

Supplementary materials for: Resource Allocation and Service Provisioning Schedule for Cloud Edge based Cyber Physical Systems

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Abstract. The integration of Cyber-Physical Systems (CPS) with advanced computational resources and networking is critical for optimizing resource allocation and service provisioning across various sectors such as healthcare, manufacturing, and transportation. This paper explores the challenges and solutions for effective resource management in CPS, focusing on dynamic provisioning and virtualization techniques. We present a comprehensive resource provisioning architecture that includes cloud coordinators, data centers, hosts, and sensors, designed to improve resource utilization and service reliability. The proposed architecture virtualizes physical sensors into virtual sensors within a cloud environment, enabling seamless access and management. Our approach leverages algorithms for resource node selection, global resource provisioning, and load balancing, ensuring optimal resource allocation and high service availability. Through a series of case studies, we demonstrate significant improvements in resource utilization for different sensor types, highlighting the effectiveness of our techniques. This work underscores the importance of scalable, adaptive, and secure resource management strategies in enhancing the performance and reliability of CPS.

Keywords: Cyber-Physical Systems (CPS), dynamic resource provisioning, data centers, load balancing, resource allocation, service provisioning.

1 Introduction

This is a supplementary document which consists of Figures, Tables, Algorithms and Result graphs.

Algorithm 1 Resource_Provisioning (task, discoveredService)

```

1: Input: Task, DiscoveredService
2: Output: resourceNode
3: cpsUUID = discoveredService.cpsUUID
4: resourceSystemUUID = discoveredService.resourceSystemUUID
5: cpsSystem = GetCpsSystem (cpsUUID)
6: resourceSystem = GetResourceSystem (resourceSystemUUID)
7: resourceGeoLocation = resourceSystem.geoLocation
8: resourceNodeList = resourceSystem.resourceNodeList (Task)
9: if resourceNodeList.size > 0 then
10:   availableNodeList = Get AvailableResourceNodeList()
11: else
12:   return NULL
13: end if
14: for each node in availableNodeList do
15:   Apply Merge Sort on availableNodeList by injecting Re-
     source_Node_Comparator (ND1, ND2)
16: end for
17: resourceNode = availableNodeList[0]
18: nodeAttributes = resourceNode.getAttributes()
19: serviceAllocationCount = nodeAttributes.getServiceAllocationCount()
20: serviceAllocationCount = serviceAllocationCount + 1
21: return resourceNode

```

Algorithm 2 Resource_Node_Comparator (ND1, ND2)

```

1: Input: ND1, ND2
2: Output: return -1 if ND1 > ND2, 1 if ND1 < ND2, 0 if ND1 = ND2
3: pm1 = ND1.Attributes.Model
4: pm2 = ND2.Attributes.Model
5: getAttributes of ND1
6: fromlocation = resourceSystem.geoLocation
7: distance1 = pm1.Geodistance
8: Geodistance1 = GeoDistance(fromLocation, distance1)
9: getAttributes of ND2
10: fromlocation = resourceSystem.geoLocation
11: distance2 = pm2.Geodistance
12: Geodistance2 = GeoDistance(fromLocation, distance2)
13: prepare attribute lists
14: Compare Node Attributes using Multi_Attribute_Comparator (ND1, ND2)

