

NANYANG TECHNOLOGICAL UNIVERSITY

SEMESTER 1 EXAMINATION 2016-2017

EE3010 – ELECTRICAL DEVICES AND MACHINES

November / December 2016

Time Allowed: 2 hours

INSTRUCTIONS

1. This paper contains 4 questions and comprises 6 pages.
2. Answer ALL questions.
3. All questions carry equal marks.
4. This is a closed-book examination.
5. Unless specifically stated, all symbols have their usual meanings.

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1. (a) A magnetic circuit with the specified dimensions is as shown in Figure 1 on page 2. The center limb has a winding of 500 turns and there are air gaps in the left and right limbs as shown. The mean lengths of the various magnetic sections are $l_1 = 100$ cm, $l_2 = 79.85$ cm, $l_3 = 120$ cm and $l_g = 1.5$ mm. The center limb has a cross-sectional area of 32 cm^2 and each of the side limbs has a cross-sectional area of 16 cm^2 . The magnetization curve for the material is given by the following:

H (At/m)	100	220	260	300	320
B (T)	0.1	0.2	0.25	0.3	0.35

- (i) Let ϕ_c be the flux in the center limb and ϕ_g be the flux in the air gaps. Using the magnetic equivalent circuit of Figure 1, determine the exciting current I required to produce a flux of 0.4 mWb in each air gap. You may neglect leakage and fringing in your calculations. The permeability of free space μ_0 is $4\pi \times 10^{-7} \text{ H/m}$.

(12 Marks)

Note: Question No. 1 continues on page 2.

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- (ii) Determine the energy stored in the air gaps and in the core, respectively. (5 Marks)

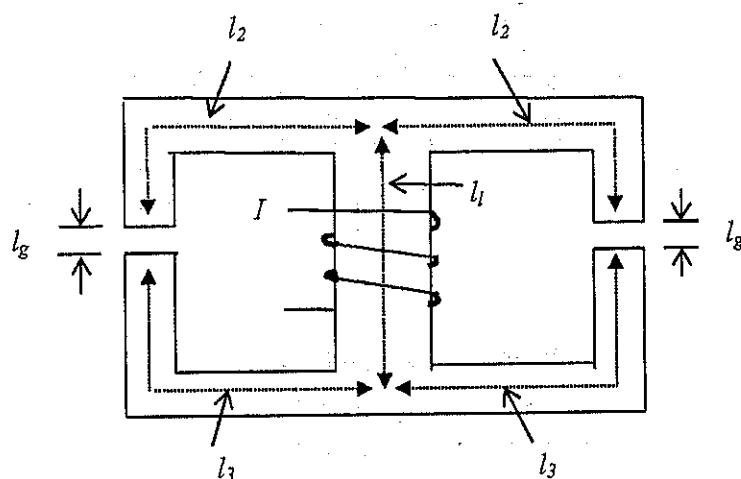


Figure 1

- (b) A magnetic circuit is as shown in Figure 2, where f_s is the force exerted on the movable part. Each of the fixed and movable parts has a cross-sectional area of 12 cm^2 . The fixed part has a winding of 200 turns. Determine the supply voltage V_s required to keep the movable part at a distance of $x = 1.5 \text{ mm}$ from the fixed part if $R_s = 25 \Omega$ and the magnetic force acting on the movable part is $f_s = 167 \text{ N}$. Also, determine the energy stored in the magnetic field for $x = 1.5 \text{ mm}$. The permeability of free space μ_0 is $4\pi \times 10^{-7} \text{ H/m}$. You may neglect the reluctances of the fixed and moveable parts in your calculations.

