

**Test Name : Oct-MidTerm-T1-AY2021-22-
CS513-Software-Systems****Name : Harsh Shah -
harsh.shah050@iitb.ac.in****Test Start Time**

22/10/2021, 11:28:02 AM

Marks Scored

33.0 / 50.0

Total Questions**20****Attempted Questions****14****Correct Questions****11****Incorrect Questions****3****Skipped Questions****6****Pending Evaluation****0****Reevaluation application status****Not Applied****Actions****Apply for reevaluation****List of Sections****Section A****Marks per question : 7.0 | Marks Scored : 28.5**

Q No.	Q. Type	Status	Marks
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1	File Upload	✓	5.5
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Hide Answer

Servers can be designed to limit the number of open connections. For example, a server may wish to have only N socket connections at any point in time. As soon as N connections are made, the server will not accept another incoming connection until an existing connection is released. Explain how semaphores can be used by a server to limit the number of concurrent connections in Socket Programming.

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P_r is given higher priority and P_H will be given lower priority.

→ So by this, problem is solved.

9.

→ Socket is a medium in the internet for the process to communicate between processes.

→ Socket Mens simply TCP + PORT.

2

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7.0

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Explain the following kernel types with suitable Architecture diagrams

- a. Monolithic
- b. Micro
- c. Hybrid

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International Institute of Information Technology Bangalore
 (Formerly Indian Institute of Information Technology)

Subject: Software System	Date: 22/10/21
Name: Harsh P. Shah	Roll No.: M72021050
Part - A	
1. → kernel is a interface between user application and hardware. → It provides interaction between user and hardware with the help of IPC, systemcalls. → kernel is the first thing that loads into Memory (After bootloader) → kernel is present in the RAM. It will be present in the RAM till OS shuts down. There is dedicated space in the Memory (RAM) for kernel. And rest will be given to user as per its requirement. → There are three types of kernel. ① Monolithic kernel ② Micro kernel ③ Hybrid kernel.	

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3 File Upload ✓

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Assume XFS file system has 15 direct and (one) single indirect and (one) double indirect data blocks. Each data block size is 4 KiB. The single and double indirect blocks store only addresses of data blocks. Each data block's address size is 4 bytes.

- What is the maximum size of a file that you can store in the above file system?
- If each data block has stored a single file then how many files can be stored in the file system? What would be the maximum number of inode entries in the inode block?

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5 Q 41 % Q C

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3. Given Data,

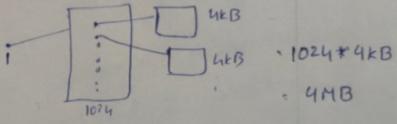
Number of Direct Block = 15
 Number of single indirect Block = 1
 Number of double indirect Block = 1

DBS = 4KB
 DBA = 4B

∴ Max number of address a file can store
 $= \frac{4KB}{4B} = 1K = 1024$

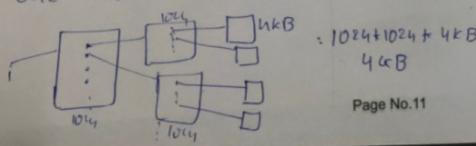
a. Maximum file size

1. 15 Direct block
 $\therefore 15 \times 4KB = 60 KB$
2. One Single indirect Block



$$\begin{aligned} & \text{1. } 15 \text{ Direct block} \\ & \therefore 15 \times 4KB = 60 KB \\ & \text{2. One Single indirect Block} \\ & \quad \begin{array}{l} \text{Diagram: A vertical stack of 1024 slots, each pointing to a 4KB block.} \\ \text{Calculation: } 1024 \times 4KB = 4MB \end{array} \end{aligned}$$

3. One double indirect Block



$$\begin{aligned} & \text{3. One double indirect Block} \\ & \quad \begin{array}{l} \text{Diagram: A vertical stack of 1024 slots, each pointing to another level of 1024 slots, which then point to 4KB blocks.} \\ \text{Calculation: } 1024 \times 1024 \times 4KB = 4GB \end{array} \end{aligned}$$

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File
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2.0

[Hide Answer](#)

Answer the following with suitable diagrams:

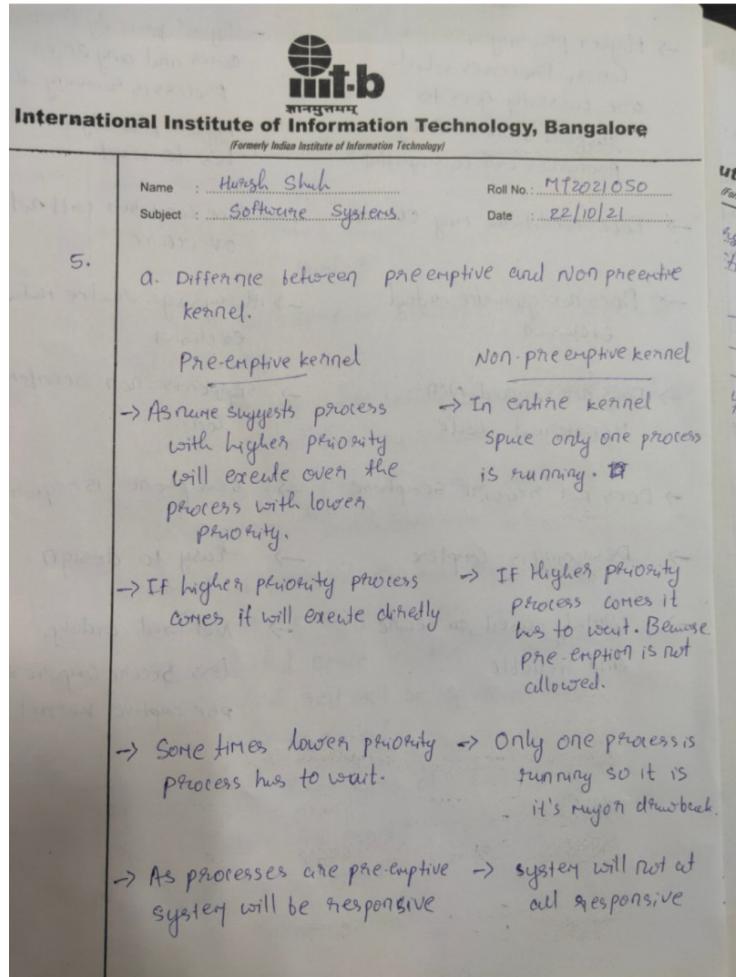
- Explain the difference between preemptive and non-preemptive kernel.
- In pre-emptive scheduling, when will a higher priority process can be blocked by a lower priority process and how do you overcome this problem?