```

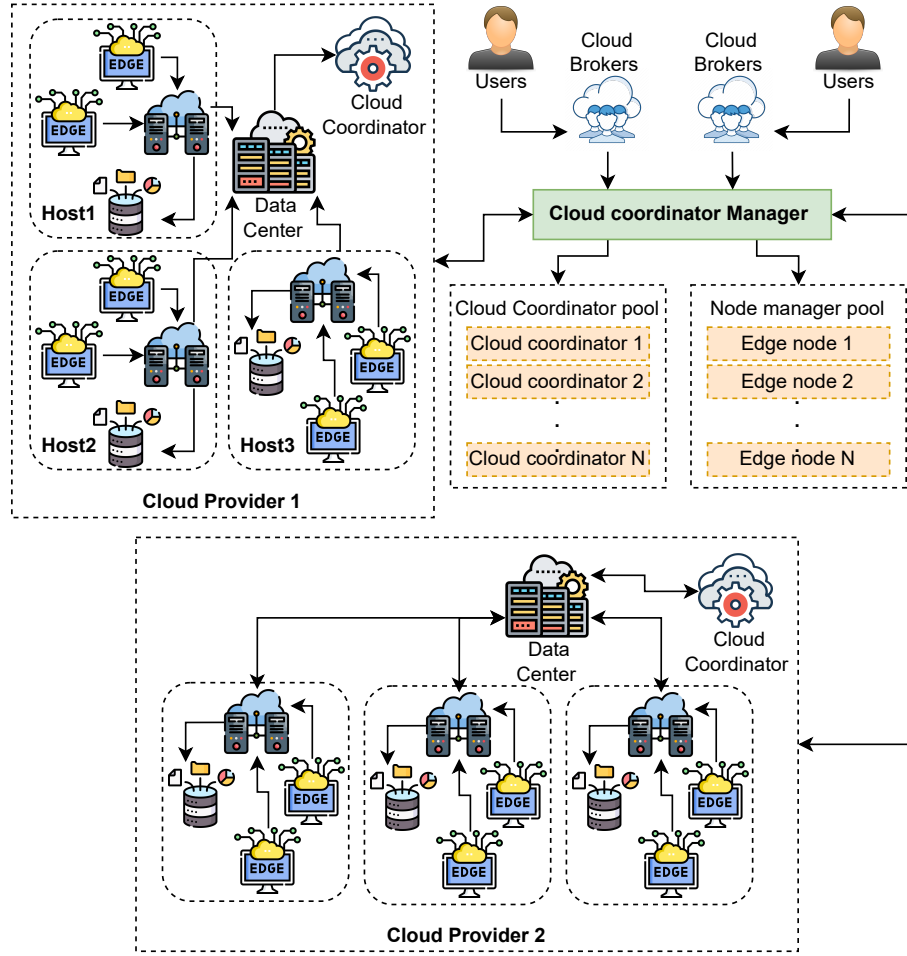


Fig. 1. Architecture of Resource Provisioner - Cloud Sensor Simulator

Table 1: Summary of Existing Resource provisional algorithm

Ref.	Method Used	Advantages	Limitations
[17]	Dynamic resource provisioning integrating cloud, fog, and edge computing	Improved system performance, resource utilization, and responsiveness	Focuses on performance improvements but neglects security considerations

Ref.	Method Used	Advantages	Limitations
[11]	Optimal flower pollination algorithm for resource provisioning in cyber-physical-social systems	Optimized resource allocation, improved efficiency, and reduced latency	May not scale well in very large networks
[8]	Resource offload consolidation based on deep-reinforcement learning for smart cities	Improved quality of service, reduced operational costs	Struggles with integrating strategies into existing legacy systems
[10]	Secure resource provisioning for protecting sensitive data	Enhanced data protection and security in CPS	Cybersecurity measures need more real-world testing
[3]	Robotic edge resource allocation for agricultural CPS	Efficient resource management and task allocation in agriculture	Does not fully address complexities of diverse robotic systems
[19]	Blockchain technology for enhancing security and transparency	Improved security and transparency in resource provisioning	Potential scalability issues with high transaction volumes
[4]	Energy-efficient resource management in fog computing for medical CPS	Reduced energy consumption, improved resource management	Energy-efficient model might reduce performance in some cases
[16]	Joint sampling time and resource allocation for power efficiency in industrial CPS	Optimized system performance, reduced latency	Requires more validation across different scenarios
[7]	Learning-assisted real-time resource allocation	Adapts to changing workloads, improves real-time allocation	May struggle with adaptability in highly dynamic environments
[12]	QoS-aware virtual machine scheduling for energy conservation	Ensures quality of service, optimizes resource utilization	Does not account for all possible QoS parameters
[15]	Resource provisioning in edge/fog computing for IoT-based healthcare systems	Improved efficiency and responsiveness in healthcare applications	Needs more real-world testing
[6]	Dynamic edge and cloud service integration for industrial IoT	Enhanced efficiency and responsiveness in industrial applications	Needs more real-world testing
[2]	Resource allocation in cloud-fog-edge computing for smart agriculture	Optimized resource allocation, improved efficiency in agriculture	May not effectively address all environmental variables
[1]	CyberTwin concept for resource provisioning in IoE applications	Improved resource management in 6G-enabled edge networks	Needs practical deployment for full assessment

