# Supplementary materials for: Resource Allocation and Service Provisioning Schedule for Cloud Edge based Cyber Physical Systems

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Abstract. The integration of Cyber-Physical Systems (CPS) with advanced computational resources and networking is critical for optimizing resource allocation and service provisioning across various sectors such as healthcare, manufacturing, and transportation. This paper explores the challenges and solutions for effective resource management in CPS, focusing on dynamic provisioning and virtualization techniques. We present a comprehensive resource provisioning architecture that includes cloud coordinators, data centers, hosts, and sensors, designed to improve resource utilization and service reliability. The proposed architecture virtualizes physical sensors into virtual sensors within a cloud environment, enabling seamless access and management. Our approach leverages algorithms for resource node selection, global resource provisioning, and load balancing, ensuring optimal resource allocation and high service availability. Through a series of case studies, we demonstrate significant improvements in resource utilization for different sensor types, highlighting the effectiveness of our techniques. This work underscores the importance of scalable, adaptive, and secure resource management strategies in enhancing the performance and reliability of CPS.

**Keywords:** Cyber-Physical Systems (CPS), dynamic resource provisioning, data centers, load balancing, resource allocation, service provisioning.

### 1 Introduction

This is a supplementary document which consists of Figures, Tables, Algorithms and Result graphs.

#### **Algorithm 1** Resource Provisioning (task, discoveredService)

```
1: Input: Task, DiscoveredService
2: Output: resourceNode
3: cpsUUID = discoveredService.cpsUUID
4: resourceSystemUUID = discoveredService.resourceSystemUUID
5: cpsSystem = GetCpsSystem (cpsUUID)
6: resourceSystem = GetResourceSystem (resourceSystemUUID)
7: resourceGeoLocation = resourceSystem.geoLocation
8: resourceNodeList = resourceSystem.resourceNodeList (Task)
9: if resourceNodeList.size > 0 then
10:
     availableNodeList = Get AvailableResourceNodeList()
11: else
12:
     return NULL
13: end if
14: for each node in availableNodeList do
                                      available Node List\\
```

16: end for 17: resourceNode = availableNodeList[0]

Merge

18: nodeAttributes = resourceNode.getAttributes()

source\_Node\_Comparator (ND1, ND2)

19: serviceAllocationCount = nodeAttributes.getServiceAllocationCount()

on

by

injecting

Re-

20: serviceAllocationCount = serviceAllocationCount + 1

Sort

21: return resourceNode

Apply

### Algorithm 2 Resource Node Comparator (ND1, ND2)

- 1: **Input:** ND1, ND2
- 2: Output: return -1 if ND1 > ND2, 1 if ND1 < ND2, 0 if ND1 = ND2
- 3: pm1 = ND1.Attributes.Model
- 4: pm2 = ND2.Attributes.Model
- 5: getAttributes of ND1
- 6: from location = resource System.geo Location
- 7: distance1 = pm1.Geodistance
- 8: Geodistance1 = GeoDistance(fromLocation, distance1)
- 9: getAttributes of ND2
- 10: from location = resource System.geo Location
- 11: distance 2 = pm2.Geodistance
- 12: Geodistance2 = GeoDistance(fromLocation, distance2)
- 13: prepare attribute lists
- 14: Compare Node Attributes using Multi\_Attribute\_Comparator (ND1, ND2)

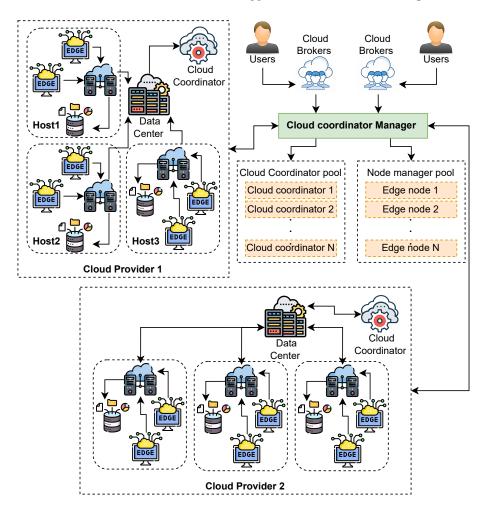


Fig. 1. Architecture of Resource Provisioner - Cloud Sensor Simulator

Table 1: Summary of Existing Resource provisional algorithm

Ref.	Method Used	Advantages	Limitations
[?]	Dynamic resource provi-	Improved system per-	Focuses on perfor-
	sioning integrating cloud,	formance, resource uti-	mance improvements
	fog, and edge computing	lization, and respon-	but neglects security
		siveness	considerations

