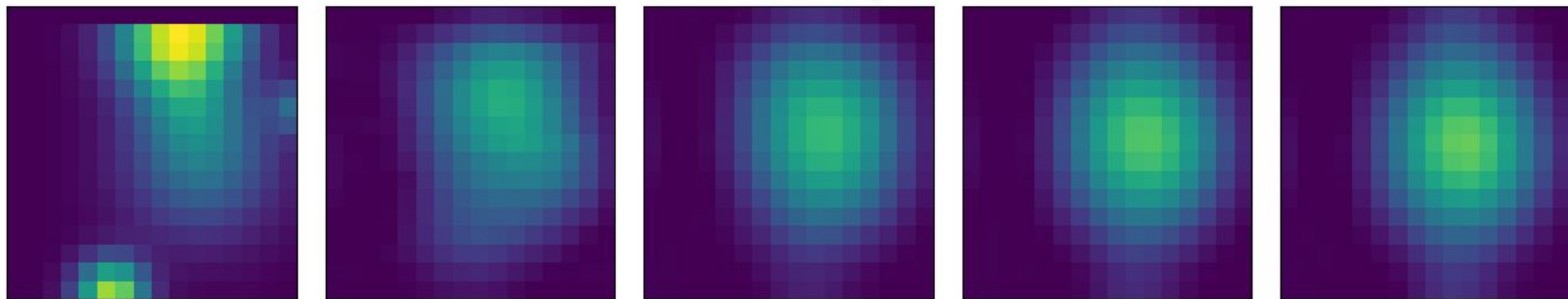
16x16 resolution, Gamma = 0.1000



Results

What if γ is outside the training range?

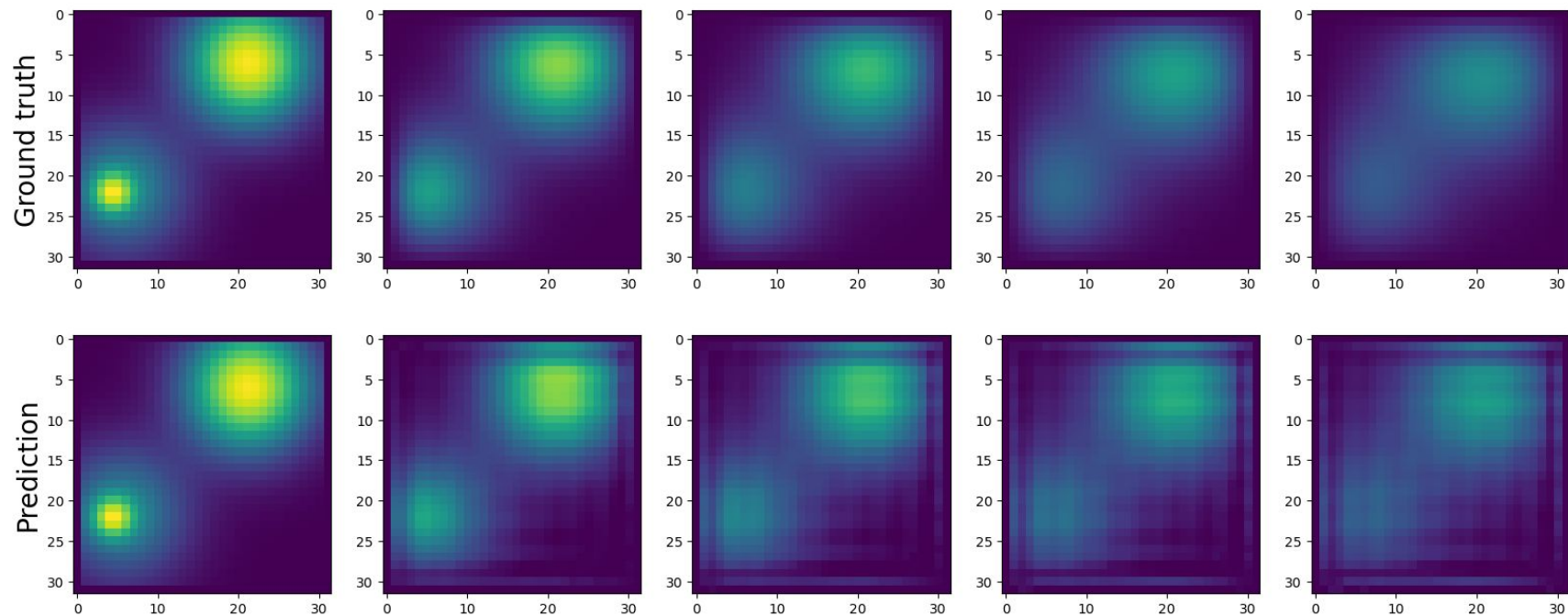
Predictions for 16x16 resolution, Gamma = 5.0000