Ref.	Method Used	Advantages	Limitations
[5]	Learning-based resource provisioning in fog computing	Reduced latency, improved resource allocation	Requires more real-time testing
[14]	IoT-based digital twin for energy CPS	Enhanced design and implementation of energy CPS	Needs further scalability and efficiency improvements
[9]	Ephemeral-CPS using shared devices in open IoT	Reduced resource wastage, improved efficiency	Needs further scalability improvements
[18]	Multi-objective task scheduling for fog computing	Balances performance, cost, and energy efficiency	Might not balance all objectives in complex environments effectively
[13]	GoodSpread algorithm for criticality-aware static scheduling	Improved resource allocation and system performance	Needs more benchmarking for validation

Algorithm 3 Geo_Distance (from, to)

```

1: Input: from, to
2: Output: geographical distance in meters
3: lat1 = from.latitude and lat2 = to.latitude
4: lon1 = from.longitude and lon2 = to.longitude
5: R = 6371000
6: diff = lon1 - lon2
7: dist = sin(lat1) * sin(lat2) + cos(lat1) * cos(lat2) * cos(diff)
8: dist = cos(dist)
9: dist = dist * R
10: return dist

```

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Algorithm 4 Global_Resource_Provisioning (Rg)

```

1: Input: Rg is group request of virtual node, where  $Rg = \{Rv1, Rv2, \dots, Rvi\}$ 
2: Output: Vng =  $\{Gid\{VNid1, VNid2, \dots, VNidn\}\}$ , where Gid is UUID of virtual
   node group, VNid1 is UUID of first virtual node group and so on
3: Cloud Coordinator Manager collects Broker List B
4: for each bi in B do
5:   Get request group Rg from bi
6:   Initialize Virtual node VN
7:   Generate group UUID and set GId = UUID
8:   for each Rvi in Rg do
9:     Vni = CALL ProvisionNode(Rvi)
10:    VN[i] = Vni
11:   end for
12:   Vng =  $\{Gid\{VN[1].Id, VN[2].Id, \dots, VN[N].Id\}\}$ 
13:   Set output Vng in broker bi
14: end for
15: return Vng

```

Algorithm 5 Schedule (CL)

```

1: Input: CL = set of cloudlet
2: Collect Broker List B by CCM
3: for each bi in B do
4:   get CL from bi
5:   for each cli in CL do
6:     Get Vnuuid from cli
7:     Vni = getVirtualNode(Vnuuid)
8:     cli = Vni
9:     dcId = Vn.dcId
10:    hId = Vn.hId
11:    Pn = getPhysicalNode(dcId, hId)
12:    Sc = Pn.getScheduler()
13:    CALL Sc.Schedule1(cli)
14:   end for
15: end for

```

Algorithm 6 Deprovision (VnUUID)

```

1: Input: VnUUID is UUID of virtual node
2: Get list of group ids (Gid[ ]) from node repository
3: for each gid in Gid do
4:   VN = get virtual node list against gid
5:   for each Vn in VN do
6:     datacentre = GetDatacentre(dcId)
7:     host = GetHost(dcId, hId)
8:     node = GetNode(nId)
9:     removeMapping(host, node, VnUUID)
10:    Remove Vn from VN
11:   break
12:   end for
13: end for
14: if Vng against Gid of node repository is empty then
15:   remove Vng from node repository
16: end if
17: Update and save repository

