# **Unidad 6: Grafos**

Algoritmos y Estructuras de Datos

Operaciones Tipos Algoritmos

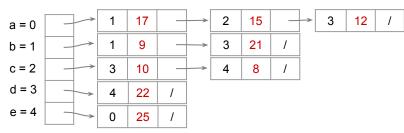
Acciones básicas

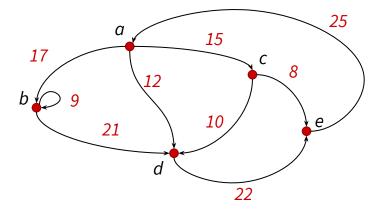
## Matriz de adyacencia

Adjacency Matrix

	0	1	2	3	4
a = 0	0	17	15	12	0
b = 1	0	9	0	21	0
c = 2	0	0	0	10	8
d = 3	0	0	0	0	22
e = 4	25	0	0	0	0

## Listas de adyacencia





Acciones básicas

¿Cómo resolver operaciones básicas?

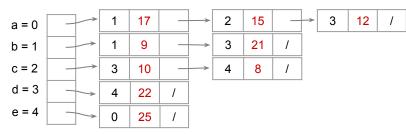
Insertar arista

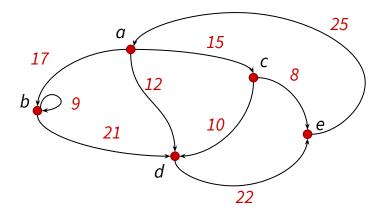
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### Listas de adyacencia





Acciones básicas

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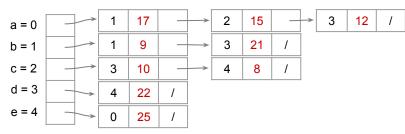
- Insertar arista
- Eliminar arista

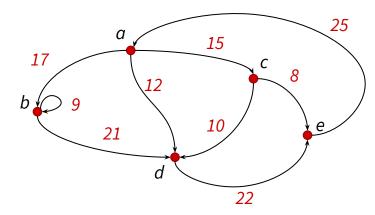
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### Listas de adyacencia





Acciones básicas

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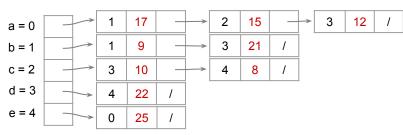
- Insertar arista
- Eliminar arista
- Insertar vértice

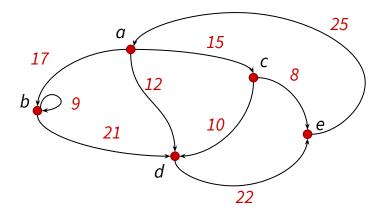
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### Listas de adyacencia





Acciones básicas

¿Cómo resolver operaciones básicas?

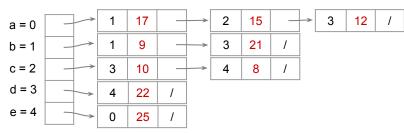
- Insertar arista
- Eliminar arista
- Insertar vértice
- Eliminar vértice

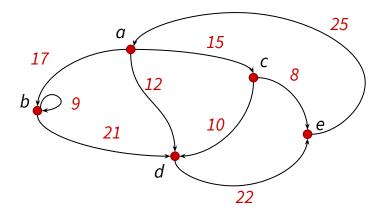
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### Listas de adyacencia





Acciones básicas

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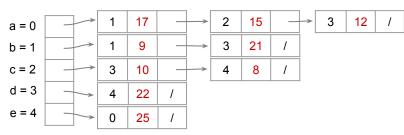
- Insertar arista
- Eliminar arista
- Insertar vértice
- Eliminar vértice
- Comprobar la existencia de una arista

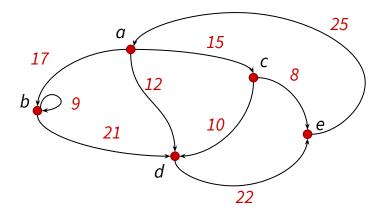
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### Listas de adyacencia





Acciones básicas

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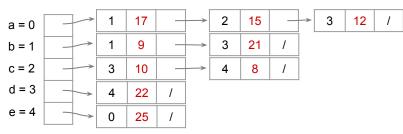
- Insertar arista
- Eliminar arista
- Insertar vértice
- Eliminar vértice
- Comprobar la existencia de una arista
- Verificar si un vértice es adyacente de otro

