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# Low-Power Wakeup Receiver

Semester Thesis 2019

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**Subject**

Wireless Communications

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# **Abstract**

aktelle iekopiere!!

## **Introduction**

In company buildings, universities and other similar facilities, it is usual to attach occupancy schedules next to room entrances. These schedules are most of the time printed on paper, or in more modern buildings, displayed on a screen. Using paper, it is impracticable to take short-term changes into account, since every adjustment needs to be made by printing a new schedule. Screens on the other hand need either to be connected to the power grid, which entails extensive installation work, or powered by a battery, which needs to be replaced from time to time. All these disadvantages could be avoided by using a screen which harvests its energy from the indoor light, and is updated via a wireless interface. The screen should therefore be completely wireless.

## **Approach**

Energy is harvested with solar cells and is stored in a super-capacitor. Because this harvesting unit cannot provide unlimited energy, the whole system with display, microcontroller and wireless interface should consume as little energy as possible. To achieve this, an e-paper display is used, which only needs energy to update the screen, but not to maintain the displayed image. A constantly listening wakeup receiver can generate an wakeup interrupt and makes a periodic wake up of the microcontroller to check for incoming events redundant while maintaining a reasonable response time. A lot of energy can be saved this way, since updating the screen usually doesn't happen more than a few times a week.

## **Conclusion**

Energy harvesting provides enough energy if updating of the schedule does not occur too frequently. This semester thesis shows, that a wakeup receiver is suitable for this kind of problem. By implementing a self-holding circuit, it is even possible to switch off the whole system (except wakeup receiver) when unused. The wakeup receiver consumes in this listening mode  $4.5 \mu\text{W}$  at most.



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# Abbreviations

**IIS** Fraunhofer-Institut für Integrierte Schaltungen

**ASK** Amplitude Shift Keying

**OOK** On-Off Keying

**GUI** Graphical User Interface

**SPI** Serial Peripheral Interface

**GPIO** General Purpose Input/Output

**FIFO** First In First Out

**HSR** Hochschule für Technik Rapperswil

**BLE** Bluetooth Low Energy

**IoT** Internet of Things

**UART** Universal Asynchronous Receiver Transmitter

**USB** Universal Serial Bus

**TTL** Transistor-Transistor Logic

**FRAM** Ferroelectric Random Access Memory



# **Chapter 1**

## **Introduction**

In company buildings, universities and other similar facilities, it is usual to attach occupancy schedules next to room entrances. These schedules are mostly printed on paper, or in more modern buildings, displayed on a screen. Using paper, it is impracticable to take short-term changes into account, since every adjustment needs to be made by printing a new schedule. Screens on the other hand need either to be connected to a power supply, which entails extensive installation work, or are powered by a battery, which needs to be replaced from time to time. All these disadvantages could be avoided by using a screen which can be updated wireless and is in itself autarkic. The goal of this semester thesis is to develop a functional prototype of such a schedule.

### **1.1 Task analysis**

The prototype should combine both the advantages of the paper method and the screen. Updating should happen via a wireless interface while a expensive installation should be avoided. The screen should therefore be placed on the desired location just like a paper schedule. To consume as low power as possible, the microcontroller, display and interface should be switched off when not needed.

### **1.2 Approach**



# Chapter 2

## Theory

### 2.1 E-Paper Display

There are several different technologies which are applied in e-paper displays. But since the developed prototype uses a microencapsulated electrophoretic display, this section only describes this specific implementation.

A film, consisting of microscopic capsules, is coated onto a backplane, which basically is a matrix of electrodes. On top of that comes a common electrode, called the frontplane. This setup is shown in figure 2.1.

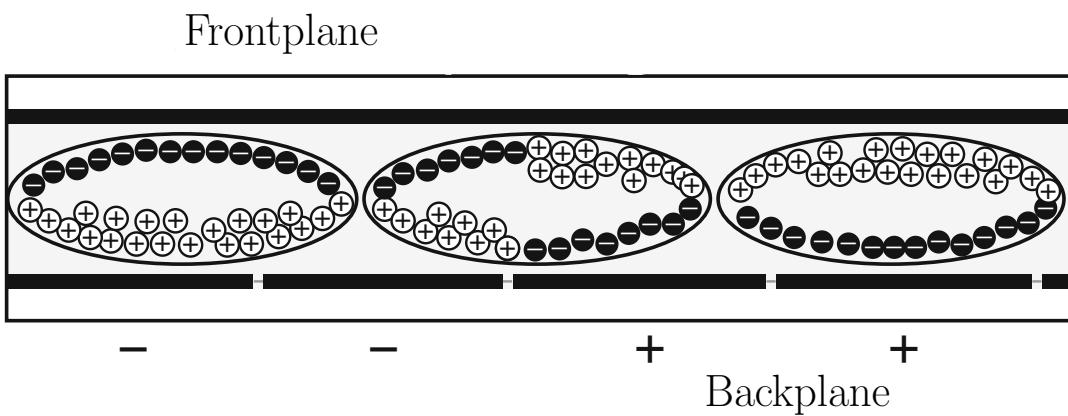


Figure 2.1: filler pic

Each capsule in the film itself contains a transparent fluid and particles of two opposite charges. One type of particle scatters the light while the other one absorbs it. The particles now begin to move in opposite directions thought the fluid when exposed two a electrical field. The pixel (defined by the electrode size) appears white if the scattering particles ar near the frontplane and black if otherwise. If no voltage is applied to the electrodes, the particles maintain their last position. This makes it possible to switch off the power supply when no image update is needed which is the reason why the power consumption is strongly reduced compared to other types of display [1].

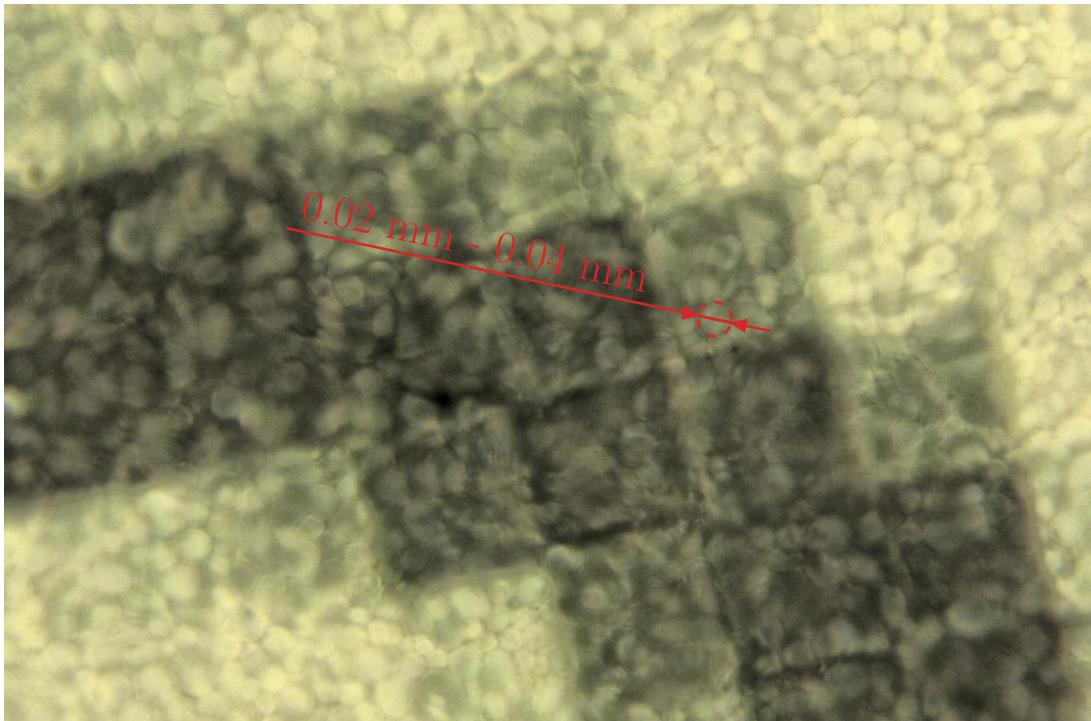


Figure 2.2: E-paper display under microscope with 250x magnification

Figure 2.2 shows a e-paper display with 250x magnification. One electrode is coated by many capsules, which are between 0.02 mm and 0.04 mm in diameter.

