**Digital Image Processing** 

### **Digital Halftoning**

Ming-Sui (Amy) Lee Lecture 06

- Goal
  - Render the illusion of a continuous-tone image based on two-tone (half-tone) display

- Applications
  - Computer hardcopies
    - Laser printers/dot-matrix printers/color printers
    - Fax machine
- Implementation
  - Thresholding at 1/2 ?





**Gray-level image** 









Half-toned images

#### Color Printer

Continuous Image

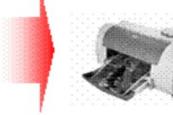




Binary Image









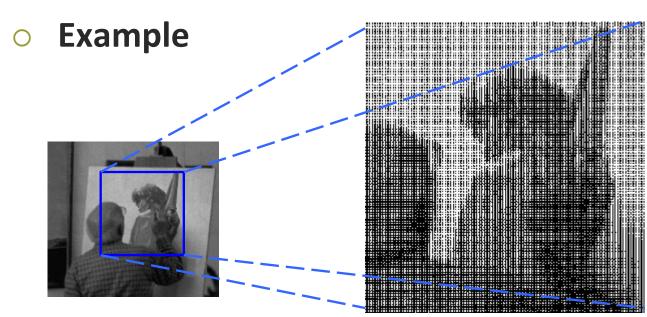
- Basic idea
  - Spatial modulation
  - Three approaches
    - Patterning
    - Dithering
    - Error Diffusion

**Patterning** p If p=4 $\rightarrow$  16 binary pixels → 17 levels (0~16) → 256 gray levels **→** Quantization 1 Gray-level pixel 1 Dot pattern Rylander's recursive

Rylander's recursive patterning matrices

- Patterning
  - Four steps
    - Read in the given grey-level image
    - Quantization
    - Design the patterning table
    - Map each pixel to its corresponding pattern
  - Simplest way
  - Generates image with higher spatial resolution than the source image

Patterning



Original gray-level image

Half-toned image: patterning

- Dithering
  - Create an image with the same number of dots as the number of pixels in the source image
  - Idea

$$N(j,k) o Why??$$

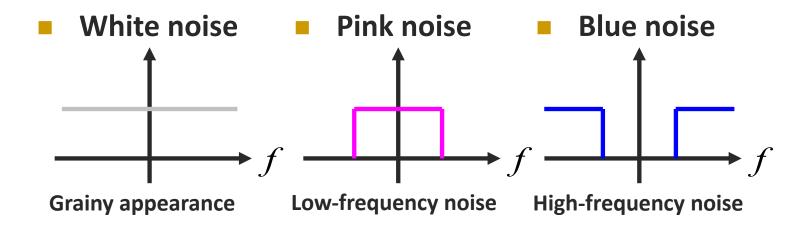
$$F(j,k) o H(j,k) o G(j,k)$$

- Dithering
  - Why adding noise?
    - Under fixed thresholding → taking MSB
      - E.g. before and after adding noise

$$\geq$$
 128  $\Rightarrow$  1;  $<$  127  $\Rightarrow$  0

- To break the monotonicity of accumulated error in the area of constant (nearly constant) gray level
- Noise type
  - White noise, pink noise, blue noise and green noise

- Dithering
  - Noise Type
    - Power spectral density



- Robert Ulichney, "Digital Halftoning"
  - http://www.hpl.hp.com/people/u/

#### Dithering

- Adaptive thresholding
  - Generate a threshold matrix according to a dither matrix
  - Whenever the pixel value of the image is greater than the value in the threshold matrix, the pixel is turned on

#### Notes

- No randomness
- Region-to-region mapping
- Recursive definition allowed

#### Dithering

Dither matrix

$$I_2(i,j) = \begin{bmatrix} 1 & 2 \\ 3 & 0 \end{bmatrix}; \quad I_2(i,j) = \begin{bmatrix} 3 & 1 \\ 0 & 2 \end{bmatrix}$$

- 0 → lowest threshold
- 3 → highest threshold

#### Dithering

- The general form of the NxN dither matrix
  - $2x2 \rightarrow 4x4 \rightarrow 8x8 \rightarrow 16x16...$

$$I_{2n}(i,j) = \begin{bmatrix} 4I_n(i,j) + 1 & 4I_n(i,j) + 2 \\ 4I_n(i,j) + 3 & 4I_n(i,j) + 0 \end{bmatrix}$$

Eg. What is  $I_4(i,j)$  if  $I_2(i,j) = \begin{bmatrix} 1 & 2 \\ 3 & 0 \end{bmatrix}$ ?