(8 Marks)

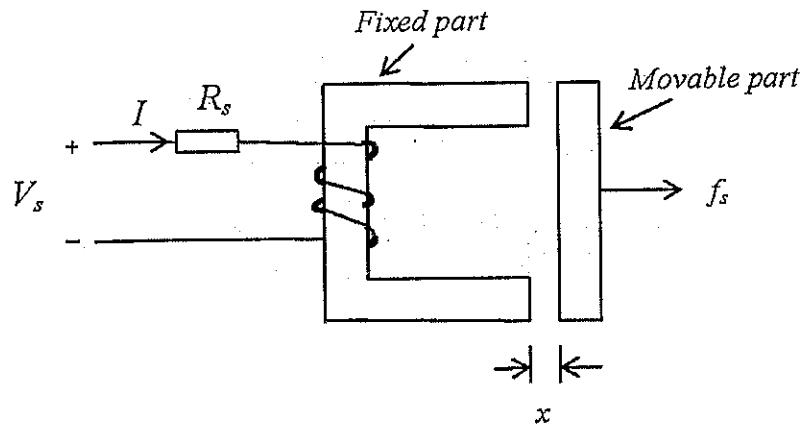


Figure 2

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2. (a) Consider a 10-kVA, 440/220-V, 50-Hz single-phase transformer. The open-circuit test measurement was performed on the low-voltage side of the transformer and the short-circuit test measurement was performed on the high-voltage side of the transformer. The tests gave the following results:

Open-circuit test:

$$V_{oc} = 220 \text{ V}, I_{oc} = 1.5 \text{ A}, P_{oc} = 80 \text{ W}.$$

Short-circuit test:

$$V_{sc} = 15 \text{ V}, I_{sc} = 22.727 \text{ A}, P_{sc} = 80 \text{ W}.$$

Find the parameters of the approximate equivalent circuit referred to the low-voltage side. Using the approximate equivalent circuit obtained, determine the (a) voltage regulation and (b) efficiency of the transformer at full-load and 0.85 power factor lagging with rated voltage across the load.

(17 Marks)

- (b) A 440/220-V, 20-kVA, 50-Hz transformer is connected as an autotransformer to give 440/660 V. Calculate its kVA rating and the currents in its windings as well as the efficiency at full-load, 0.8 power factor lagging if the two-winding transformer has an efficiency of 98% at full-load, 0.8 power factor lagging.

(8 Marks)

3. (a) A 3-phase, 460-V, 60-Hz, 4-pole wye-connected induction motor draws a line current of 90 A at a lagging power factor of 0.8 from the supply when running at a slip of 2.5%. The stator resistance per phase is 0.07Ω and the rotational losses are 2800 W. Determine

- (i) the speed at which the motor is running.
- (ii) the torque developed by the motor.
- (iii) the efficiency of the motor.

(6 Marks)

Note: Question No. 3 continues on page 4.

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- (b) A 3-phase, 2300-V, 60-Hz, 4-pole, wye-connected induction motor is tested with the following results:

No-load test : $V_{line} = 2300 \text{ V}$, $I_{line} = 7.7 \text{ A}$, $P_{in} = 2870 \text{ W}$

Locked-rotor test : $V_{line} = 768 \text{ V}$, $I_{line} = 50.3 \text{ A}$, $P_{in} = 18.2 \text{ kW}$

DC test : $V_{DC} = 23.2 \text{ V}$, $I_{DC} = 10.3 \text{ A}$

- (i) Calculate the rotational losses of the motor.

(3 Marks)

- (ii) Obtain the parameters of the induction motor and draw its single-phase equivalent circuit referred to the stator. Assume that the stator leakage reactance and the rotor leakage reactance referred to the stator are equal in magnitude.

(9 Marks)

- (c) A 3-phase, 230-V, 60-Hz, 6-pole, wye-connected induction motor develops its maximum torque at a slip of 15% when operated at rated voltage and frequency. Assume that the stator resistance R_1 is negligible. Determine the speed at which maximum torque is developed if the motor is operated at rated voltage and 50-Hz frequency. (Hint: You may use the Thevenin's equivalent circuit.)

(7 Marks)

4. (a) The armature and field resistances of a dc machine are 0.15Ω and 150Ω , respectively. The effects of armature reaction can be neglected. The magnetization curve of the machine obtained at a speed of 1700 rpm is shown in Figure 3 on page 6. Consider the following cases:

- (i) The machine is driven at 1700 rpm and is operated as a separately-excited dc generator. If the generator is supplying a load with an armature current of 100 A, determine its output power for a constant field current of 0.5 A.

(4 Marks)

- (ii) The machine is driven at 1500 rpm and is operated as a separately-excited dc generator. If the generator is supplying a load with an armature current of 100 A, determine its output power for a constant field current of 1 A.

