

# Advances in Quantitative MRI: Acquisition, Estimation, and Application

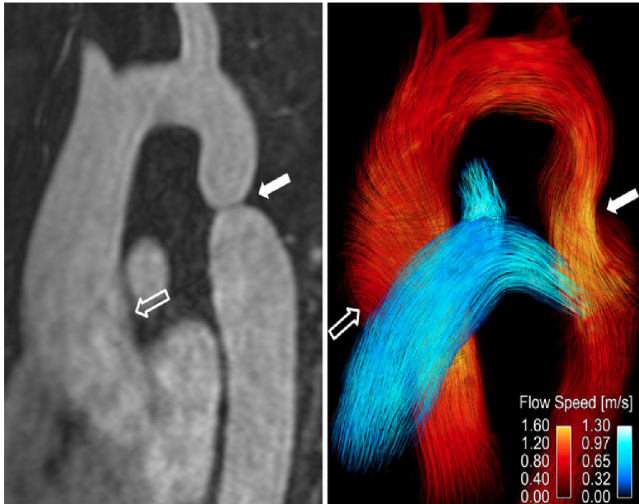
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Dissertation Defense  
March 23, 2018

Dept. of Electrical Engineering and Computer Science  
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## Example: flow imaging

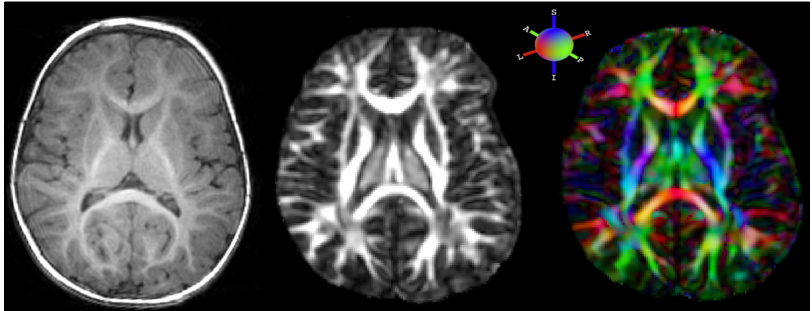


qualitative

quantitative<sup>1</sup>

<sup>1</sup>figure borrowed from [Hope et al., 2013]

## Example: diffusion imaging



qualitative

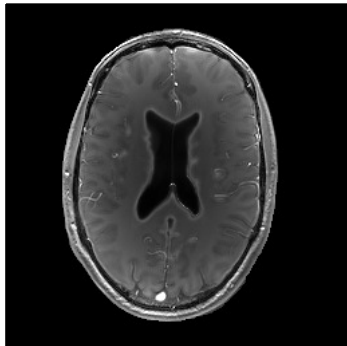
fractional anisotropy (FA)

directional FA<sup>2</sup>

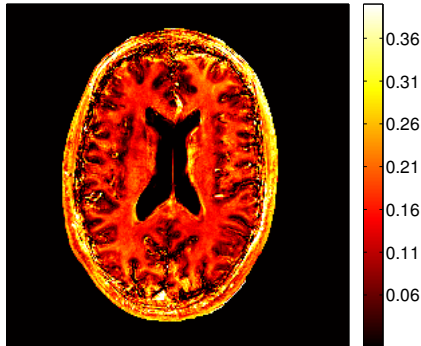
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<sup>2</sup>figure borrowed from [www.diffusion-imaging.com](http://www.diffusion-imaging.com)

## Example: myelin water imaging



qualitative



fast-relaxing fraction<sup>3</sup>

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<sup>3</sup>figure adapted from [Nataraj et al., 2017a]

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- localize produce quantitative MR images
- accurately physically realistic signal models
- rapidly fast acquisition, fast estimation

**Challenge:** rapidly vs. accurately often competing goals

- more accurate models typically depend on more markers
- precisely estimating more markers usually requires  
longer scans and more computation

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After reconstruction, single voxel  $y_d$  in  $d$ th image modeled as

$$y_d = s_d(\mathbf{x}; \boldsymbol{\nu}, \mathbf{p}_d) + \epsilon_d \quad (1)$$

- $\mathbf{x} \in \mathbb{R}^L$  unknown parameters
- $\boldsymbol{\nu} \in \mathbb{R}^K$  “known” parameters
- $\mathbf{p}_d \in \mathbb{R}^A$  acquisition parameters
- $s_d : \mathbb{R}^{L+K+A} \mapsto \mathbb{C}$   $d$ th signal model
- $\epsilon_d \in \mathbb{C}$  noise  $\sim \mathbb{CN}(0, \sigma_d^2)$

## Signal Model

A *scan profile* is a set of  $D$  scans that produces at each voxel a measurement vector  $\mathbf{y} := [y_1, \dots, y_D]^T$  modeled as

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- $\mathbf{s} : \mathbb{R}^{L+K+AD} \mapsto \mathbb{C}^D$  vector signal model
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**Task:** design  $\mathbf{P}$  to enable precise unbiased estimation of  $\mathbf{x}$



## Towards an Objective Function

When  $\mathbf{s}$  is analytic in  $\mathbf{x}$  (as is typical),

**Fisher information** characterizes unbiased estimator precision:

$$\mathbf{F}(\mathbf{x}; \boldsymbol{\nu}, \mathbf{P}) := (\nabla_{\mathbf{x}} \mathbf{s}(\mathbf{x}; \boldsymbol{\nu}, \mathbf{P}))^H \boldsymbol{\Sigma}^{-1} \nabla_{\mathbf{x}} \mathbf{s}(\mathbf{x}; \boldsymbol{\nu}, \mathbf{P}). \quad (2)$$

