

# Homework 1 Solutions

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## 1 Problem 1

Solutions:

1.

$$\det \begin{pmatrix} a^2 & ab \\ ab & b^2 \end{pmatrix} = a^2b^2 - abab = 0.$$

2.

$$\det \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} = \cos^2 \alpha + \sin^2 \alpha = 1.$$

3.

$$\det \begin{pmatrix} 1 & x & x \\ x & 2 & x \\ x & x & 3 \end{pmatrix} = 1 \times 2 \times 3 + x^3 + x^3 - 2x^2 - x^2 - 3x^2 = 2x^3 - 6x^2 + 6.$$

4. Similar to the problem above,

$$\begin{aligned} \det \begin{pmatrix} 1 & 1 & 1 \\ a & b & c \\ a^2 & b^2 & c^2 \end{pmatrix} &= bc^2 + a^2c + ab^2 - a^2b - ac^2 - b^2c \\ &= ab(b - a) + ac(a - c) + bc(c - b). \end{aligned}$$

5. Change the order of columns. And apply the operations on matrix blocks:

$$\begin{aligned} \det \begin{pmatrix} 1 & 0 & 2 & a \\ 2 & 0 & b & 0 \\ 3 & c & 4 & 5 \\ d & 0 & 0 & 0 \end{pmatrix} &= -\det \begin{pmatrix} 0 & 2 & a & 1 \\ 0 & b & 0 & 2 \\ c & 4 & 5 & 3 \\ 0 & 0 & 0 & d \end{pmatrix} \\ &= -\det \begin{pmatrix} 0 & 2 & a \\ 0 & b & 0 \\ c & 4 & 5 \end{pmatrix} \cdot d \\ &= abcd. \end{aligned}$$

6. Same idea as the problem above. Note that it won't change the determinant of a matrix if we add one row multiplied by a constant number on another row.  
 suppose  $a \neq 0$ . Then, add  $\frac{1}{a}$ row1 on row2. The determinant doesn't change.

$$\det \begin{pmatrix} a & 1 & 0 & 0 \\ -1 & b & 1 & 0 \\ 0 & -1 & c & 1 \\ 0 & 0 & -1 & d \end{pmatrix} = \det \begin{pmatrix} a & 1 & 0 & 0 \\ 0 & b + \frac{1}{a} & 1 & 0 \\ 0 & -1 & c & 1 \\ 0 & 0 & -1 & d \end{pmatrix}$$

Then change orders of rows, and change orders of columns.

$$\begin{aligned} \det \begin{pmatrix} a & 1 & 0 & 0 \\ 0 & b + \frac{1}{a} & 1 & 0 \\ 0 & -1 & c & 1 \\ 0 & 0 & -1 & d \end{pmatrix} &= -\det \begin{pmatrix} 0 & b + \frac{1}{a} & 1 & 0 \\ 0 & -1 & c & 1 \\ 0 & 0 & -1 & d \\ a & 1 & 0 & 0 \end{pmatrix} \\ &= \det \begin{pmatrix} b + \frac{1}{a} & 1 & 0 & 0 \\ -1 & c & 1 & 0 \\ 0 & -1 & d & 0 \\ 1 & 0 & 0 & a \end{pmatrix} \\ &= \det \begin{pmatrix} b + \frac{1}{a} & 1 & 0 \\ -1 & c & 1 \\ 0 & -1 & d \end{pmatrix} \cdot a \\ &= 1 + ab + ad + cd + abcd. \end{aligned}$$

## 2 Problem 2

Solution: All linear systems can be formed as  $Ax = b$ .

1. In this problem,  $x \in \mathbb{R}^4$ ,  $A$  is a 4 by 4 matrix and  $b$  is a 4 by 1 vector.

$$[A|b] = \begin{bmatrix} 2 & -1/2 & -1/2 & 0 & 0 \\ -1/2 & 2 & 0 & -1/2 & 3 \\ -1/2 & 0 & 2 & -1/2 & 3 \\ 0 & -1/2 & -1/2 & 2 & 0 \end{bmatrix} \xrightarrow{\text{Gauss elimination}} \begin{bmatrix} 1 & -1/4 & -1/4 & 0 & 0 \\ 0 & 1 & -1/15 & -4/15 & 8/5 \\ 0 & 0 & 1 & -2/7 & 12/7 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix}$$

Thus, the solution to the linear system is  $x = (1, 2, 2, 1)^T$ .

