VISVESVARAYA TECHNOLOGICAL UNIVERSITY

"JnanaSangama", Belgaum -590014, Karnataka.



LAB REPORT on

Artificial Intelligence (23CS5PCAIN)

Submitted by

Gopal Agrawal(1BM22CS361)

in partial fulfillment for the award of the degree of BACHELOR OF ENGINEERING
in
COMPUTER SCIENCE AND ENGINEERING



B.M.S. COLLEGE OF ENGINEERING
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B.M.S. College of Engineering,

Bull Temple Road, Bangalore 560019

(Affiliated To Visvesvaraya Technological University, Belgaum)

Department of Computer Science and Engineering



CERTIFICATE

This is to certify that the Lab work entitled "Artificial Intelligence (23CS5PCAIN)" carried out by Gopal Agrawal(1BM22CS361), who is bonafide student of B.M.S. College of Engineering. It is in partial fulfillment for the award of Bachelor of Engineering in Computer Science and Engineering of the Visvesvaraya Technological University, Belgaum. The Lab report has been approved as it satisfies the academic requirements in respect of an Artificial Intelligence (23CS5PCAIN) work prescribed for the said degree.

Saritha A.N Assistant Professor Department of CSE, BMSCE Dr. Kavitha Sooda Professor & HOD Department of CSE, BMSCE

Index

Sl. No.	Date	Experiment Title	Page No.
1	4-10-2024	Implement Tic –Tac –Toe Game Implement vacuum cleaner agent	
2	18-10-2024	Implement 8 puzzle problems using Depth First Search (DFS) Implement Iterative deepening search algorithm	
3	25-10-2024	Implement A* search algorithm	
4	8-11-2024	Implement Hill Climbing search algorithm to solve N-Queens problem	
5	15-11-2024	Simulated Annealing to Solve 8-Queens problem	
6	22-11-2024	Create a knowledge base using propositional logic and show that the given query entails the knowledge base or not.	
7	29-12-2024	Implement unification in first order logic	
8	6-12-2024	Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.	
9	6-12-2024	Create a knowledge base consisting of first order logic statements and prove the given query using Resolution	
10	13-12-2024	Implement Alpha-Beta Pruning.	

 $\underline{\textbf{GITHUB LINK:}} \ \text{https://github.com/gopalagrawalcs/AL-LAB}$

Program 1
Implement Tic –Tac –Toe
Game

Algorithm:

Algorithm:	Mark and the second
	Date 4/10/24
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7:1 8:01 4, 9:0 10.3	AND IN A PROPERTY OF
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def Point Board (board):	
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return True	102
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```
Code:
```

```
def print_board(board):
  print("\n")
  for row in board:
     print("|".join(row))
     print("-" * 5)
  print("\n")
def check_winner(board, player):
  for row in board:
     if all([cell == player for cell in row]):
       return True
  for col in range(3):
     if all([board[row][col] == player for row in range(3)]):
       return True
  if board[0][0] == player and board[1][1] == player and board[2][2] == player:
     return True
  if board[0][2] == player and board[1][1] == player and board[2][0] == player:
     return True
  return False
def is_board_full(board):
  return all([cell != ' ' for row in board for cell in row])
```

```
def player_move(board, player):
  while True:
     try:
       move = int(input(f"Player {player}, enter your move (1-9): ")) - 1
       if move < 0 or move >= 9:
         raise ValueError
       row, col = divmod(move, 3)
       if board[row][col] == ' ':
          board[row][col] = player
          break
       else:
         print("This spot is already taken. Try again.")
     except ValueError:
       print("Invalid input. Enter a number between 1 and 9.")
def play_game():
  board = [[''for_in range(3)] for_in range(3)]
  current_player = 'X'
  game_over = False
  print("Welcome to Tic Tac Toe!")
  print("Player X goes first.")
  print("Enter a number between 1-9 to make your move (1 is top-left and 9 is
bottom-right).")
```