## 2.2 Wakeup Receiver

To save power with a conventional receiver, it needs to be programmed in such a way, that it is kept in a sleep mode. To check if any data was sent, it needs to wake up periodically to check for notifications. To set this duty cycle is a trade off between response time and power consumption. Is the period longer, the receiver is also longer time in its sleep mode. On the other side defines this period directly the response time, since data can only be received in the running mode. A wakeup receiver now allows a device to be constantly in listening mode, while consuming low energy. Added to the system, the actual microcontroller, which coordinates the data transmission and other tasks stays shut down with only the wakeup receiver in listening mode. After receiving a defined pattern over this channel, the wakeup receiver generates an interrupt to wake up the microcontroller. It can now establish a channel over a different wireless module, or execute another task. When done, the microcontroller puts itself and all other modules except the wakeup receiver in sleep mode again. Figure 2.3 shows a comparison of both the conventional approach and the solution with the wakeup receiver.

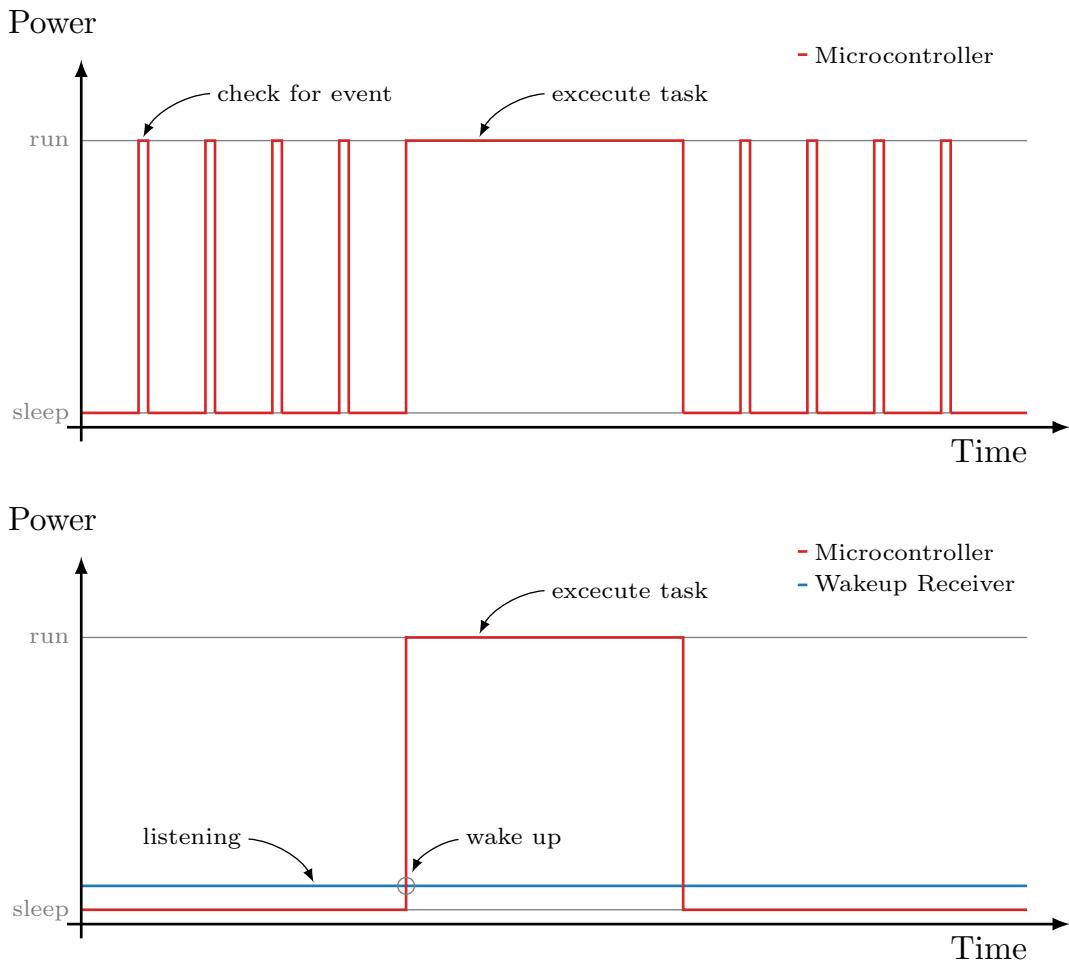


Figure 2.3: Microcontroller checks periodically for incoming data (top), additional, constantly listening wakeup receiver (bottom)

One can argue, that the wakeup receiver module consumes in general more power, than the microcontroller in sleep mode. But since the microcontroller only wakes up, when a task needs to be done, the overall energy consumption (area underneath the curves summarized) is going to be smaller if the occurring wakeup event comes infrequently or over longer periods of time. The response time on the other hand can be kept in the microsecond range.

## 2.3 software grafik zeichen



# Chapter 3

## Evaluation

### 3.1 Wakeup Receiver

In this semester thesis, two different implementations of the wakeup receiver technology were compared. The AS3933 from AMS and the RFicient from the Fraunhofer-Institut für Integrierte Schaltungen (IIS) which kindly provided an evaluation kit before the actual release of the product.

#### 3.1.1 AS3933

The AS3933 is a low frequency wakeup receiver, which uses ASK to modulate a carrier frequency between 15-150 kHz. The transmitter sends a manchester encoded, programmable wakeup pattern of length 16 or 32 bit. If this pattern is detected on the receiver end, a wakeup interrupt is generated. It is also possible to disable the the pattern decoder to run the chip in a frequency detection mode, where a wakeup interrupt is generated as soon as the specified frequency is received. More important features on the receiver end are:

- Receiver sensitivity  $80\mu\text{V}_{\text{RMS}}$
- Current consumption in 3-channel listening mode  $2.3\mu\text{A}$
- Operating supply range  $2.4\text{ V} - 3.6\text{ V}$
- Three antennas (enables 3D detection)
- Channels individually selective to reduce power consumption

The low power consumption makes it possible run the receiver in listening mode below  $8.3\mu\text{W}$ [2].

The demo kit comes with a GUI, which enables the user to set the parameters as desired and address the registers directly. The range of the receiver of about 6 m as first measurement turns out to be very limited. Even with a 3db sensitivity boost on the receiver side, it is only possible to detect wakeup events from a distance of 9 m. The environment (indoor, outdoor) seems to make no huge difference.

As a result, the limited range makes the AS3933 unusable for the prototype.