Results

32x32

32x32 resolution, Gamma = 0.1000



Exploring higher dimensions



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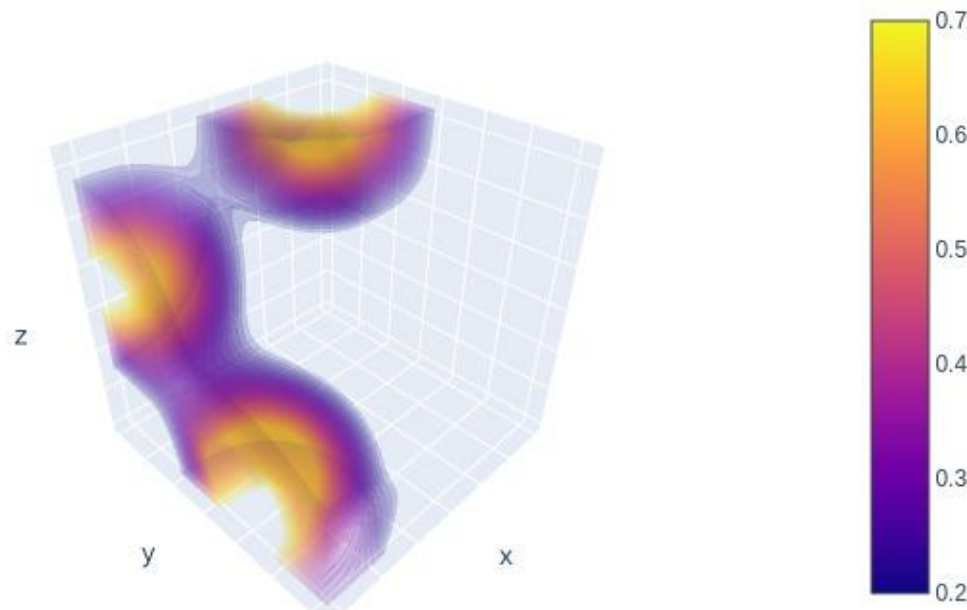
3D heat equation

Initial condition

36

There are no
constraints on the
dimensionality of input
data!

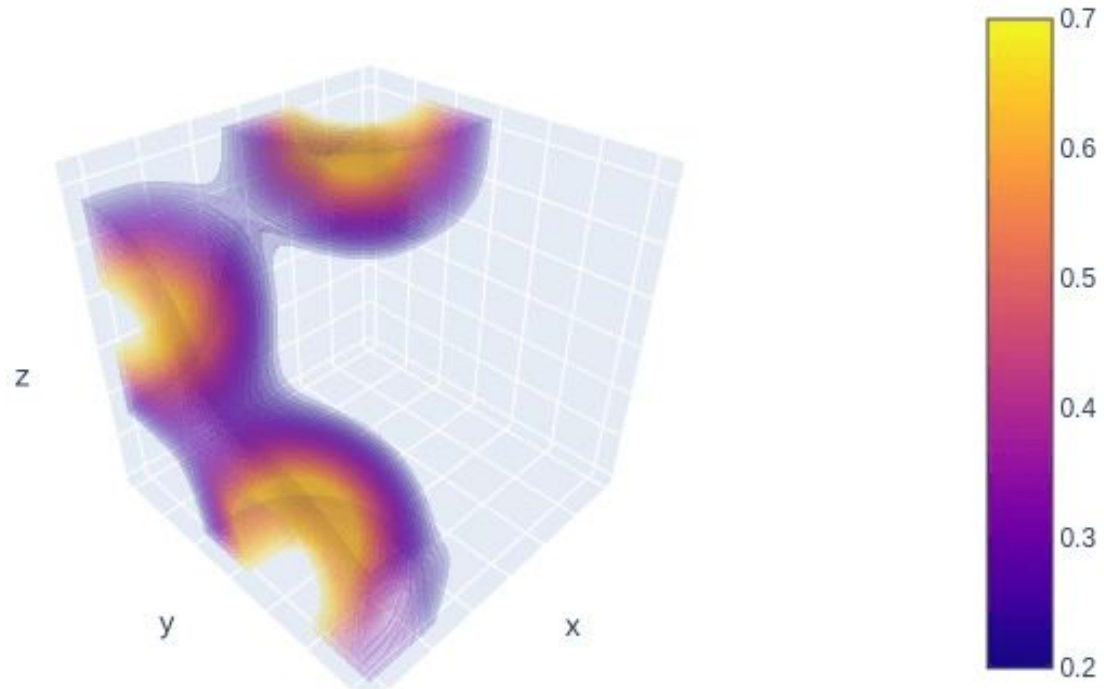
(Only the
computational cost...)