```
print_board(board)
while not game_over:

player_move(board, current_player)
print_board(board)
if check_winner(board, current_player):
    print(f"Player {current_player} wins!")
    game_over = True
elif is_board_full(board):
    print("It's a tie!")
    game_over = True
else
current_player = 'O' if current_player == 'X' else 'X'
if _name__ == "_main_":
    play_game()
```

Implement Vaccum Cleaner Agent

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a valcum cleanex	Emulando #A-
Algo:	Delica State Martina
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(1) Institute the a	gents starting (x, x)
(2) Loop unil all	cells are sean:
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(B) 3 f and call &	a distry:
(i) clean the	correct cell
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```
Code:
if state ['A'] == 0 and state ['B'] == 0:
print("Turning vacuum off") return
      if state[loc] == 1:
         state[loc] = 0
         count += 1
         print(f"Cleaned {loc}.")
         next_loc = 'B' if loc == 'A' else 'A'
         state[loc] = int(input(f"Is {loc} clean now? (0 if clean, 1 if dirty): "))
         if(state[next_loc]!=1):
          state[next_loc]=int(input(f"Is {next_loc} dirty? (0 if clean, 1 if dirty): "))
      if(state[loc]==1):
        rec(state,loc)
      else:
       next_loc = 'B' if loc == 'A' else 'A'
        dire="left" if loc=="B" else "right"
        print(loc,"is clean")
        print(f"Moving vacuum {dire}")
        if state[next_loc] == 1:
          rec(state, next_loc)
    state = \{\}
```

```
state['A'] = int(input("Enter state of A (0 for clean, 1 for dirty): "))
state['B'] = int(input("Enter state of B (0 for clean, 1 for dirty): "))
loc = input("Enter location (A or B): ")
rec(state, loc)
print("Cost:",count)
print(state)

Enter state of A (0 for clean, 1 for dirty): 0
Enter state of B (0 for clean, 1 for dirty): 0
Enter location (A or B): A
Turning vacuum off
Cost: 0
{'A': 0, 'B': 0}
```

Program 2
Implement 8 puzzle problems using (DFS) and (BFS)

1AB-3
Page
Q 8-Puzzle game
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BFS:
Algor Let trange be a list containing the
tration State
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Mode + remove - 1988+ (forge)
If NODE in a good
then return the path from Indial state
to Niche.
elle generale all successor of mode
and add generated nodes to the
End Loop back of Foliage (in levels).
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- DFS- Badarant Francisco
Algoi lot folinge be a list containing the
initial state.
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and add generated nodes to me land
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```
CODE:for dfs
goal_state=[
[1,2,3],
[4,5,6],
[7, 8, 0]]
    def is_goal(state):
      return state == goal_state
    def find_blank(state):
      for i in range(3):
         for j in range(3):
            if state[i][j] == 0:
              return i, j
    def swap(state, i1, j1, i2, j2):
      new_state = [row[:] for row in state]
      new_state[i1][j1], new_state[i2][j2] = new_state[i2][j2], new_state[i1][j1]
      return new_state
    def get_neighbors(state):
      neighbors = []
      i, j = find_blank(state)
      if i > 0:
         neighbors.append(swap(state, i, j, i - 1, j))
      if i < 2:
         neighbors.append(swap(state, i, j, i + 1, j))
      if j > 0:
         neighbors.append(swap(state, i, j, i, j - 1))
      if j < 2:
```

```
neighbors.append(swap(state, i, j, i, j + 1))
   return neighbors
def dfs(state, visited, path):
  state_tuple = tuple(tuple(row) for row in state)
  if state_tuple in visited:
     return None
  visited.add(state_tuple)
  if is_goal(state):
     return path
  for neighbor in get_neighbors(state):
     result = dfs(neighbor, visited, path + [neighbor])
     if result is not None:
        return result
  return None
initial\_state = [[1, 2, 3],
           [4, 0, 6],
           [7, 5, 8]]
visited = set()
solution = dfs(initial_state, visited, [])
```

```
if solution:

print("Solution found in", len(solution), "steps:")

for step in solution:

for row in step:

print(row)

print()

else:

print("No solution found.")

Solution found in 2 steps:

[1, 2, 3]
[4, 5, 6]
[7, 0, 8]

[1, 2, 3]
[4, 5, 6]
[7, 8, 0]
```

```
CODE: for bfs
```

```
class PuzzleState:
  def __init__(self, board, moves=0):
     self.board = board
     self.blank\_index = board.index(0) # Find the index of the blank space(0)
     self.moves = moves
  def get_possible_moves(self):
     possible_moves = []
     row, col = divmod(self.blank_index, 3)
     # Define possible movements: up, down, left, right
     directions = [(-1, 0), (1, 0), (0, -1), (0, 1)] # (row_change, col_change)
     for dr, dc in directions:
       new\_row, new\_col = row + dr, col + dc
       if 0 \le \text{new\_row} \le 3 and 0 \le \text{new\_col} \le 3:
          new_blank_index = new_row * 3 + new_col
          new_board = self.board[:]
          # Swap the blank with the adjacent tile
          new_board[self.blank_index], new_board[new_blank_index] =
new_board[new_blank_index], new_board[self.blank_index]
          possible_moves.append(PuzzleState(new_board, self.moves + 1))
     return possible_moves
```

def is_goal(self, goal_state):