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### **3.1.2 RFicient**

The RFicient from the IIS uses OOK to modulate a 868 MHz signal. It can either run in pure wakeup mode, where the receiver generates an interrupt as soon as a code is received or a selective mode, where a 16 bit wakeup preamble needs to match the receiver. After the preamble is detected, the data rate can be changed to transfer more bits which can be sent over an SPI-bus to a connected device. This way, it is possible to transmit data bits after the actual wakeup. Data rates can be set in a range between 256 bp/s – 32 kbp/s. The most important features are:

- Receiver sensitivity -80 dBm
- Energy consumption  $3 \mu\text{A}$  at 1.5 V (data rate 1 kbit/s)
- Unidirectional data transfer possible

The power consumption therefore is in listening mode (data rate = 1 kb/s)  $4.5 \mu\text{W}$ .

Just as the AS3933, the RFicient demo kit comes with a GUI, which enables the user to set the important parameters and access the register [3]. First measurements showed that the range of the RFicient is far higher than the range of the AS3933. It is therefore used in the prototype.

## **3.2 Microcontroller**

To handle incoming data and write it to the display driver, some kind of microcontroller is needed. A derivate of the MSP430 and one of the STM32 were looked at more closely.

### **3.2.1 MSP430**

### **3.2.2 STM32**

# Chapter 4

## Development

### 4.1 Hardware

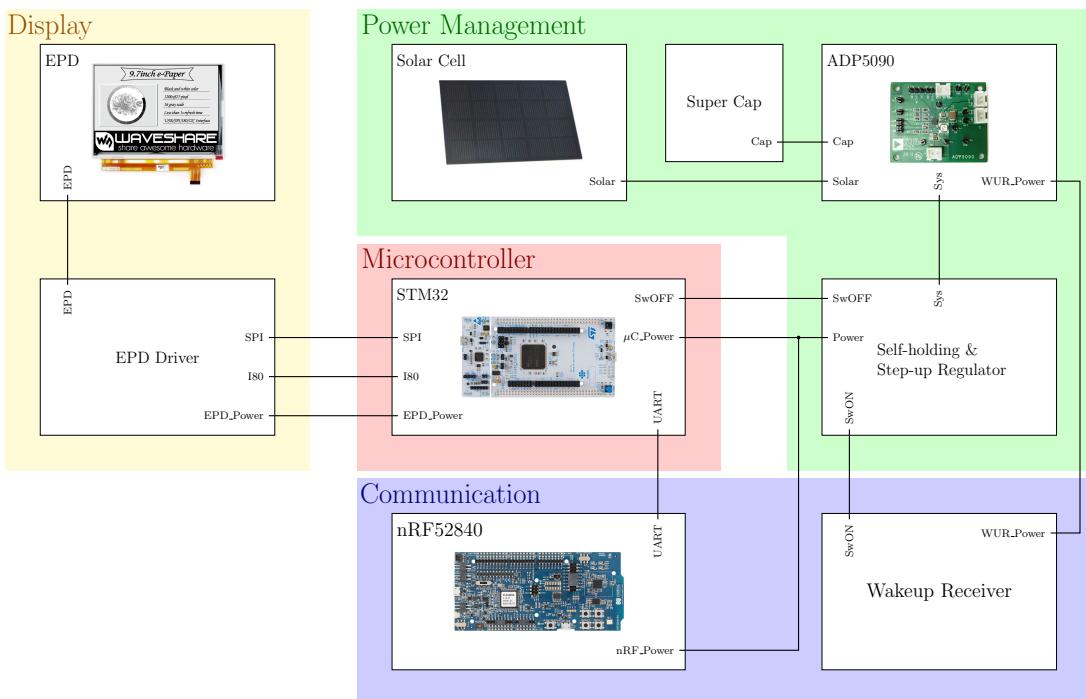


Figure 4.1: Receiver schematics

#### 4.1.1 Microcontroller

#### 4.1.2 Communication

##### Rficient

**Transmitter** The Rficient demo kit comes, as previously stated with a GUI. If the transmitter module connected, simple steps make it possible to set the preamble and payload data rate. The payload itself can partly serve as an ID and as additional transmitted data. The power of the transmission can also be set between -30 dBm and 10 dBm. The transmitter-GUI is shown in

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figure 4.2. To test, if any data is received, it is helpful to activate the infinite loop (top right in

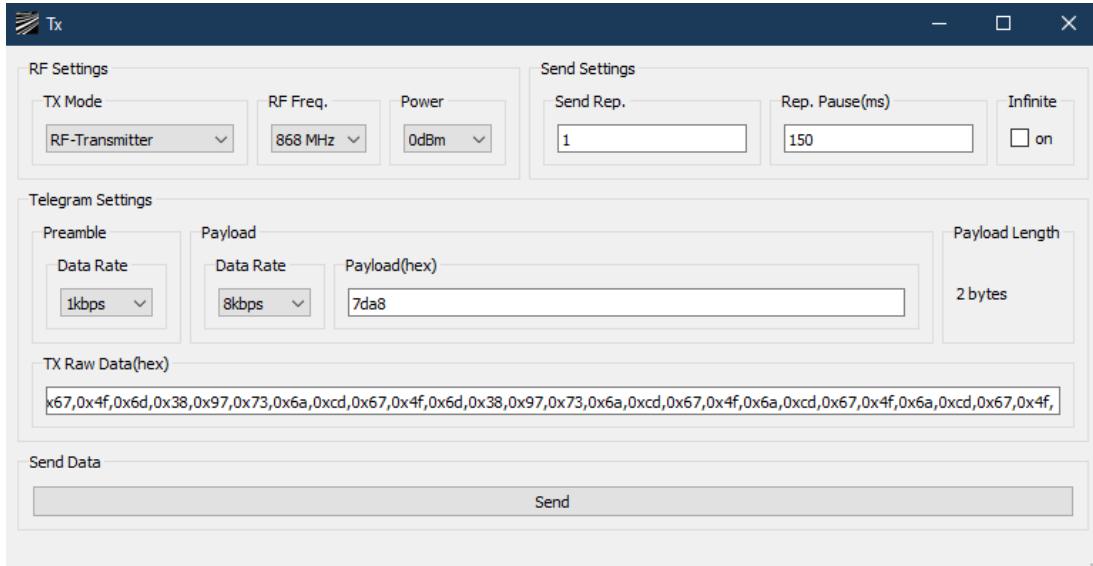


Figure 4.2: Transmitter GUI

figure 4.2). The defined data is in this case sent repeatedly with an adjustable period.

**Receiver** To receive the data, the setting of the receiver module need to be matched to the transmitter. The provided receiver-GUI makes this step very simple. As visible in figure 4.3, one can enable the four possible interrupt sources: CodeA/B, ID, FIFO length and FIFO overflow. In the finished product, it should be possible to wake up the receivers individually. For this reason, only the ID as interrupt source is of interest. If an interrupt is generated, the RFcient sets a GPIO-pin to high, and transfers the received data to a FIFO-buffer. This data can be passed to a microcontroller over an SPI-bus. For the purpose of this thesis, only the GPIO high level is used as a on switch of a self-holding circuit.

**Tests in a realistic environment** To test the RFcient in more detail, some indoor measurements were made. As test environment served several buildings of the Hochschule für Technik Rapperswil (HSR), since this type of facility represents a realistic condition for the developed schedule.

