



Gonzalo Olguín Moncada

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Home: Providencia, Santiago (Chile)

ABOUT ME

Student passionate and devoted to Science and Engineering, with ability to solve problems using the tools and knowledge gained by studies and the abstraction in mathematical logic.

EDUCATION AND TRAINING

MSc in Electrical Engineering

University of Chile [01/12/2023 – Current]

City: Santiago

Country: Chile

BSc Electrical Engineering

University of Chile [01/03/2019 – 19/12/2023]

City: Santiago

Country: Chile

Exchange semester in Electrical Engineering

Technical University of Munich [01/04/2022 – 30/09/2022]

City: München

Country: Germany

WORK EXPERIENCE

Engineering Intern

AMTC - Advanced Mining Technology Center [01/01/2024 – Current]

City: Santiago

Country: Chile

- Documented and proposed electrical system for a laboratory version LHD-mini.
- Carried experiments for a Bachelor thesis on coverage navigation.
- Implemented soft-geofencing, path sampling for BT's and Minimum Oriented Bounding Box for map division algorithms.

Embedded developer

URacing Team Chile (FSAE) [01/12/2023 – Current]

City: Santiago

Country: Chile

Part of the electronics and data team of the first Formula SAE car in Chile.

Laboratory co-manager and project lead

Robotics Laboratory - University of Chile [01/10/2023 – Current]

City: Santiago

Country: Chile

- In charge of coordination, activities, projects and weekly meetings.
- Lead of the autonomous navigation team, focusing on all 3 mobile platforms in the laboratory.

Robotics engineer

Maquintel Robotic Services [01/09/2023 – 30/12/2023]

City: Santiago

Country: Chile

- Prepared on-board software of robot for 3D-mapping of tailings channels.
- Helped post-process data for aligning point clouds using ICP, RANSAC and other methods, combined with IMU data.

Engineering Intern

Maquintel Robotic Services [03/01/2023 – 03/01/2023]

City: Santiago

Country: Chile

- Created simulated version of Vizca D400 robot and appropriate tunnel/ditch like environments.
- Implemented sensor-fused odometry for robust data acquisition.

RESEARCH EXPERIENCE

Autonomous navigation team - Robotics Laboratory

[01/09/2021 – Current]

Permanent member, working on service robots.

- Implemented the full navigation stack (with custom packages) of Bender, a humanoid robot designed and built 100% at University of Chile.
- Created robot skills that are cross-platform and easy to implement on state machines for solving RoboCup@home tasks.
- Developed human-robot interactions modules for Bender, such as speech recognition, text processing via LLM's and command execution routines.
- Made custom packages to compress RGB-D point clouds into 2D and merge it with LiDAR data.

Research assistant - Computer Vision Laboratory

[01/01/2022 – 31/01/2022]

Assistant in an investigation concerning multi-target tracking using Poisson Labeled Multi-Bernoulli (PLMB) filter

TEACHING EXPERIENCE

Duckietown Engineering Chile

[01/08/2023 – 19/12/2023]

Entry level adaptation of MIT's Duckietown course for 2nd year students. I was in charge of two projects:

- Fault detection in pipes using LiDAR.
- Mapping of Duckietown's streets using LiDAR + IMU.

Computational Intelligence and Robotics Laboratory

[01/08/2023 – Current]

TA of the introductory course to the specialization of Computational Intelligence and Robotics. We focus mainly on teaching ROS and programming for robotics.

Introduction to classical physics

[01/03/2021 – 20/07/2021]

TA of the first year course. In charge of doing extra classes and grading exams.

Niñas Pro Foundation

[01/07/2021 – 31/07/2021]

Volunteer mentoring girls at schools in electronics projects, as an attempt to reduce the gender gap in STEM careers.

DIGITAL SKILLS

Programming

Python / C++ / ROS (Robot Operating System) / Arduino / Matlab/Simulink

Development

Git / Linux / Docker

Publishing and design

LaTeX / Adobe Photoshop (basic elements) / Adobe Premier

Others

FUSION360 / Microsoft Office

LANGUAGE SKILLS

Mother tongue(s): **Spanish**

Other language(s):

English

LISTENING C1 READING C1 WRITING C1

SPOKEN PRODUCTION B2 SPOKEN INTERACTION B2

Levels: A1 and A2: Basic user; B1 and B2: Independent user; C1 and C2: Proficient user