```

Algorithm 7 Schedule1(cli)

```

1: Input: cli
2: Output: ND = set of records
3: Add cli in Q
4: start thread if thread is stopped or not created
5: while queue not empty do
6:   cli = get cloudlet from queue (Q)
7:   Vn = cli.getVirtualNode()
8:   dcId = Vn.dcId
9:   hId = Vn.hId
10:  nId = Vn.nId
11:  fromDate = cli.fromDate
12:  toDate = cli.toDate
13:  ND = load(dcId, hId, nId, fromDate, toDate)
14:  get broker bi from cli
15:  submit cloudlet data (ND) to bi
16: end while
17: stop thread

```

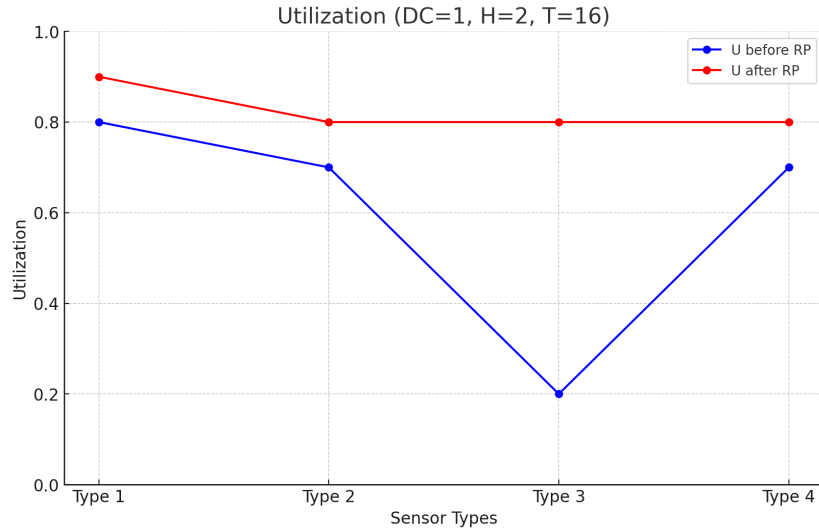


Fig. 2. Resource Utilization Case 1: DC=1, H=2, T=16

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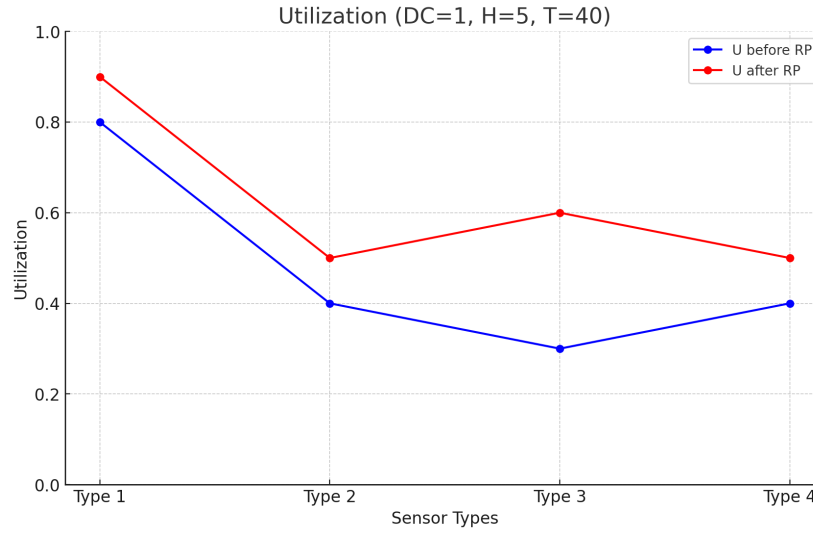


