

# NeutralLandscapes.jl: a library for efficient generation of neutral landscapes with temporal change

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Soon to be a paper, maybe. TK authors, MKB,VB,RS,TP

# 1 Introduction

2 Neutral landscapes are increasingly used in ecological and evolutionary studies to provide a null  
3 expectation of the variance of a given metric over space.

4 Wide range of disciplines: from landscape genetics [], to spatial ecology [], and biogeography [].

5 As biodiversity science becomes increasingly concerned with temporal change and its consequences, its  
6 clear there is a gap generating neutral landscapes that change over time. In this ms we present how  
7 `NeutralLandscapes.jl` is orders of magnitudes faster than packages `nlmpy` (in python) or `NLMR` (in R). In  
8 addition we then present a novel method for generating landscape change with prescribed levels of spatial  
9 and temporal autocorrelation.

## 10 Software Overview

11 This software can generate neutral landscapes using several methods, enables masking and works with  
12 other julia packages.

13 fig. 1 shows a replica of Figure 1 from (**nlmpycite?**), which shows the capacity of the library to generate  
14 different types of neutral landscapes, and then apply masks and categorical classification to them.

15 Table of methods.

Model	nlmpy?	NLMR	Description	References
No gradient	x	x	Each cell is drawn randomly	
Planar gradient	x	x	A gradient from low to high at a given angle	
Distance gradient	x	x	Each cell is the distance between that cell and a location	
Random rectuangular cluster	x	x	Covers the plane in random rectangles until covered	
Random element nearest-neighbor	x	x*	Discrete categories based on distance a set of n random points	<code>nlm_mosaictess</code> , k- means

Model	nlmpy?	NLMR	Description	References
Random cluster nearest-neighbor	x	x	Starts with $n$ seed points and grows clusters probabilistically	
Random curds		x		
Gaussian Field		x		
Diamond-square			Improvement on Diamond-square and fractal brownian motion.	
Perlin noise	x		Method for noise with “smoother” features than DS/MPD	
Mosaic random field		x		

[Figure 1 about here.]

## What methods have been called different things but are actually the same thing?

### Interoperability

Ease of use with other julia packages

Mask of neutral variable masked across quebec in 3 lines.

```
using NeutralLandscapes
```

```
using SimpleSDMLayers
```

```
quebec = SimpleSDMPredictor(WorldClim, BioClim; left=-90., right=-50., top=75., bottom=40.)
```

```
qcmask = fill(true, size(quebec))
```

```
qcmask[findall(isnothing, quebec.grid)] .= false
```

```
pltsettings = (cbar=:none, frame=:box)
```

```
plot(
```

```
    heatmap(rand(MidpointDisplacement(0.8), size(layer), mask=qcmask); pltsettings),
```

```

32     heatmap(rand(PlanarGradient(), size(layer), mask=qcmask); pltsettings),
33     heatmap(rand(PerlinNoise((4,4)), size(layer), mask=qcmask); pltsettings),
34     heatmap(rand(NearestNeighborCluster(0.5), size(layer), mask=qcmask); pltsettings),
35     dpi=400
36 )
37
38 savefig("interoperable.png")

```

39 [Figure 2 about here.]

## 40 **Benchmark comparison to nlmpy and NLMR**

41 It's fast. As the scale and resolution of raster data increases, neutral models must be able to scale to match  
42 those data dimensions. Here we provide two benchmark tests. First a comparison of the speed variety of  
43 methods from each NeutralLandscapes.jl, NLMR, and nlmpy. Second we compare these performance of  
44 each of these software packages as rasters become larger. We show that Julia even outperforms the NLMR  
45 via C++ implementation of a particularly slow neutral landscape method (midpoint displacement).

46 [Figure 3 about here.]

## 47 **Generating dynamic neutral landscapes**

48 We implement methods for generating change that are temporally autocorrelated, spatially autocorrelated,  
49 or both.

$$50 \quad M_t = M_{t-1} + f(M(t-1))$$

## 51 **Models of change**

### 52 **Directional**

### 53 **Temporally autocorrelation**

54  $r$ : rate,  $v$ : variability,  $U$  matrix of draws from standard Normal(0, 1)

55 
$$f_T(M_{ij}) = r + vU_{ij}$$

### 56 **Spatial autocorrelation**

57  $r$ : rate,  $v$ : variability,  $[Z(\delta)]_{ij}$ : the  $(i, j)$  entry of the zscore of the  $\delta$  matrix

