Building a better metaweb: predicting spatiotemporally explicit plant-pollinator networks

Michael D. Catchen ^{1,2} Paul CaraDonna ^{3,4} Jane E. Ogilvie ³ Francis Banville ³ Dominique Caron ^{1,2} Philippe Desjardins-Proulx ^{5,2} Norma R. Forero-Muñoz ^{5,2} Dominique Gravel ^{6,2} Laura Pollock ^{1,2} Tanya Strydom ^{5,2} Timothée Poisot ^{5,2} Julian Resasco ⁷ Andrew Gonzalez ^{1,2}

Correspondance to:

Michael D. Catchen — michael.catchen@mail.mcgill.ca

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 ¹ McGill University
² Québec Centre for Biodiversity Sciences
³ Rocky Mountain Biological Laboratory
⁴ Chicago Bontanic Garden
⁵ Université de Montréal
⁶ Université de Sherbrooke
⁷ University of
Colorado Boulder

Purpose: This template provides a series of scripts to render a markdown document into an interactive website and a series of PDFs.

Motivation: It makes collaborating on text with GitHub easier, and means that we never need to think about the output.

Internals: GitHub actions and a series of python scritpts. The markdown is handled with pandoc.

1 Abstract

- 2 Using a data set of [DESCRIBE EACH DATASET IN A NICE WAY], we predict a spatiotemporally explicit
- metaweb of interactions between bumblebees (Bombus) and wildflowers (within find clade). We integrate
- 4 this data with crowdsourced occurrence data and climate data to [best paint the picture of the Colorado
- 5 bumblebee-plant metaweb]. Using temporal climate data, we forecast how the spatiotemporal overlap of
- 6 interacting species will change under proposed climate scenarios. We use this to estimate what
- 7 interactions between bees and plants need the most attention to prevent the spatiotemporal decoupling of
- 8 an interactions from threatening ecosystem functioning or the persistence of a species.

Introduction

- 10 Ecosystems emerge from sets of interactions between pairs of species, these interactions produce the
- dynamics and persistence of ecosystems, and the abundance and diversity of the species within them.
- Plant-pollinator interactions specifically drive the function and persistence of "architecture of biodiversity"
- 13 (Bascompte & Jordano 2007). However, we are far from a robust understanding of plant-pollinator
- networks. This is because sampling interactions is costly. Interactions vary in space and time (Poisot et al.
- 2015)—particularly relevant in this system (CaraDonna et al. 2014). This is why there is interest in using
- models to predict interactions from sparse data (**Strydom2021?**). In this paper, we combine several
- datasets, each spanning several years, to produce spatially and temporally explicit predictions of the
- bumblebee (genus *Bombus*) and wildflower pollination network across the state of Colorado.
- We do this in two parts: (1) metaweb prediction and (2) conditioning our metaweb prediction on
- 20 co-occurrence probability. First, we build a model to predict the metaweb—the network of all
- interactions, aggregated across all times and spatial locations—of Bombus and wildflower species across
- ²² Colorado. (Why do this? The metaweb is more predictable than local interactions.) We do this using
- 23 network embedding (cite?). Network embedding takes each node in the network (either a bumblebee or a
- wildflower) and represents it in a latent n dimensional space. Combination of running models on
- 25 Temporal niche (T), Phylogenetic niche (P), Environmental niche (E), and relative abundance in
- 26 community (RA).
- ²⁷ Second, we then use this metaweb to predict the structure of networks at specific locations and times of

- year (Gravel et al. 2019). Finally we suggest a map of sampling priority, which suggests the locations to
- 29 sample that will best improve our understanding of the Colorado *Bombus* pollination metaweb.
- 30 Why is this good for science, what does this contribute to our understanding of plant-pollinator ints,
- 31 networks, Bombus, predictive models, etc., and how can these results be useful.

Data and methodology

- 33 We use three separate field datasets to estimate the Colorado *Bombus* metaweb.
- [Figure 1 about here.]

Predicting the metaweb

36 Feature Embedding

37 Environmental niche features

- We take the 19 BioClim layers from CHELSA (cite; 1km resolution) and a map of elevation and PCA them.
- 39 A resulting 4 layers cover 99.5% of the variance. We use species occurrence data from GBIF, and consider
- 40 each occurrence record as a point in environment space. Then we fit a multivariate normal distribution to
- these points in environmental space.