#### Dithering

Determine the threshold matrix

$$T(i,j) = 255 \cdot \frac{I(i,j) + 0.5}{N^2}$$

■ Eg. N=4

$$I_4(i,j) = \begin{bmatrix} 5 & 9 & 6 & 10 \\ 13 & 1 & 14 & 2 \\ 7 & 11 & 4 & 8 \\ 15 & 3 & 12 & 0 \end{bmatrix}, \qquad T_4(i,j) = ?$$

#### Dithering

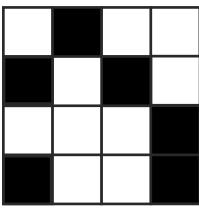
Input image

12	51	34	121
78	254	10	97
45	113	110	16
90	200	206	34

Repeated threshold matrix

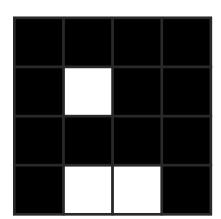
0	60	0	60
110	110	110	45
0	60	0	60
110	45	110	45

**Output image** 



**Another repeated threshold matrix** 

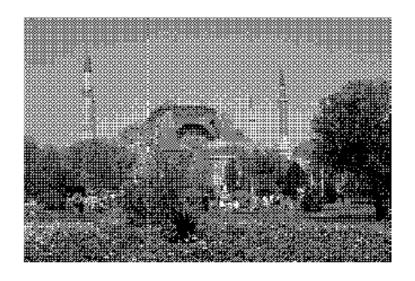
128	128	128	128
128	128	128	128
128	128	128	128
128	128	128	128



#### Experimental results



**Original Image** 



**Dithering** 

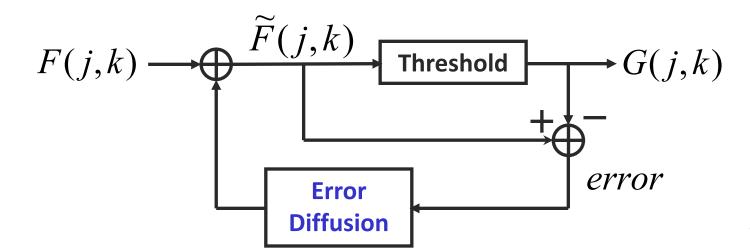
#### Experimental results



**Original Image** 

**Dithering** 

- Error diffusion
  - 1975 Floyd & Steinberg
    - A practical algorithm to implement blue noise dithering
    - Framework



- Error diffusion
  - Normalize F(j,k) to lie between [0,1]
  - Set threshold=0.5
  - Output image: 0 or 1

$$F(j,k) \xrightarrow{\widetilde{F}(j,k)} \text{Threshold} G(j,k)$$

$$Error$$

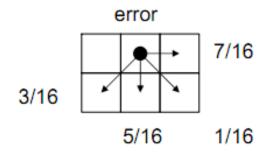
$$Diffusion$$

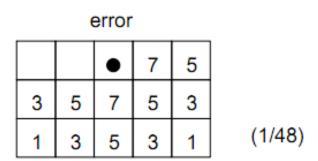
if 
$$\widetilde{F}(j,k) \ge 0.5 \rightarrow G(j,k) = 1$$
  
if  $\widetilde{F}(j,k) < 0.5 \rightarrow G(j,k) = 0$   
Define  $E(j,k) = \widetilde{F}(j,k) - G(j,k)$ 

- Error diffusion
  - Error diffusion filter masks
- F(j,k)  $\widetilde{F}(j,k)$  Threshold G(j,k) error Diffusion

1976 Jarvis et al:

1975 Floyd Steinberg:





- Other diffusion matrices
  - http://www.tannerhelland.com/4660/dithering-elevenalgorithms-source-code/

- **Error diffusion** 
  - **Error diffusion + serpentine scanning**

$$\frac{1}{16} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 7 \\ 3 & 5 & 1 \end{pmatrix}$$

**Left to Right** 

$$\frac{1}{16} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 7 \\ 3 & 5 & 1 \end{pmatrix} \qquad \frac{1}{16} \begin{pmatrix} 0 & 0 & 0 \\ 7 & 0 & 0 \\ 1 & 5 & 3 \end{pmatrix}$$

Right to Left

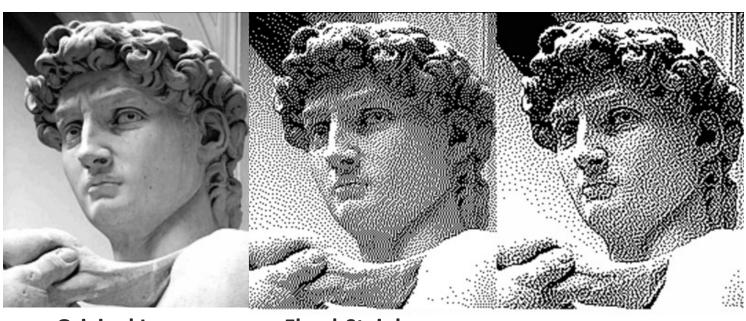
#### Experimental results



**Original Image** 

**Error Diffusion** 

#### Experimental results



**Original Image** 

**Floyd-Steinberg** 

**Jarvis** 

- Multi-scale Error diffusion
  - Several issues
    - Region-to-region mapping
      - Multi-resolution
    - Time series/causal error diffusion process
      - Easy to implement
      - Causality appears to be artificial in images
      - Is non-causal error diffusion possible?
    - Quality metrics of half-toned images

