

Lecture 6:

Electromagnetic Principles and Actuators

EE3010: Electrical Devices and Machines

School of Electrical and Electronic Engineering

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Learning Objectives

By the end of this lecture, you should be able to:

- ❖ Describe the principles of electromechanical energy conversion and the operations of electromechanical devices, i.e., convert electrical energy into mechanical energy and vice versa.
- ❖ Apply the Law of Conservation of Energy to establish the energy balance equation.
- ❖ Employ differential calculus to derive the incremental analysis equation.
- ❖ Apply Constant Flux and Constant Current methods to evaluate the magnetic force with respect to the magnetic field energy.

- ❖ Electromechanical devices (e.g., machines) convert electrical energy into mechanical energy and vice versa. Most of these devices utilise magnetic field as a medium.
- ❖ Conservation of energy has to be satisfied by all these processes.

$$W_i = W_o + W_f + W_\ell$$

where

W_i is the input (electrical) energy,

W_o is the output (mechanical) energy,

W_f is the field or stored energy, and

W_ℓ is the energy lost in the system.

- ❖ The flow of energy in the process is shown in Fig. 51. This process is reversible except for the losses.
- ❖ Ignoring losses, the energy balance equation is reduced to

$$W_i = W_o + W_f$$

- ❖ Incremental analysis between two states gives

$$dW_i = dW_o + dW_f$$

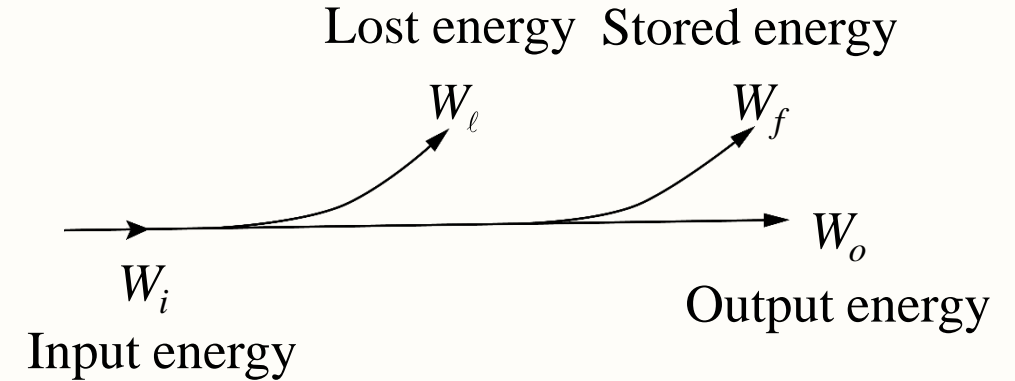


Fig. 51. Energy flow diagram.

- ❖ Consider an electromagnetic system with one fixed and one movable part separated by a gap x as shown in Fig. 52.
- ❖ If the total reluctance is \mathcal{R}_1 , the flux in the structure for an input current i is given by

$$\phi = \frac{Ni}{\mathcal{R}_1}$$

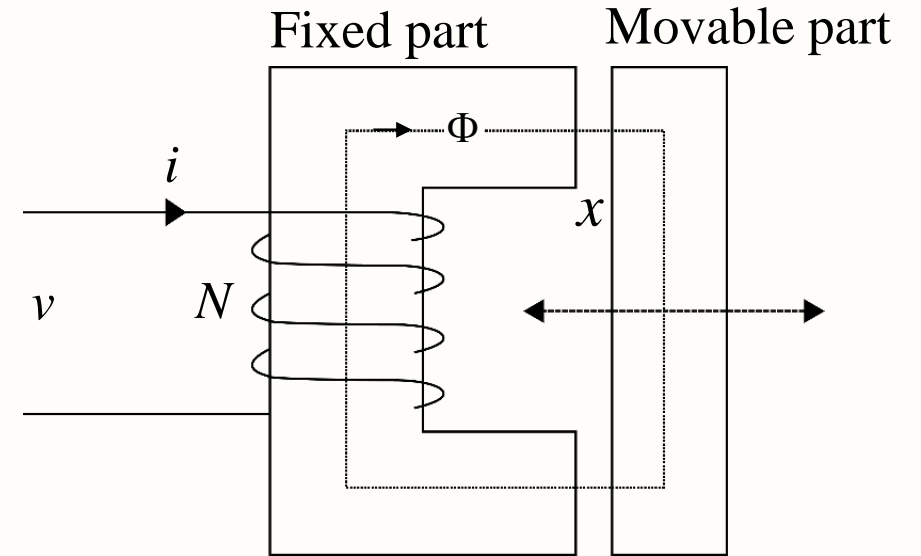


Fig. 52. Electromagnetic system.

