

Recap: FTCS for the 1D Heat Equation

We consider the one-dimensional heat equation

$$\frac{\partial T}{\partial t} = \alpha \frac{\partial^2 T}{\partial x^2}.$$

Using finite differences in space and an explicit time update, the *Forward Time, Centered Space (FTCS)* scheme is

$$T_j^{n+1} = T_j^n + \lambda (T_{j+1}^n - 2T_j^n + T_{j-1}^n), \quad \lambda = \frac{\alpha \Delta t}{\Delta x^2}.$$

Key features:

- ▶ Fully explicit
- ▶ Easy to implement
- ▶ Conditionally stable

FTCS Stability: What We Know

For the one-dimensional heat equation, FTCS is stable only if

$$\lambda = \frac{\alpha \Delta t}{\Delta x^2} \leq \frac{1}{2}.$$

Implications:

- ▶ Time step is restricted by spatial resolution
- ▶ Small $\Delta x \Rightarrow$ very small Δt
- ▶ Long-time simulations can become expensive

This motivates the use of *implicit* time integration schemes.

Motivation for Crank–Nicolson

FTCS evaluates spatial diffusion entirely at time level n .

Crank–Nicolson evaluates diffusion at the *midpoint in time*:

$$\frac{T^{n+1} - T^n}{\Delta t} = \alpha \frac{1}{2} \left(\frac{\partial^2 T^{n+1}}{\partial x^2} + \frac{\partial^2 T^n}{\partial x^2} \right).$$

Interpretation:

- ▶ Average of explicit and implicit diffusion
- ▶ Second-order accurate in time
- ▶ Improved stability properties

Crank–Nicolson: Discrete Form

Using centered finite differences in space, we obtain

$$T_j^{n+1} - \frac{\lambda}{2} (T_{j+1}^{n+1} - 2T_j^{n+1} + T_{j-1}^{n+1}) = T_j^n + \frac{\lambda}{2} (T_{j+1}^n - 2T_j^n + T_{j-1}^n).$$

Unlike FTCS, all unknown temperatures at time level $n + 1$ appear on the *left-hand side*.

This leads to a linear system that must be solved at each time step.

Crank–Nicolson as a Linear System

At each time step, we solve

$$\mathbf{A} \mathbf{T}^{n+1} = \mathbf{d}.$$

The coefficient matrix \mathbf{A} has a special structure:

$$\mathbf{A} = \begin{bmatrix} b_1 & c_1 & & & 0 \\ a_2 & b_2 & c_2 & & \\ & a_3 & b_3 & c_3 & \\ & & \ddots & \ddots & \ddots \\ 0 & & & a_N & b_N \end{bmatrix}.$$

This is called a *tridiagonal* matrix.

Structure of the Linear System

The Crank–Nicolson system has the form

$$\begin{bmatrix} b_1 & c_1 & & & 0 \\ a_2 & b_2 & c_2 & & \\ a_3 & b_3 & c_3 & & \\ \ddots & \ddots & \ddots & & \\ 0 & & a_N & b_N & \end{bmatrix} \begin{bmatrix} T_1^{n+1} \\ T_2^{n+1} \\ \vdots \\ T_N^{n+1} \end{bmatrix} = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_N \end{bmatrix}.$$

- ▶ Lower diagonal: a_i ;
- ▶ Main diagonal: b_i ;
- ▶ Upper diagonal: c_i ;

Looking Ahead

- ▶ Crank–Nicolson is unconditionally stable for linear diffusion
- ▶ Each time step requires solving a tridiagonal system
- ▶ The special matrix structure enables very efficient solvers

Coming next:

- ▶ Efficient solution of tridiagonal systems
- ▶ Implementation details in Python
- ▶ Comparison of FTCS and Crank–Nicolson on real problems