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When  $\mathbf{F}$  is invertible, Cramér-Rao Bound (CRB) [Cramér, 1946] ensures covariance of unbiased estimates  $\hat{\mathbf{x}}$  of  $\mathbf{x}$  satisfy

$$\text{cov } \hat{\mathbf{x}}; \boldsymbol{\nu}, \mathbf{P} \succeq \mathbf{F}^{-1}(\mathbf{x}; \boldsymbol{\nu}, \mathbf{P}). \quad (3)$$

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**Idea:** choose  $\mathbf{P}$  such that imprecision matrix  $\mathbf{F}^{-1}$  “small”

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$$\Psi(\mathbf{x}; \nu, \mathbf{P}) = \text{tr}(\mathbf{W}\mathbf{F}^{-1}(\mathbf{x}; \nu, \mathbf{P})\mathbf{W}^T), \quad (4)$$

where  $\mathbf{W} \in \mathbb{R}^{L \times L}$  is a pre-selected diagonal matrix of weights.

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**Two problems considered:**

- min-max scan design [Nataraj et al., 2017b]

$$\check{\mathbf{P}} \in \left\{ \arg \min_{\mathbf{P} \in \mathbb{P}} \max_{\substack{\mathbf{x} \in \mathbb{X}^t \\ \boldsymbol{\nu} \in \mathbb{N}^t}} \Psi(\mathbf{x}; \boldsymbol{\nu}, \mathbf{P}) \right\} \quad (5)$$

where  $\mathbb{X}^t \subseteq \mathbb{R}^L$  and  $\mathbb{N}^t \subseteq \mathbb{R}^K$  are “tight” ranges of interest and  $\mathbb{P}$  is defined by acquisition/timing constraints

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# Scan Design

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- Consider scan profiles consisting of two fast pulse sequences
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## Detailed Example Study

**Task:** design fast acquisition for precise estimation of relaxation parameters  $T_1, T_2$  in white/gray matter (WM/GM) of brain

- Consider scan profiles consisting of two fast pulse sequences
  - Spoiled Gradient-Recalled Echo (SPGR) [Zur et al., 1991]
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- For each scan profile feasible under total time constraint:
  1. Let  $\mathbf{s}$  model corresponding single-component signal
    - $\mathbf{x} \leftarrow [m_0, T_1, T_2]^T$ , where  $m_0$  is a scale factor
    - $\nu \leftarrow$  flip angle variation
    - $\mathbf{P} \leftarrow$  nominal flip angles, repetition times
  2. Optimize  $\mathbf{P}$  subject to flip angle, sequence timing constraints
    - $\mathbf{W} \leftarrow \text{diag}(0, 0.1, 1)$  emphasizes  $T_1, T_2$  est roughly equally
    - $\mathbb{X}^t$  chosen to focus on WM/GM at 3T field strength
    - $\mathbb{N}^t$  chosen to allow 10% flip angle variation

## Scan Profile Comparison

| (#SPGR, #DESS) Profiles | (2, 1)       | (1, 1) | (0, 2)       |
|-------------------------|--------------|--------|--------------|
| SPGR nom. flip (deg)    | (15, 5)      | 15     | –            |
| DESS nom. flip (deg)    | 30           | 10     | (35, 10)     |
| SPGR rep. times (ms)    | (12.2, 12.2) | 13.9   | –            |
| DESS rep. times (ms)    | 17.5         | 28.0   | (24.4, 17.5) |
| <b>optimal max cost</b> | 4.0          | 4.9    | <b>3.5</b>   |

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**Main finding:** 2 DESS sequences can yield  $T_1$ ,  $T_2$  WM/GM estimates that are at least as precise as  $T_1$ ,  $T_2$  estimates from SPGR/DESS scan profiles, under this competitive time constraint.

## Experimental Setup

Candidate  $(2, 1)$ ,  $(1, 1)$ ,  $(0, 2)$  SPGR/DESS scan profiles

- Prescribed optimized nominal flip angles, repetition times
- Used  $256 \times 256 \times 8$  3D matrix over  $24 \times 24 \times 4$ cm FOV
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- Four inversion recovery (IR) scans for  $T_1$  estimation
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Bloch-Siegert (BS) acquisition for separate flip angle calibration

- Acquired 2 BS-shifted 3D SPGR scans in 1m40s total
- Used for  $T_1$ ,  $T_2$  est from both candidate and reference profiles



# Phantom Accuracy Results

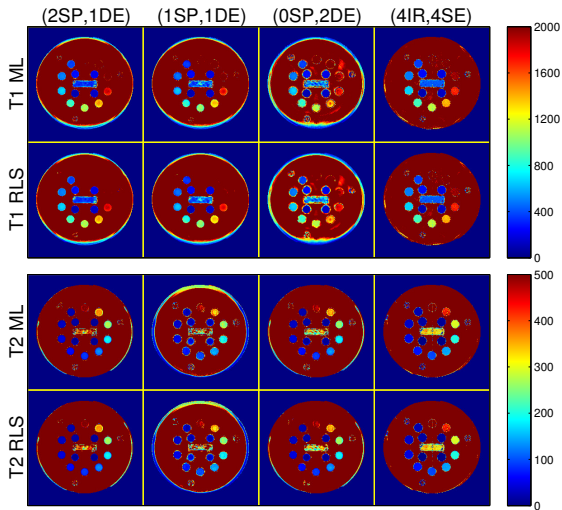
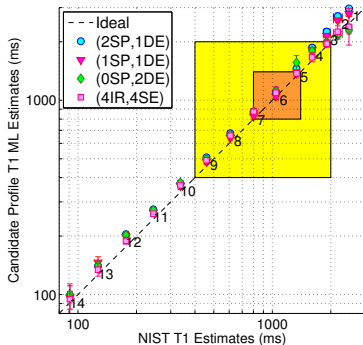
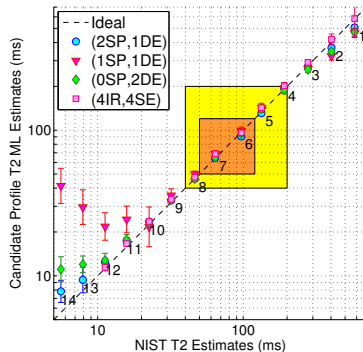


Figure 1: Colorbar ranges in ms.