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- ❖ The relationship between Ni and ϕ is a straight line (1) with slope $1/\mathcal{R}_1$ as shown in Fig. 53. If the system is operating at point p_1 with input current i_1 and flux ϕ_1 , the field energy is

$$W_f = \frac{1}{2} Ni_1 \phi_1$$

which is the area indicated in the diagram.

- ❖ Let the force experienced by the movable part at a gap distance of x be F_m , and it moves towards the fixed part by an incremental distance of dx . The incremental energy output is $dW_o = F_m dx$.

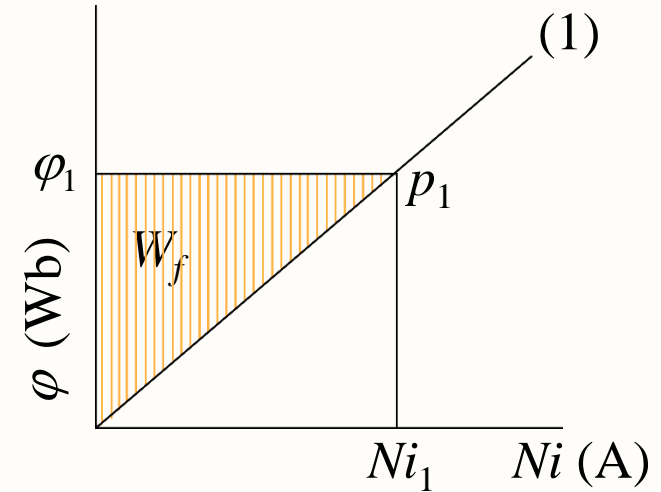


Fig. 53. Field energy diagram.

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- ❖ In this process, since the air gap has decreased, the reluctance should be reduced to, say \mathcal{R}_2 , ($\mathcal{R}_2 < \mathcal{R}_1$) and the relationship between the flux and the mmf is given by

$$\phi = \frac{Ni}{\mathcal{R}_2}$$

which is a straight line with slope $1/\mathcal{R}_2$ and can be represented by the line (2) in Fig. 54.

- ❖ The operating point has to move from p_1 to somewhere in line (2). Consequently, there will be changes in various energy components: input energy and stored energy.

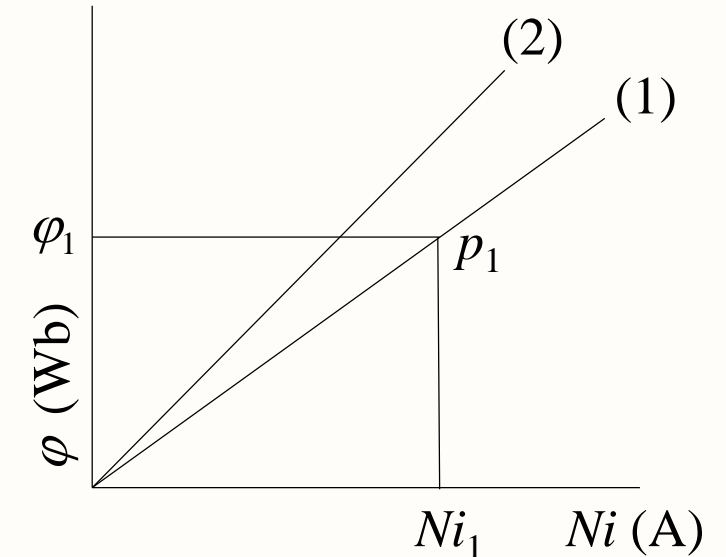


Fig. 54. Field energy diagram.

