Building a better metaweb: predicting spatiotemporally explicit plant-pollinator networks

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Purpose: This template provides a series of scripts to render a markdown document into an interactive website and a series of PDFs.

Motivation: It makes collaborating on text with GitHub easier, and means that we never need to think about the output.

Internals: GitHub actions and a series of python scritpts. The markdown is handled with pandoc.

1 Abstract

- 2 Using a data set of [DESCRIBE EACH DATASET IN A NICE WAY], we predict a spatiotemporally explicit
- metaweb of interactions between bumblebees (Bombus) and wildflowers (within find clade). We integrate
- 4 this data with crowdsourced occurrence data and climate data to [best paint the picture of the Colorado
- 5 bumblebee-plant metaweb]. Using temporal climate data, we forecast how the spatiotemporal overlap of
- 6 interacting species will change under proposed climate scenarios. We use this to estimate what
- 7 interactions between bees and plants need the most attention to prevent the spatiotemporal decoupling of
- 8 an interactions from threatening ecosystem functioning or the persistence of a species.

9 Introduction

- 50 Species interactions are important. It is ultimately interactions between individuals of different species
- that drive the structure, dynamics, and persistence of ecosystems, and the abundance and diversity of the
- species within them. Plant-pollinator interactions specifically drive the function and persistence of
- "architecture of biodiversity" (Bascompte & Jordano 2007). However, we are far from a robust
- understanding of plant-pollinator networks. This is because sampling interactions is costly. Interactions
- vary in space and time (Poisot et al. 2015)—particularly relevent in this system (CaraDonna et al. 2014).
- 16 This is why there is interest in using models to predict interactions from sparse data (**Strydom2021?**). In
- this paper, we combine several datasets, each spanning several years, to produce spatially and temporally
- explicit predictions of the bumblebee (genus *Bombus*) and wildflower pollination network across the state
- 19 of Colorado.
- 20 We do this in two parts: (1) metaweb prediction and (2) conditioning our metaweb prediction on
- 21 co-occurrence probability. First, we build a model to predict the metaweb—the network of all
- 22 interactions, aggregated across all times and spatial locations—of Bombus and wildflower species across
- ²³ Colorado. (Why do this? The metaweb is more predictable than local interactions.) We do this using
- network embedding (cite?). Network embedding takes each node in the network (either a bumblebee or a
- ²⁵ wildflower) and represents it in a latent *n* dimensional space. Combination of running models on
- Temporal niche (T), Phylogenetic niche (P), Environmental niche (E), and relative abundance in
- 27 community (RA).

- 28 Second, we then use this metaweb to predict the structure of networks at specific locations and times of
- 29 year (Gravel et al. 2019). Finally we suggest a map of sampling priority, which suggests the locations to
- sample that will best improve our understanding of the Colorado *Bombus* pollination metaweb.
- 31 Why is this good for science, what does this contribute to our understanding of plant-pollinator ints,
- networks, Bombus, predictive models, etc., and how can these results be useful.

3 Data

³⁴ We use three separate field datasets to estimate the Colorado *Bombus* metaweb.

35 Methods

36

[Figure 1 about here.]

37 Predicting the metaweb

38 Feature Embedding

39 Environmental niche features

- 40 We take the 19 BioClim layers from CHELSA (cite; 1km resolution) and a map of elevation and PCA them.
- 41 A resulting 4 layers cover 99.5% of the variance. We use species occurrence data from GBIF, and consider
- each occurrence record as a point in environment space. Then we fit a multivariate normal distribution to
- these points in environmental space.

44 Temporal niche features

- We take the mean and variance of the distribution of number of observations per week of year in the
- 46 interaction field data.

47 Phylogenetic features

- 48 **Phylogeny Construction** We construct phylogenies for both *Bombus* and wildflower species using
- ⁴⁹ barcode markers, mitochondrial COI and chloroplast rbcL, respectively. These sequences were obtained
- from NCBI GenBank for all species. For species for which no sequence was available (only a handful of
- 51 plants), their was substituted with a barcode from a member of the same genus. Justify why this is fine
- 52 here.
- 53 These sequences were aligned using ClustalOmega v???, and then a posterior distribution of phylogenies
- and consensus tree was obtained via MrBayes v??, using XX substition model with gamma-distributed
- rates. Run until convergence, which here we define as the standard-deviation of splits falling below 0.1.
- 56 Creating an embedding from phylogenies We simulate traits. Relationship between number of
- traits, num output PCA dimensions, and number of used dimensions in the model matter. Describe how
- 58 that works.

65

59 Relative Abundance

60 This embedding is the simplest.

61 Metaweb Model Fitting and Validation

- We fit a bunch of models using MLJ.jl.
- 63 Some of them are bagged, some are not bagged.
- 64 AUC-ROC and AUC-PR values below in fig. 2

[Figure 2 about here.]

- 66 What does this tell us? The ensemble model is regularly the best for ROC, but not for PR. This illustrates
- an inherent trade-off between models being as "right" as possible versus a model being useful for
- 68 discovering false-negatives.