Fig. 3. Resource Utilization Case 2: DC=1, H=5, T=40

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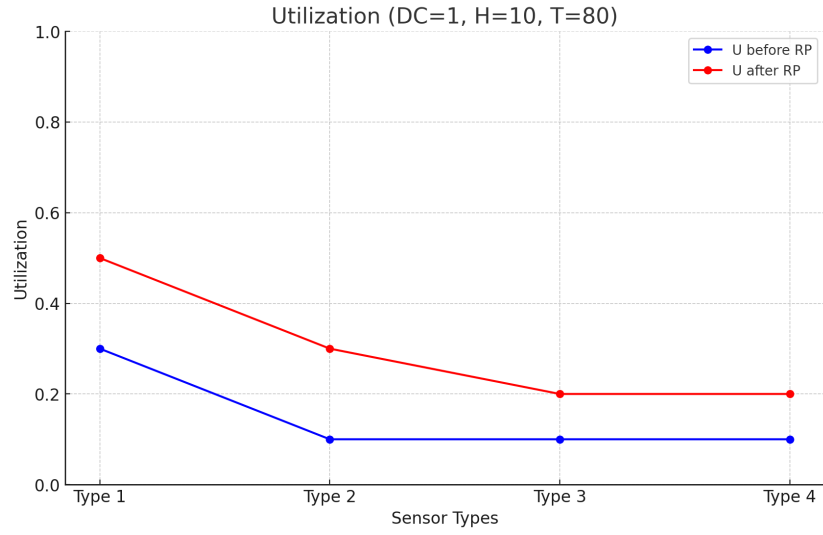