(4 Marks)

Note: Question No. 4 continues on page 5.

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- (iii) The machine is reconnected as a shunt dc generator and is driven at 1700 rpm. An external resistor $R_{ex} = 20 \Omega$ is connected in series with the field winding. If the generator is delivering an armature current of 200 A, determine its terminal voltage. (5 Marks)
- (b) A 240-V dc shunt motor has an armature resistance of 0.75Ω . At full load, the motor rotates at 1200 rpm, draws a line current of 7 A from the supply and the field current is 1 A. The rotational losses and armature reaction in the motor are negligible. Assume that the motor is operating in the linear part of the magnetization curve. Consider the following cases:
- (i) If the field current is reduced to 0.7 A due to the addition of a series resistance in the field circuit, determine the speed of the motor when it is running with 60% full load torque. (6 Marks)
 - (ii) Determine the speed of the motor when driving a load whose torque varies directly as the speed (i.e., $T_L \propto n_m$) and the field current is reduced to 0.5 A due to the addition of a series resistance in the field circuit. (6 Marks)

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Magnetization curve at a speed of 1700 rpm

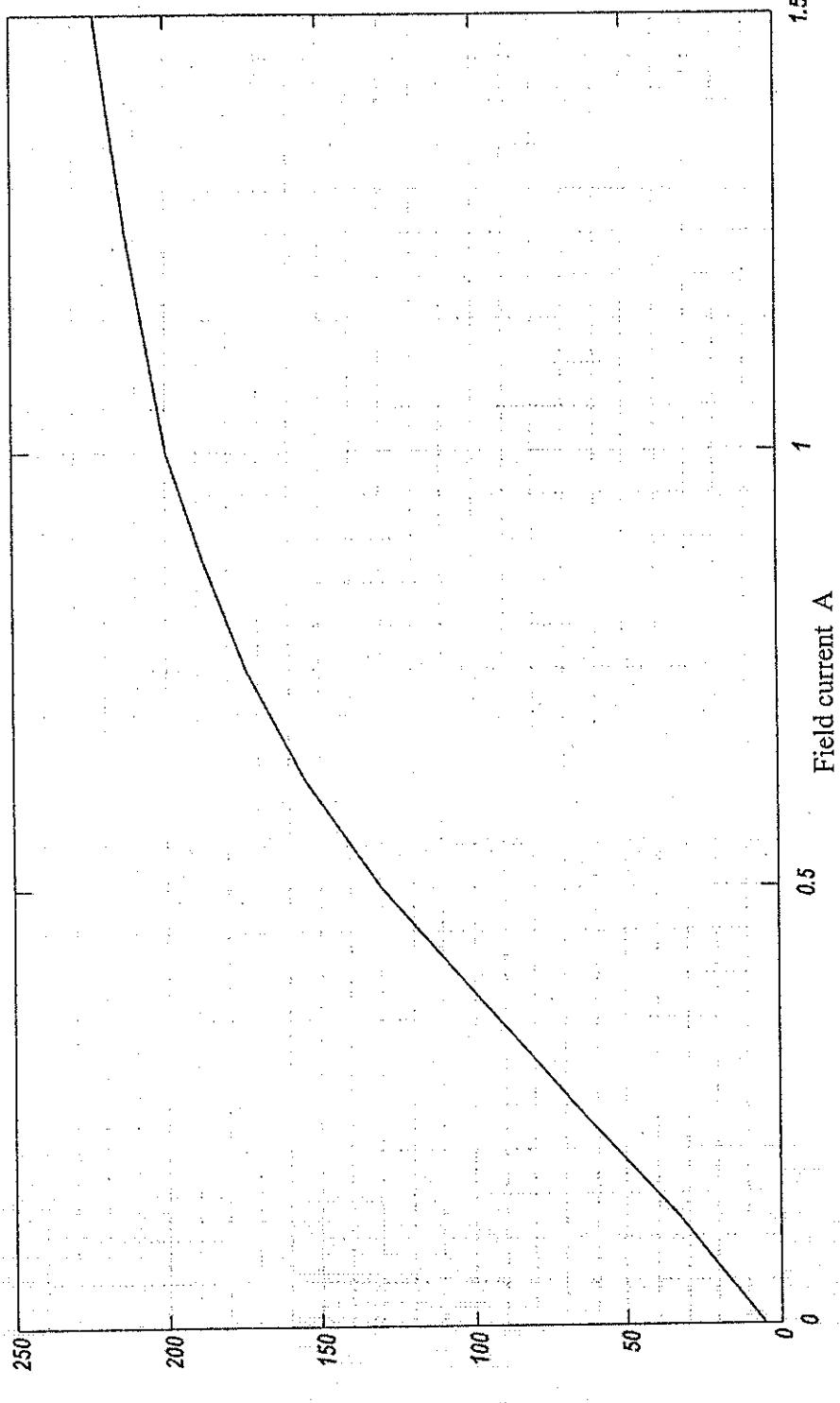


Figure 3

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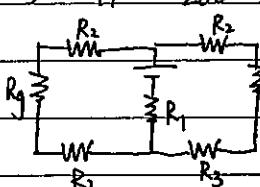
$$l_1 = 1\text{ m}, l_2 = 0.7985\text{ m}, l_3 = 1.2\text{ m}, l_g = 1.5 \times 10^{-3}\text{ m}$$

$$A_c = 32 \times 10^{-4}\text{ m}^2, A_s = 16 \times 10^{-4}\text{ m}^2$$

$$i) \Phi_g = 0.4 \times 10^{-3}\text{ Wb}, B_g = \frac{0.4 \times 10^{-3}}{16 \times 10^{-4}} = 0.25$$

