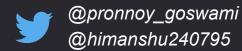
REDUCING THE EFFECT OF TURBIDITY IN UNDERWATER IMAGES

March 25, 2018







NEED FOR UNDERWATER IMAGERY

- Monitoring marine benthic habitats, such as, coral reefs, kelp forests, etc.
- Classify and count various aquatic species in an area
- In Marine Archeology, to analyze the sea-bed and shipwrecks
- Surveillance and monitoring activities with the help of AUVs and ROVs

RAW IMAGE FROM THE DATASET



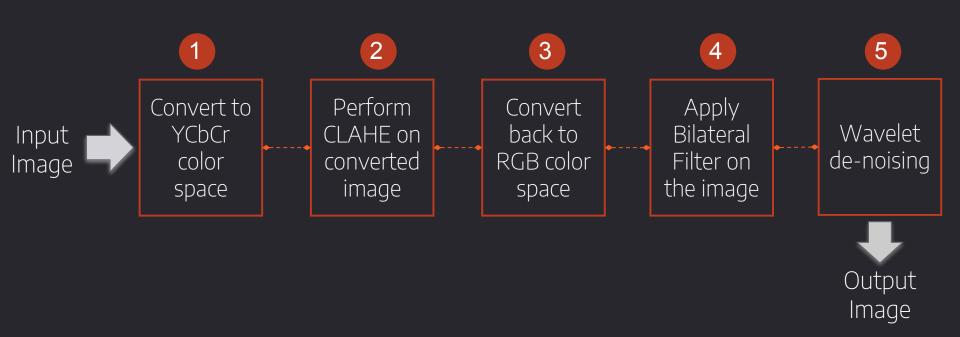
HOW IS IT DIFFERENT FROM IMAGERY ON LAND?

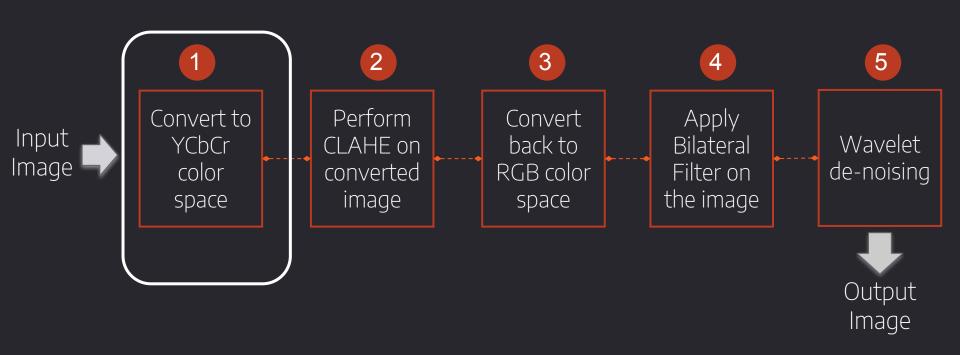
- Due to the medium (water), scattering causes a blurring effect
- Wavelength absorption causes color reduction

 Artificial lighting causes vignetting in captured images

PROBLEM STATEMENT

- This solution aims to reduce the effect of turbidity from underwater images for Marine Archaeologists
- The research took place at National Institute of Oceanography (NIO), Goa - India
- We worked on datasets provided by underwater explorations in the Arabian Sea, along the west coast of India



