

Writing Multithreaded Code

Some info and technics



Agenda

1. **The Thread:** History 📄, APIs 🔌, & Properties
2. **The Race:** Mechanics 🏎️ & Detection 🕵️
3. **C++ Primitive Safety:** The "Is it Safe?" Checklist ✅
4. **Thread vs. Task:** Architecture 🏗️ & Pools 🏊
5. **Synchronization:** Mutex 🔒, CV 🔔, & Custom
6. **Priority Inversion:** The Silent Killer 🔔🚫
7. **OS Nuances:** Windows 🖥️ / Linux 🐧 / VxWorks 🤖

What is a Thread? 🧵

📄 Evolution

- **Process Era** 🏭: Heavyweight, isolated memory.
- **OS Threads (pthreads/WinAPI)** 🤝: Lightweight, shared address space.
- **Language Support** 🗣️:
 - **Pre-C++11** 🌑: Library only (Boost, Qt). No memory model.
 - **C++11** 🌟: `std::thread`, Memory Model defined.
 - **C++20** ✨: `std::jthread` (Cooperative, auto-join).

APIs: The Wrapper Layers

// 1. POSIX (Raw & Dangerous ☠️)

```
pthread_t t;  
pthread_create(&t, NULL, func, arg);
```

// 2. Boost (The Precursor 🦖)

```
boost::thread t(func);
```





// 3. C++11 (The Standard 📖)


```
std::thread t([]{ /* work */ });
```

// 4. C++20 (The Safe Wrapper 🛡️)

```
std::jthread t([](std::stop_token st){  
    while(!st.stop_requested()) { /*...*/ }  
});
```

Thread Properties

- **Affinity** : Binding to a CPU Core.
- **Priotiry** 
- **Stack Size** 
- **Name** 

```
// Example: Setting name (Platform specific )  
pthread_setname_np(pthread_self(), name);
```

```
// Example: Affinity (Core Binding )
```

```
cpu_set_t cpuset;
```

```
CPU_ZERO(&cpuset);
```

```
CPU_SET(0, &cpuset); // Core 0
```

```
pthread_setaffinity_np(thread.native_handle(), sizeof(cpu_set_t), &cpuset);
```

The Race 🏎️💨

Data Race Definition ⚠️:

Two threads access memory concurrently, one is a **write** ✍️.

```
int counter = 0; // Shared Resource

void run() {for (int i = 0; i < 100000; ++i) { counter++; }}

int main() {
    std::thread t1(run);    std::thread t2(run);
    t1.join(); t2.join();

    std::cout << counter << "\n";
}
```

Static Initialization

Is it safe?


- **C++98** ❌: No. (Broken Double-Checked Locking).
- **C++11** ✅: **YES**. "Magic Statics".

```
bool& a()  
{  
    static bool b = [](){bool c; std::cin>>c;return c;}();  
    return b;  
}
```

Smart Pointers: `shared_ptr`



Thread Safety Levels:

1. **Control Block (Ref Count)** : Thread-Safe (Atomic).
2. **Managed Object** : **NOT** Thread-Safe.

```
std::shared_ptr<int> ptr = std::make_shared<int>(0);
```

```
// Thread A ●
```

```
*ptr = 20;
```

```
std::shared_ptr<int> a = ptr;
```

```
// Thread B ●
```

```
*ptr = 20;
```

Containers (`vector` , `map`)

- Read/Read 👁️: Safe.
- Write/Write ✍️: Unsafe.
- Read/Write 💣: Unsafe.

```
std::vector<int> v = {1, 2, 3};
```

```
// Thread A ●  
int x = v[0]; // OK
```


```
// Thread B ●  
v.push_back(4); // DATA RACE! ✨  
                // Reallocation invalidates A's view.
```

IO

IO (cout): Thread-safe characters, interleaved lines .

```
void speak(int id) {  
    std::cout << "Thread " << id << " says: " << "Hello!\n";  
}  
  
int main(  
  
) {  
    std::thread t1(speak, 1);  
    std::thread t2(speak, 2);  
    t1.join(); t2.join();  
}
```

Atomics: What Can Be Atomic?