$$\Phi_c = 0.4 \times 10^{-3} \times 2 = 0.8 \times 10^{-3}\text{ Wb}, B_c = \frac{0.8 \times 10^{-3}}{32 \times 10^{-4}} = 0.25$$

$$\mu = \frac{B}{H} = \frac{0.25}{260}$$



$$R_1 = \frac{l_1}{\mu_0 A_c} = \frac{1}{4 \pi \times 10^{-7} \times 32 \times 10^{-4}} = 325000 \text{ At/Wb}$$

$$R_2 = \frac{l_2}{\mu_0 A_s} = \frac{0.7985}{4 \pi \times 10^{-7} \times 16 \times 10^{-4}} = 519025 \text{ At/Wb}$$

$$R_3 = \frac{l_3}{\mu_0 A_s} = \frac{1.2}{4 \pi \times 10^{-7} \times 16 \times 10^{-4}} = 780000 \text{ At/Wb}$$

$$R_g = \frac{l_g}{\mu_0 A_s} = \frac{1.5 \times 10^{-3}}{4 \pi \times 10^{-7} \times 16 \times 10^{-4}} = 746039 \text{ At/Wb}$$

$$\text{mmf}_{\text{total}} = R_1 \cdot \Phi_g + (R_2 + R_3 + R_g) \Phi_g \\ = 325000 \times 0.8 \times 10^{-3} + (519025 + 780000 + 746039) \times 0.4 \times 10^{-3} \\ = 1078.0256 \text{ At}$$

$$I = \frac{\text{mmf}}{N} = \frac{1078.0256}{500} = 2.156 \text{ A}$$

$$ii) E_g = \frac{1}{2} \times R_g \cdot \Phi_g^2 \times 2 = 746039 \times (0.4 \times 10^{-3})^2 \\ = 0.1194 \text{ J}$$

$$E_c = \frac{1}{2} (R_2 + R_3) \cdot \Phi_g^2 \times 2 + \frac{1}{2} R_1 \cdot \Phi_g^2 \\ = (519025 + 780000) \times (0.4 \times 10^{-3})^2 + \frac{1}{2} \times 325000 \times (0.8 \times 10^{-3})^2 \\ = 0.3118 \text{ J}$$

$$b) R = \frac{2x}{\mu_0 \cdot A} = \frac{2x}{4 \pi \times 10^{-7} \times 12 \times 10^{-4}} \\ = 1326291192 \text{ X}$$

$$x = 1.5 \times 10^{-3} \text{ m} \quad |f| = \left| \frac{df}{dx} \right| \\ R = 1989437 \text{ At/Wb} \quad 167 = \frac{1}{2} I^2 \cdot \left| \frac{d}{dx} \right| \frac{200^2}{1326291192} \\ 167 \times 2 = I^2 \cdot \frac{40000}{1326291192} \left| \frac{d}{dx} \right| \frac{1}{x} \Big|_{x=1.5 \times 10^{-3}}$$