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Ref.	Method Used	Advantages	Limitations
[?]	Optimal flower polli-	Optimized resource al-	
		location, improved effi-	very large networks
		ciency, and reduced la-	
	in cyber-physical-social	tency	
	systems		
[?]	Resource offload consol-		
	idation based on deep-		
	reinforcement learning for	tional costs	existing legacy systems
[0]	smart cities		
[?]	Secure resource provision-		
	ing for protecting sensitive		
[0]	data	CPS	real-world testing
[?]	Robotic edge resource al-		
	location for agricultural		
[9]		cation in agriculture	
[?]	Blockchain technology for enhancing security and		
	transparency		
[?]	Energy-efficient resource	Reduced energy con-	Energy-efficient model
[•]	management in fog com-		
	puting for medical CPS		
[?]		Optimized system per-	
[[•]	and resource allocation		
	for power efficiency in		scenarios
	industrial CPS	, and the second	
[?]	Learning-assisted real-	Adapts to changing	May struggle with
	time resource allocation	workloads, improves	adaptability in highly
		real-time allocation	dynamic environments
[?]	QoS-aware virtual ma-		
	chine scheduling for		all possible QoS pa-
	energy conservation	resource utilization	rameters
[?]	Resource provisioning in		
	edge/fog computing for		
	IoT-based healthcare sys-	healthcare applications	
To.	tems		
[?]	Dynamic edge and cloud		Needs more real-world
	service integration for in-		testing
[9]	dustrial IoT	industrial applications	M
[?]		Optimized resource al-	
	cloud-fog-edge computing		I I
[9]	for smart agriculture	ciency in agriculture	variables
[?]	CyberTwin concept for re-		1 -
	source provisioning in IoE	_	ployment for full
	applications	enabled edge networks	assessment

Ref.	Method Used	Advantages	Limitations
[?]	Learning-based resource	Reduced latency, im-	Requires more real-
	provisioning in fog com-	proved resource alloca-	time testing
	puting	tion	
[?]	IoT-based digital twin for	Enhanced design and	Needs further scalabil-
	energy CPS	implementation of en-	ity and efficiency im-
		ergy CPS	provements
[?]	Ephemeral-CPS using	Reduced resource	Needs further scalabil-
	shared devices in open	wastage, improved	ity improvements
	IoT	efficiency	
[?]	Multi-objective task	Balances performance,	Might not balance
	scheduling for fog com-	cost, and energy effi-	all objectives in com-
	puting	ciency	plex environments
			effectively
[?]	GoodSpread algorithm	Improved resource al-	Needs more bench-
	for criticality-aware static	location and system	marking for validation
	scheduling	performance	

# Algorithm 3 Geo Distance (from, to)

```
1: Input: from, to
```

- 2: Output: geographical distance in meters
- 3: lat1 = from.latitude and lat2 = to.latitude
- 4: lon1 = from.longitude and lon2 = to.longitude
- 5: R = 6371000
- 6: diff = lon1 lon2
- 7: dist =  $\sin(\text{lat1}) * \sin(\text{lat2}) + \cos(\text{lat1}) * \cos(\text{lat2}) * \cos(\text{diff})$
- 8: dist = cos(dist)
- 9: dist = dist \* R
- $10: \ \mathbf{return} \ \mathrm{dist}$

## Algorithm 4 Global\_Resource\_Provisioning (Rg)

```
1: Input: Rg is group request of virtual node, where Rg = \{Rv1, Rv2, ..., Rvi\}
2: Output: Vng = {Gid{VNid1, VNid2, ..., VNidn}}, where Gid is UUID of virtual
   node group, VNid1 is UUID of first virtual node group and so on
3: Cloud Coordinator Manager collects Broker List B
4: for each bi in B do
      Get request group Rg from bi
5:
6:
      Initialize Virtual node VN
7:
      Generate group UUID and set GId = UUID
8:
      {f for} each Rvi in Rg {f do}
9:
        Vni = CALL ProvisionNode(Rvi)
10:
        VN[i] = Vni
11:
      end for
12:
      Vng = \{Gid\{VN[1].Id, VN[2].Id, \dots, VN[N].Id\}\}
13:
      Set output Vng in broker bi
14: end for
15: return Vng
```

#### Algorithm 5 Schedule (CL)

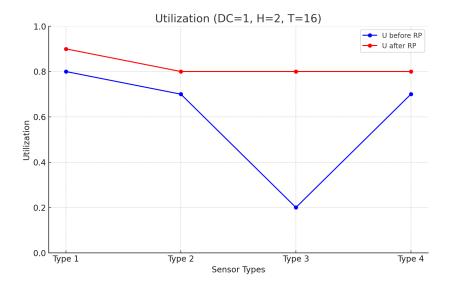
```
1: Input: CL = set of cloudlet
2: Collect Broker List B by CCM
3: for each bi in B do
      get CL from bi
4:
      {\bf for}each cli in CL {\bf do}
5:
6:
        Get Vnuuid from cli
        Vni = getVirtualNode(Vnuuid)
7:
        cli = Vni
8:
9:
        dcId = Vn.dcId
10:
        hId = Vn.hId
11:
        Pn = getPhysicalNode(dcId, hId)
12:
        Sc = Pn.getSchedular()
         CALL Sc.Schedule1(cli)
13:
      end for
14:
15: end for
```