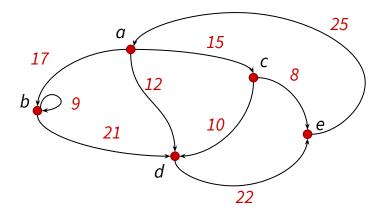
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### Listas de adyacencia





Acciones básicas

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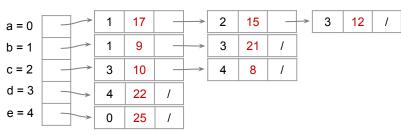
- Insertar arista
- Eliminar arista
- Insertar vértice
- Eliminar vértice
- Comprobar la existencia de una arista
- Verificar si un vértice es adyacente de otro
- Obtener la lista de vértices adyacentes

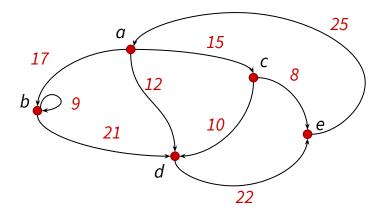
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#### Listas de adyacencia





Acciones básicas

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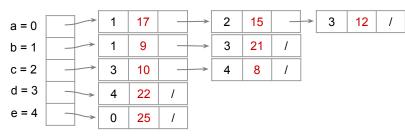
- Insertar arista
- Eliminar arista
- Insertar vértice
- Eliminar vértice
- Comprobar la existencia de una arista
- Verificar si un vértice es adyacente de otro
- Obtener la lista de vértices adyacentes
- Obtener el costo de recorrer una arista

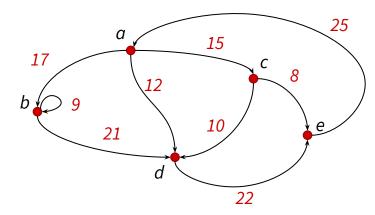
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#### Listas de adyacencia





Clasificación de gráfos

¿Cómo saber que si un grafo es ...?

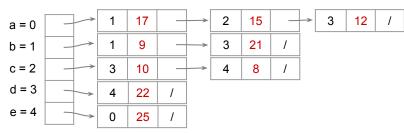
Grafo o digrafo

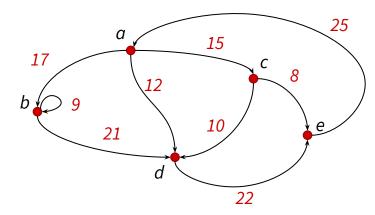
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## Listas de adyacencia





Clasificación de gráfos

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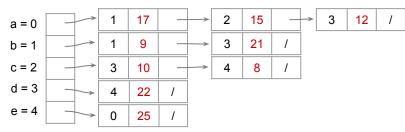
- Grafo o digrafo
- Grafo euleriano

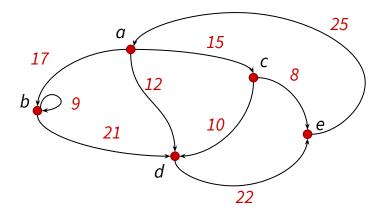
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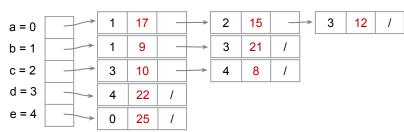
- Grafo o digrafo
- Grafo euleriano
  - Encontrar el ciclo euleriano

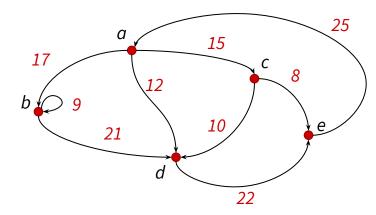
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Clasificación de gráfos

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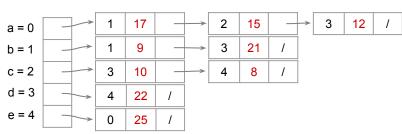
- Grafo o digrafo
- Grafo euleriano
  - Encontrar el ciclo euleriano
- Bipartito

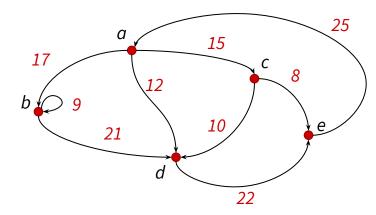
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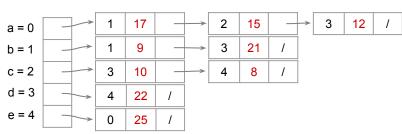
- Grafo o digrafo
- Grafo euleriano
  - Encontrar el ciclo euleriano
- Bipartito
- Conexo