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- ❖ Incremental analysis of the various energy components in this process gives

$$dW_i = dW_o + dW_f \Rightarrow dW_o = dW_i - dW_f$$

$$\Rightarrow F_m dx = dW_i - dW_f$$

- ❖ This relationship can be used to derive the expression for the force F_m by evaluating the energy components dW_i and dW_f corresponding to the new operating point in line (2). This will be done for two different processes.

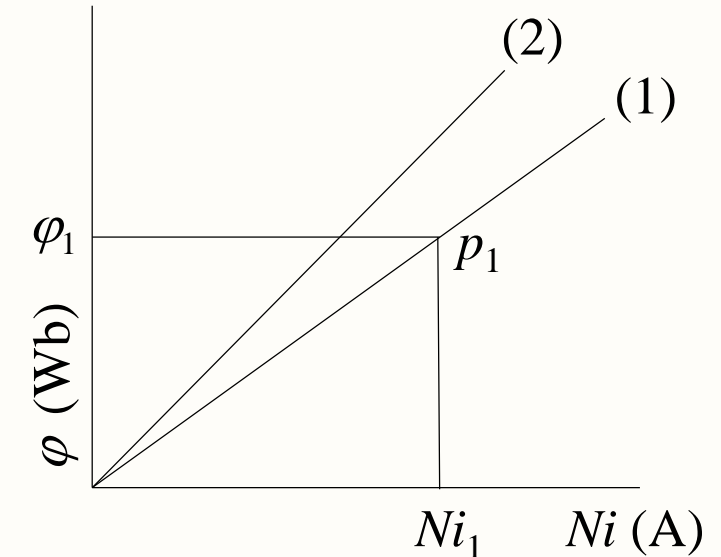


Fig. 54. Field energy diagram.

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Method 1 – Constant Flux

- ❖ If the flux ϕ is held constant while the movable part moves a distance dx under the force F_m , the operating point changes from p_1 to p_2 (see Fig. 55) Then,

$$dW_i = id\lambda = Nid\phi = Ni(\phi_2 - \phi_1) = 0$$

($\phi_2 = \phi_1$ since the flux is held constant.)

Therefore, $F_m dx = dW_i - dW_f = -dW_f$

$$\Rightarrow F_m = -\frac{dW_f}{dx}$$

- ❖ The force developed is proportional to the rate of decrement of the stored energy.

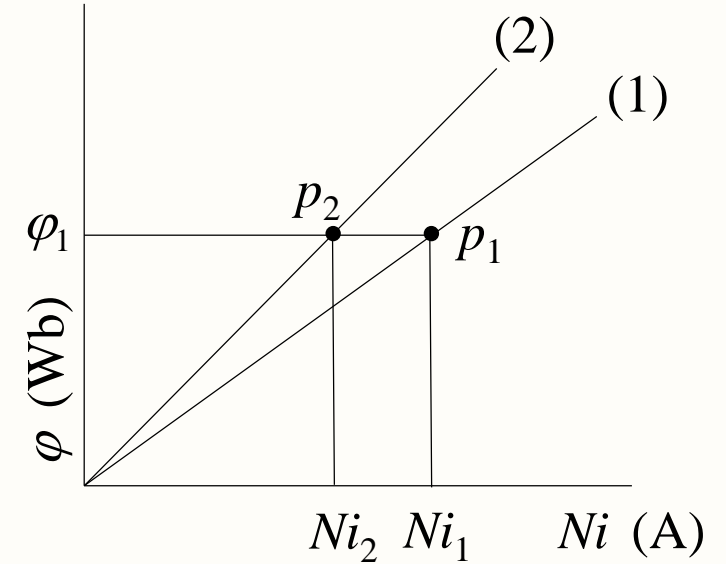


Fig. 55. Field energy diagram.