# Phantom Accuracy Results



(a)  $\hat{T}_1^{\text{ML}}$  Estimates



(b)  $\hat{T}_2^{\text{ML}}$  Estimates

Compared against NIST NMR measurements [Keenan et al., 2016]

## Phantom Precision Results

- Repeated each profile 10 times
- Estimated  $T_1$ ,  $T_2$  std dev of typical voxel across repetitions

## Phantom Precision Results

|   | (2, 1)         | (1, 1)         | (0, 2)                          |
|---|----------------|----------------|---------------------------------|
| V5 $\hat{\sigma}_{\hat{T}_1^{\text{ML}}}$ | $50 \pm 12$    | $40 \pm 10.$   | $39 \pm 9.4$                    |
| V6 $\hat{\sigma}_{\hat{T}_1^{\text{ML}}}$ | $70 \pm 18$    | $60 \pm 15$    | $60 \pm 16$                     |
| V7 $\hat{\sigma}_{\hat{T}_1^{\text{ML}}}$ | $60 \pm 13$    | $50 \pm 13$    | $50 \pm 13$                     |
| V5 $\hat{\sigma}_{\hat{T}_2^{\text{ML}}}$ | $2.6 \pm 0.63$ | $6 \pm 1.4$    | $3.5 \pm 0.84$                  |
| V6 $\hat{\sigma}_{\hat{T}_2^{\text{ML}}}$ | $1.9 \pm 0.46$ | $5 \pm 1.1$    | $2.3 \pm 0.54$                  |
| V7 $\hat{\sigma}_{\hat{T}_2^{\text{ML}}}$ | $1.4 \pm 0.34$ | $3.4 \pm 0.80$ | $1.5 \pm 0.35$                  |
| $\sqrt{\text{opt max cost}}$ estimate     | $8.9 \pm 1.8$  | $11 \pm 2.6$   | <b><math>8.3 \pm 2.1</math></b> |

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Similar trends across profiles of empirical vs. theoretical std dev!

## Contributions

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## Summary

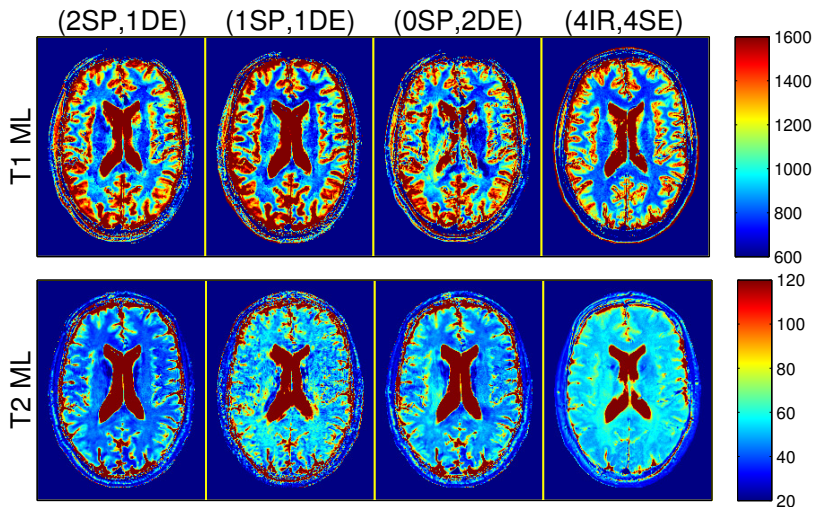


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## How to address *in vivo* model mismatch?

- More accurate *in vivo* signal models
- More scalable parameter estimation

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- dictionary-based grid search

**Grid search** computational costs

|                          | $L$ | $\sim$ number dictionary atoms |
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| flow velocity              | 4    | $\sim 100^3$                   |
| diffusivity tensor         | 7    | $\sim 100^6$                   |
| 2-3 compartment relaxivity | 6-10 | $\sim 100^5 - 100^9$           |

## Grid search computational costs

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Can we scale computation with  $L$  more gracefully?