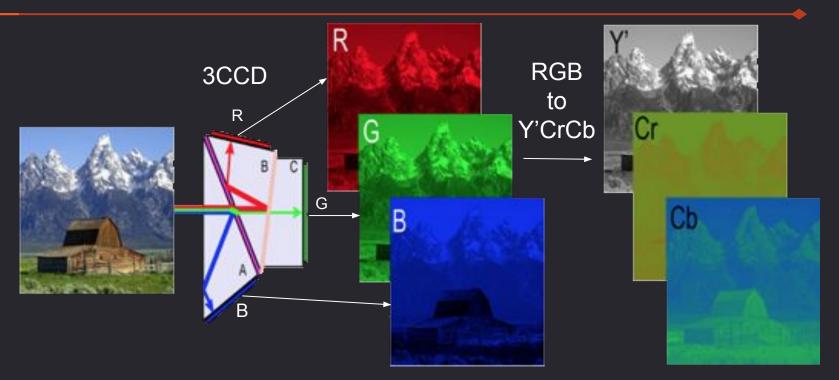


1. CONVERT IMAGE TO YCbCr COLOR SPACE

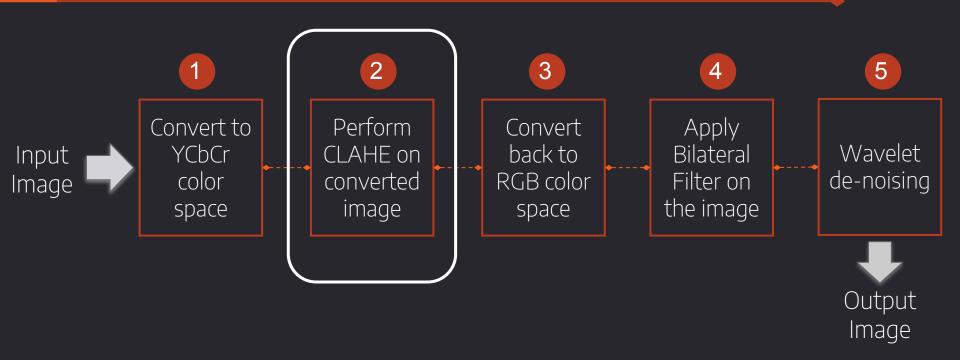
YCbCr is a storage efficient color model

- For histogram equalisation, we need only the luminescence values (i.e., Y channel), and no colors
- To tackle the issue of non-uniform light distribution with increasing depth

1. CONVERT IMAGE TO YCbCr COLOR SPACE



Source: http://www.wikiwand.com/en/YCbCr



2. Perform CLAHE on converted Image

Contrast Limited Adaptive Histogram Equalization

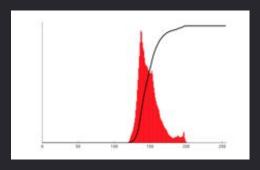
- Improves the local contrast and at the same time limits over-amplification of the noise
- The result value of a pixel under CLAHE is proportional to its rank among the pixels in its neighbourhood

2. Perform CLAHE on converted Image

Original Image







After performing CLAHE





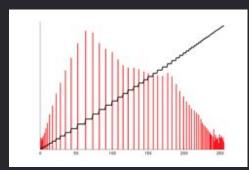
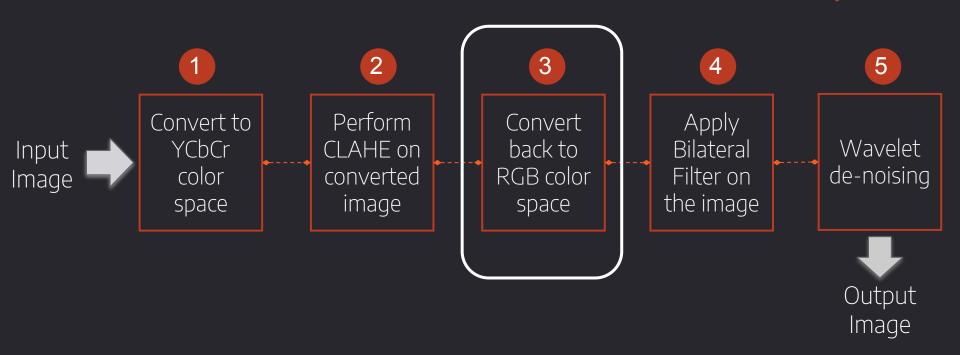


Image Histograms

Source: https://en.wikipedia.org/wiki/Histogram_equalization



3. Convert Image back to RGB color space

To make the processed image coherent to the original image



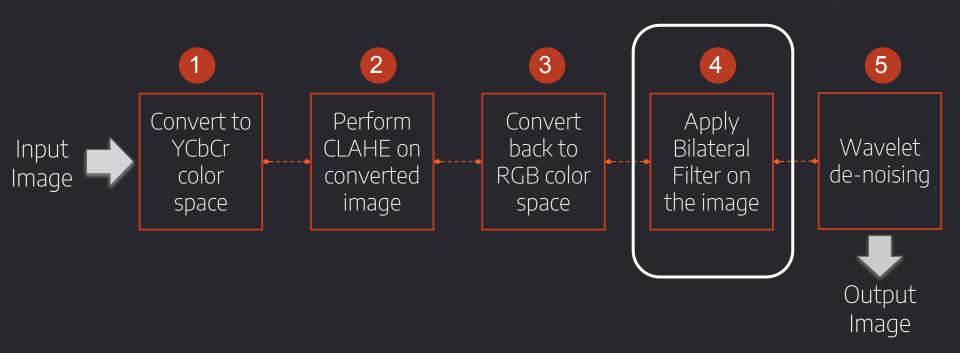
YCbCr Image





RGB Image

Source: https://en.wikipedia.org/wiki/Common_kingfisher



4. Apply Bilateral Filter on the RGB image

- Non-linear, edge preserving, and noise reducing filter
- Each pixel is replaced by weighted average of its neighbours
- Preserves the features and strong edges in images which is essential for marine archaeological studies