#### Algorithm 6 Deprovision (VnUUID)

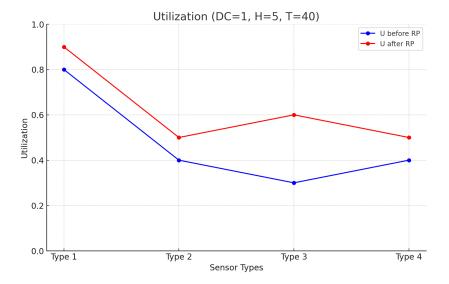
```
1: Input: VnUUID is UUID of virtual node
 2: Get list of group ids (GId[]) from node repository
 3: for each gid in Gid do
      VN = get virtual node list against gid
 4:
 5:
      \mathbf{for} \ \mathrm{each} \ \mathrm{Vn} \ \mathrm{in} \ \mathrm{VN} \ \mathbf{do}
 6:
         datacentre = GetDatacentre(dcId)
 7:
         host = GetHost(dcId, hId)
 8:
         node = GetNode(nId)
9:
         removeMapping(host, node, VnUUID)
         Remove Vn from VN
10:
11:
         break
       end for
12:
13: end for
14: if Vng against Gid of node repository is empty then
      remove Vng from node repository
16: end if
17: Update and save repository
```

### Algorithm 7 Schedule1(cli)

```
1: Input: cli
2: Output: ND = set of records
3: Add cli in Q
4: start thread if thread is stopped or not created
5: while queue not empty do
     cli = get cloudlet from queue (Q)
6:
7:
      Vn = cli.getVirtualNode()
8:
      dcId = Vn.dcId
     hId = Vn.hId
9:
10:
      nId = Vn.nId
      from Date = cli.from Date
11:
12:
      toDate = cli.toDate \\
      ND = load(dcId, hId, nId, fromDate, toDate)
13:
      get broker bi from cli
15:
      submit cloudlet data (ND) to bi
16: end while
17: stop thread
```



**Fig. 2.** Resource Utilization Case 1: DC=1, H=2, T=16



**Fig. 3.** Resource Utilization Case 2: DC=1, H=5, T=40

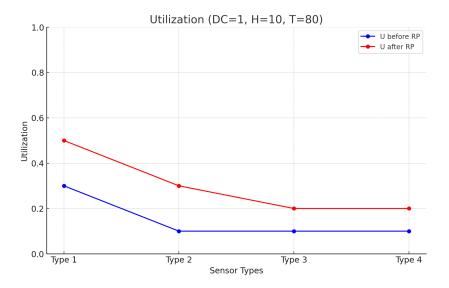
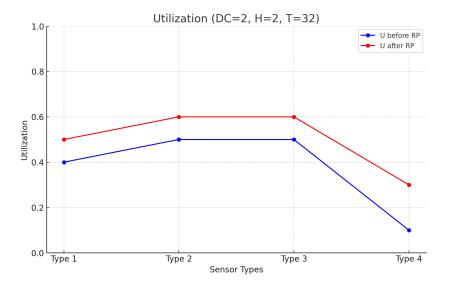


Fig. 4. Resource Utilization Case 3: DC=1, H=10, T=80



**Fig. 5.** Resource Utilization Case 4: DC=2, H=2, T=32

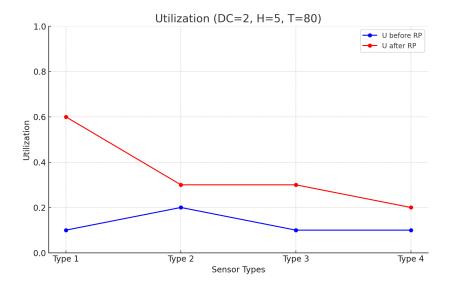
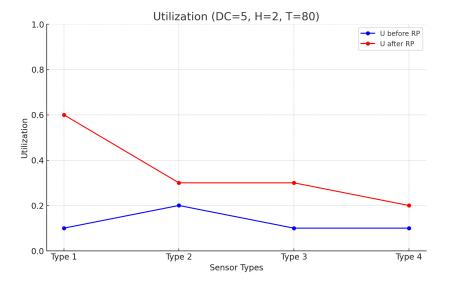
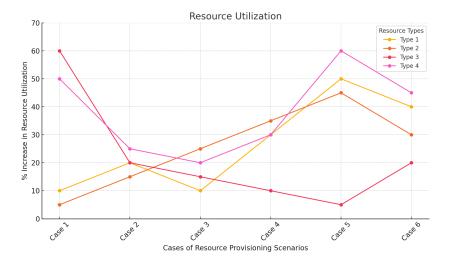


Fig. 6. Resource Utilization Case 5: DC=2, H=5, T=80



**Fig. 7.** Resource Utilization Case 6: DC=5, H=2, T=80



 ${\bf Fig.\,8.}$  Resource Utilization of All Sensor Types for Above Scenarios