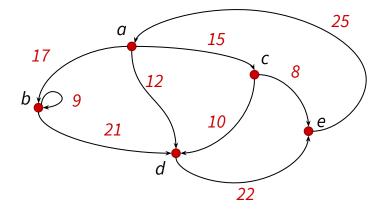
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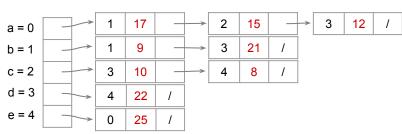
- Grafo o digrafo
- Grafo euleriano
  - Encontrar el ciclo euleriano
- Bipartito
- Conexo
- Orientado

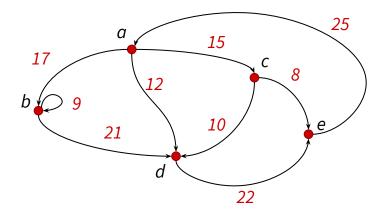
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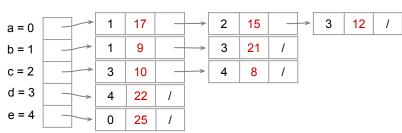
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- Bipartito
- Conexo
- Orientado
- Completo

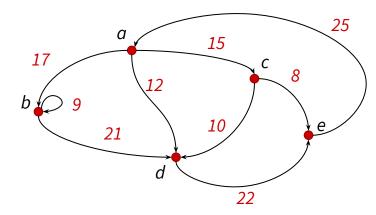
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### Listas de adyacencia





Clasificación de gráfos

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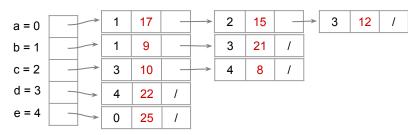
- Grafo o digrafo
- Grafo euleriano
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- Bipartito
- Conexo
- Orientado
- Completo
- Vacío

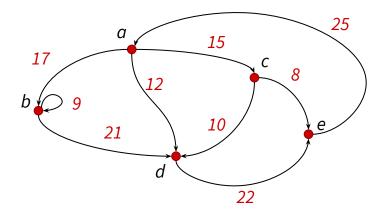
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Clasificación de gráfos

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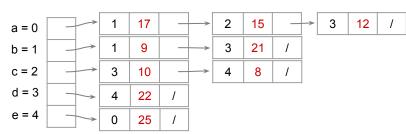
- Grafo o digrafo
- Grafo euleriano
  - o Encontrar el ciclo euleriano
- Bipartito
- Conexo
- Orientado
- Completo
- Vacío
- Denso o Disperso

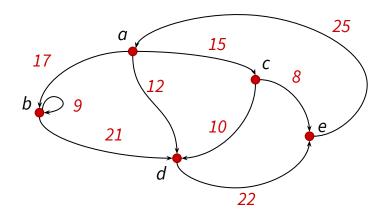
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### Listas de adyacencia





Clasificación de gráfos

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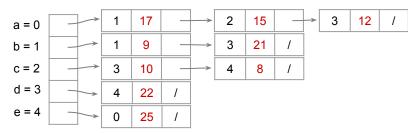
- Grafo o digrafo
- Grafo euleriano
  - o Encontrar el ciclo euleriano
- Bipartito
- Conexo
- Orientado
- Completo
- Vacío
- Denso o Disperso
- Simple o no simple

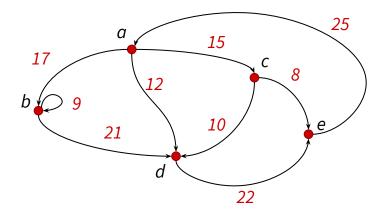
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### Listas de adyacencia





Recorrido en anchura (amplitud)

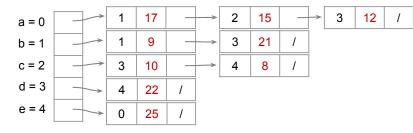
```
void graphBFP (graph *g, int from){
    if (!g) return;
    if (g->size <= from) return;</pre>
    int v[MAX];
    for (int i = 0; i < g > size; i++){
        v[i] = 0;
    queue *q = createQ();
    v[from] = 1;
    enqueueQ(q,from);
    while (notEmptyQ(q)){
        int e = dequeueQ(q);
        for (int i = 0; i < g > size; i++){
            if ((v[i]==0) \&\& (g->A[e][i] != 0)){
                v[i] = 1;
                enqueueQ(q,i);
        printf ("%s ", g->V[e]->value);
    printf ("\n");
```