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$$(\hat{h}_l, \hat{b}_l) \in \left\{ \arg \min_{\substack{h_l \in \mathbb{H} \\ b_l \in \mathbb{R}}} \frac{1}{N} \sum_{n=1}^N (h_l(\mathbf{q}_n) + b_l - x_{l,n})^2 + \rho_l \|h_l\|_{\mathbb{H}}^2 \right\} \quad (8)$$

**Solution:** Param Estimation via Regression with **Kernels** (PERK)

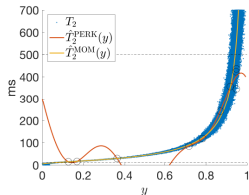
[Nataraj et al., 2018]

- restrict optimization to a **certain rich function space**  $\mathbb{H}$
- optimal  $\hat{h}_l \in \mathbb{H}$  takes form  $\hat{h}_l = \sum_{n=1}^N \hat{a}_{l,n} k(\cdot, \mathbf{q}_n)$

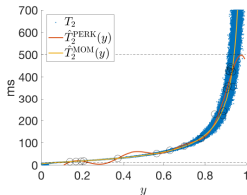
[Schölkopf et al., 2001]

# PERK in a 1-D Toy Problem

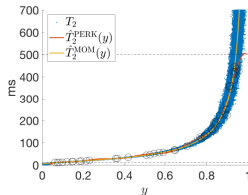
**Task:** estimate  $T_2$ , given samples from  $y = \exp(-T_E/T_2) + \epsilon$



(a)  $N \leftarrow 10$



(b)  $N \leftarrow 20$



(c)  $N \leftarrow 50$

**Compare:**  $\hat{T}_2^{\text{PERK}}$  with method-of-moments (MOM) estimator

$$\hat{T}_2^{\text{MOM}}(\cdot) := -T_E / \log |\cdot|$$

(PERK more useful when good MOM estimator unavailable)

## PERK Solution

Non-iterative closed-form solution, for  $l \in \{1, \dots, L\}$ :

$$\hat{x}_l(\cdot) = \mathbf{x}_l^T \left( \frac{1}{N} \mathbf{1}_N + \mathbf{M}(\mathbf{K}\mathbf{M} + N\rho_l \mathbf{I}_N)^{-1} \left( \mathbf{k}(\cdot) - \frac{1}{N} \mathbf{K} \mathbf{1}_N \right) \right) \quad (9)$$

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Can we scale computation with  $L$  more gracefully?

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- However, explicitly computing  $\mathbf{K}$  may be undesirable...

## PERK as High-Dimensional Affine Regression

Suppose there exists “approximate feature mapping”  $\tilde{\mathbf{z}} : \mathcal{Q} \mapsto \mathbb{R}^Z$  such that  $\tilde{\mathbf{Z}} := [\tilde{\mathbf{z}}(\mathbf{q}_1), \dots, \tilde{\mathbf{z}}(\mathbf{q}_N)]$  has for  $\dim(\mathcal{Q}) \ll Z \ll N$

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Does such a  $\tilde{\mathbf{z}}$  exist and work well in practice?

- Yes, e.g. for Gaussian  $k(\mathbf{q}, \mathbf{q}') \leftarrow \exp \left( -\frac{1}{2} \|\Lambda^{-1}(\mathbf{q} - \mathbf{q}')\|_2^2 \right)$   
[Rahimi and Recht, 2007]
- In such cases, can reduce from  $\sim N^2$  to  $\sim NZ$  computations

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## Experimental Setup

Demonstrated PERK for  $T_1$ ,  $T_2$  est from optim (2SP,1DE) scan

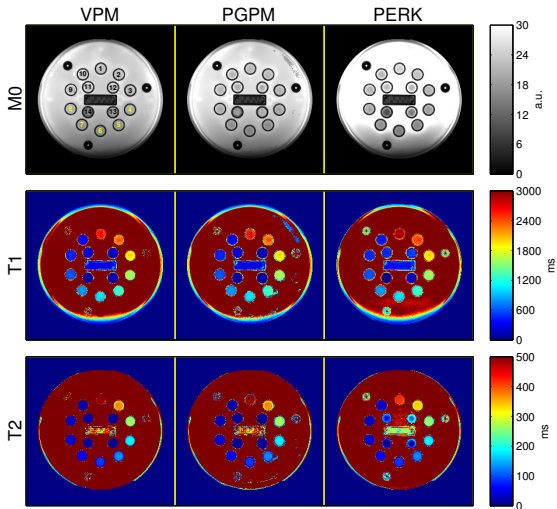
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Compared PERK to two well-suited ML estimators:

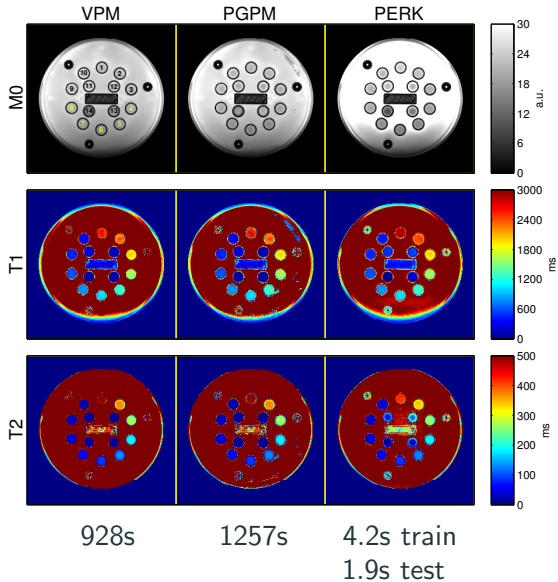
- dictionary-based grid search estimator via variable projection method (VPM) [Golub and Pereyra, 2003]
- local optim estimator via preconditioned variant (PGPM) of classical gradient projection method [Rosen, 1960]



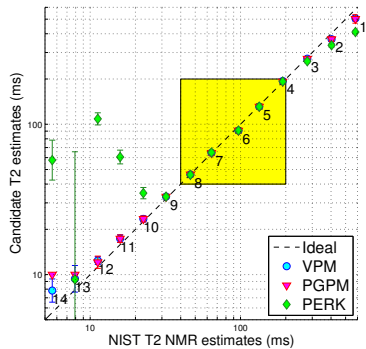
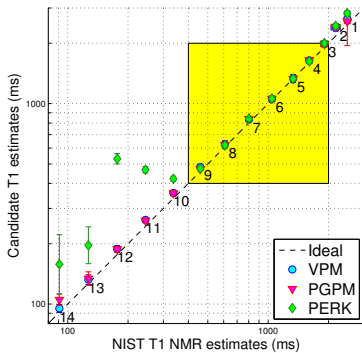
# Phantom Results