$$I = 4.992 \text{ A}$$

$$R = 1989437 \text{ At/Wb} \text{ when } x = 1.5 \times 10^{-3} \text{ m.}$$

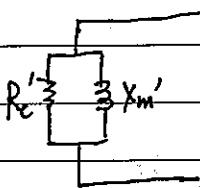
$$W = \frac{1}{2} L I^2$$

$$= \frac{1}{2} \frac{N^2}{R} \cdot I^2$$

$$= \frac{1}{2} \times \frac{200^2}{1989437} \times 4.992^2$$

$$= 0.2505 \text{ J}$$

7(a)



$$PF = \frac{P_{oc}}{V_{oc} \cdot I_{oc}} = \frac{80}{220 \times 1.5} = 0.2424$$

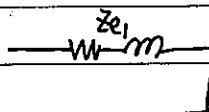
$$\theta = \cos^{-1} 0.2424 = 75.97^\circ$$

$$I_{c'} = 1.5 \times \cos 75.97^\circ = 0.3636$$

$$I_{m'} = 1.5 \times \sin 75.97^\circ = 1.4553$$

$$R_c' = \frac{220}{0.3636} = 605.06 \Omega$$

$$X_m' = \frac{220}{1.4553} = 151.17 \Omega$$



$$Z_{e1} = \frac{V_{sc}}{I_{sc}} = \frac{15}{22.727} = 0.66 \Omega$$

$$I_{sc}^2 \cdot R_{e1} = P_{sc}$$

$$R_{e1} = \frac{80}{22.727} = 0.155 \Omega$$

$$X_{e1} = \sqrt{Z_{e1}^2 - R_{e1}^2} = \sqrt{0.66^2 - 0.155^2}$$

$$\alpha = \frac{440}{220} = 2$$

$$R_{e2} = \frac{R_{e1}}{\alpha^2} = \frac{0.155}{4} = 0.03875 \Omega$$

$$X_{e2} = \frac{X_{e1}}{\alpha^2} = \frac{0.6425}{4} = 0.1605 \Omega$$

$$\theta = \cos^{-1} 0.85 = 31.788^\circ$$

$$S = 10000 \angle 31.788^\circ \text{ kVA}$$

$$I_2 = \left(\frac{S}{V_2} \right)^* = \left(\frac{10000 \angle 31.788^\circ}{220} \right)^* = 45.455 \angle -31.788^\circ \text{ A}$$

$$V_1' = V_2 + I_2 \cdot Z_{e2}$$

$$= 220 + 45.455 \angle -31.788 \times (0.03875 + j0.1605)$$

$$= 225.402 \angle 1.341^\circ \text{ V}$$

$$\text{Voltage regulation} = \frac{225.402 - 220}{220} = 2.455\%$$

$$P_{out} = 10000 \times 0.85 = 8500 \text{ W}$$

$$\begin{aligned} P_{loss} &= I_2^2 \cdot R_{e2} + \frac{V_1'^2}{R_c} \\ &= 45.455^2 \times 0.155 + \frac{225.402^2}{605.06} \\ &= 404.223 \text{ W} \end{aligned}$$

$$\eta = \frac{8500}{8500 + 404.223} = 95.46\%$$

b)

I_2

$$I_2 = \frac{20000}{220} = 90.909 \text{ A}$$

$$\begin{aligned} 66^\circ \text{ KVA Rating} &= I_2 \cdot V_2' = 90.909 \times 660 \\ &= 60 \text{ kVA} \end{aligned}$$

$$P_{loss} = 10k \times 0.8 \times (1 - 98\%) = 160 \text{ W}$$

$$\eta = \frac{60000 \times 0.8}{60000 \times 0.8 + 160} = 99.67\%$$

$$3/ \text{air} \quad N_{\text{sync}} = \frac{120f}{P} = \frac{120 \times 60}{4} \\ = 1800 \text{ rpm}$$