42 Temporal niche features

- 43 We take the mean and variance of the distribution of number of observations per week of year in the
- 44 interaction field data.

45 Phylogenetic features

- 46 **Phylogeny Construction** We construct phylogenies for both *Bombus* and wildflower species using
- 47 barcode markers, mitochondrial COI and chloroplast rbcL, respectively. These sequences were obtained
- 48 from NCBI GenBank for all species. For species for which no sequence was available (only a handful of

- plants), their was substituted with a barcode from a member of the same genus. Justify why this is fine
- 50 here.
- These sequences were aligned using ClustalOmega v???, and then a posterior distribution of phylogenies
- ⁵² and consensus tree was obtained via MrBayes v??, using XX substition model with gamma-distributed
- rates. Run until convergence, which here we define as the standard-deviation of splits falling below 0.1.
- 54 Creating an embedding from phylogenies We simulate traits. Relationship between number of
- traits, num output PCA dimensions, and number of used dimensions in the model matter. Describe how
- 56 that works.

63

57 Relative Abundance

This embedding is the simplest.

59 Metaweb Model Fitting and Validation

- 60 We fit a bunch of models using MLJ.jl. Some of them are bagged, some are not bagged.
- We train each model on each possible combination of features.
- 62 AUC-ROC and AUC-PR values below in fig. 2

[Figure 2 about here.]

- 64 What does this tell us? The ensemble model is regularly the best for ROC, but not for PR. This illustrates
- an inherent trade-off between models being as "right" as possible versus a model being useful for
- 66 discovering false-negatives.
- 67 Figure 3: Embedded networks pre and post prediction a la that virus paper

Predicting networks in space and time

- 69 Now that we have a metaweb, we can extend this to predict interactions at particular places and times by
- decomposing the probability of interaction at particular place and time into probability of interaction

multiplied by probability of co-occurrence via properties of conditional probability (Gravel et al. 2019).

72 Spatial prediction

- Page 73 Boosted regression tree using EvoTrees.jl, using data from GBIF.
- How do we define? $P(i \leftrightarrow j)$ Is it $P(A_{ij})P(O_{ij})$ or $P(A_{ij})P(O_i)P(O_j)$

75 Temporal prediction

[Figure 3 about here.]

Figure 5: Maps over time figure and Prob(Connectance) vs. Month figure

78 Prioritizing spatial sampling of pollinator interactions

- How do we improve out understanding of this pollination network, or determine if it is changing over
- 80 time?

76

81 Figure 4: Uncertainty and sampling priority map

Discussion

- 83 We predict things alright. Emphasizes how heterogenous data sources can improve interaction prediction
- 84 (rocpr fig). Advances network embedding as a framework for prediction of species interaction networks.
- Embedding is a good tool for x. How do we select the dimensionality of our predictors? [Paper on
- ecological dimensionality]. But this doesn't mean 7-dimensions is adaquete to describe our predictors in
- models to predict species interactions.
- 88 Bascompte, J. & Jordano, P. (2007). Plant-Animal Mutualistic Networks: The Architecture of Biodiversity.
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- and Grinnell together: A quantitative framework to represent the biogeography of ecological
- interaction networks. *Ecography*, 42, 401–415.
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- through space and time. *Oikos*, 124, 243–251.

Metaweb Prediction Models Embedding Predicted Metaweb Environmental Niche Logistic Regression Neural Network Temporal Niche ADABoost Regression Model fitting, validation and selection Phylogenetic Niche Boosted Regression Tree Random Forest Relative Abundance Ensemble Model **Spatiotemporal Network Prediction** Species Richness $P_{SC}(i,j)$ $P_{TC}(i,j)$ $P(A_{ij})$ $P(i \leftrightarrow j)$ Temporal Co-occurrence probability Spatial Co-occurrence Interaction probability probability $\begin{array}{c} \text{time} \\ t-1 \end{array}$ Occurrence Probability time of year Interaction Richness time Time of year predicted metaweb