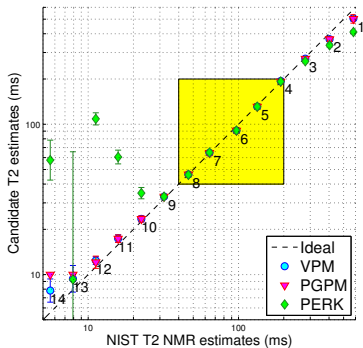
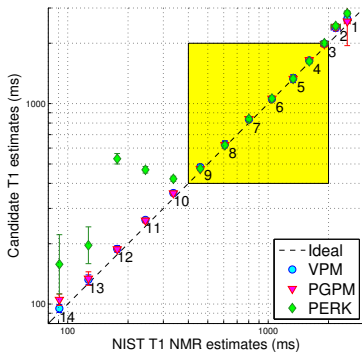
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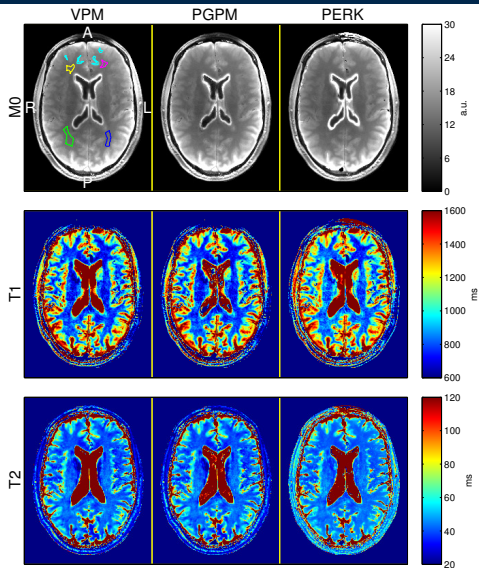


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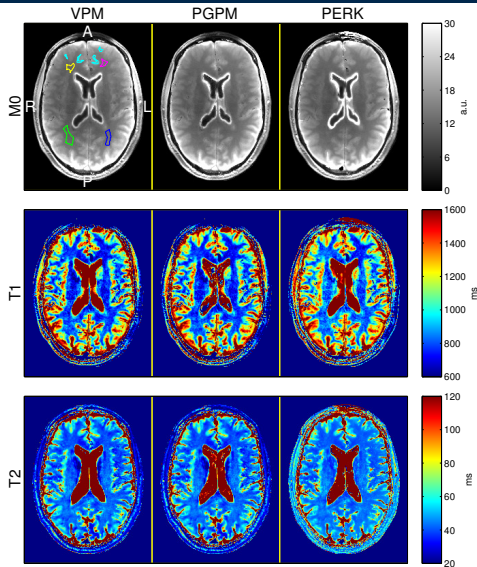


Within support of  $p_{x,\nu}$ ,  
**PERK** and grid search estimates agree excellently.

# In vivo Results



# In vivo Results



838s

2178s

4.2s train  
1.6s test

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**Can we exploit PERK's speed in a more compelling problem?**

## Advances in Quantitative MRI:

- **Acquisition** [Ch. 4]  
How can we assemble fast, informative collections of scans to enable precise biomarker quantification?
- **Estimation** [Ch. 5]  
Given accurate models and informative data, how can we rapidly quantify these biomarkers?
- **Application** [Ch. 6]  
Using these tools, can we design a state-of-the-art biomarker?

## Previous MW imaging acquisitions

Multi-echo spin-echo (**MESE**)

[Mackay et al., 1994]

- Considered a gold-standard
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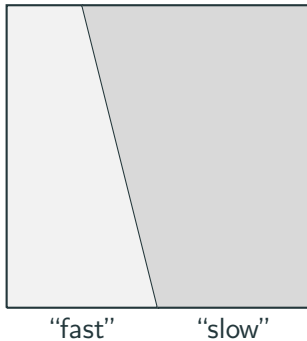
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**Goal:** fast, accurate MW content quantification in WM

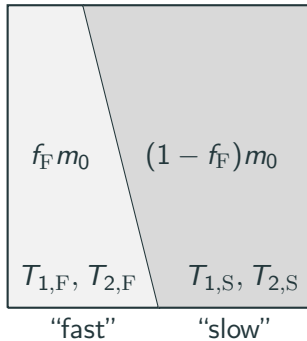
## A voxel-scale MW content model

simple two-compartment model



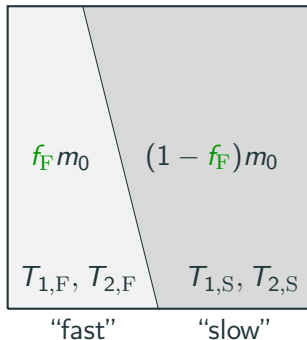
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## A voxel-scale MW content model

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Take fast-relaxing fraction  $f_F$  as a simple measure of MW content



## Multi-compartmental MR signal models

Two-compartment SPGR model [Spencer and Fishbein, 2000]