99 Predicting networks in space and time

- Now that we have a metaweb, we can extend this to predict interactions at particular places and times by
- decomposing the probability of interaction at particular place and time into probability of interaction
- multiplied by probability of co-occurrence via properties of conditional probability (Gravel et al. 2019).
- How do we define? $P(i \leftrightarrow j)$ Is it $P(A_{ij})P(O_{ij})$ or $P(A_{ij})P(O_i)P(O_j)$
- Figure 3: Maps over time figure and Prob(Connectance) vs. Month figure

75 Prioritizing spatial sampling of pollinator interactions

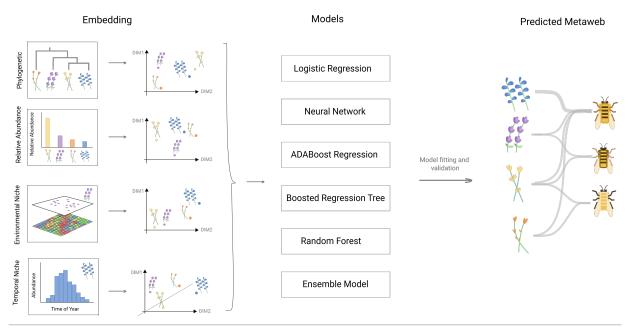
- How do we improve out understanding of this pollination network, or determine if it is changing over
- 77 time?
- 78 Figure 4: Uncertainty and sampling priority map

79 Discussion

- 80 We predict things alright. Emphasizes how heterogenous data sources can improve interaction prediction
- (rocpr fig). Advances network embedding as a framework for prediction of species interaction networks.
- 82 Embedding is a good tool for x. How do we select the dimensionality of our predictors? [Paper on
- 83 ecological dimensionality]. But this doesn't mean 7-dimensions is adaquete to describe our predictors in
- models to predict species interactions.
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Metaweb Prediction



Spatiotemporal Network Prediction

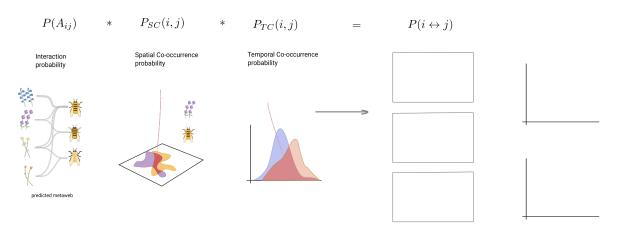


Figure 1: todo

	ROC-AUC									PR-AUC						
T+P+E+R	0.75	0.72	0.84	0.85	0.86	0.87	0.87	T+P+E+R	0.55	0.47	0.67	0.58	0.70	0.73	0.71	
T+E+R	0.76	0.78	0.84	0.83	0.85	0.87	0.86	T+E+R	0.52	0.53	0.67	0.57	0.68	0.71	0.69	
P+E+R	0.75	0.71	0.85	0.84	0.85	0.88	0.87	P+E+R	0.53	0.46	0.69	0.57	0.68	0.74	0.70	
T+P+E	0.73	0.70	0.82	0.84	0.80	0.86	0.86	T+P+E	0.51	0.44	0.65	0.67	0.61	0.71	0.68	
T+P+R	0.75	0.71	0.84	0.83	0.86	0.86	0.87	T+P+R	0.53	0.42	0.68	0.58	0.70	0.72	0.70	
E+R	0.75	0.77	0.85	0.82	0.85	0.87	0.86	E+R	0.49	0.53	0.67	0.59	0.65	0.70	0.68	
P+R	0.75	0.71	0.85	0.84	0.86	0.88	0.87	P+R	0.52	0.46	0.69	0.61	0.69	0.73	0.70	
T+R	0.75	0.77	0.84	0.81	0.85	0.85	0.85	T+R	0.49	0.52	0.68	0.53	0.68	0.69	0.68	
T+P	0.70	0.71	0.81	0.83	0.81	0.85	0.85	T+P	0.47	0.46	0.63	0.64	0.59	0.68	0.66	
T+E	0.65	0.60	0.82	0.83	0.81	0.84	0.84	T+E	0.41	0.32	0.64	0.64	0.63	0.66	0.67	
P+E	0.71	0.70	0.82	0.85	0.79	0.87	0.86	P+E	0.50	0.44	0.62	0.68	0.54	0.70	0.66	
R	0.77	0.77	0.85	0.80	0.84	0.82	0.84	R	0.52	0.52	0.68	0.47	0.67	0.64	0.65	
Е	0.64	0.52	0.79	0.81	0.80	0.81	0.82	E	0.35	0.23	0.56	0.57	0.56	0.59	0.59	
Р	0.69	0.71	0.80	0.82	0.77	0.84	0.84	Р	0.44	0.44	0.57	0.59	0.52	0.63	0.61	
Т	0.57	0.57	0.80	0.80	0.80	0.82	0.82	Т	0.31	0.31	0.59	0.57	0.61	0.62	0.63	
	Logistic	Neural Network	ADABoost	Decision Tree	Boosted Regression Tree	Random Forest	Ensemble		Logistic	Neural Network	ADABoost	Decision Tree	Boosted Regression Tree	Random Forest	Ensemble	

Figure 2: todo