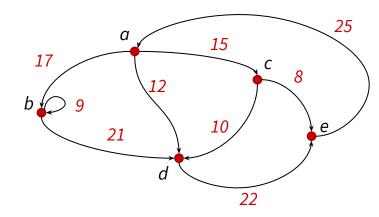
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#### Listas de adyacencia





Una posible implementación

```
typedef struct Graph graph;
typedef struct GraphVertex vertex;

typedef struct GraphVertex {
   int index;
   char *value;
} vertex;

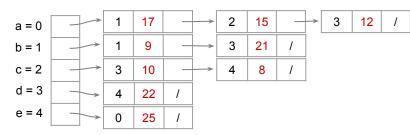
typedef struct Graph {
   vertex *V[MAX];
   int A[MAX][MAX];
   int size;
} graph;
```

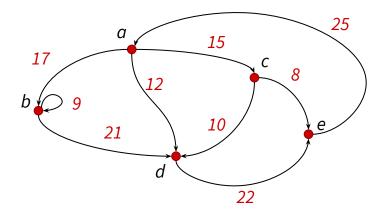
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#### Listas de adyacencia





Recorrido en profundidad

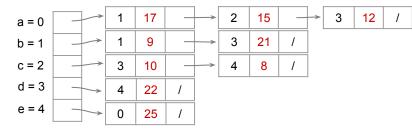
```
void graphDFP (graph *g, int from){
                                          //ACTUALIZADO
    if (!g) return;
    if (g->size <= from) return;</pre>
    int v[MAX];
    for (int i = 0; i < g > size; i++){
        v[i] = 0;
    stack *s = createS();
    push(&s,from);
    while (!isEmptyS(s)){
        int e = pop(&s);
        if (v[e] == 0){
            for (int i = g \rightarrow size - 1; i >= 0; --i){
                 if (g->A[e][i] != 0){
                     push(&s,i);
            v[e] = 1;
            printf ("%s ", g->V[e]->value);
    printf ("\n");
```

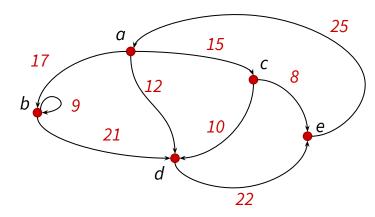
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### Listas de adyacencia





Árbol de cobertura en amplitud

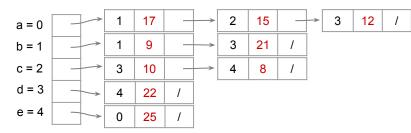
```
ntn *graphBFTree (graph *g, int from){
    if (!g) return NULL;
    if (g->size <= from) return NULL;</pre>
    ntn *root = createNTN(from);
    int v[MAX];
    for (int i = 0; i < g \rightarrow size; i++){
        v[i] = 0;
    queue *q = createQ();
    v[from] = 1;
    enqueueQ(q,from);
    while (notEmptyQ(q)){
        int e = dequeueQ(q);
        for (int i = 0; i < g > size; i++){
            if ((v[i]==0) \&\& (g->A[e][i] != 0)){
                 v[i] = 1;
                 insertSonValueOfNTN(root, e, i);
                 enqueueQ(q,i);
    return root;
```

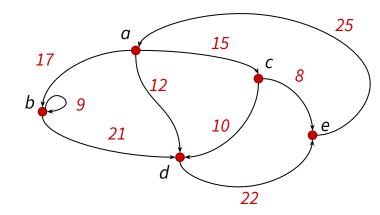
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#### Listas de adyacencia





Árbol de cobertura en profundidad

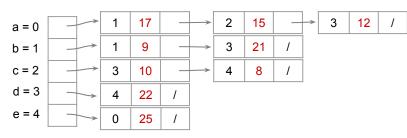
```
void graphDFTree (graph *g, ntn *root, int parent, int vertex, int 0
visited[]){
    if (!g) return;
    if (!root) return;
    if (visited[vertex] == 0){
        visited[vertex] = 1;
        insertSonValueOfNTN (root, parent, vertex);
        for (int i = 0; i < g \rightarrow size; i++){
             if (g->A[vertex][i]>0){
                 graphDFTree(g,root,vertex,i,visited);
}
ntn *graphDFTree (graph *g, int from){
    if (!g) return NULL;
    if (g->size <= from) return NULL;</pre>
    int v[MAX];
    for (int i = 0; i < g \rightarrow size; i++){
        v[i] = 0;
    ntn *root = createNTN(from);
    v[from] = 1;
    for (int i = 0; i < g \rightarrow size; i++){
        if (g->A[from][i]>0){
                 _graphDFTree(g,root,from,i,v);
    return root;
```