- 2.

$$[A|b] = \begin{bmatrix} 2 & 3 & 5 & 1 & 3 \\ 3 & 4 & 2 & 3 & -2 \\ 1 & 2 & 28 & -1 & 8 \\ 7 & 9 & 1 & 8 & 0 \end{bmatrix} \xrightarrow{\text{Gauss elimination}} \begin{bmatrix} 1 & 3/2 & 5/2 & 1/2 & 3/2 \\ 0 & 1 & 11 & -3 & 13 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

We see  $[A|b]$  is not in full rank so there is no solution to the linear system.

### 3 Problem 3

$A = P\Lambda Q$ ,  $A^2 = P\Lambda Q P\Lambda Q$ . Since  $QP = I$ ,  $A^2 = P\Lambda^2 Q$ . Hence,  $A^k = P\Lambda^k Q$ .

It is enough to calculate what  $\Lambda^k$ . Since  $\Lambda$  is a diagonal matrix,

- $k$  is a odd number,

$\Lambda^k = \Lambda$ . Then

$$A^k = P\Lambda Q = \begin{pmatrix} 7 & -12 \\ 6 & -7 \end{pmatrix}.$$

- $k$  is an even number,

$\Lambda^k = I$ . Then

$$A^k = PIQ = PQ = I.$$

### 4 Problem 4

The linear system can be formed as  $Ax = b$ , where

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 2 \\ 1 & -1 & 0 \end{bmatrix}, \quad b = \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$$

It is clear that  $A$  is invertible. (You may check that  $A$  is of full rank) To find the inverse of  $A$ , i.e.  $A^{-1}$ , there is one method by Gauss elimination

$$[A|I] = \begin{bmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 2 & 2 & 0 & 1 & 0 \\ 1 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{\text{Gauss elimination}} \begin{bmatrix} 1 & 0 & 0 & 1 & -1/2 & 0 \\ 0 & 1 & 0 & 1 & -1/2 & -1 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix} = [I|A^{-1}]$$

The solution is  $x = A^{-1}b = (1/2, -3/2, 2)^T$ .

### 5 Problem 5

1. False Counter example:

Let

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \quad B = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

Neither  $A$  nor  $B$  is invertible, but  $A + B = I$ , which is invertible.

2. True

You may use different method to prove this claim. We will give two methods here. The second one is a more popular one. For those students who are also taking MA 523/723 courses, you may want to have a look at the first method.

(a) Method 1

*Proof.* We use the notation  $\mathcal{R}(A)$  on be half of "Range of matrix  $A$ ". And there is a fact that  $\mathcal{R}(AB) \subset \mathcal{R}(A)$ . Hence, the dimensions of  $\mathcal{R}(A)$  and  $\mathcal{R}(B)$  are related in the following inequality chain:

$$\dim(\mathcal{R}(AB)) \leq \dim(\mathcal{R}(A)) \leq n.$$

Since  $AB$  is invertible,  $\dim(\mathcal{R}(AB)) = n$ . Hence,  $\dim(\mathcal{R}(AB)) = \dim(\mathcal{R}(A)) = n$ , which implies two facts that

- i.  $\mathcal{R}(A)$  is of full rank.
- ii.  $\mathcal{R}(A) = \mathcal{R}(AB)$ .

From (2(a)i) we know  $A$  is invertible and from (2(a)ii) we know that  $B$  is of full rank, which also implies that  $B$  is invertible.  $\square$

(b) Method 2

*Proof.* Since  $AB$  is invertible, we know  $\det(AB) \neq 0$ . With  $\det(AB) = \det(A) \cdot \det(B)$ , it implies  $\det(A) \cdot \det(B) \neq 0$ , which means both  $\det(A) \neq 0$  and  $\det(B) \neq 0$ . This proves that both  $A$  and  $B$  are invertible.  $\square$

3. False Counter example: We might let

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

Hence,

$$AB = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

Obviously,  $AB$  is not invertible, but  $A$  is invertible.

4. True.

*Proof.* Since  $A$  is invertible, we know that the kernel of  $A$ , denoted as  $\mathcal{N}(A) = \{0\}$ . i.e.,  $Ax = 0$  implies  $x = 0$ .

Let  $kAx = 0$ . Change the order of factors on left side and we obtain  $A \cdot kx = 0$ , which implies that  $kx = 0$ . With  $k \neq 0$ , we know that  $x = 0$ . In all, we conclude that  $\mathcal{N}(kA) = \{0\}$ , which is an equivalent to the fact that  $kA$  is invertible. And this proves the claim.  $\square$

## 6 Problem 6

Solution: (b)

*Proof.* Since  $A = B^T$ , we know  $A^{-1} = B^{-T}$ . Then,

$$\begin{aligned} A^T(B^{-1}A^{-1} + I)^T &= A^T(A^{-T}B^{-T} + I) \\ &= A^TA^{-T}B^{-T} + A^T \\ &= B^{-T} + A^T \\ &= (B^T)^{-1} + A^T = A^{-1} + B \end{aligned}$$

□

## 7 Problem 7

Solution:

Let  $A = [\alpha_1^T, \alpha_2^T, \alpha_3^T, \alpha_4^T]$ , and  $x = (x_1, x_2, x_3, x_4)^T$ . Solve linear system  $Ax = \alpha^T$  and we obtain  $x = (\frac{5}{4}, \frac{1}{4}, -\frac{1}{4}, -\frac{1}{4})^T$ .