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Method 2 – Constant Current

- ❖ If the input current is held constant during the process, the operating point moves from p_1 to p_3 and the flux changes from φ_1 to φ_2 in Fig. 56, so that

$$d\varphi = \varphi_2 - \varphi_1$$

Under this condition,

$$\text{a) } dW_i = id\lambda = Ni_1 d\varphi = Ni_1 (\varphi_2 - \varphi_1)$$

$$\begin{aligned} \text{b) } dW_f &= W_{f2} - W_{f1} = \frac{1}{2} Ni_1 \varphi_2 - \frac{1}{2} Ni_1 \varphi_1 \\ &= \frac{1}{2} Ni_1 (\varphi_2 - \varphi_1) = \frac{1}{2} dW_i \end{aligned}$$

$$\text{Thus, } dW_i = 2dW_f$$

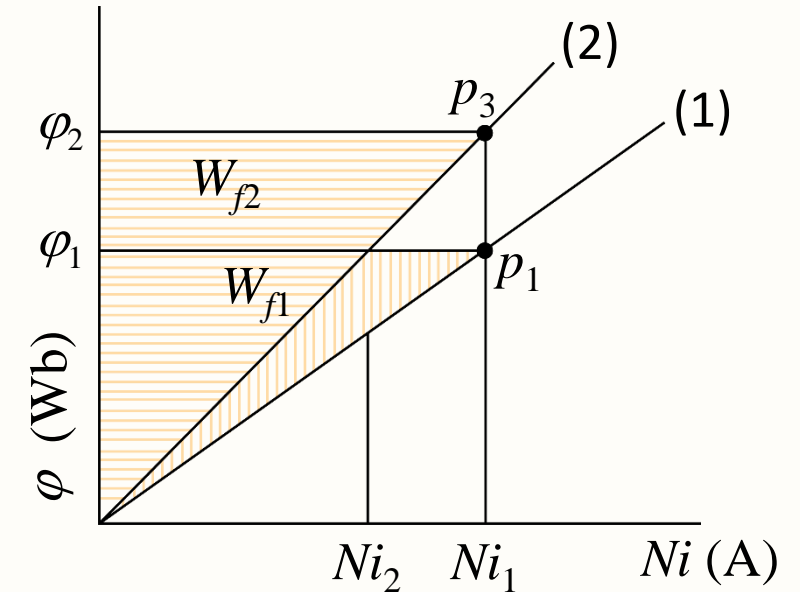


Fig. 56. Field energy diagram.

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Therefore,

$$F_m dx = dW_i - dW_f = 2dW_f - dW_f = dW_f$$

$$\text{and, } F_m = \frac{dW_f}{dx}$$

Thus, the force developed is proportional to the rate of increment of the stored energy.

Constant Flux and Constant Current

- ❖ In both the cases, the evaluation of force F_m requires the expression for the magnetic field energy W_f , which may be a function of either
 - flux ϕ and gap distance x , or
 - current i and gap distance x .

- ❖ When the flux is held constant, $F_m = -\frac{dW_f}{dx} = -\frac{\partial W_f(\phi, x)}{\partial x}$

Since $W_f = \frac{1}{2}\phi^2 \mathcal{R}$, this approach usually takes the form,

$$F_m = -\frac{dW_f}{dx} = -\frac{\partial W_f(\phi, x)}{\partial x} = -\frac{\partial \left[\frac{1}{2}\phi^2 \mathcal{R}(x) \right]}{\partial x} = -\frac{1}{2}\phi^2 \frac{d\mathcal{R}(x)}{dx}$$

❖ When the current is held constant,

$$F_m = \frac{dW_f}{dx} = \frac{\partial W_f(i, x)}{\partial x}$$

Since $W_f = \frac{1}{2}i^2L$, this approach usually takes the form,

$$F_m = \frac{dW_f}{dx} = \frac{\partial W_f(i, x)}{\partial x} = \frac{\partial \left[\frac{1}{2}i^2L(x) \right]}{\partial x} = -\frac{1}{2}i^2 \frac{dL(x)}{dx}$$

Example 9

Determine the minimum amount of current required to keep the magnetic plate at a distance of 1 mm from the pole faces of the fixed electromagnet having 1000 turns when the force exerted by the spring is 100 N as shown in Fig. 57. Each pole face cross-sectional area is 9 cm^2 . Ignore the reluctances of the core material and magnetic plate.