```
def depth_limited_search(state, depth, goal_state):
  if state.is_goal(goal_state):
     return state
  if depth == 0:
     return None
  for next_state in state.get_possible_moves():
     result = depth_limited_search(next_state, depth - 1, goal_state)
     if result is not None:
       return result
  return None
def iterative_deepening_search(initial_state, goal_state):
  depth = 0
  while True:
     result = depth_limited_search(initial_state, depth, goal_state)
     if result is not None:
       return result
     depth += 1
```

return self.board == goal_state

```
# Example Usage
if __name__ == "__main__":
  initial_board = [2, 8, 3, 1, 6, 4, 7, 0, 5] # Initial state
  goal_state = [2, 0, 3, 1, 8, 4, 7, 6, 5] # Final state
  initial_state = PuzzleState(initial_board)
  solution = iterative_deepening_search(initial_state, goal_state)
  if solution:
     print("Solution found!")
     print("Moves:", solution.moves)
     print("Final Board State:", solution.board)
  else:
     print("No solution found.")
```

Solution found!

Moves: 2

Final Board State: [2, 0, 3, 1, 8, 4, 7, 6, 5]

Program 3

Implement A* Search Algorithm

Misplaced Tiles:

Tilispi	aced Tiles.
	LAB-03 Date 25/10/24 Page 8
-	A* algorithm:
	Anchon A* seasch (problem) return a saution
	or taluxe
10.10	node to node n were n-state problem in
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	and a the second of the second
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```
import heapq
      def manhattan_distance(state, goal):
      distance = 0
      for i in range(3):
         for j in range(3):
            tile = state[i][j]
           if tile != 0:
              for r in range(3):
                 for c in range(3):
                    if goal[r][c] == tile:
                      target_row, target_col = r, c
                      break
              distance += abs(target_row - i) + abs(target_col - j)
      return distance
    def findmin(open_list, goal):
      minv = float('inf')
      best_state = None
      for state in open_list:
         h = manhattan_distance(state['state'], goal)
         f = state['g'] + h
         if f < minv:
            minv = f
            best_state = state
      open_list.remove(best_state)
```

```
def operation(state):
  next_states = []
  blank_pos = find_blank_position(state['state'])
  for move in ['up', 'down', 'left', 'right']:
     new_state = apply_move(state['state'], blank_pos, move)
     if new_state:
       next_states.append({
          'state': new_state,
          'parent': state,
          'move': move,
          'g': state['g'] + 1
        })
  return next_states
def find_blank_position(state):
  for i in range(3):
     for j in range(3):
       if state[i][j] == 0:
          return i, j
```

return best_state

return None

```
def apply_move(state, blank_pos, move):
  i, j = blank_pos
  new_state = [row[:] for row in state]
  if move == 'up' and i > 0:
     new_state[i][j], new_state[i - 1][j] = new_state[i - 1][j], new_state[i][j]
  elif move == 'down' and i < 2:
     new_state[i][j], new_state[i+1][j] = new_state[i+1][j], new_state[i][j]
  elif move == 'left' and j > 0:
     new_state[i][j], new_state[i][j-1] = new_state[i][j-1], new_state[i][j]
  elif move == 'right' and j < 2:
     new_state[i][j], new_state[i][j+1] = new_state[i][j+1], new_state[i][j]
  else:
     return None
  return new_state
def print_state(state):
  for row in state:
     print(' '.join(map(str, row)))
initial_state = [[2, 8, 3], [1, 6, 4], [7, 0, 5]]
goal\_state = [[1, 2, 3], [8, 0, 4], [7, 6, 5]]
open_list = [{'state': initial_state, 'parent': None, 'move': None, 'g': 0}]
visited_states = []
```

```
while open_list:
  best_state = findmin(open_list, goal_state)
  h = manhattan_distance(best_state['state'], goal_state)
  f = best\_state['g'] + h
  print(f''g(n) = \{best\_state['g']\}, h(n) = \{h\}, f(n) = \{f\}''\}
  print_state(best_state['state'])
  print()
  if h == 0:
     print("Goal state reached!")
     break
  visited_states.append(best_state['state'])
  next_states = operation(best_state)
  for state in next_states:
     if state['state'] not in visited_states:
        open_list.append(state)
```