Purpose of the first test was to measure the achievable range. Figure 4.4 shows the hallway where this test was executed. With a transmission power of 0 dBm (1 mW) it is possible to receive interrupt over a 50 m distance (line of sight). Is the transmission power increased to 10 dBm (10 mW), interrupts can be sent over a distance up to 80 m. In this environment, the RFcient has enough range. But maybe reflections off the walls, floor and ceiling have contributed to this result.

Out of this reason, a second test was performed to check how the RFcient penetrates obstacles. As test environment served this time the HSR builing 8, as depicted in figure 4.5. An attempt was made to send wakeup signals through the ceiling. To avoid reflections, the RFcient was placed in such a way, that the zero point of the antenna pointed directly at the opposite walls. With a transmission power of 0 dBm, two ceilings can be penetrated. Is the power again increased to 10 dBm, the signal reached through three ceilings.

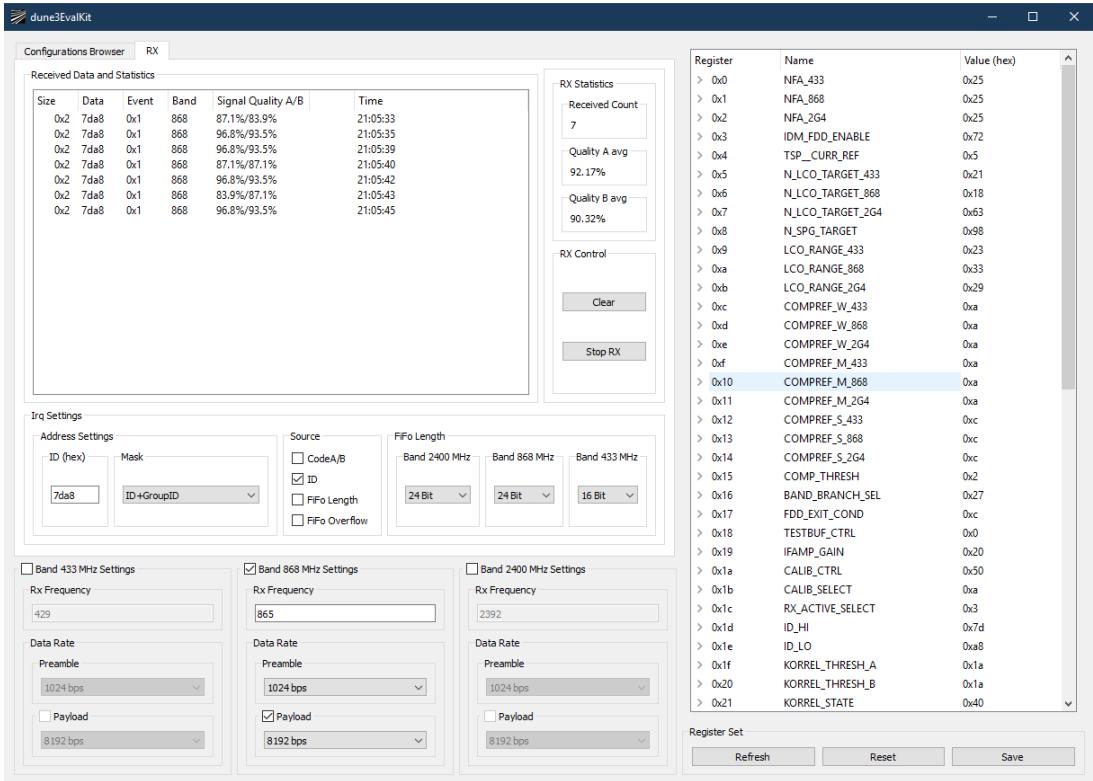


Figure 4.3: Receiver GUI

These measurements further confirmed, that the RFicient is suitable for the use-case of this semester thesis.

## nRF52480

A nRF52580 from nordic semiconductor serves as the wireless module. It is used because it supports multiple protocols like Thread, Zigbee and more important Bluetooth 5 which includes Bluetooth Low Energy (BLE)[4]. Since BLE allows mesh networking and is applied in many existing devices, such as smartphones, the connection to transmit data is established over this protocol. This way, the developed prototype could later be extended to a mesh network.

Two nRF52480 development kits are used, one on transmitter and one on receiver end. Data can be transferred from a computer with a USB-TTL-adapter to the UART-interface of the transmitter development kit. This data is then sent over BLE to the receiver kit and passed to the microcontroller again over UART. In the same way, data can be transferred from the receiver to the transmitter kit. The data channel is therefore bi-directional.

### 4.1.3 Power Management

The screen should be self-sustaining, thus some sort of energy-harvesting unit is needed. It was apparent to choose light as the energy source, since the screen will be used in rooms, that are artificially illuminated most of the time. The energy obtained by solar cells is converted to a suitable voltage, using a ADP5090 chip. This way, a super-capacitor, which is used as an energy storage device, is charged.



Figure 4.4: Test environment 1 (HSR building 1)

### Solar cell

As solar cell, the AM-1522 by Panasonic is used. One panel has an area of  $55.0\text{ mm} \times 40.5\text{ mm}$  and delivers up to  $58.7\mu\text{A}$  when operating at an optimal voltage of  $2.1\text{ V}$ , provided an illuminance of  $200\text{ lux}$ . To keep a reasonable display to panel ratio, four cells where connected in parallel, which corresponds to an area of ca.  $89.1\text{ cm}^2$  (Display area =  $283\text{ cm}^2$ ). Therefore, the solar cells should provide a power of

$$P = U \cdot I = 4 \cdot 57.8\mu\text{A} \cdot 2.1\text{ V} = 485.52\mu\text{W}, \quad (4.1)$$

given a  $200\text{ lux}$  illuminance [5].

### ADP5090

The ADP5090 from Analog Devices is used to manage the energy harvesting process. This boost regulator makes it possible to charge storage elements, such as rechargeable batteries and super capacitors with the input dc-power provided by the PV-cell. Utilized features are:

- Maximum power point tracking
- Efficiency up to 90%
- Input voltage  $V_{IN}$  from  $80\text{ mV}$  to  $3.3\text{ V}$



Figure 4.5: Test environment 2 (HSR building 8)

- Programmable voltage range (2.2 V to 5.2 V) for the storage element

To prevent the storage element from overdischarging, the ADP5090 enables the user to set a maximal Voltage with resistors:

$$V_{\text{BAT\_TERM}} = \frac{3}{2} V_{\text{REF}} \left( 1 + \frac{R_{\text{TERM1}}}{R_{\text{TERM2}}} \right). \quad (4.2)$$

The same procedure is applied to set a minimal voltage:

$$V_{\text{BAT\_SD}} = V_{\text{REF}} \left( 1 + \frac{R_{\text{SD1}}}{R_{\text{SD2}}} \right). \quad (4.3)$$

While discharging, the ADP5090 will switch off the output  $V_{\text{SYS}}$  if  $V_{\text{BAT\_SD}}$  is reached. This prevents the storage element from overdischarging. The output voltage  $V_{\text{SYS}}$ , where the load is attached, will therefore always stay in this programmed range ( $V_{\text{BAT\_SD}} \leq V_{\text{SYS}} \leq V_{\text{BAT\_TERM}}$ ) [6].

For this prototype, the evaluation board for the ADP5090 was used, where the internal reference voltage ( $V_{\text{REF}}$  in (4.2) and (4.3)) is 1.21 V [7].