$$N_m = N_{\text{sync}} (1-s) \\ = 1800 \times (1 - 2.5\%) \\ = 1755 \text{ rpm}$$

$$\text{i)} \quad P_{\text{in}} = V_L I_L \text{pf} \cdot \sqrt{3} \\ = 460 \times 90 \times 0.8 \times \sqrt{3} \\ = 57366 \text{ W}$$

$$P_{\text{SCL}} = 3 \times I_L^2 \cdot R_1 \\ = 3 \times 90^2 \times 0.07 \\ = 1701 \text{ W}$$

$$P_{\text{AG}} = P_{\text{in}} - P_{\text{SCL}} = 57366 - 1701 \\ = 55665 \text{ W}$$

$$T_{\text{dev}} = \frac{P_{\text{AG}}}{W_m} \\ = \frac{55665}{1755 \times \frac{2\pi}{60}} \\ = 302.884 \text{ N-m}$$

$$\text{ii)} \quad P_{\text{dev}} = P_{\text{AG}} (1-s) \\ = 55665 \times (1 - 2.5\%) \\ = 54273.375 \text{ W}$$

$$P_{\text{out}} = P_{\text{dev}} - P_{\text{rot}} \\ = 54273.375 - 2800 \\ = 51473.375 \text{ W}$$

$$\eta = \frac{P_{\text{out}}}{P_{\text{in}}} = \frac{51473.375}{57366} = 89.73\%$$

b) DC Test

$$2R_1 = \frac{V_{DC}}{I_{DC}} = \frac{23.2}{0.3}$$

$$R_1 = 1126.52$$

Lock-rotor Test ($S=1$)

$$3 \cdot I_{\text{line}}^2 \cdot (R_1 + R_2) = P_{\text{in}}$$

$$3 \times 50.3^2 \cdot (R_1 + R_2) = 18.2 \times 10^3$$

$$R_1 + R_2 = 2.397852$$

$$R_2 = 1.2716 \Omega$$

$$Z = \frac{V_{\text{line}}/\sqrt{3}}{I_{\text{line}}} = \frac{768/\sqrt{3}}{50.3} \\ = 8.8152 \Omega$$

$$X_1 + X_2 = \sqrt{Z^2 - (R_1 + R_2)^2}$$

$$= \sqrt{8.8152^2 - 2.3978^2}$$

$$= 8.4828 \Omega$$

$$X_1 = X_2 = 4.2414 \Omega$$

No-load Test ($S=0$)

$$Z' = \frac{V_{\text{line}}/\sqrt{3}}{I_{\text{line}}} = 172.4553 \Omega$$

$$X_1 + X_m = \sqrt{Z'^2 - R_1^2} \\ = \sqrt{172.4553^2 - 1.1262^2}$$

$$= 172.4516 \Omega$$

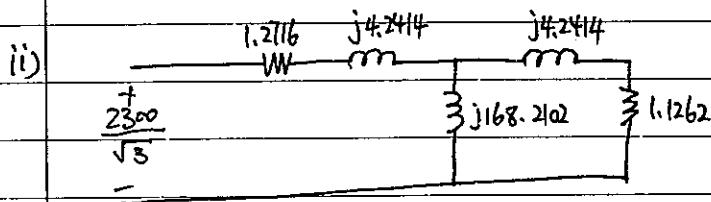
$$X_m = 172.4516 - 4.2414$$

$$= 168.2102 \Omega$$

$$\text{i)} P_{\text{rot}} = P_{\text{in}} - 3 \cdot I_{\text{line}}^2 \cdot R_1 \quad @ \text{no-load}$$

$$= 2870 - 3 \times 7.7^2 \times 1.1262$$

$$= 2670 \text{ W}$$

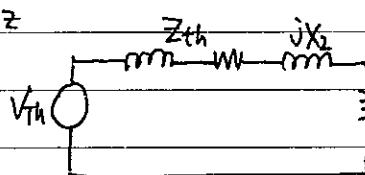


$$\text{c)} n_{\text{sync}} = \frac{50 \times 120}{6} = 1000 \text{ rpm} \quad @ 50 \text{ Hz}$$

$$n_m = n_{\text{sync}} (1 - S_{\text{max}})$$

$$= 1000 \times (1 - 15\%)$$

$$= 850 \text{ rpm.}$$

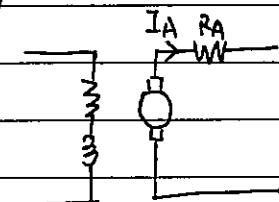


$$S_{\text{max}} = \frac{R_2}{|jX_2 + Z_{\text{th}}|}$$

Z_{th} no change

so S_{max} no change.