#### Multi-scale Error diffusion

"A multiscale error diffusion technique for digital halftoning" loannis Katsavounidis and C. –C. Jay Kuo

#### Problem set-up

- Input image  $\rightarrow$   $X(i,j) \in [0,1]$
- Output image  $\rightarrow B(i, j) \in \{0,1\}$
- Error image  $\rightarrow$  E(i,j) = X(i,j) B(i,j)
- Intermediate stage →

$$X_k(i_k, j_k), \quad 0 \le k \le r, \quad r = \log_2 N$$

$$X_k(i_k, j_k) = \sum_{i=0}^{1} \sum_{j=0}^{1} X_{k+1}(2i_k + i, 2j_k + j)$$

 $r = \log_2$ 

#### Multi-scale Error diffusion

$$X_{k}(i_{k}, j_{k}) = \sum_{i=0}^{1} \sum_{j=0}^{1} X_{k+1}(2i_{k} + i, 2j_{k} + j), \quad 0 \le k \le r$$

$$E_{k}(i_{k}, j_{k}) = X_{k}(i_{k}, j_{k}) - B_{k}(i_{k}, j_{k}), \quad 0 \le k \le r$$

Goal: minimize the error pyramid in a certain way!

#### Multi-scale Error diffusion

- //Step 1// Initialization
  - Set the entire output image pyramid to "0"
- //Step 2// Dot assignment
  - Find the largest error from top to bottom level
  - 1 parent node distributes its dots (integer numbers) to 4 children
- //Step 3// Error diffusion process

$$\frac{1}{12} \begin{pmatrix} 1 & 2 & 1 \\ 2 & -12 & 2 \\ 1 & 2 & 1 \end{pmatrix} \qquad \frac{1}{8} \begin{pmatrix} 0 & 0 & 0 \\ 2 & -8 & 2 \\ 1 & 2 & 1 \end{pmatrix} \qquad \frac{1}{5} \begin{pmatrix} 0 & 0 & 0 \\ 0 & -5 & 2 \\ 0 & 2 & 1 \end{pmatrix}$$

$$\frac{1}{5} \begin{pmatrix} 0 & 0 & 0 \\ 0 & -5 & 2 \\ 0 & 2 & 1 \end{pmatrix}$$

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- Multi-scale Error diffusion
  - Quality management
    - MSE vector

$$MSEV = \begin{pmatrix} MSE_0 \\ MSE_1 \\ \vdots \\ MSE_r \end{pmatrix} \qquad MSE_k = \frac{1}{N^2} \sum_{i=0}^{2^k - 1} \sum_{j=0}^{2^k - 1} E_k^2(i, j)$$

- Notes
  - Preserve contrast of the original image
  - Does not over-smooth the image

#### Experimental results

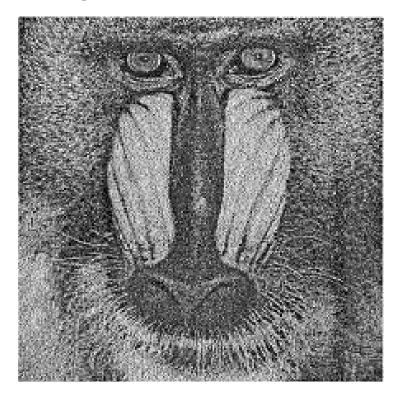




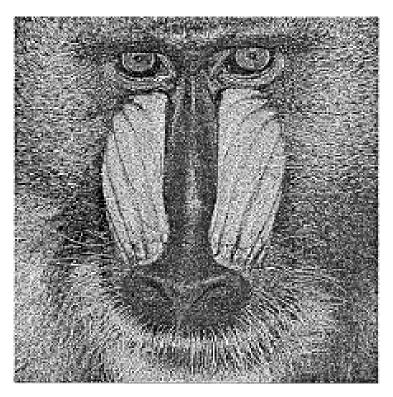


**Multi-Scale Error Diffusion** 

#### Experimental results



**Error Diffusion** 



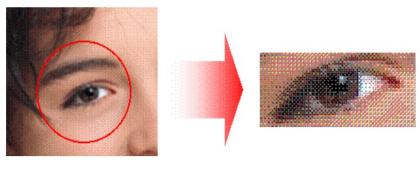
**Multi-Scale Error Diffusion** 

Color image

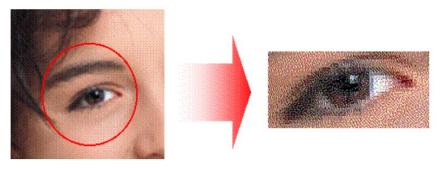


#### Examples





**Dithering** 



**Error Diffusion** 

#### Application

Visual cryptography

"visual cryptography based on void-and-cluster halftoning technique" E. Myodo, S. Sakazawa and Y. Takishima