## Super capacitor

As energy storage, a super capacitor from Taiyo Yuden (LIC1235RS3R8406) has proven to be suitable, which is a 40 F cylinder type lithium ion capacitor. The operating voltage range is

between 2.2 V and 3.8 V. Discharging the capacitor lower than 2.2 V causes shorter lifetime and higher leakage current. The same unwanted behaviour occurs when charging the capacitor over 3.8 V [8].

## Combined test

To test the behaviour of the power management, supercapacitor and solar cells, a couple of measurements are executed. Figure 4.6 shows the layout of the test setup.

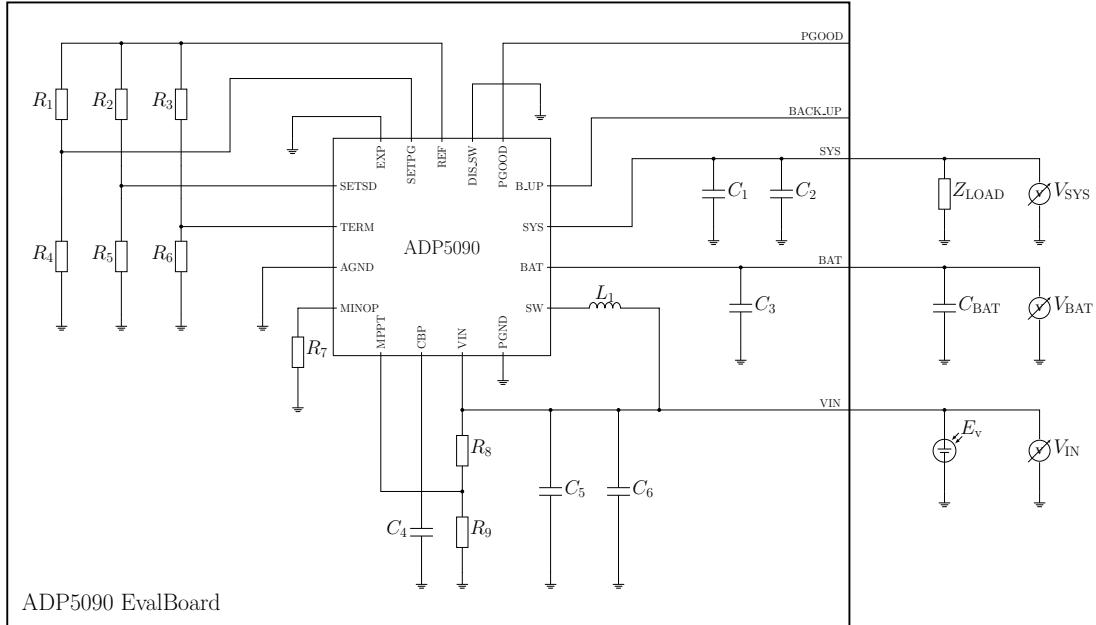


Figure 4.6: Schematics of the test setup

To carry out these measurements, it is first necessary to adjust the minimal and maximal voltage of the ADP5090. The nrf58240 accepts supply voltages between 1.6 V up to 5.5 V [9]. The STM32 on the other side is less flexible with an input voltage range of 1.71 V to 3.6 V [10]. As stated in the section above, the super capacitors operating voltage is between 2.2 V and 3.8 V. Hence it seems reasonable, to set  $V_{BAT\_TERM} \leq 3.6$  V and  $V_{BAT\_SD} \geq 2.2$  V, to satisfy all of these three elements. In order to do this, the four resistors have to be chosen as  $R_3 = 4.3 \text{ M}\Omega$ ,  $R_6 = 4.7 \text{ M}\Omega$ ,  $R_2 = 4.3 \text{ M}\Omega$  and  $R_5 = 5.1 \text{ M}\Omega$ . Inserted in the equation (4.2) and (4.3) we get

$$V_{BAT\_TERM} = \frac{3}{2} 1.21 \text{ V} \left(1 + \frac{4.3 \text{ M}\Omega}{4.7 \text{ M}\Omega}\right) \approx 3.48 \text{ V} \quad (4.4)$$

and

$$V_{BAT\_SD} = 1.21 \text{ V} \left(1 + \frac{4.3 \text{ M}\Omega}{5.1 \text{ M}\Omega}\right) \approx 2.23 \text{ V}. \quad (4.5)$$

While testing, the input voltage from the solar cells ( $V_{IN}$ ), voltage of the supercap ( $V_{BAT}$ ) and the output voltage ( $V_{SYS}$ ) are tracked. Additionally, the illuminance ( $E_v$ ) near the PV-cells is recorded as indicated in figure 4.6.

The purpose of the first test is to check, if the ADP5090 converts  $V_{IN}$  to a voltage  $\leq V_{BAT\_TERM}$ . The measurements where taken over a couple hours and are plotted in Figure 4.7.

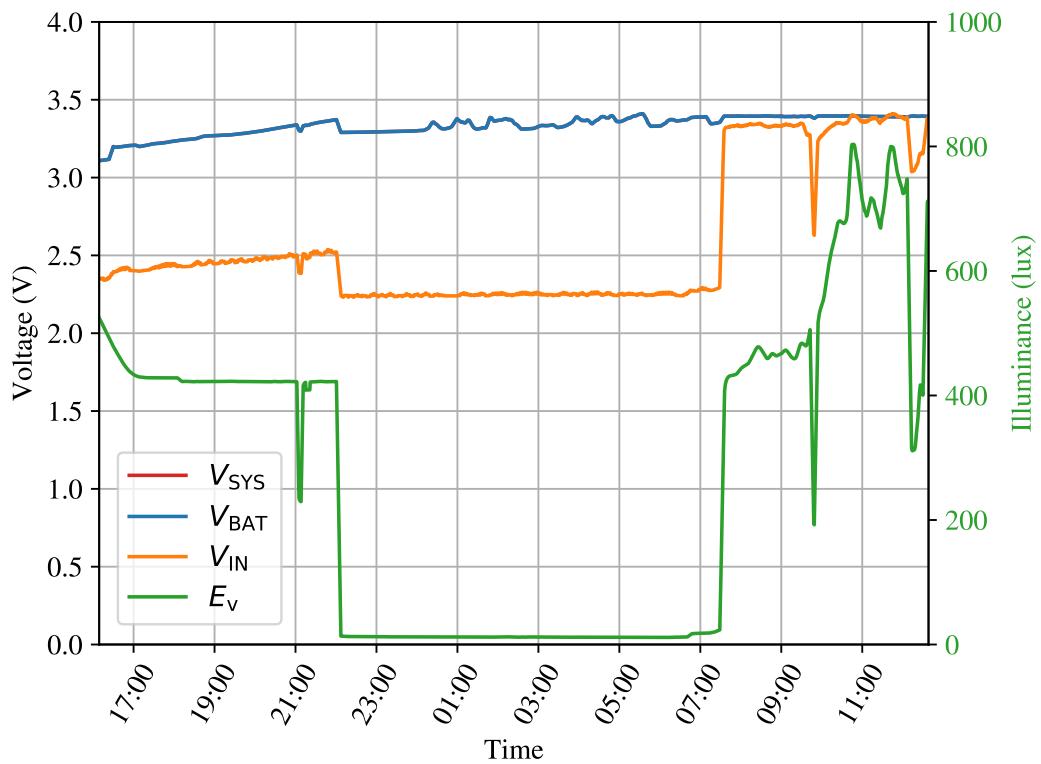


Figure 4.7: Charging behaviour

No load was connected to the output ( $Z_{LOAD} \rightarrow \infty$ ), which is the reason  $V_{SYS}$  is overlapped by  $V_{BAT}$ . It can be seen, that between 17:00 and 23:00, the super capacitor was being charged and that the ADP5090 controls the voltage  $V_{BAT}$  like expected to the adjusted maximum voltage  $V_{BAT\_TERM}$ .