58 
$$f_S(M_{ij}) = r + v \cdot [Z(\delta)]_{ij}$$

### 59 **Spatiotemporal autocorrelation**

### 60 **Rescaling to mimic real data**

## 61 **Discussion**

## 62 **References**

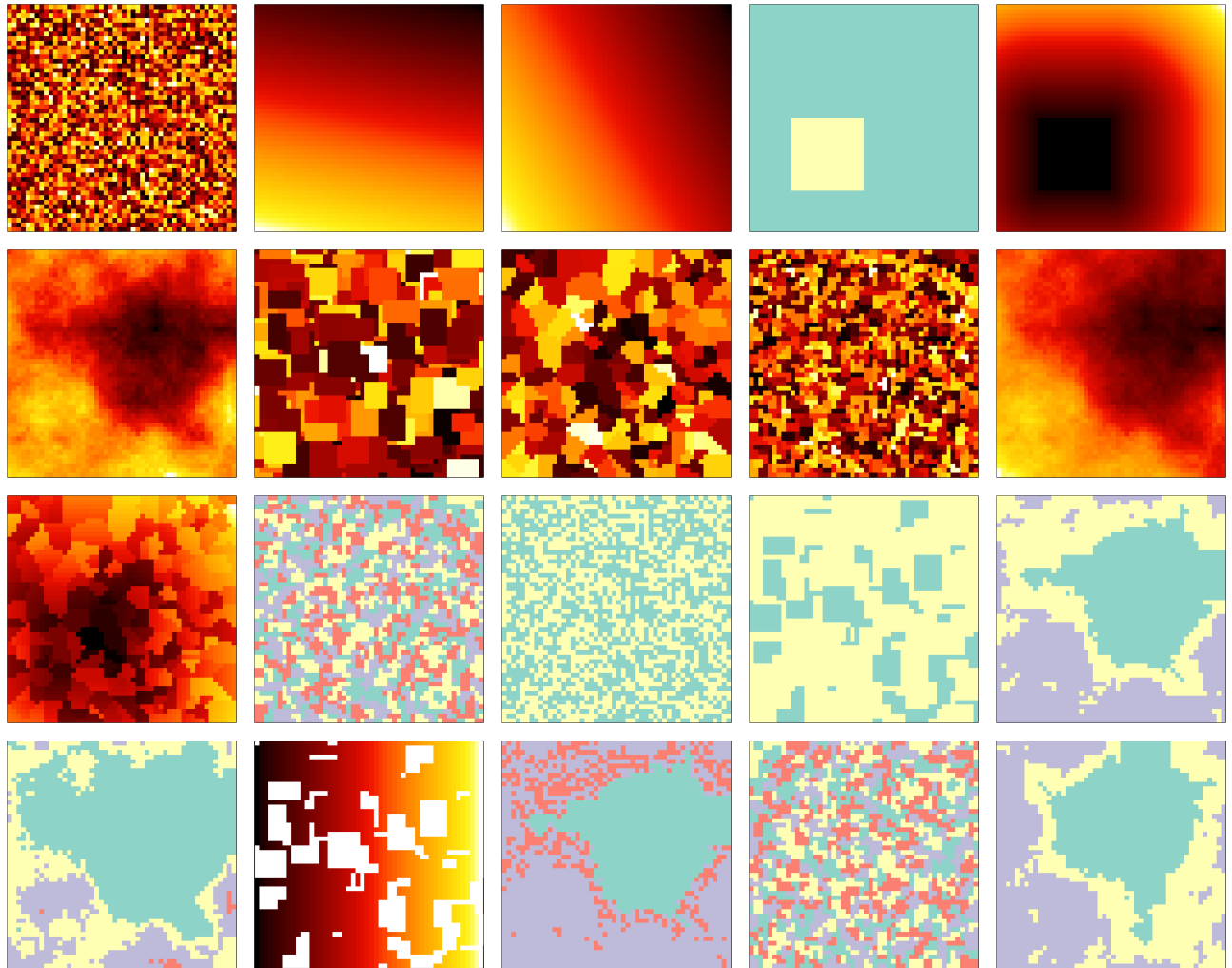


Figure 1: Recreation of the figure in n1mpy paper and the source, supplied in less than 40 lines of code.