$$\mathcal{F}f(\xi_1, \xi_2, \dots, \xi_n) = \int_{\mathbf{R}^n} e^{-2\pi i(x_1\xi_1 + \dots + x_n\xi_n)} f(x_1, \dots, x_n) dx_1 \dots dx_n ,$$

Results

Time propagation of
the 3D heat equation



Future improvements



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- Regression to find the equation parameter.
- Upgrade the model to be N-dimensional.

Conclusion



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- We reviewed the literature on Neural Operators.
- We implemented and tested the Fourier Neural Operators for the 2D and 3D Heat Diffusion equation.
- We implemented parameter embedding into the model.

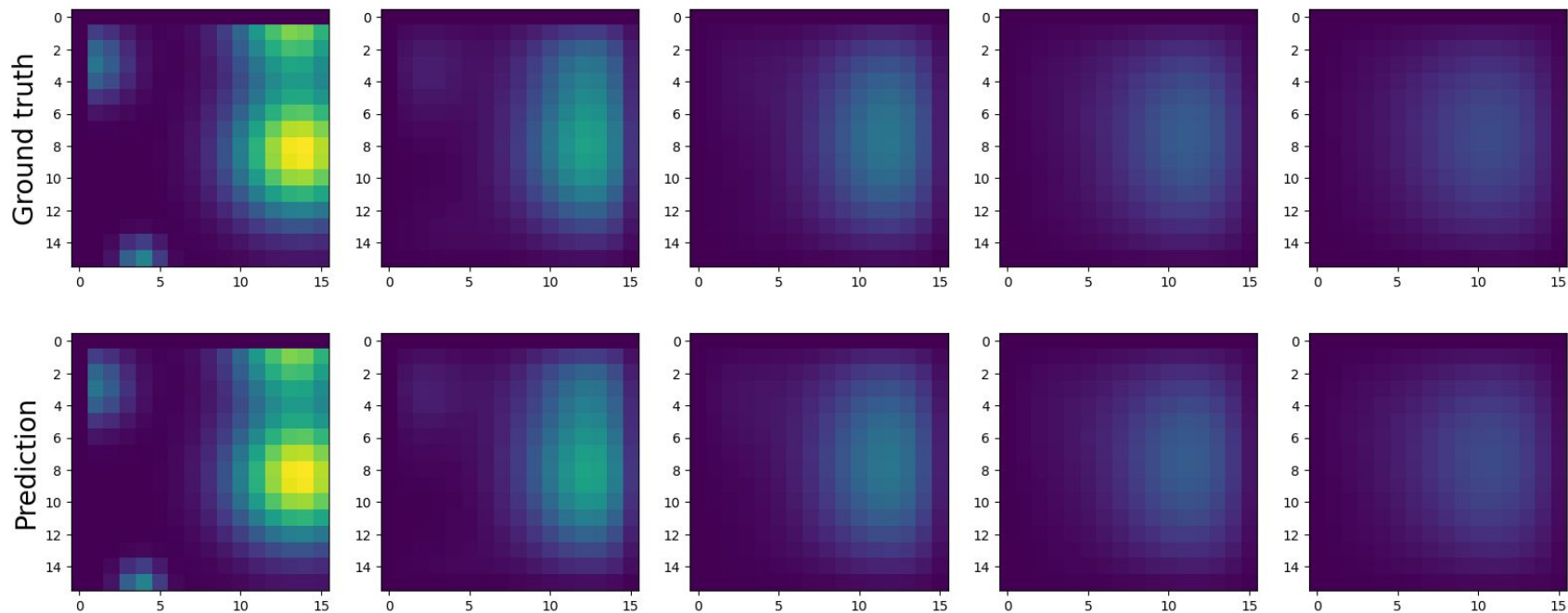
Appendix



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Results

16x16 resolution, Gamma = 0.2500



Results

16x16 resolution, Gamma = 0.0010