- included first-order physical exchange
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**For simplicity, we use short echo times and neglect exchange.**

$$\begin{aligned} \check{\mathbf{P}} &\in \left\{ \arg \min_{\mathbf{P} \in \mathbb{P}} \bar{\Psi}(\mathbf{P}) \right\}, \text{ where} \\ \bar{\Psi}(\mathbf{P}) &:= \mathbb{E}_{\mathbf{x}, \nu} \left( \text{tr} \left( \mathbf{W} \mathbf{F}^{-1}(\mathbf{x}; \nu, \mathbf{P}) \mathbf{W}^T \right) \right) \end{aligned} \quad (12)$$

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- $\mathbf{x}$   $[\mathbf{f}_{\mathbf{F}}, T_{1,\mathbf{F}}, T_{2,\mathbf{F}}, T_{1,\mathbf{S}}, T_{2,\mathbf{S}}, m_0]^T$
- $\nu$  transmit field spatial variation  $s^t$
- $\mathbf{P}$  SPGR/DESS nominal flip angles, repetition times

$$\check{\mathbf{P}} \in \left\{ \arg \min_{\mathbf{P} \in \mathbb{P}} \bar{\Psi}(\mathbf{P}) \right\}, \text{ where}$$
$$\bar{\Psi}(\mathbf{P}) := E_{\mathbf{x}, \nu} \left( \text{tr} \left( \mathbf{W} \mathbf{F}^{-1}(\mathbf{x}; \nu, \mathbf{P}) \mathbf{W}^T \right) \right) \quad (12)$$

- $\mathbf{x}$   $[f_F, T_{1,F}, T_{2,F}, T_{1,S}, T_{2,S}, m_0]^T$
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- $\mathbb{P}$  nom flip angle, total scan time constraints

## Optimized SPGR/DESS Acquisition

|      | Optimized flip angles (deg) | Optimized rep. times (ms) |
|------|-----------------------------|---------------------------|
| SPGR | –                           | –                         |
| DESS | 33.0, 18.3, 15.1            | 17.5, 30.2, 60.3          |

**Table 2:** Optimized Scan Parameters,  $\check{\mathbf{P}}$

- Predicted  $f_F$  relative standard deviation in WM
  - Optimized SPGR/DESS:  $\sqrt{\check{\Psi}(\check{\mathbf{P}})} = 0.425$
  - mcDESPOT: at least 1 [Lankford and Does, 2013]

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- MESE regularized NNLS (RNNLS)  $f_M$  estimates

## Two-Compartment Simulation without Model Mismatch

Simulated data to arise from **two** water compartments  
each with different nominal  $T_2$  values but **same nominal  $T_1$  value**

- DESS  $f_F$  estimates use known  $s^t$
- MESE  $f_M$  estimates use known  $s^t$ , bulk  $T_1$



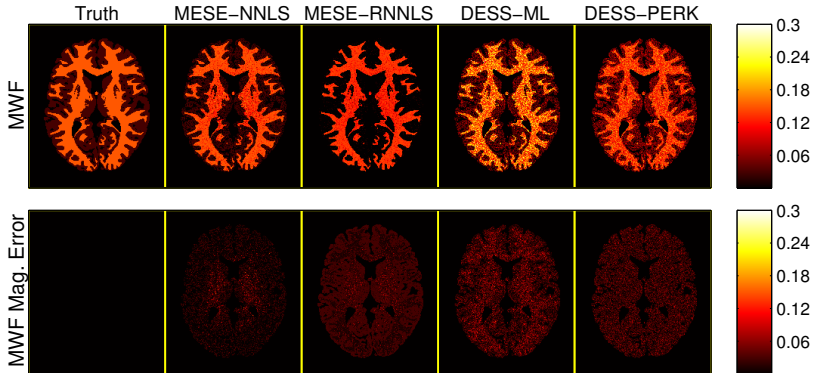
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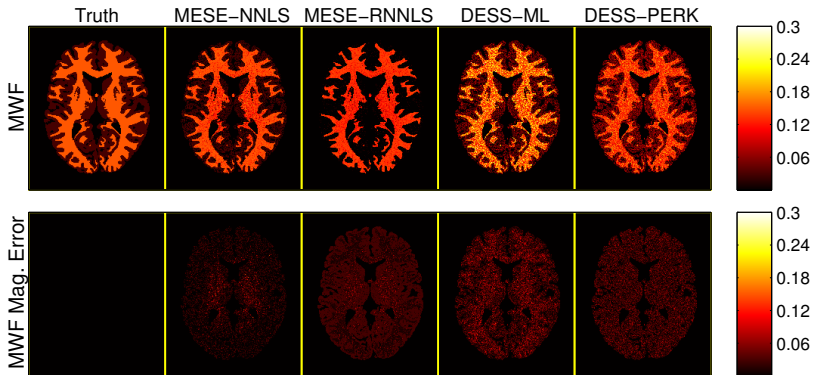
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- MESE  $f_M$  estimates use known  $s^t$ , bulk  $T_1$

Since no model mismatch,  $f_F$  and  $f_M$  estimates are comparable

# Two-Compartment Simulation Result



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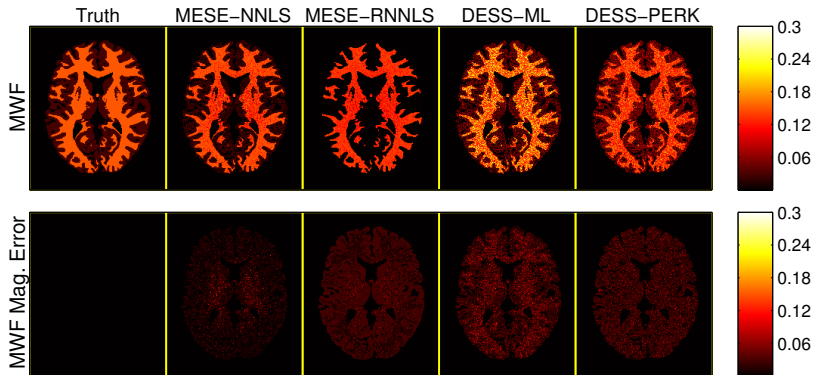
estimation time:

~5h

33.8s train

1.0s test

# Two-Compartment Simulation Result



estimation time:

~5h

33.8s train

1.0s test

WM RMSE:

0.0225

0.0260

0.0433

0.0305

## Three-Compartment Simulation with Model Mismatch

Next simulated data to arise from **three** water compartments each with different nominal  $T_2$  **and**  $T_1$  **values**

- DESS  $f_F$  estimators now incur bias  
due to two-compartment model assumption
- MESE  $f_M$  estimators now incur bias  
due to bulk- $T_1$  model assumption (significant for  $T_R \sim 1s$ )

# Three-Compartment Simulation with Model Mismatch

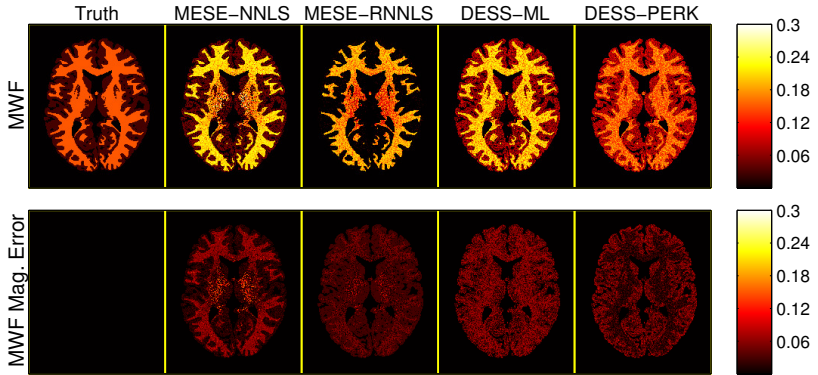
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- MESE  $f_M$  estimators now incur bias  
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Due to model mismatch,

$f_F$  and  $f_M$  estimates **need not be comparable**.

# Three-Compartment Simulation Result

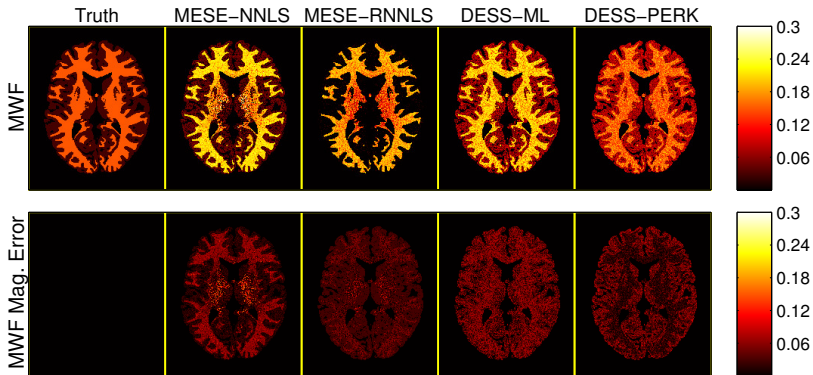


estimation time:

~5h

34.2s train  
1.1s test

# Three-Compartment Simulation Result



estimation time:

~5h

34.2s train

1.1s test

WM RMSE:

0.0618

0.0406

0.0559

0.0254



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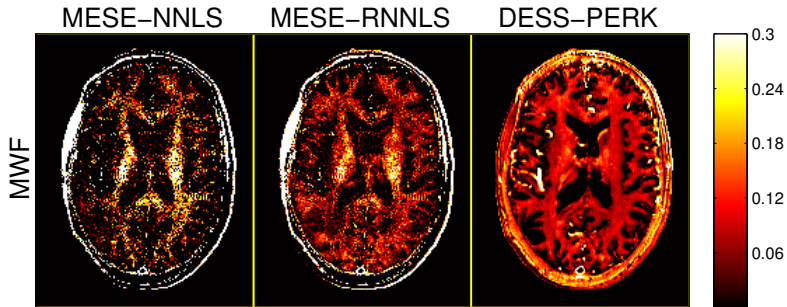
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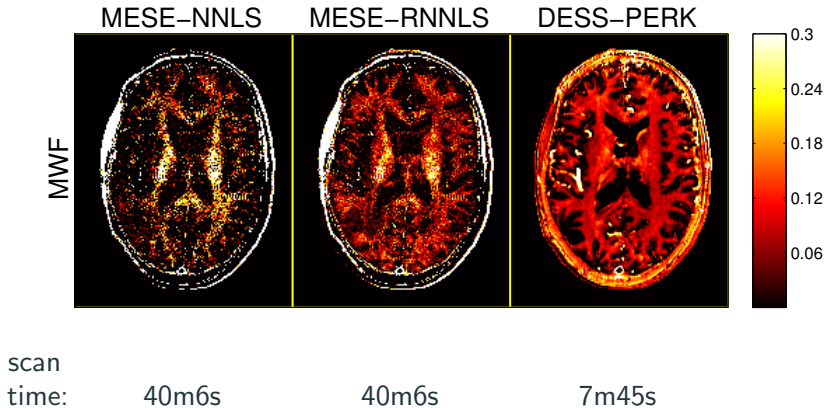
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## In vivo Results



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- Combine PERK with image reconstruction