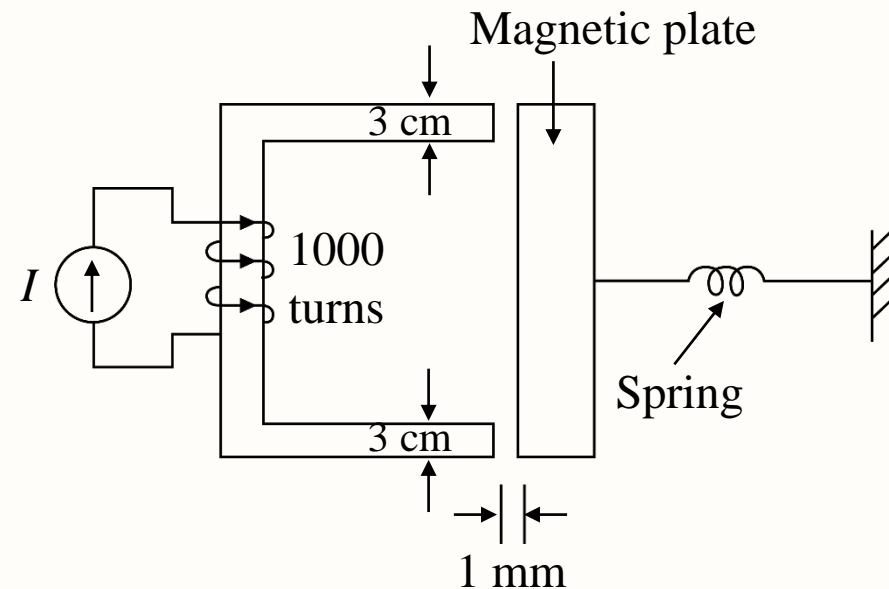


Fig. 57. Electromagnet System.

(Solutions →)

Example 9 – Solutions

The magnetic equivalent circuit can be drawn as shown in Fig. 58. For a gap x , the total reluctance is

$$\mathcal{R}_{eq} = \frac{2x}{4\pi \times 10^{-7} \times 9 \times 10^4} = 1.768 \times 10^9 x \text{ H}^{-1}$$

$$L = \frac{N^2}{\mathcal{R}_{eq}} = \frac{1000^2}{1.768 \times 10^9 x} = \frac{565.5 \times 10^{-6}}{x} \text{ H}$$

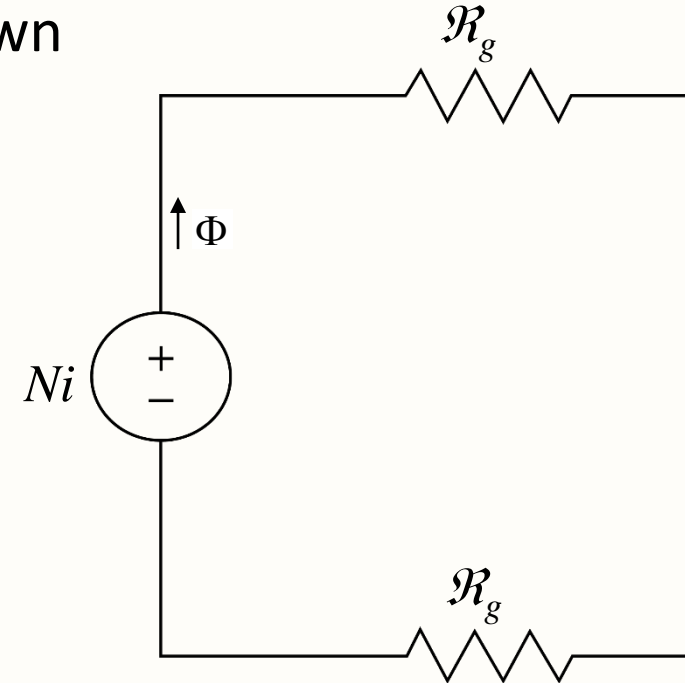


Fig. 58. Magnetic equivalent circuit.