The second test should simulate the discharging when a load is connected, after the capacitor was fully charged. It was necessary to estimate the consumed power by the electronic components of the prototype. A rough measurement with a power analyser showed, that the microcontroller and the e-paper display together draw at its peak about 240 mA when connected to 5 V. The nrf52840 on the other hand, only consumes 6 mA with a 3 V source. Thus the expected consumed power at its peak is:

$$P_e = 5 \text{ V} \cdot 0.24 \text{ A} + 3 \text{ V} \cdot 0.006 \text{ A} = 1.218 \text{ W.} \quad (4.6)$$

If  $Z_{LOAD} = 10\Omega$  the load draws currents between 0.223 A and 0.348 A which again lead to a power consumption that should approximately match the power consumption of the finished prototype. Furthermore, the solar cells were covered to observe the discharging without interference of additionally charging behaviour. Figure 4.8 shows the result.

As soon as the load is connected (after 25 s),  $V_{SYS}$  and  $V_{BAT}$  first drop by almost 1 V and after that steadily decrease. After ca. 100 s,  $V_{BAT}$  reached the value of  $V_{BAT\_SD}$  and the ADP5090 switches the output off ( $V_{SYS}$  drops to 0) to prevent the capacitor from overdischarging. The output now stays switched off, until  $V_{IN}$  again supplies energy, and  $V_{BAT} \leq V_{BAT\_SD}$ . It can also clearly be seen, that after 160 seconds, the ADP5090 controls  $V_{IN}$  to ca. 2.1 V. Recall that this is the optimal power point of the solar cell.

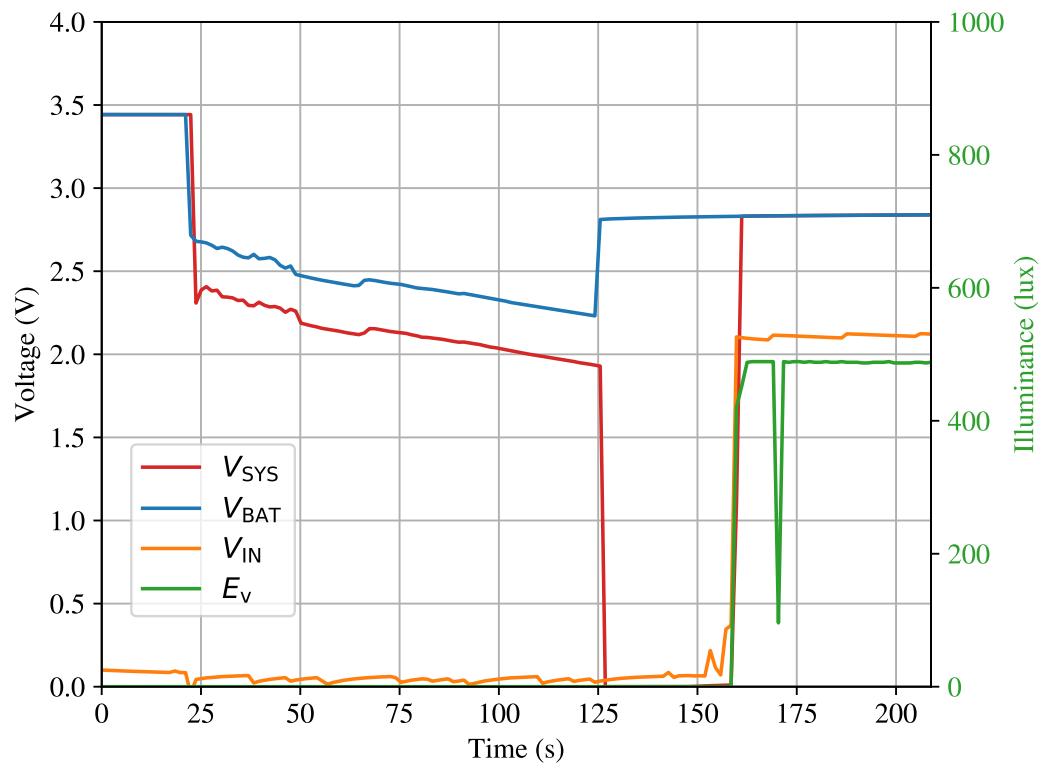


Figure 4.8: Discharging behaviour

#### 4.1.4 Display

## 4.2 Software

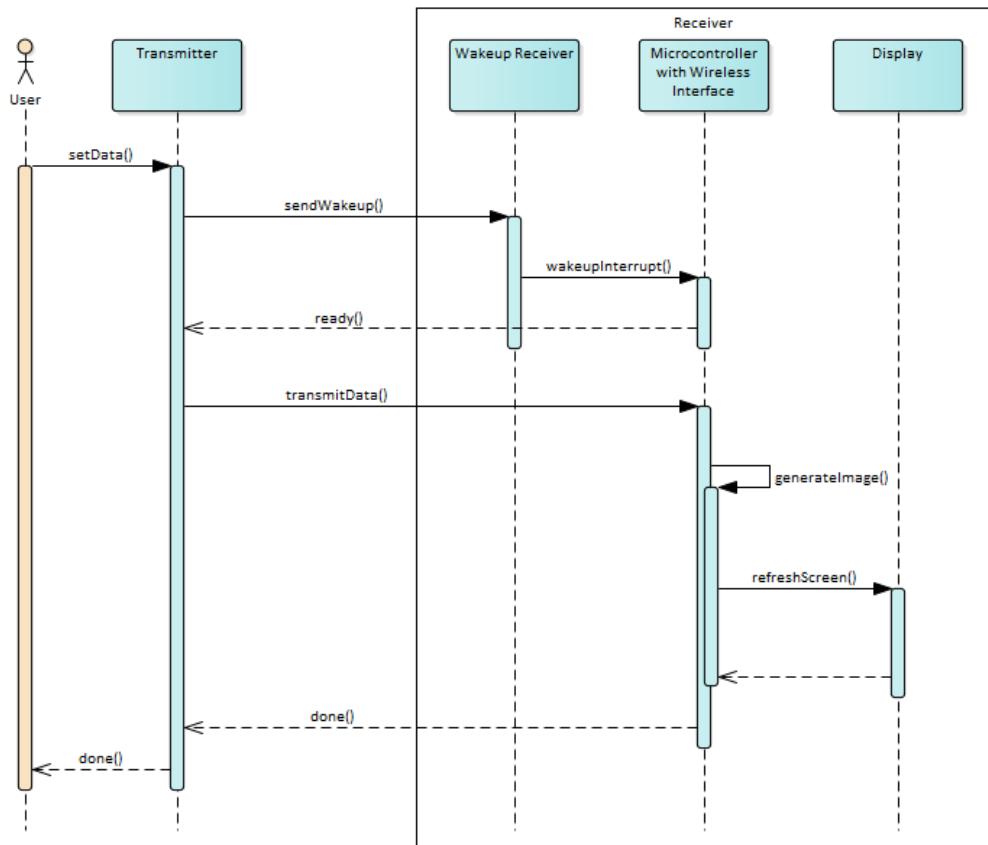
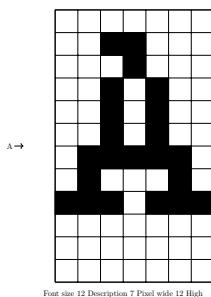


Figure 4.9: not up to date sequence

The software of the ULPWUR is separated in three different parts.