if h == 0:

```
moves = []
         goal_state_reached = best_state
         while goal_state_reached['move'] is not None:
            moves.append(goal_state_reached['move'])
            goal_state_reached = goal_state_reached['parent']
         moves.reverse()
         print("\nMoves to reach the goal state:", moves)
     else:
        print("No solution found.")
g(n) = 0, h(n) = 5, f(n) = 5
2 8 3
1 6 4
7 0 5
g(n) = 1, h(n) = 4, f(n) = 5
2 8 3
1 0 4
7 6 5
g(n) = 2, h(n) = 3, f(n) = 5
2 0 3
1 8 4
7 6 5
g(n) = 3, h(n) = 2, f(n) = 5
0 2 3
1 8 4
7 6 5
g(n) = 4, h(n) = 1, f(n) = 5
1 2 3
0 8 4
7 6 5
```

g(n) = 5, h(n) = 0, f(n) = 5 1 2 3 8 0 4 7 6 5

Moves to reach the goal state: ['up', 'up', 'left', 'down', 'right']

```
Misplaced Tiles:
          import heapq
       defind_blank_tile(st
          ate):
       for i in range(3):
          for j in range(3):
       if state[i][j] == 0:
          return i, j
  return None
def count_misplaced_tiles(state, goal):
  misplaced = 0
  for i in range(3):
     for j in range(3):
       if state[i][j] != 0 and state[i][j] != goal[i][j]:
          misplaced += 1
  return misplaced
def generate_moves(state):
  moves = []
  x, y = find_blank_tile(state)
  directions = [(-1, 0), (1, 0), (0, -1), (0, 1)]
  for dx, dy in directions:
     new_x, new_y = x + dx, y + dy
```

```
moves.append(new_state)
  return moves
def print_state(state):
  for row in state:
     print(row)
  print()
def a_star_8_puzzle(start, goal):
  open_list = []
  heapq.heappush(open_list, (count_misplaced_tiles(start, goal), 0, start, None))
  visited = set()
  while open_list:
     f_n, g_n, current_state, previous_state = heapq.heappop(open_list)
     print(f"g(n) = \{g_n\}, h(n) = \{f_n - g_n\}, f(n) = \{f_n\}")
     print_state(current_state)
```

```
if current_state == goal:
                 print("Goal state reached!")
                return
             visited.add(tuple(map(tuple, current_state)))
             for move in generate_moves(current_state):
                 move_tuple = tuple(map(tuple, move))
                if move_tuple not in visited:
                    g_{move} = g_n + 1
                    h_move = count_misplaced_tiles(move, goal)
                    f_{move} = g_{move} + h_{move}
                    heapq.heappush(open_list, (f_move, g_move, move, current_state))
     start\_state = [[2, 8, 3], [1, 6, 4], [7, 0, 5]]
     goal\_state = [[1, 2, 3], [8, 0, 4], [7, 6, 5]]
     a_star_8_puzzle(start_state, goal_state)
g(n) = 0, h(n) = 4, f(n) = 4

[2, 8, 3]

[1, 6, 4]

[7, 0, 5]
g(n) = 1, h(n) = 3, f(n) = 4

[2, 8, 3]

[1, 0, 4]

[7, 6, 5]
g(n) = 2, h(n) = 3, f(n) = 5

[2, 0, 3]

[1, 8, 4]

[7, 6, 5]
g(n) = 2, h(n) = 3, f(n) = 5

[2, 8, 3]

[0, 1, 4]

[7, 6, 5]
g(n) = 3, h(n) = 2, f(n) = 5

[0, 2, 3]

[1, 8, 4]

[7, 6, 5]
g(n) = 5, h(n) = 0, f(n) = 5

[1, 2, 3]

[8, 0, 4]

[7, 6, 5]
```

Goal state reached!

Program 4

Implement Hill Climbing search algorithm to solve N-Queens problem.

	LAB-Y
	Page CA
11-2	HILL Clark algosthing Later 18
	Algorithms
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	function Hall clamb (problem)
	oction a solution cos) fallure
	waren't node with a titen about studen
	soop do Mark O Carlo
	neighboure a highest valued successor of
	current 3110
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```
import random
class NQueens:
  def __init__(self, n):
     self.n = n
     self.board = self.init_board()
  def init_board(self):
     # Randomly place one queen in each column
     return [random.randint(0, self.n - 1) for _ in range(self.n)]
  def fitness(self, board):
     # Count the number of pairs of queens attacking each other
     conflicts = 0
     for col in range(self.n):
       for other_col in range(col + 1, self.n):
          if board[col] == board[other_col] or abs(board[col] - board[other_col]) == abs(col -
other_col):
            conflicts += 1
     return conflicts
  def get_neighbors(self, board):
     neighbors = []
     for col in range(self.n):
       for row in range(self.n):
          if row != board[col]: # Move queen to a different row in the same column
            new_board = board[:]
```