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Evaluator Comments

part b not attempted

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7.0

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Explain the following process states with process state diagram :

- a. TASK_RUNNING
- b. TASK_INTERRUPTIBLE
- c. TASK_UNINTERRUPTIBLE
- d. TASK_STOPPED
- e. TASK_ZOMBIE

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Choice -
Single
Answer

When a process is executing in kernel mode, if it receives any signal the signal will be executed:

- when it returns to user mode
- immediately
- when it is in protected mode
- not predictable

2 Multiple ✓ 1.0

[Hide Answer](#)

Orphan process's pid is -----.

- init pid.
- systemd pid
- its own pid
- 1

3 Multiple ⚠ 0.0

[Hide Answer](#)

If a process exits without unlocking a semaphore, which one of the following should be assigned in the sem_flg (in the sembuf structure) to release the semaphore?

- SEM_EXIT
- IPC_NOWAIT
- SEM_RELEASE
- SEM_UNDO

4 Multiple ✓ 1.0

[Hide Answer](#)

Which functionality is handled by the architecture-dependent code of the kernel?

- Network communication support
- Terminal-interface driver
- IPC
- Input-Output Runtime Support

5 Multiple Choice - Single Answer ⚠ 0.0

[Hide Answer](#)

Which one of the following is never set as value of backlog argument in the listen () system call?

- 5
- 0
- 1
- 3

6 Multiple Choice - Single Answer ✖ -0.5

[Hide Answer](#)

Which of the following is false regarding shared memory?

- shmemget () is used to create a shared memory segment.
- Shared Memory is a much faster method of communication than either semaphores or message queues.
- Shared Memory does not require an intermediate buffer.
- On success, shmemget () returns 1 else return -1.

7 Multiple Choice - Single Answer ⚠ 0.0

[Hide Answer](#)

On the expiration of ITIMER_REAL will generate the ----- signal.

- SIGVTALRM
- SIGALRM
- SIGHUP
- SIGTSTP

8	Multiple Choice - Single Answer		-0.5	<button>Hide Answer</button>
Which of the following command /system call is used to change the real-time attributes of a process?				
<input checked="" type="radio"/> nice				
<input type="radio"/> chmod				
<input type="radio"/> chrt				
<input type="radio"/> sched_get_priority_max				
9	Multiple Choice - Single Answer		1.0	<button>Hide Answer</button>
What is buffer/cache?				
<input type="radio"/> It is an on-disk memory that stores the recently accessed data from a file system.				
<input type="radio"/> It is another caching device like the primary cache to improve paging performance.				
<input checked="" type="radio"/> It is an in-memory store that stores the recently accessed data from a filesystem.				
<input type="radio"/> None of the above.				
10	Multiple Choice - Single Answer		1.0	<button>Hide Answer</button>
Which one of the following is the disadvantage of a message queue?				
<input checked="" type="radio"/> All of the options				
<input type="radio"/> very expensive for large data transfer				
<input type="radio"/> during message sending, the message is copied from the user buffer into the kernel buffer				
<input type="radio"/> a message in a queue cannot be reused				
11	Multiple Choice - Single Answer		0.0	<button>Hide Answer</button>
In the msgrecv function, if the msgrtype argument is some negative integer value means, the message will be retrieved in:				
<input type="radio"/> the exact value of the message type				

- FIFO order
- first message or <= to the absolute value
- depends on the priority of the messages

12 Multiple Choice - Single Answer ✓ 1.0

Hide Answer

Which one of the following is false regarding a FIFO?

- zero buffering capacity.
- communicate between only related processes.
- half-duplex.
- uses circular buffer.

13 Multiple Choice - Single Answer ⚠ 0.0

Hide Answer

A successful execl() call changes (choose more appropriate one)

- Address space, process image, resetting pending signals, pid.
- only the address space and process image and files.
- Address space, process image, reset pending signals and dropping existing memory locks.
- Address space, process image, resetting pending signals.

14 Multiple Choice - Single Answer ⚠ 0.0

Hide Answer

Which of the signals cannot be caught or ignored:

- SIGILL
- SIGSTOP
- SIGSEGV
- SIGFPE

15 Multiple Choice - Single Answer ✓ 1.0

Hide Answer

Multiple

Choice -

Single

Answer

[Hide Answer](#)

How many times getpid () will be executed?

```
#include<stdio.h>
main()
{
    int i;
    for (i = 1; i <= 5; i++)
        fork();
    printf("my pid = %d\n", getpid());
}
```

 32 16 31 5