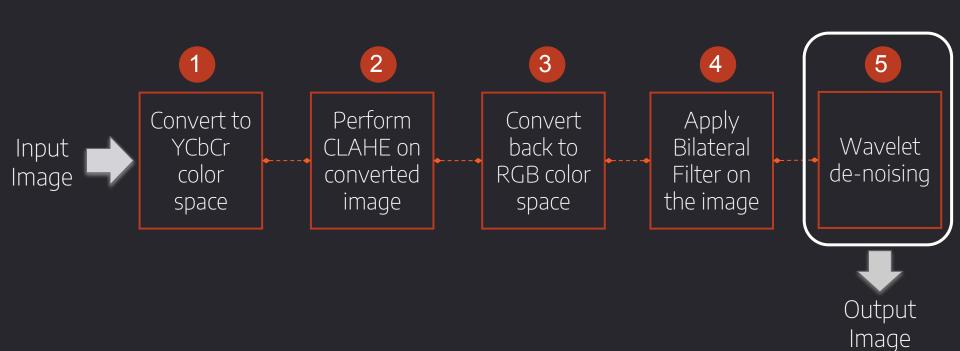
4. Apply Bilateral Filter on the RGB image



a.) Original Image

b.) Smoothened Image

Source: https://en.wikipedia.org/wiki/Bilateral_filter



5. Wavelet De-noising

- Reconstruct a signal from a noisy one
- Idea is to have the amplitude, rather than the location of the spectrum, to be as out-of-phase from that of the noise
- Allowing shrinking of amplitude of the transform to remove noise

5. Wavelet De-noising



a.) Noisy Image SNR = 10.02 dB



b.) Denoised Image SNR = 17.57 dB

Source: http://www-cs.ccny.cuny.edu/~wolberg/capstone/opencv/LearningOpenCV.pdf



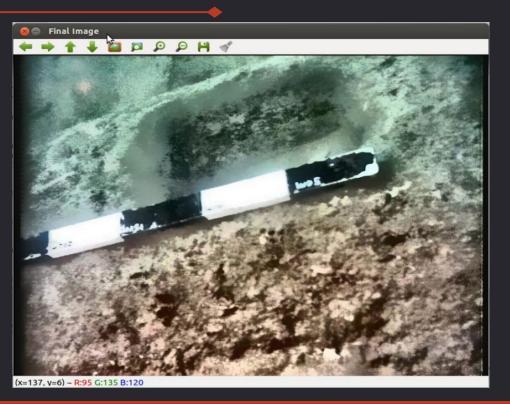
a.) Original Image



b.) Grayscale Image

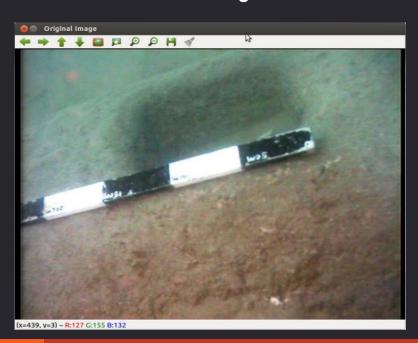


c.) Image after CLAHE



d.) Final Image after Bilateral Smoothing and Wavelet Denoising

Initial Image



Final Image





IMPACT OF OUR WORK

- This solution was integrated in the AUVs and ROVs present at the research facility at NIO, Goa
- It automated the underwater explorations with the help of AUVs & ROVs, and image processing using the NIO servers
- Being further extended to create image mosaics for model reconstruction of shipwrecks

At least **10,000** man-hours saved in a year at NIO, Goa alone.

Whoa! That's a big number, aren't you proud?

REFERENCES

- Garcia R, Gracias N, "Detection of interest points in turbid underwater images."
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- Arnold-Bos A., et. al., "Towards a model-free denoising of underwater optical images."
- Gupta A, Murgai P, Goswami P, et al., "Delhi Technological University: Design and Development of the Littoral AUV Zyra 2.0", AUVSI Robosub Journal 2014.
- Taswell C "The What, How, and Why of Wavelet Shrinkage Denoising"
- Bryson M et. al., "True Color Correction of Autonomous Underwater Vehicle Imagery"

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THANKS!

QUESTIONS?