### 4.2.1 Receiver

#### Python-script

A short python script enables the user to send the data to the display. This script is looked at here little by little.

```
import serial
import time
```

---

```

baudrate = 115200
com_port = 'COM14'

device = serial.Serial(com_port, baudrate, writeTimeout=0)

```

## nRF52840

The software on both sides of the bluetooth channel is very similar, thus it is explained in this section. A BLE example project, which was provided by nordic, was only slightly changed to fit the purpose of this prototype.

Before a connection is established, the module on the receiver side is known as peripheral, and the module on transmitter end as the central device. After the receiver is woken up with the RFicient, the peripheral starts advertising. Advertising basically means sending data packets periodically with information for the central device. The central is scanning for this advertisement and can based on this information decide, if it wants to connect. Is the connection established, it is now possible to exchange data through this channel. This process is illustrated in figure 4.10.

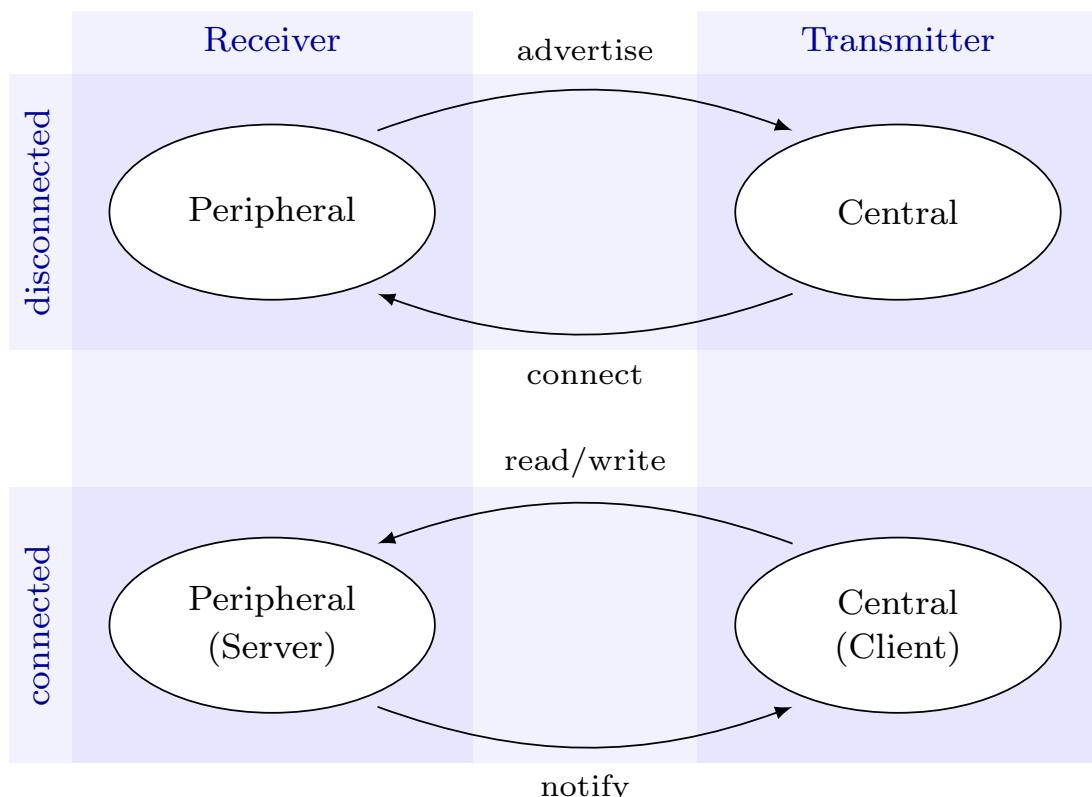


Figure 4.10: BLE-communication with the nRF52480

The central serves after connection as the client. It can make read and write requests to access the data on the peripheral, which acts as the server. The server on the other hand can only send notifications to the client if new data is ready. It should be noted, that the roles of client and server do not in any case have to be assigned to the central and peripheral, but also the other way around.

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#### **4.2.2 Transmitter**



# **Chapter 5**

## **Results**



# **Chapter 6**

## **Summary**



# Sources

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# **Statement of Plagiarism**

We declare that, apart from properly referenced quotations, this report is our own work and contains no plagiarism; it has not been submitted previously for any other assessed unit on this or other degree courses.

<b>Place</b>	<b>Date</b>
Rapperswil	December 16, 2019

## **Signatures**

Cedric Renda

Manuel Tischhauser



# **Appendix A**

## **Requirements**

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# A.1 Assignment



## Low power wakeup receiver

Semesterarbeit für Manuel Tischhauser und Cédric Renda

Herbst 2019

### 1. Einführung

Im Gebäudemanagement ist es üblich, Belegungspläne an den Eingängen der Räume anzubringen. Oftmals sind diese in Papierformat und müssen bei einer Änderung von Hand gewechselt werden. Mit dieser Methode werden kurzfristige Belegungen nicht aufgezeigt. Dies könnte man umgehen, wenn man mit Displays arbeitet die Wireless aktualisiert werden können. Dabei stellt sich allerdings das Problem, dass man entweder Kabel für die Netzeinspeisung verlegen muss oder Batterien verwendet, die regelmässig ersetzt werden müssen. Im Idealfall entfällt die Speisung komplett.

### 2. Aufgabenstellung

Zu einem Empfängermodul soll eine bidirektionale low power Kommunikationsstrecke aufgebaut werden. Der Empfänger soll durch Energy-harvesting Massnahmen möglichst passiv betrieben werden können. Dieser enthält einen Ultra Low Power Wake-up Receiver und eine Anzeige mit dem die empfangenen Daten auf entsprechende Weise dargestellt werden. Ein System kann aus mehreren Empfängern bestehen, welche unabhängig voneinander vom Sender selektiert werden können.

### 3. Ablauf

Zu Beginn der Arbeit sind ein Projektplan und ein Pflichtenheft zu erstellen, welche in den ersten Wochen dem Betreuer abgegeben werden müssen. Ein Vorschlag des Pflichtenheftes befindet sich im Arbeitsplatzordner oder als \*.docx File auf dem Public Server ([\\hsr.ch\\root\\auw\\sge\\labors\\Mk\\pub\\_for\\_students](\\hsr.ch\\root\\auw\\sge\\labors\\Mk\\pub_for_students)). Planen Sie total 240 Arbeitsstunden (8 ECTS \* 30 h/ECTS) ein. Die Arbeiten sollen innerhalb der Gruppe geeignet aufgeteilt werden; die Aufteilung ist im Bericht entsprechend festzuhalten, genauso wie ein Vergleich des geplanten und des effektiv durchgeföhrten Projektplans. Weitere Einzelheiten werden an den wöchentlichen Besprechungen festgelegt. Die Arbeiten sollen möglichst selbstständig durchgeführt werden. Die Kriterien der Beurteilung und Notengebung sind im unten erwähnten Leitfaden zu finden.