Fig. 4. Resource Utilization Case 3: DC=1, H=10, T=80

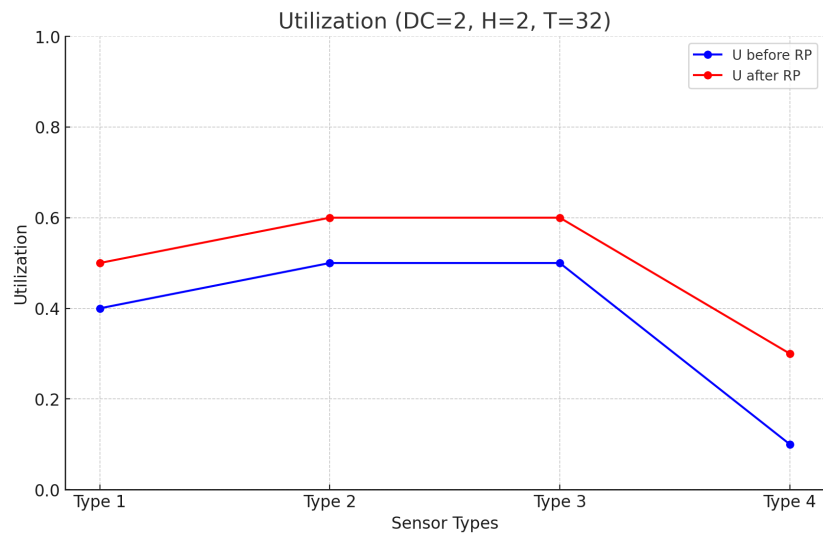


Fig. 5. Resource Utilization Case 4: DC=2, H=2, T=32

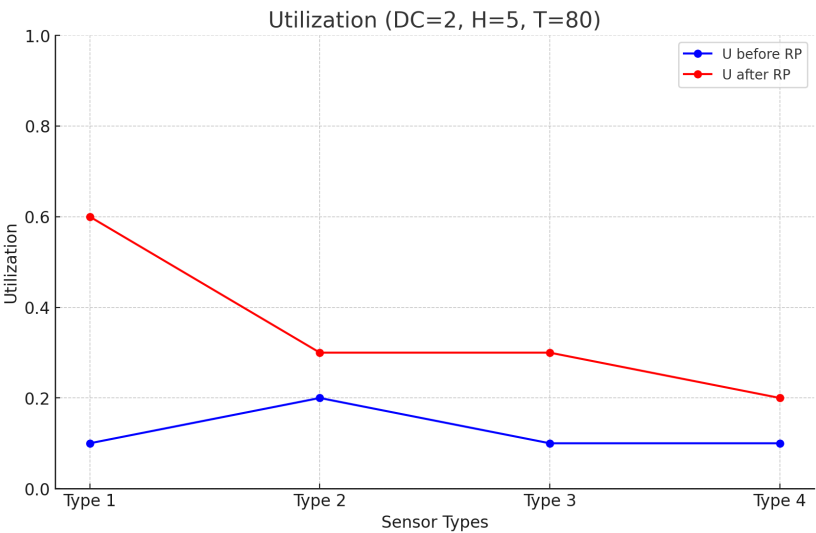


Fig. 6. Resource Utilization Case 5: DC=2, H=5, T=80

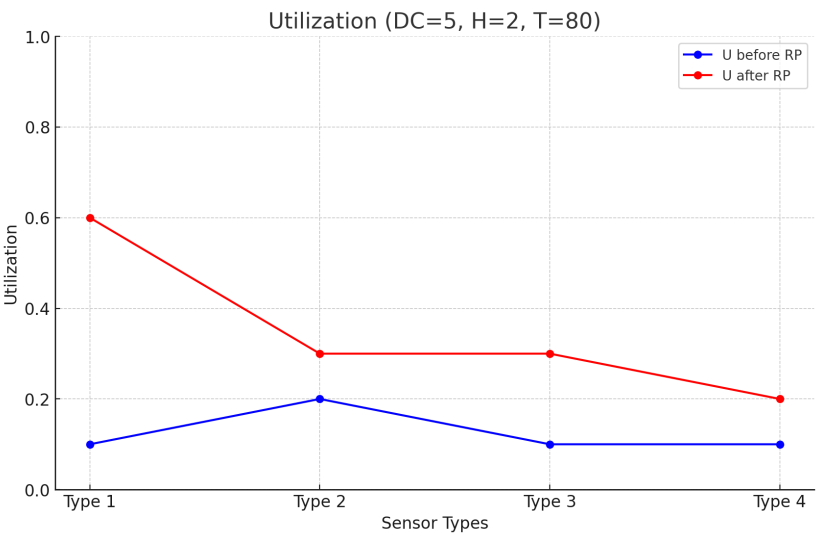


Fig. 7. Resource Utilization Case 6: DC=5, H=2, T=80

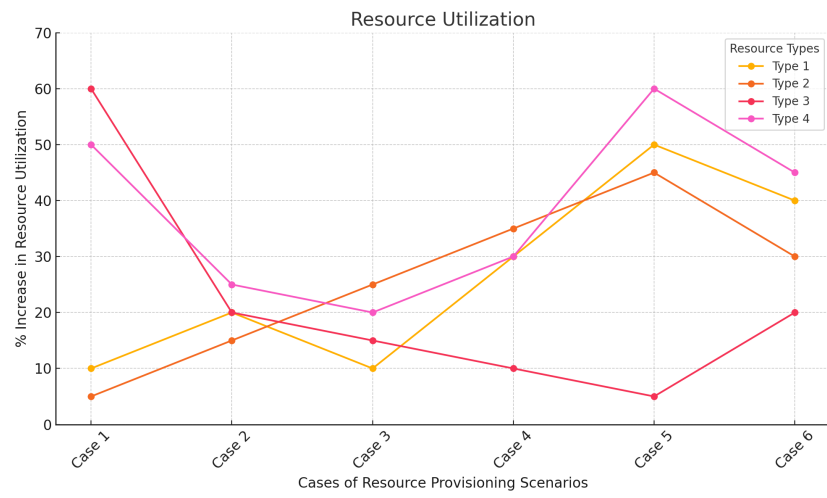


Fig. 8. Resource Utilization of All Sensor Types for Above Scenarios