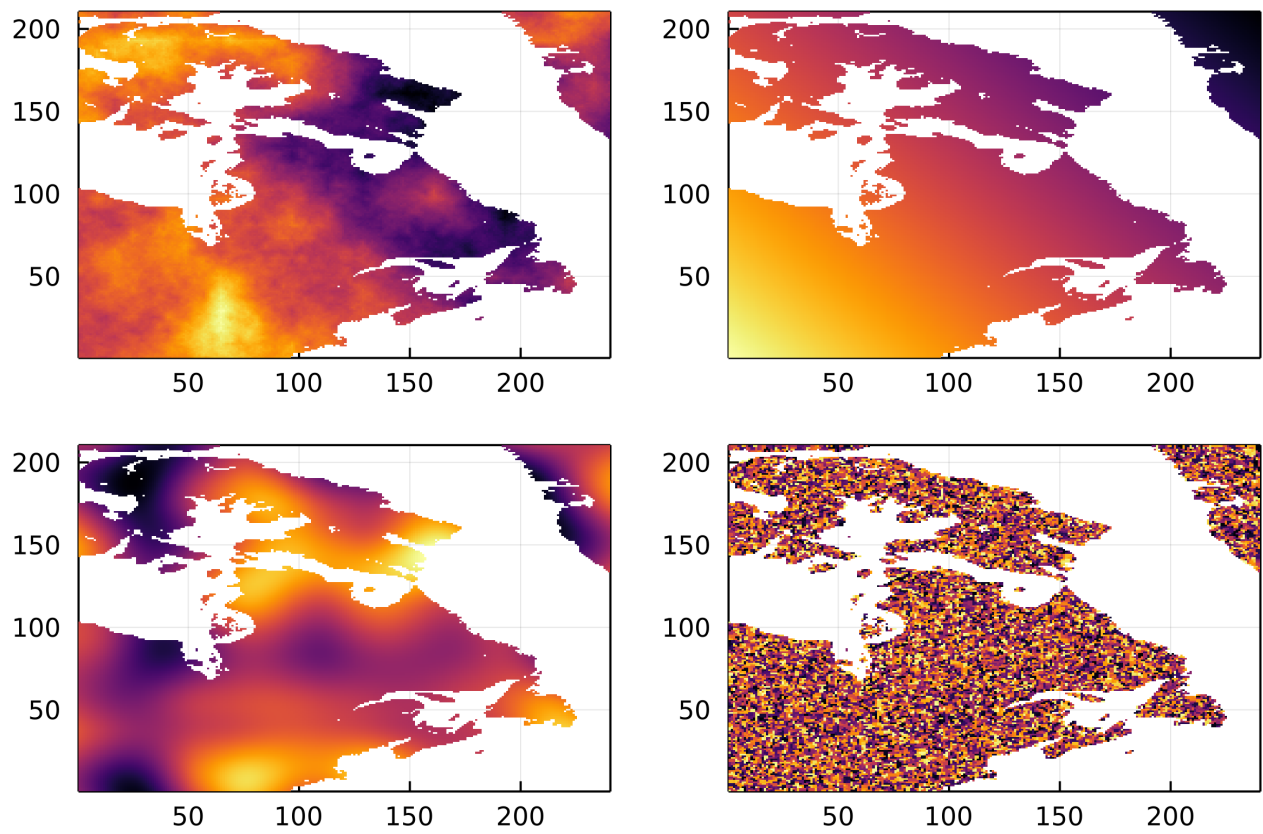


Figure 2: todo



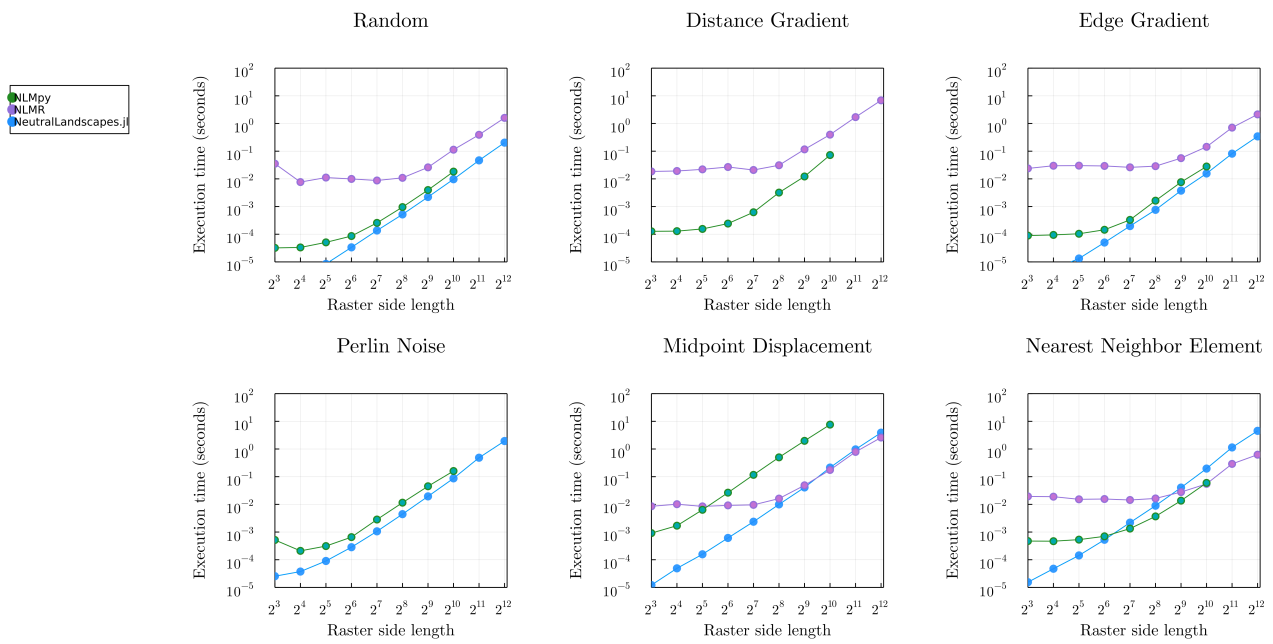


Figure 3: todo