```
new_board[col] = row
          neighbors.append(new_board)
  return neighbors
def hill_climbing(self):
  current_board = self.board
  current_fitness = self.fitness(current_board)
  while current_fitness > 0:
     neighbors = self.get_neighbors(current_board)
     next_board = None
     next\_fitness = current\_fitness
    for neighbor in neighbors:
       neighbor_fitness = self.fitness(neighbor)
       if neighbor_fitness < next_fitness:
          next_fitness = neighbor_fitness
          next_board = neighbor
    if next_board is None:
       # Stuck at local maximum, can either return or restart
       print("Stuck at local maximum. Restarting...")
       self.board = self.init_board()
       current_board = self.board
       current_fitness = self.fitness(current_board)
     else:
```

```
current\_board = next\_board
                current\_fitness = next\_fitness
          return current_board
    # Example usage
    if __name__ == "__main__":
       n = 4 # Size of the board (N)
       n_queens_solver = NQueens(n)
       solution = n_queens_solver.hill_climbing()
       print("Solution:")
       for row in solution:
          line = ['Q' \text{ if } i == \text{row else '.' for } i \text{ in } range(n)]
          print(' '.join(line))
Solution:
. Q . .
. . . Q
Q . . .
. . Q .
```

Simulated Annealing to Solve 8-Queens problem.

PAB-5
Date 13/11/24
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cato:
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fox en ange (n):
fox i in range (i+1, N):
Susts = Carpon Fi
confinit +1; return conflict

```
import random
import math
def print_board(state):
  size = len(state)
  for i in range(size):
     row = ['.'] * size
     row[state[i]] = 'Q'
     print(''.join(row))
  print()
def calculate_conflicts(state):
  conflicts = 0
  size = len(state)
  for i in range(size):
     for j in range(i + 1, size):
       if state[i] == state[j] or abs(state[i] - state[j]) == abs(i - j):
          conflicts += 1
  return conflicts
def random_state(size):
  return [random.randint(0, size - 1) for _ in range(size)]
```

```
def neighbor(state):
  new_state = state[:]
  idx = random.randint(0, len(state) - 1)
  new_state[idx] = random.randint(0, len(state) - 1)
  return new_state
def simulated_annealing(size, initial_temp, cooling_rate):
  current_state = random_state(size)
  current_conflicts = calculate_conflicts(current_state)
  temperature = initial_temp
  while temperature > 1:
     new_state = neighbor(current_state)
     new_conflicts = calculate_conflicts(new_state)
    # If new state is better, accept it
    if new_conflicts < current_conflicts:
       current_state, current_conflicts = new_state, new_conflicts
     else:
       # Accept with a probability based on temperature
       acceptance_probability = math.exp((current_conflicts - new_conflicts) / temperature)
       if random.random() < acceptance_probability:
          current_state, current_conflicts = new_state, new_conflicts
```

```
temperature *= cooling_rate
  return current_state
def main():
  size = 8
  initial\_temp = 1000
  cooling\_rate = 0.995
  solution = simulated_annealing(size, initial_temp, cooling_rate)
  print("Solution found:")
  print_board(solution)
  print("Conflicts:", calculate_conflicts(solution))
if __name__ == "__main__":
  main()
```


Conflicts: 6

```
Program 6:
def truth_table_entailment():
      print(f"{'A':<7}{'B':<7}{'C':<7}{'A or C':<12}{'B or not C':<15}{'KB':<8}{'alpha':<10}")
      print("-" * 65)
      all_entail = True
      for A in [False, True]:
        for B in [False, True]:
           for C in [False, True]:
             # Calculate individual components
             A_{or}C = A \text{ or } C
                                            # A or C
             B_{or_not_C} = B \text{ or (not } C)
                                               #B or not C
             KB = A\_or\_C and B\_or\_not\_C # KB = (A or C) and (B or not C)
              alpha = A or B
                                         # alpha = A or B
             # Determine if KB entails alpha for this row
             kb_entails_alpha = (not KB) or alpha # True if KB implies alpha
             # If in any row KB does not entail alpha, set flag to False
             if not kb_entails_alpha:
                all_entail = False
```

 $print(f"\{str(A):<7\}\{str(B):<7\}\{str(C):<7\}\{str(A_or_C):<12\}\{str(B_or_not_C):<15\}\{str(KB):<8\}\{str(alpha):<10\}")$

Print the results for this row

Final result based on all rows

if all_entail:

 $print("\nKB entails alpha for all cases.")$

else:

print("\nKB does not entail alpha for all cases.")

Run the function to display the truth table and final result truth_table_entailment()

A	В	C	A or C	B or not C	KB	alpha
False	False	False	False	True	False	False
False	False	True	True	False	False	False
False	True	False	False	True	False	True
False	True	True	True	True	True	True
True	False	False	True	True	True	True
True	False	True	True	False	False	True
True	True	False	True	True	True	True
True	True	True	True	True	True	True

KB entails alpha for all cases.

Implement unification in first order logic.

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Date 22/11/24 Page 11
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Algorithm: Writy (4, 42) 7-107
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Stop-16 97 4, 00 42 in a variable or constant, the
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(a) if 42 occurs in 4 mon weburn fallure
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Step-4: NO Subastruction set (SUBST) to NI
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(B) If I - failure then return Ballure.
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(b) SUBST = PRPEND (S, SUBST).
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Perform unification on two expressions in first-order logic.