- **Integers/Pointers (≤ 8 bytes): Lock-Free** (CPU Instructions) ⚡.
- **Large Structs (> 16 bytes): Uses a Mutex** .

```
struct Tiny { uint8_t a; uint8_t b; }; // 2 bytes
struct Heavy { long data[100]; };      // 800 bytes 
```

```
std::atomic<Tiny> fast;
std::atomic<Heavy> slow;
```

```
// Runtime Check :
if (fast.is_lock_free()) { /* fast */ }
if (!slow.is_lock_free()) { /* mutex */ }
```

Memory Ordering I


```
std::atomic<std::string*> ptr;  
int data;  
  
void producer()  
{  
    std::string* p = new std::string("Hello");  
    data = 42;  
    ptr.store(p);  
}  
  
void consumer()  
{  
    std::string* p2;  
    while (!(p2 = ptr.load()))  
        ;  
    assert(*p2 == "Hello");  
    assert(data == 42);  
}
```

Memory Ordering II

```
std::atomic<std::string*> ptr;  
int data;  
  
void producer()  
{  
    std::string* p = new std::string("Hello");  
    data = 42;  
    ptr.store(p, std::memory_order_release);  
}  
  
void consumer()  
{  
    std::string* p2;  
    while (!(p2 = ptr.load(std::memory_order_acquire)))  
        ;  
    assert(*p2 == "Hello");  
    assert(data == 42);  
}
```

Malloc/New

- **Safety: Thread-Safe** .
- **Performance: Contention** .

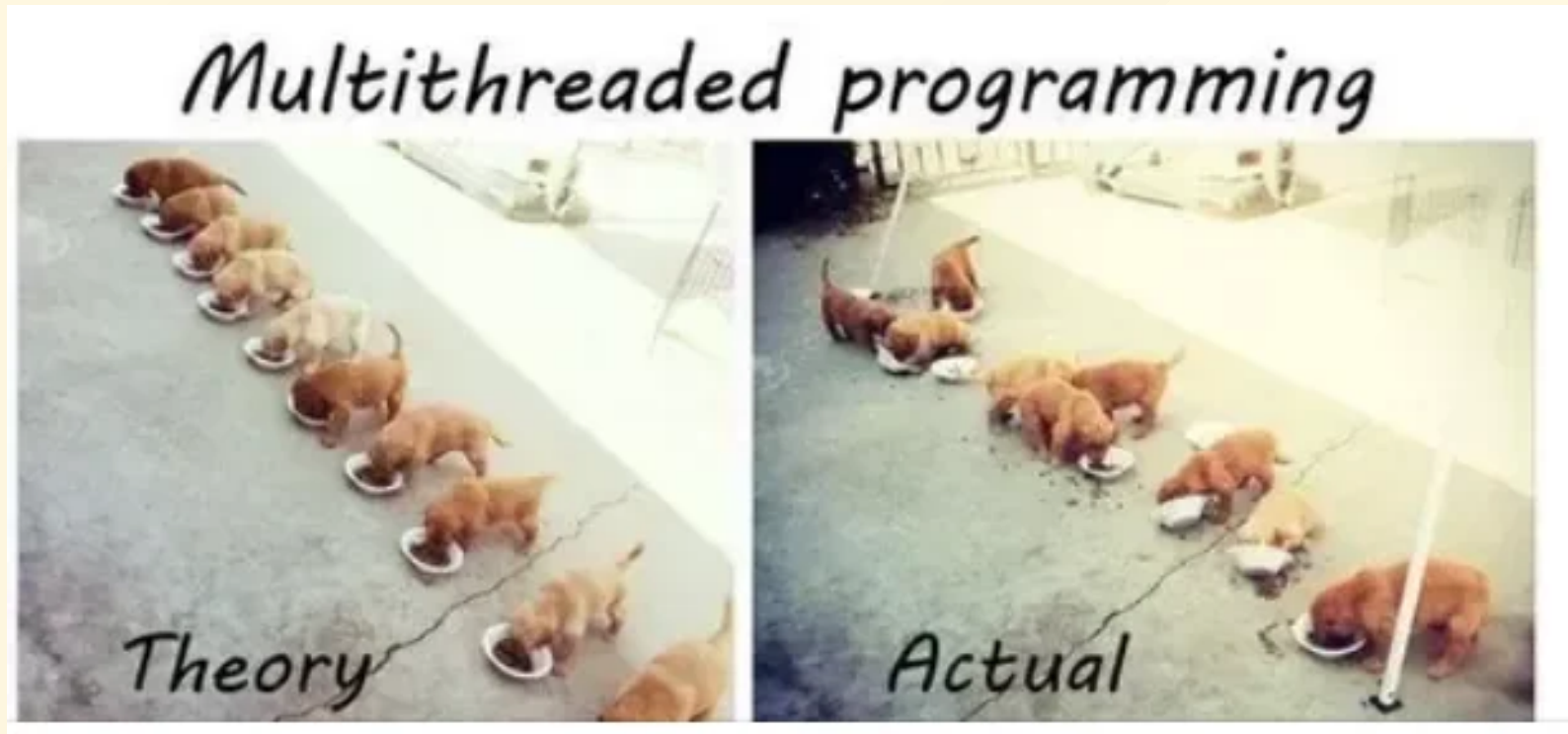
```
void worker() {  
    std::vector<int> temp(1000); // Global lock   
}
```