## 8 Problem 8

Solution:

Build matrix  $A = [\alpha_1, \alpha_2, \alpha_3]$ . vectors  $\alpha_1, \alpha_2$  and  $\alpha_3$  are linearly independent if and only if  $A$  is of full rank. Hence, we only need to check the rank of  $A$  by Gauss elimination.

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 1 & 2 & 3 \\ 1 & 5 & 6 \end{pmatrix} \xrightarrow{\text{Gauss elimination}} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

This implies that  $\text{Rank}(A) = 2 < 3$ . In conclusion,  $\alpha_1, \alpha_2$  and  $\alpha_3$  are NOT linearly independent.

## 9 Problem 9

*Proof.* First step, we'd like to show  $\delta_1 + \delta_2$ ,  $\delta_2 + \delta_3$  and  $\delta_3 + \delta_1$  are linearly independent based on  $\delta_1, \delta_2$  and  $\delta_3$  are linearly independent.

Recall the definition of linearly dependence  $\delta_1, \delta_2$  and  $\delta_3$  are linearly independent if

$$\alpha_1\delta_1 + \alpha_2\delta_2 + \alpha_3\delta_3 = 0 \iff \alpha_1 = \alpha_2 = \alpha_3 = 0.$$

Hence suppose  $\beta_1(\delta_1 + \delta_2) + \beta_2(\delta_2 + \delta_3) + \beta_3(\delta_3 + \delta_1) = 0$ , we only need to show that  $\beta_1 = \beta_2 = \beta_3 = 0$ .

Rearrange the left side of it and obtain  $(\beta_1 + \beta_3)\delta_1 + (\beta_1 + \beta_2)\delta_2 + (\beta_2 + \beta_3)\delta_3 = 0$ . From the independence of  $\delta_1, \delta_2$  and  $\delta_3$ , we have

$$\beta_1 + \beta_3 = 0, \beta_1 + \beta_2 = 0, \beta_2 + \beta_3 = 0.$$

which implies  $\beta_1 = \beta_2 = \beta_3 = 0$ .

For the opposite direction of this claim, use the similar idea above and we only need to show that

$$\eta_1\delta_1 + \eta_2\delta_2 + \eta_3\delta_3 = 0 \Rightarrow \eta_1 = \eta_2 = \eta_3 = 0$$

based on the linear independence of  $\delta_1 + \delta_2$ ,  $\delta_2 + \delta_3$  and  $\delta_3 + \delta_1$ .

Suppose  $\eta_1\delta_1 + \eta_2\delta_2 + \eta_3\delta_3 = 0$ . And construct coefficient  $\gamma_1 = \frac{1}{2}(\eta_2 + \eta_1 - \eta_3)$ ,  $\gamma_2 = \frac{1}{2}(\eta_2 - \eta_1 + \eta_3)$  and  $\gamma_3 = \frac{1}{2}(\eta_3 - \eta_2 + \eta_1)$ . It is easy to verify that

$$\gamma_1(\delta_1 + \delta_2) + \gamma_2(\delta_2 + \delta_3) + \gamma_3(\delta_3 + \delta_1) = \eta_1\delta_1 + \eta_2\delta_2 + \eta_3\delta_3 = 0.$$

By the independence of  $\delta_1 + \delta_2$ ,  $\delta_2 + \delta_3$  and  $\delta_3 + \delta_1$ , we obtain  $\gamma_1 = \gamma_2 = \gamma_3 = 0$ , which implies  $\eta_1 = \eta_2 = \eta_3 = 0$ .

Hence, the claim is proved. □

## 10 Problem 10

Solution:

1.

$$A \xrightarrow{\text{Gauss elimination}} \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

From this we know that  $\text{Rank}(A) = 3$ .

2.

$$A \xrightarrow{\text{Gauss elimination}} \begin{pmatrix} 3 & 2 & -1 & -3 & -2 \\ 0 & -7/3 & 11/3 & 3 & -5/3 \\ 0 & 0 & 0 & 1 & 2 \end{pmatrix}$$

From this we know that  $\text{Rank}(A) = 3$ .