```
Args:
  expr1: The first expression (can be a variable, constant, or list representing a function).
  expr2: The second expression.
  substitution: The current substitution (dictionary).
Returns:
  A dictionary representing the most general unifier (MGU), or None if unification fails.
if substitution is None:
  substitution = {}
# Debug: Print inputs and current substitution
print(f"Unifying {expr1} and {expr2} with substitution {substitution}")
# Apply existing substitutions to both expressions
expr1 = apply_substitution(expr1, substitution)
expr2 = apply_substitution(expr2, substitution)
# Debug: Print expressions after applying substitution
print(f"After substitution: {expr1} and {expr2}")
```

```
# Case 1: If expressions are identical, no substitution is needed
if expr1 == expr2:
  return substitution
#Case 2: If expr1 is a variable
if is_variable(expr1):
  return unify_variable(expr1, expr2, substitution)
# Case 3: If expr2 is a variable
if is_variable(expr2):
  return unify_variable(expr2, expr1, substitution)
# Case 4: If both are compound expressions (e.g., functions or predicates)
if is_compound(expr1) and is_compound(expr2):
  if expr1[0] != expr2[0] or len(expr1) != len(expr2):
     print(f"Failure: Predicate names or arity mismatch {expr1[0]} != {expr2[0]}")
     return None # Function names or arity mismatch
  for arg1, arg2 in zip(expr1[1:], expr2[1:]):
     substitution = unify(arg1, arg2, substitution)
     if substitution is None:
       print(f"Failure: Could not unify arguments {arg1} and {arg2}")
       return None
```

return substitution

```
# Case 5: Otherwise, unification fails
  print(f"Failure: Could not unify {expr1} and {expr2}")
  return None
def unify_variable(var, expr, substitution):
  ,,,,,,
  Handles the unification of a variable with an expression.
  Args:
     var: The variable.
     expr: The expression to unify with.
     substitution: The current substitution.
  Returns:
     The updated substitution, or None if unification fails.
  *****
  if var in substitution:
     # Apply substitution recursively
     return unify(substitution[var], expr, substitution)
  elif occurs_check(var, expr):
     # Occurs check fails if the variable appears in the term it's being unified with
```

```
print(f"Occurs check failed: {var} in {expr}")
     return None
  else:
     substitution[var] = expr
     print(f"Substitution added: {var} -> {expr}")
     return substitution
def occurs_check(var, expr):
  ,,,,,,
  Checks if a variable occurs in an expression (to prevent cyclic substitutions).
  Args:
     var: The variable to check.
     expr: The expression to check against.
  Returns:
     True if the variable occurs in the expression, otherwise False.
  *****
  if var == expr:
     return True
  elif is_compound(expr):
     return any(occurs_check(var, arg) for arg in expr[1:])
  return False
```

```
def is_variable(expr):
  """Checks if the expression is a variable."""
  return isinstance(expr, str) and expr[0].islower()
def is_compound(expr):
  """Checks if the expression is compound (e.g., function or predicate)."""
  return is instance (expr., list) and len(expr.) > 0
def apply_substitution(expr, substitution):
  ,,,,,,
  Applies a substitution to an expression.
  Args:
     expr: The expression to apply the substitution to.
     substitution: The current substitution.
  Returns:
     The updated expression with substitutions applied.
  *****
  if is_variable(expr) and expr in substitution:
     return apply_substitution(substitution[expr], substitution)
  elif is_compound(expr):
```

return [apply_substitution(arg, substitution) for arg in expr] return expr

```
# Example Usage:

expr1 = ['P', 'X', 'Y']

expr2 = ['P', 'a', 'Z']

result = unify(expr1, expr2)

print("Unification Result:", result)