4(a) generator



$$I_F = 0.5 \text{ A}, E_A = 130 \text{ V}$$

$$\begin{aligned} V_T &= E_A - I_A R_A \\ &= 130 - 100 \times 0.15 \\ &= 115 \text{ V} \end{aligned}$$

$$\begin{aligned} P_{\text{out}} &= V_T I_A \\ &= 115 \times 100 \\ &= 11.5 \text{ kW} \end{aligned}$$

ii) $I_F = 1 \text{ A}, E_A = 200 \text{ V}$ @ 1700 rpm

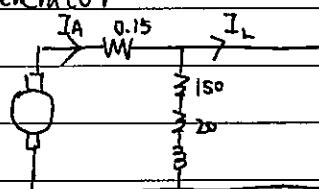
$$\frac{E_A}{E_A'} = \frac{n_m}{n_m'} \quad \frac{200}{E_A'} = \frac{1700}{1500}$$

$$E_A' = 176.4706 \text{ V}$$

$$\begin{aligned} V_T' &= E_A' - I_A R_A \\ &= 176.4706 - 100 \times 0.15 \\ &= 161.4706 \text{ V} \end{aligned}$$

$$\begin{aligned} P_{\text{out}} &= V_T' \cdot I_A \\ &= 16147.06 \text{ W} \end{aligned}$$

iii) generator

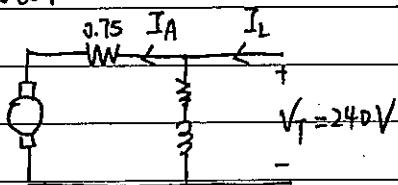


$$\begin{aligned} E_A &= I_A R_A + I_F (R_F + R_{\text{ext}}) \\ &= 0.15 \times 200 + I_F (150 + 20) \\ &= 30 + I_F \cdot 170 \\ &= 30 + 170 I_F \end{aligned}$$

$$\therefore I_F = 1 \text{ A}, E_A = 200 \text{ V}$$

$$\begin{aligned} V_T &= I_F (R_F + R_{\text{ext}}) \\ &= 1 \times 170 \\ &= 170 \text{ V} \end{aligned}$$

bi) motor



$$T_{dev} \propto \Phi \cdot I_A \quad \Phi \propto I_F$$

$$\frac{T_{dev}}{T_{dev}'} = \frac{I_F \cdot I_A}{I_F' \cdot I_A}$$

$$\frac{1}{0.6} = \frac{1}{0.7} \times \frac{(7-1)}{I_A}$$

$$I_A' = 5.1429 A$$

$$E_A' = V_T - I_A' \cdot R_A$$

$$= 236.1428 V \quad E_A \propto \Phi \cdot W_m \quad \Phi \propto I_F \quad W_m \propto n_m$$

$$\frac{E_A}{E_A'} = \frac{I_F}{I_F'} \cdot \frac{W_m}{W_m'}$$

$$\frac{240 - 6 \times 0.75}{236.1428} = \frac{1}{0.7} \times \frac{1200}{W_m'}$$

$$W_m' = 1719 \text{ rpm.}$$

$$(ii) E_A'' = V_T - I_A'' \cdot R_A$$

$$= 240 - (7-0.5) \times 0.75$$

$$= 235.125 V$$

$$T_L = T_{dev} \text{ (no Prot)} \quad T_{dev} = \frac{E_A I_A}{W_m} \propto W_m$$

$$\therefore E_A \propto W_m^2$$

$$\frac{E_A}{E_A''} = \frac{I_F}{I_F''} \cdot \frac{W_m^2}{W_m''^2}$$

$$\frac{240 - 6 \times 0.75}{235.125} = \frac{1}{0.5} \times \frac{1200^2}{W_m''^2}$$

$$W_m'' = 1696 \text{ rpm}$$