### 4. Laborjournal

Während der Arbeit ist ein persönliches (d.h. pro Person eines), gebundenes, handschriftliches und datiertes Laborjournal zu führen. Darin werden alle Tätigkeiten betreffend Dauer und Resultate eingetragen. Ebenfalls soll darin ein Protokoll geführt werden von den wöchentlichen Treffen. Das Laborjournal wird am Ende der Arbeit abgegeben und wird mitbenotet.

### 5. Bericht

Über die Arbeit ist ein Bericht zu verfassen, dessen Textteil maximal 60 Seiten umfassen und eine Dateigrösse von 5MB nicht überschreiten soll. Im Bericht sollen alle gemachten Überlegungen, Abklärungen, Berechnungen und Untersuchungen detailliert (in Text und Bild) dokumentiert werden. Der Bericht muss gut leserlich geschrieben und übersichtlich gegliedert sein. Weitere Richtlinien, wie ein Bericht aufgebaut sein kann, und weitere nützliche Informationen findet man im Leitfaden, welcher in gedruckter Version im Arbeitsplatzordner und auf dem Public Server abgelegt ist.

Des Weiteren muss im Bericht unbedingt eine unterschriebene Nicht-Plagiatsklärung enthalten sein, ein Beispiel dieser Erklärung befindet sich auf dem Public Server.

Der Bericht ist in 1 Papier-Exemplar abzugeben, mit einer beiliegenden CD-ROM, auf der alle anfallenden Daten, wie auch der Bericht selbst (im PDF-Format) gespeichert sind.

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## **Semesterarbeit**

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Writing in English is highly encouraged.

### **6. Termine**

Beginn der Arbeit:

Abgabe des Berichts:

Mündliche Präsentation:

### **7. Organisatorisches**

Betreuung der Arbeit:

Betreuung des Labors:

Arbeitsplatz:

Industriepartner:

Besprechungen: wöchentlich, nach Vereinbarung, an der HSR

Examinator: Prof. Dr. Heinz Mathis, [hmathis@hsr.ch](mailto:hmathis@hsr.ch)

Rapperswil, [Datum]

Viel Erfolg wünscht Ihnen

Heinz Mathis,  
Dozent Mobilkommunikation

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## A.2 Requirement Specification



### Pflichtenheft

Projekt: Low power wakeup receiver

Version 0.1

Cédric Renda, Manuel Tischhauser

Name	Datum	Unterschrift
Prof. Dr. Heinz Mathis		
Selina Malacarne		
Cédric Renda		
Manuel Tischhauser		

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27. September 2019

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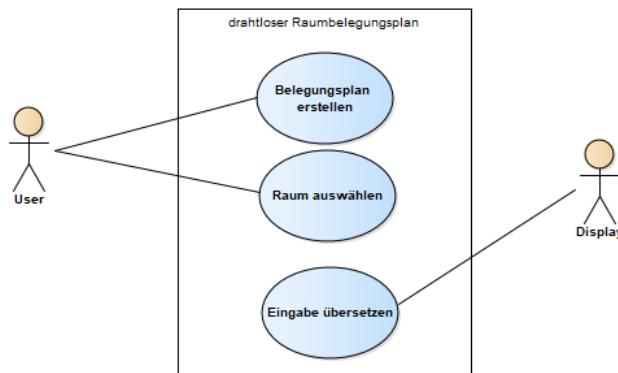
## 1 Einleitung

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## 2 Auftrag

Im Rahmen dieser Semesterarbeit soll eine Lösung zur oben beschriebenen Problematik ausgearbeitet werden. Der Fokus liegt auf der Erstellung eines autarken Anzeigesystems welches über eine drahtlose Schnittstelle bedient werden kann. Die folgende Punkte sollen dabei abgearbeitet werden:

- Recherche bezüglich Schnittstelle und Energy Harvesting.
- Vor- und Nachteile bestehender Technologien abwägen und geeignete Hardware wählen.
- Erstellen eines lauffähigen Prototypen.



*Abbildung 2.1: Use-Case Diagramm*

Der Prototyp richtet sich nach dem Use-Case Diagramm in Abbildung 2.1.

## 3 Produktanforderungen

Das Empfängermodul ist autark und kann auf einem Display Stundenpläne anzeigen. Diese werden über eine drahtlose, bidirektionale Schnittstelle gesendet. Der Sender wird mit einem Computer bedient.

Besteht das System aus mehreren Empfängern, so kann das Sendemodul diese unabhängig von einander selektieren.

### 3.1 Hardware

#### Sender

- Schnittelle zum Computer
- Sendemodul

#### Empfänger

- Mikrocontroller oder Vergleichbares (Prozessor, Speicher, usw.)
- E-Paper-Display
- Energy-Harvesting-Einheit
- Energiespeicher
- Empfangsmodul

### 3.2 Software

#### Sender

- Treiber für Sendemodul

#### Empfänger

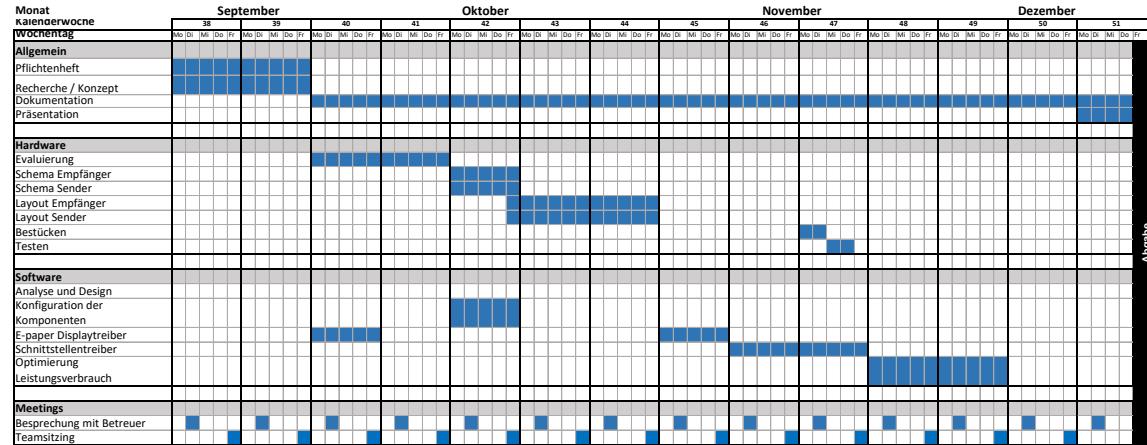
- Firmware für Mikrocontroller

### 3.3 Varianten/Optionen

Ist der Prototyp funktionsfähig, soll zu einem späteren Zeitpunkt auch möglich sein, verschiedene Bildschirmgrößen zu verwenden, wobei sich auch Anzeige nicht nur auf Raumbelegungspläne beschränkt. Deshalb soll das System und insbesondere die Software so flexibel wie möglich entwickelt werden.

### 3.4 Dokumentation

Die Dokumentation beinhaltet sämtliche Überlegungen, Abklärungen, Berechnungen und Untersuchungen, welche im Laufe der Semesterarbeit gemacht wurden.



## 4 Zeitplan