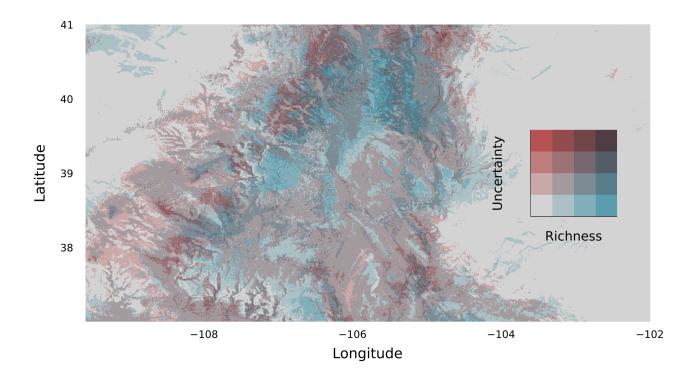
Figure 1: todo

time of year

	ROC-AUC									PR-AUC						
T+P+E+R	0.75	0.72	0.84	0.85	0.86	0.87	0.87	T+P+E+R	0.55	0.47	0.67	0.58	0.70	0.73	0.71	
T+E+R	0.76	0.78	0.84	0.83	0.85	0.87	0.86	T+E+R	0.52	0.53	0.67	0.57	0.68	0.71	0.69	
P+E+R	0.75	0.71	0.85	0.84	0.85	0.88	0.87	P+E+R	0.53	0.46	0.69	0.57	0.68	0.74	0.70	
T+P+E	0.73	0.70	0.82	0.84	0.80	0.86	0.86	T+P+E	0.51	0.44	0.65	0.67	0.61	0.71	0.68	
T+P+R	0.75	0.71	0.84	0.83	0.86	0.86	0.87	T+P+R	0.53	0.42	0.68	0.58	0.70	0.72	0.70	
E+R	0.75	0.77	0.85	0.82	0.85	0.87	0.86	E+R	0.49	0.53	0.67	0.59	0.65	0.70	0.68	
P+R	0.75	0.71	0.85	0.84	0.86	0.88	0.87	P+R	0.52	0.46	0.69	0.61	0.69	0.73	0.70	
T+R	0.75	0.77	0.84	0.81	0.85	0.85	0.85	T+R	0.49	0.52	0.68	0.53	0.68	0.69	0.68	
T+P	0.70	0.71	0.81	0.83	0.81	0.85	0.85	T+P	0.47	0.46	0.63	0.64	0.59	0.68	0.66	
T+E	0.65	0.60	0.82	0.83	0.81	0.84	0.84	T+E	0.41	0.32	0.64	0.64	0.63	0.66	0.67	
P+E	0.71	0.70	0.82	0.85	0.79	0.87	0.86	P+E	0.50	0.44	0.62	0.68	0.54	0.70	0.66	
R	0.77	0.77	0.85	0.80	0.84	0.82	0.84	R	0.52	0.52	0.68	0.47	0.67	0.64	0.65	
Е	0.64	0.52	0.79	0.81	0.80	0.81	0.82	Е	0.35	0.23	0.56	0.57	0.56	0.59	0.59	
Р	0.69	0.71	0.80	0.82	0.77	0.84	0.84	Р	0.44	0.44	0.57	0.59	0.52	0.63	0.61	
Т	0.57	0.57	0.80	0.80	0.80	0.82	0.82	Т	0.31	0.31	0.59	0.57	0.61	0.62	0.63	
	Logistic	Neural Network	ADABoost	Decision Tree	Boosted Regression Tree	Random Forest	Ensemble		Logistic	Neural Network	ADABoost	Decision Tree	Boosted Regression Tree	Random Forest	Ensemble	

Figure 2: todo

Bombus



Flowers

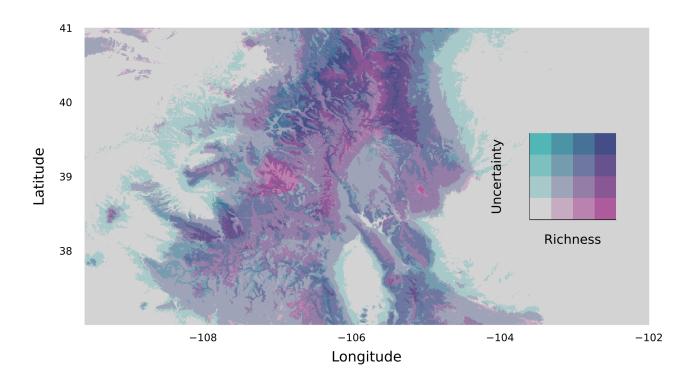


Figure 3: todo