Unifying ['P', 'X', 'Y'] and ['P', 'a', 'Z'] with substitution {}

After substitution: ['P', 'X', 'Y'] and ['P', 'a', 'Z']

Unifying X and a with substitution {}

After substitution: X and a

Substitution added: a -> X

Unifying Y and Z with substitution {'a': 'X'}

After substitution: Y and Z

Failure: Could not unify Y and Z

Failure: Could not unify arguments Y and Z

Unification Result: None
```

Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.

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	I h a specifican	
	Forward Reasoning Algorithm	
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	Function FOL-PC-ASK (KB, x) returns a substitution	
	inputs: ICB the knowledge baxe, q set or	
	FOL clauser ~,	
	of the query, an abonion suden	
	* London of the poly of the standard	
	local variables: new, the new sentences intend	
	on each steeting	
	repeat until new is empty	
	new < 2 }	
	for each rule in 108 do	
	(p, 1. 1pn => 9;) ← 5~ (sule)	
	for each O such that subset (OP.M.)	
	= suBust (0, Pi11 pp')	
	q' = subset (0, q)	
	9 - SUBSET (0, 9)	
	if 9' does not venify with some	
	sentence already in the or new	
	then	
	add q' to new	
	1x 1 (9,2)	
	orten & not fail they	
	stum falso	
	John false	

Class Forward_reasoninig:

self.rules = rules # List of rules (condition -> result)

self.facts = set(facts) # Known facts

```
def infer(self):
     applied_rules = True
     while applied_rules:
        applied_rules = False
        for rule in self.rules:
          condition, result = rule
          if condition.issubset(self.facts) and result not in self.facts:
             self.facts.add(result)
             applied_rules = True
             print(f"Applied rule: {condition} -> {result}")
     return self.facts
# Define rules as (condition, result) where condition is a set
rules = [
  (\{"A"\}, "B"),
  ({"B"}, "C"),
  (\{"C", "D"\}, "E"),
  ({"E"}, "F")
]
# Define initial facts
facts = {"A", "D"}
# Initialize and run forward reasoning
reasoner = ForwardReasoning(rules, facts)
final_facts = reasoner.infer()
print("\nFinal facts:")
print(final_facts)
```

```
Applied rule: {'A'} -> B
Applied rule: {'B'} -> C
Applied rule: {'C', 'D'} -> E
Applied rule: {'E'} -> F

