ΕΘΝΙΚΟ ΜΕΤΣΟΒΙΟ ΠΟΛΥΤΕΧΝΕΙΟ ΣΧΟΛΗ ΗΛΕΚΤΡΟΛΟΓΩΝ ΜΗΧΑΝΙΚΩΝ ΚΑΙ ΜΗΧΑΝΙΚΩΝ ΥΠΟΛΟΓΙΣΤΩΝ

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Άσκηση 1

```
LXI B,03E8H ; B = 1000d \rightarrow delay = 1s
    MVI D,00H
2
3
    START:
             LDA 2000H
5
             ANI OFH
6
             JZ START
                               ; check if zero dip switches are turned on
             MOV E,A
                                  ; make E the LSB value
8
             CALL CHECK
                                ; if MSB is on continue, else wait for it to turn on
9
    INC:
10
             MOV A,D
11
             CMA
12
             STA 3000H
                                ; show the value of D in the LEDS
13
                                ; delay 1 sec
             CALL DELB
14
             CALL CHECK
                                 ;same as before
15
             INR D
                                     ;D++
16
             MOV A,D
17
             CMP E
18
             JC INC
                                      ;while D<E go to INC
    DEC:
20
21
             MOV A,D
             CMA
22
             STA 3000H
23
             CALL DELB
^{24}
             CALL CHECK
25
             DCR D
                                     ;D--
                               ;while D>O go to DEC
             JNZ DEC
27
             JMP START
                                ; if D = 0 then go to Start to refresh the value of E
28
29
30
31
    CHECK:
32
             LDA 2000H
33
             ANI 80H
34
             CPI 80H
35
             JNZ CHECK
36
             RET
37
38
    END
39
```

Άσκηση 2

```
MVI A,10H ; empty space on 7seg

STA 0B53H

STA 0B54H
```

```
STA OB55H
   START:
6
   CALL KEYBOARDINPUT ; read the first number
   MOV B,A
   CALL KEYBOARDINPUT ; read the second number
   MOV C,A
11
   MOV A,B
12
   RLC
13
   RLC
14
   RLC
15
   RLC
16
   ADD C
17
   CALL HEXTODEC
   LXI D, OB50H
   CALL STDM
20
   CALL DCD
21
22
   JMP START
23
   KEYBOARDINPUT: ;routine that reads a 1-bit number [0-F] from the keyboard
^{24}
   CALL KIND
25
   CPI 10H
   JNC KEYBOARDINPUT
   RET
28
29
   HEXTODEC:
30
31
   MVI B,00H
              ; counts the # of hundreds/tens/ones
32
33
   HUNDREDS:
35
                  ; if A < 100 store B for hundreds
   CPI 64H
36
   JC STOREHUNDREDS
37
   ; else inr # of hundreds and decrease number by 100 and repeat
   INR B
39
   SUI 64H
40
   JMP HUNDREDS
   STOREHUNDREDS:
42
                 ;temp store number
   MOV C,A
43
                 ;store # of hundreds in random address OB52H for STDM
   MOV A,B
44
   STA OB52H
45
   MOV A,C
46
              ;reinitialize B for tens
   MVI B,00H
47
   TENS:
                  ; if A < 10
   CPI OAH
50
   JC STORETENS
```

```
; same as hundreds
    INR B
53
    SUI OAH
54
    JMP TENS
55
    STORETENS:
56
    MOV C,A
57
    MOV A,B
    STA OB51H
    MOV A,C
60
    MVI B,00H
61
62
    ONES:
63
    CPI 01H
                     ; if A<1
64
    JC STOREONES
    ; same as ones
    INR B
    SUI 01H
68
    JMP ONES
69
    STOREONES:
70
    MOV C,A
71
    MOV A,B
72
    STA OB50H
73
    MOV A,C
75
    RET
76
77
    END
78
```

m 'Aσχηση m 3

```
; B = 500d \rightarrow delay = 0.5s
    LXI B,01F4H
    MVI D,01H
                               ; counter
    MVI E,01H
                               ;register to remember the state of the LSB
3
4
    INC:
5
            MOV A,D
6
            CMA
7
            STA 3000H
                                  ; show the value of D in the LEDS
            CALL DELB
                                   ;delay 0.5 sec
    INCN:
                                  ; checking if the MSB is on, if not then we wait
10
            CALL CHECK
11
            LDA 2000H
12
            ANI 01H
13
            CMP E
                                        ; checks if the state of the LSB has changed
14
            JNZ CHANGESTATE1
                                 ; if yes, then goes to CHANGESTATE1
15
    CONT:
            MOV A,D
17
```

```
CPI 80H
18
             JZ DEC
                                     ; if it has reached the MSB then go to DEC
19
                                      ;else move it one position to the left
             RLC
20
             MOV D, A
21
             JMP INC
22
23
    DEC:
24
             MOV A,D
25
             CMA
26
             STA 3000H
                                    ; show the value of D in the LEDS
27
             CALL DELB
                                    ; delay 0.5 sec
28
    DECN:
                                    ; checking if the MSB is on, if not then we wait
29
             CALL CHECK
30
             LDA 2000H
31
             ANI 01H
32
             CMP E
                                         ; checks if the state of the LSB has changed
33
             JNZ CHANGESTATE2 ; if yes, then goes to CHANGESTATE2
34
    CONT2:
35
             MOV A,D
36
             CPI 01H
37
             JZ INC
                                     ; if it has reached the LSB then go to INC
38
             RRC
                                      ;else move it one position to the right
39
             MOV D, A
40
             JMP DEC
41
42
    ;change the value of E and check if the change went from ON->OFF
43
    CHANGESTATE1:
44
             MOV E,A
                                  ;E changes State
45
             CPI OOH
46
                                  ; if A=O the LSB went from ON->OFF so we change
             JZ DECN
                 direction
                                        ;DECN if we don't want double delay for the
48
                                        \rightarrow displayed led
                                        ; if we don't mind we can simply put DEC
49
             JMP CONT
                               ;else it continues
50
51
    ; change the value of E and check if the change went from ON->OFF
52
    ; same as CHANGESTATE2
53
    CHANGESTATE2:
54
             MOV E,A
55
             CPI OOH
56
             JZ INCN
57
             JMP CONT2
58
59
    ; CHECK POWER (ON-OFF) ROUTINE
60
    CHECK:
61
        LDA 2000H
62
             ANI 80H
63
```