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Example 9 – Solutions

a) If the flux is held constant, the field energy can be expressed as

$$W_f(\varphi, x) = \frac{1}{2} \varphi^2 \mathcal{R}(x)$$

$$\text{Then, } F_m = -\frac{dW_f}{dx} = -\frac{\partial \left[\frac{1}{2} \varphi^2 \mathcal{R}(x) \right]}{\partial x} = -\frac{1}{2} \varphi^2 \frac{d\mathcal{R}(x)}{dx} = -\frac{1}{2} \varphi^2 \times 1.768 \times 10^9$$

$$\Rightarrow \frac{1}{2} \varphi^2 \times 1.768 \times 10^9 = 100 \text{ N, at } x = 1 \text{ mm}$$

$$\Rightarrow \varphi = 0.3363 \times 10^{-3} \text{ Wb, at } x = 1 \text{ mm}$$

$$\text{Also, } \varphi = \frac{NI}{\mathcal{R}} = \frac{1000I}{1.768 \times 10^9 \times 10^{-3}}, \text{ at } x = 1 \text{ mm}$$

$$\text{Therefore, } \frac{1000I}{1.768 \times 10^9 \times 10^{-3}} = 0.3363 \times 10^{-3} \Rightarrow I = 0.595 \text{ A}$$

Example 9 – Solutions

b) If the current is held constant, then

$$W_f(I, x) = \frac{1}{2} I^2 L(x)$$

so that

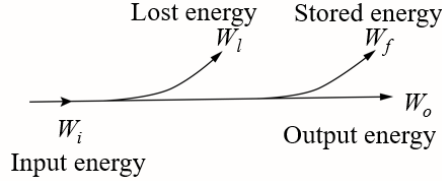
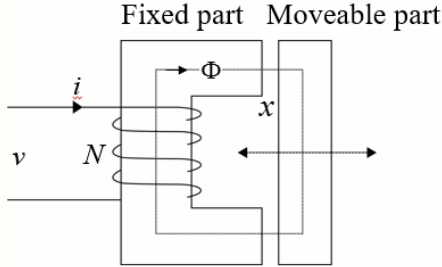
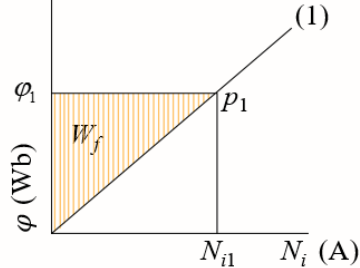
$$F_m = \frac{dW_f}{dx} = \frac{\partial \left[\frac{1}{2} I^2 L(x) \right]}{\partial x} = \frac{1}{2} I^2 \frac{dL(x)}{dx} = -\frac{1}{2} I^2 \times \frac{565.5 \times 10^{-6}}{x^2} \text{ N}$$

$$\Rightarrow \frac{1}{2} I^2 \times \frac{565.5 \times 10^{-6}}{x^2} = 100 \text{ N, at } x = 1 \text{ mm}$$

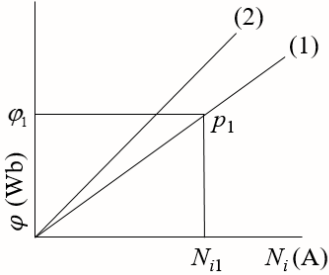
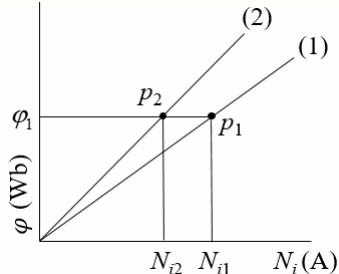
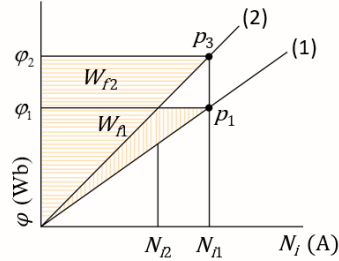
$$\Rightarrow \frac{1}{2} I^2 \times \frac{565.5 \times 10^{-6}}{10^{-6}} = 100 \text{ N} \Rightarrow I = 0.595 \text{ A}$$

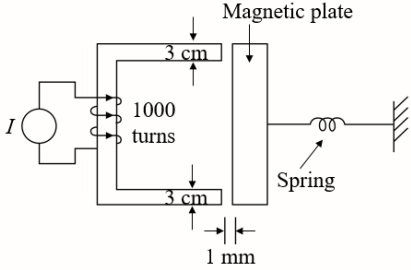
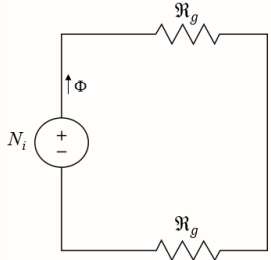
In this lecture, you have learnt:

- ❖ The principles of electromechanical energy conversion and the operations of electromechanical devices, e.g., convert electrical energy into mechanical energy.
- ❖ The Law of Conservation of Energy to establish the energy balance equation.
- ❖ Constant Flux and Constant Current methods to evaluate the magnetic force with respect to the magnetic field energy.