- Use stack
- Use thread local storage
- Allocate once
- `MALLOC_ARENA_MAX`

DO NOT



Don't write if you don't have to





Thread vs Task

Thread: An OS resource (Heavy )

Task: A unit of work (Logical )

Thread Pools

- **Thread Pool:** Fixed OS threads (Hardware Limit )
- **Single Thread Pool:** Event Loop .

Use These

- **Boost / Intel TBB**

Avoid These


- **Windows PPL / `std::async`**


Primitives

Mutex (The Lock)

RAII .

```
std::mutex mtx;

void critical_section() {
    // NEVER call mtx.lock() manually 
    std::lock_guard<std::mutex> lock(mtx);

    // Critical section... 
    // Unlocks automatically on return
}
```

Condition Variable

Signal threads to wake up .

Spot the bug !

```
std::condition_variable cv;  
std::mutex mtx;  
  
// Consumer 🤖  
{  
    std::unique_lock<std::mutex> lk(mtx);  
    cv.wait(lk);  
    process();  
}  
  
// Producer 📢  
{  
    cv.notify_one();  
}
```

Always use a predicate.

```
std::condition_variable cv;
std::mutex mtx;
bool ready = false;

// Consumer 🤖
{
    std::unique_lock<std::mutex> lk(mtx);
    cv.wait(lk, []{ return ready; }); // Prevents Spurious Wakeups 🐼
    process();
}

// Producer 📢
{
    {
        std::lock_guard<std::mutex> lk(mtx);
        ready = true;
    }
    cv.notify_one();
}
```

New Message

```
// Basic mt primitive
// Single writer - multiple readers safe
template <typename T>
class NewMessage {
public:
    // 1. Writer: Update the current value 🐢
    // Thread-Safe. Overwrites previous data if not read yet.
    void AddMessage(const T& msg);

    // 2. Reader: Get Latest message 🐢
    // Returns: The latest message. Always valid memory
    T* GetLatest();
};
---
```

Priority Inversion 📉

****Scenario:****

1. Low Priority 🐢 holds Mutex.
2. High Priority 🐢 needs Mutex -> Blocks 🐢.
3. Medium Priority 🐢 preempts Low.
****Result:**** High Priority blocked by Medium 🐢.

OS Differences 🌐

Feature	Windows 🪟	Linux 🐧
Scheduler	Preemptive	Completely Fair Scheduler
Time Slice	Variable	Dynamic
Priority	0-31	0-99 (RT)
API	WinAPI	pthread

More Topics 📖

* ****Deadlock 🐞:**** Lock A -> Lock B vs Lock B -> Lock A.
* ****Livelock 🐞:**** Polite yielding forever.
* ****False Sharing 🐞:**** Cache Line contention.

```
```cpp
// False Sharing Example 🐞
struct {
 std::atomic<int> a; // alignas(64)
 std::atomic<int> b; // alignas(64)
} shared; // 'a' and 'b' fight for L1 cache 🐞
```

# More Topics

- **API :**
  - Blocking ?
  - Reentrant ?