## Numerical Simulation: Acquisition Design

- Simulated many WM-like, GM-like voxel realizations
- Studied sample statistics of  $T_1, T_2$  ML estimates  $\hat{T}_1^{\text{ML}}, \hat{T}_2^{\text{ML}}$

| Profile                    | (2, 1)         | (1, 1)         | (0, 2)          | Truth |
|----------------------------|----------------|----------------|-----------------|-------|
| WM $\hat{T}_1^{\text{ML}}$ | $830 \pm 17$   | $830 \pm 15$   | $830 \pm 14$    | 832   |
| GM $\hat{T}_1^{\text{ML}}$ | $1330 \pm 30.$ | $1330 \pm 24$  | $1330 \pm 24$   | 1331  |
| WM $\hat{T}_2^{\text{ML}}$ | $80. \pm 1.0$  | $80. \pm 2.1$  | $79.6 \pm 0.94$ | 79.6  |
| GM $\hat{T}_2^{\text{ML}}$ | $110. \pm 1.4$ | $110. \pm 3.0$ | $110. \pm 1.6$  | 110   |

**Table 3:**  $\hat{T}_1^{\text{ML}}, \hat{T}_2^{\text{ML}}$  sample means  $\pm$  sample standard deviations

# A Function Space over which Optimization is Tractable

**Hilbert space:** complete inner product function space

## Reproducing kernel Hilbert space (RKHS)

Hilbert space  $\mathbb{H}$  over input space  $\mathcal{Q}$  with *reproducing property*

$$\langle h, k(\cdot, \mathbf{q}) \rangle_{\mathbb{H}} = h(\mathbf{q}), \quad \forall h \in \mathbb{H}, \mathbf{q} \in \mathcal{Q}$$

for some  $k : \mathcal{Q}^2 \mapsto \mathbb{R}$  called a **reproducing kernel (RK)**

## Relevant facts

- Bijection between RKHS  $\mathbb{H}$  and RK  $k$  [Aronszajn, 1950]
- Function  $k(\cdot, \mathbf{q}) \in \mathbb{H}$  called a *feature mapping*

## Function Optimization over a RKHS

**Choose:** RK  $k : \mathcal{Q}^2 \mapsto \mathbb{R}$  that induces choice of RKHS  $\mathbb{H}$

**Solve:** for each desired latent parameter  $l \in \{1, \dots, L\}$ ,

$$\left( \hat{h}_l, \hat{b}_l \right) \in \left\{ \arg \min_{\substack{h_l \in \mathbb{H} \\ b_l \in \mathbb{R}}} \frac{1}{N} \sum_{n=1}^N (h_l(\mathbf{q}_n) + b_l - x_{l,n})^2 + \rho_l \|h_l\|_{\mathbb{H}}^2 \right\} \quad (13)$$

- Optimal  $\hat{h}_l$  over  $\mathbb{H}$  takes form [Schölkopf et al., 2001]

$$\hat{h}_l(\cdot) \equiv \sum_{n=1}^N \hat{a}_{l,n} k(\cdot, \mathbf{q}_n) \quad (14)$$

- Plug (14) into (13); solve now instead for  $(\hat{a}_l, \hat{b}_l)$ ; construct:

$$\hat{x}_l(\cdot) = \sum_{n=1}^N \hat{a}_{l,n} k(\cdot, \mathbf{q}_n) + \hat{b}_l \quad (15)$$

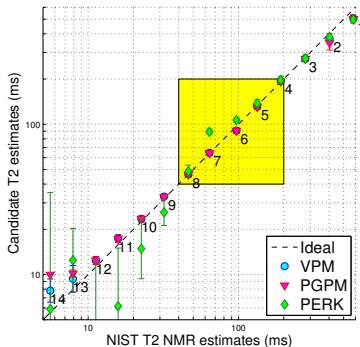
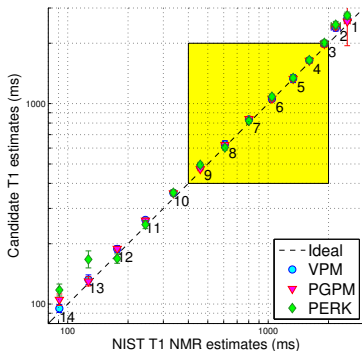


## Numerical Simulation: PERK Estimation

|          | Truth | VPM                       | PGPM                      | PERK                      |
|----------|-------|---------------------------|---------------------------|---------------------------|
| WM $T_1$ | 832   | $832.1 \pm 17.2$ (17.2)   | $832.1 \pm 16.2$ (16.2)   | $833.0 \pm 16.5$ (16.5)   |
| GM $T_1$ | 1331  | $1331.5 \pm 31.1$ (31.1)  | $1331.2 \pm 29.7$ (29.7)  | $1332.1 \pm 30.4$ (30.4)  |
| WM $T_2$ | 79.6  | $79.61 \pm 0.988$ (0.988) | $79.60 \pm 0.952$ (0.952) | $79.46 \pm 0.978$ (0.989) |
| GM $T_2$ | 110.  | $110.02 \pm 1.40$ (1.40)  | $110.02 \pm 1.35$ (1.35)  | $109.91 \pm 1.35$ (1.35)  |

**Table 4:** Sample means  $\pm$  sample standard deviations (RMSEs) of VPM, PGPM, and PERK  $m_0$ ,  $T_1$ ,  $T_2$  estimates, computed in simulation over 7810 WM-like and 9162 GM-like voxels.

# Mismatch in Scan Design vs. Sampling Dist Support



Widening  $\text{supp}(p_{x,\nu})$  degrades performance w/in scan design range.  
Thus, scan design and param est should be considered in tandem.



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