No.	Slide No.	Image	Reference
1	5	 <p>Diagram illustrating energy flow: Input energy W_i splits into Lost energy W_l and Stored energy W_f, which then combine to form Output energy W_o.</p>	Reprinted from <i>Electric Machinery and Transformers, 3rd ed.</i> , (p. 140), by B. S. Guru, & H. R. Hiziroglu, 2001, New York, NY: Oxford University Press. Copyright 2001 by Oxford University Press.
2	6	 <p>Diagram of a magnetic circuit with a Fixed part and a Moveable part. A coil with N turns carries current i. The magnetic flux is Φ and the displacement is x.</p>	Reprinted from <i>AC Circuits and Machines</i> , (p. 121), by G. B. Shrestha, & M. H. Haque, 2006, Singapore: Pearson Education South Asia Pte Ltd. Copyright 2006 by Pearson Education South Asia Pte Ltd. Reprinted with permission.
3	7	 <p>Graph showing magnetic flux ϕ (Wb) versus current N_i (A). The linear relationship (1) is shown, and the area under the curve represents the stored energy W_f.</p>	Reprinted from <i>AC Circuits and Machines</i> , (p. 121), by G. B. Shrestha, & M. H. Haque, 2006, Singapore: Pearson Education South Asia Pte Ltd. Copyright 2006 by Pearson Education South Asia Pte Ltd. Reprinted with permission.

References

No.	Slide No.	Image	Reference
4	8 and 9		Reprinted from <i>AC Circuits and Machines</i> , (p. 122), by G. B. Shrestha, & M. H. Haque, 2006, Singapore: Pearson Education South Asia Pte Ltd. Copyright 2006 by Pearson Education South Asia Pte Ltd. Reprinted with permission.
5	10		Reprinted from <i>AC Circuits and Machines</i> , (p. 123), by G. B. Shrestha, & M. H. Haque, 2006, Singapore: Pearson Education South Asia Pte Ltd. Copyright 2006 by Pearson Education South Asia Pte Ltd. Reprinted with permission.
6	11		Reprinted from <i>AC Circuits and Machines</i> , (p. 124), by G. B. Shrestha, & M. H. Haque, 2006, Singapore: Pearson Education South Asia Pte Ltd. Copyright 2006 by Pearson Education South Asia Pte Ltd. Reprinted with permission.

No.	Slide No.	Image	Reference
7	15	 <p>The diagram shows a magnetic circuit. On the left, a coil with 1000 turns is wound around a vertical core. A current I flows into the coil. The core has a vertical section of 1000 turns and two horizontal sections, each 3 cm long. The gap between the horizontal sections is 1 mm. A magnetic plate is attached to the right end of the core, and a spring is connected to it. The spring is shown in a compressed state, indicated by a double-headed arrow.</p>	Reprinted from <i>Electric Machinery and Transformers, 3rd ed.</i> , (p. 140), by B. S. Guru, & H. R. Hiziroglu, 2001, New York, NY: Oxford University Press. Copyright 2001 by Oxford University Press.
8	16	 <p>The diagram shows a circuit with a voltage source N_i on the left. The source is represented by a circle with a plus sign at the top and a minus sign at the bottom. An upward arrow labeled Φ indicates the magnetic flux. The circuit is completed by two resistors, both labeled R_g, connected in series on the right.</p>	Reprinted from <i>AC Circuits and Machines</i> , (p. 126), by G. B. Shrestha, & M. H. Haque, 2006, Singapore: Pearson Education South Asia Pte Ltd. Copyright 2006 by Pearson Education South Asia Pte Ltd. Reprinted with permission.