Final facts:
{'C', 'E', 'B', 'F', 'A', 'D'}
```

Create a knowledge base consisting of first order logic statements and prove the given query using Resolution

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	If 7 Literes found:	Electric Section 1
	& resdue two clauses	1000
	The Cure #2	1
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```
# Define the knowledge base (KB) as a set of facts KB =
set()
    # Premises based on the provided FOL problem
    KB.add('American(Robert)')
    KB.add('Enemy(America, A)')
    KB.add('Missile(T1)')
    KB.add('Owns(A, T1)')
    # Define inference rules
    def modus ponens(fact1, fact2, conclusion):
    """ Apply modus ponens inference rule: if fact1 and fact2 are true, then conclude conclusion
    if fact1 in KB and fact2 in KB:
    KB.add(conclusion)
    print(f"Inferred: {conclusion}")
    def forward_chaining():
    """ Perform forward chaining to infer new facts until no more inferences can be made """
    # 1. Apply: Missile(x) \rightarrow Weapon(x)
    if 'Missile(T1)' in KB:
    KB.add('Weapon(T1)')
    print(f"Inferred: Weapon(T1)")
    1
    #2. Apply: Sells(Robert, T1, A) from Owns(A, T1) and Weapon(T1)
    if 'Owns(A, T1)' in KB and 'Weapon(T1)' in KB:
    KB.add('Sells(Robert, T1, A)')
    print(f"Inferred: Sells(Robert, T1, A)")
    #3. Apply: Hostile(A) from Enemy(A, America)
    if 'Enemy(America, A)' in KB:
    KB.add('Hostile(A)')
    print(f"Inferred: Hostile(A)")
    #4. Now, check if the goal is reached (i.e., if 'Criminal(Robert)' can be inferred)
    if 'American(Robert)' in KB and 'Weapon(T1)' in KB and 'Sells(Robert, T1, A)' in KB and
    'Hostile(A)' in KB:
```

```
KB.add('Criminal(Robert)')

print("Inferred: Criminal(Robert)")

# Check if we've reached our goal

if 'Criminal(Robert)' in KB:

print("Robert is a criminal!")

else:

print("No more inferences can be made.")

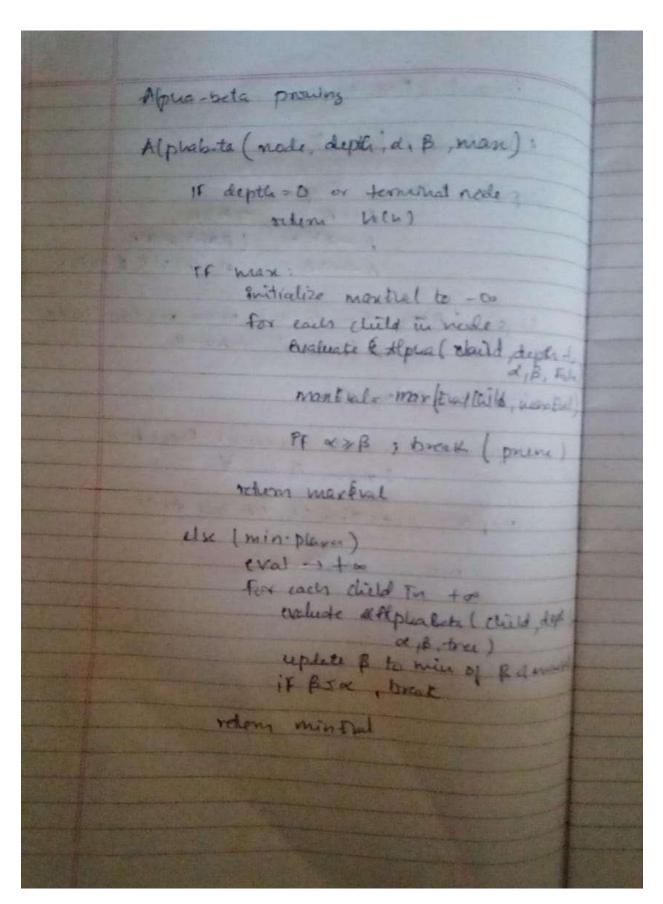
# Run forward chaining to attempt to derive the conclusion

forward_chaining()
```

```
Inferred: Weapon(T1)
Inferred: Sells(Robert, T1, A)
Inferred: Hostile(A)
Inferred: Criminal(Robert)
Robert is a criminal!
```

Program 10

Implement Alpha-Beta Pruning.



```
# Alpha-Beta Pruning Implementation
def alpha_beta_pruning(node, alpha, beta, maximizing_player):
# Base case: If it's a leaf node, return its value (simulating evaluation of the node)
if type(node) is int:
return node
# If not a leaf node, explore the children
if maximizing_player:
max_eval = -float('inf')
for child in node: # Iterate over children of the maximizer node
eval = alpha_beta_pruning(child, alpha, beta, False)
max_eval = max(max_eval, eval)
alpha = max(alpha, eval) # Maximize alpha
if beta <= alpha: # Prune the branch
break
return max eval
else:
min_eval = float('inf')
for child in node: # Iterate over children of the minimizer node
eval = alpha_beta_pruning(child, alpha, beta, True)
min_eval = min(min_eval, eval)
beta = min(beta, eval) # Minimize beta
if beta <= alpha: # Prune the branch
1
break
return min eval
# Function to build the tree from a list of numbers
def build tree(numbers):
# We need to build a tree with alternating levels of maximizers and minimizers
# Start from the leaf nodes and work up
current_level = [[n] for n in numbers]
while len(current_level) > 1:
next_level = []
for i in range(0, len(current_level), 2):
if i + 1 < len(current\_level):
next_level.append(current_level[i] + current_level[i + 1]) # Combine two nodes
else:
```

```
next_level.append(current_level[i]) # Odd number of elements, just carry forward
current_level = next_level
return current_level[0] # Return the root node, which is a maximizer
# Main function to run alpha-beta pruning
def main():
# Input: User provides a list of numbers
numbers = list(map(int, input("Enter numbers for the game tree (space-separated): ").split()))
2
# Build the tree with the given numbers
tree = build tree(numbers)
# Parameters: Tree, initial alpha, beta, and the root node is a maximizing player
alpha = -float('inf')
beta = float('inf')
maximizing_player = True # The root node is a maximizing player
# Perform alpha-beta pruning and get the final result
result = alpha_beta_pruning(tree, alpha, beta, maximizing_player)
print("Final Result of Alpha-Beta Pruning:", result)
if __name___ == "__main__":
main()
```

Enter numbers for the game tree (space-separated): 10 9 14 18 5 4 50 3 Final Result of Alpha-Beta Pruning: 50