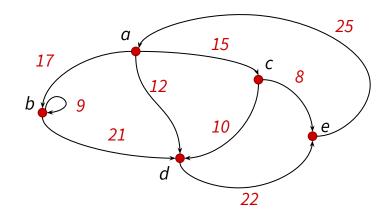
#### Matriz de adyacencia

Adjacency Matrix

```
a = 0
           17
               15
                    12
                        0
b = 1
                0
                    21
       0
                        0
c = 2
                0
                    10
                        8
d = 3
                        22
                0
                    0
e = 4
      25
           0
                0
                    0
                         0
```

### Listas de adyacencia





KRUSKAL

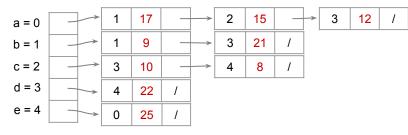
```
graph *kruskal(graph *g){
    if (!g) return NULL;
    graph *k = createGraph();
    int v[MAX];
    for (int i = 0; i < g > size; i++){
        V[i] = 0;
        graphAddNewVertex (k, strdup(g->V[i]->value));
    int minFrom, minTo;
    while (count < (g->size-1)){
        int minCost = INF;
        for (int i = 0; i < g \rightarrow size; i++){
            for (int j = \frac{1}{2}; j < g > size; j++){
                 if ((v[j] == 0)&&(graphCost(g,i,j) < minCost)){
                     minCost = graphCost(g,i,j);
                     minFrom = i;
                     minTo = j;
        graphSetArc(k, minFrom, minTo, minCost);
        graphSetArc(k, minTo, minFrom, minCost);
        v[minFrom] = 1;
        v[minTo] = 1;
    return k;
```

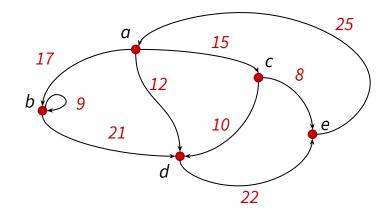
#### Matriz de adyacencia

Adjacency Matrix

	0	1	2	3	4
a = 0	0	17	15	12	0
b = 1	0	9	0	21	0
c = 2	0	0	0	10	8
d = 3	0	0	0	0	22
e = 4	25	0	0	0	0

#### Listas de adyacencia





FLOYD

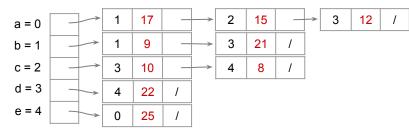
```
typedef struct FloydRes fres;
typedef struct FloydRes {
    int D[MAX][MAX];
    int C[MAX][MAX];
    int count;
} fres;
void floyd(graph *g, fres *r) {
    r->count = g->size;
    for (int i = 0; i < g \rightarrow size; i++) {
         for (int j = 0; j < g \rightarrow size; j++) {
              r\rightarrow D[i][j] = i;
              r->C[i][j] = graphCost(g, i, j);
    for (int k = 0; k < g->size; k++) {
         for (int i = 0; i < g \rightarrow size; i++) {
              for (int j = 0; j < g \rightarrow size; j++) {
                  int cost = (r->C[i][k] + r->C[k][j]);
                  if ((i!=j)&&(cost < r->C[i][j])){
                       r\rightarrow D[i][j] = r\rightarrow D[k][j];
                       r->C[i][j] = cost;
```

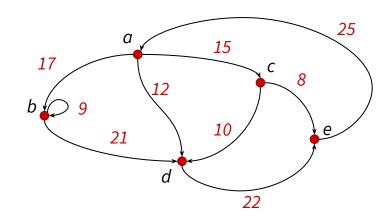
#### Matriz de adyacencia

Adjacency Matrix

	0	1	2	3	4
a = 0	0	17	15	12	0
b = 1	0	9	0	21	0
c = 2	0	0	0	10	8
d = 3	0	0	0	0	22
e = 4	25	0	0	0	0

#### Listas de adyacencia





# **Unidad 6: Grafos**

Algoritmos y Estructuras de Datos

Operaciones Tipos Algoritmos