

# NeutralLandscapes.jl: a library for efficient generation of neutral landscapes with temporal change

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Soon to be a paper, maybe. TK authors, MKB,VB,RS,TP

# 1 Introduction

2 Neutral landscapes are increasingly used in ecological and evolutionary studies to provide a null  
3 expectation spatial variation of a given measurement. Originally developed to simulate the spatially  
4 autocorrelated data (Gardner *et al.* 1987; Milne 1992), they have seen use in a wide range of disciplines:  
5 from landscape genetics (Storfer *et al.* 2007), to landscape and spatial ecology (Tinker *et al.* 2004; Rempel  
6 & Fortin 2013), and biogeography (Albert *et al.* 2017).

7 The two primary packages used to simulate neutral landscapes are NLMR in (the R language) (Sciaini *et al.*  
8 2018) and NLMpy (in Python; Etherington *et al.* 2015). We present NeutralLandscapes.jl, a package in  
9 Julia for neutral landscapes which is faster than both above packages. Here we demonstrate that  
10 NeutralLandscapes.jl, depending on the method, is orders of magnitude faster than previous neutral  
11 landscape packages. As biodiversity science becomes increasingly concerned with temporal change and  
12 its consequences, it's clear there is a gap in methodology in generating neutral landscapes that change over  
13 time. In addition we present a novel method for generating landscape change with prescribed levels of  
14 spatial and temporal autocorrelation, which is implemented in NeutralLandscapes.jl

## 15 Software Overview

16 This software can generate neutral landscapes using several methods, enables masking and works with  
17 other Julia packages.

18 fig. 1 shows a replica of Figure 1 from Etherington *et al.* (2015), which shows the capacity of the library to  
19 generate different types of neutral landscapes, and then apply masks and categorical classification to them.

20 [Figure 1 about here.]

## 21 Interoperability

22 Ease of use with other Julia packages

23 Mask of neutral variable masked across Quebec in 3 lines.

24 using NeutralLandscapes

```

25 using SimpleSDMLayers
26
27 quebec = SimpleSDMPredictor(WorldClim, BioClim; left=-90., right=-50., top=75., bottom=40.)
28 qcmask = fill(true, size(quebec))
29 qcmask[findall(isnothing, quebec.grid)] .= false
30
31 pltsettings = (cbar=:none, frame=:box)
32
33 plot(
34     heatmap(rand(MidpointDisplacement(0.8), size(layer), mask=qcmask); pltsettings),
35     heatmap(rand(PlanarGradient(), size(layer), mask=qcmask); pltsettings),
36     heatmap(rand(PerlinNoise((4,4)), size(layer), mask=qcmask); pltsettings),
37     heatmap(rand(NearestNeighborCluster(0.5), size(layer), mask=qcmask); pltsettings),
38     dpi=400
39 )
40
41 savefig("interoperable.png")

```

42 [Figure 2 about here.]

## 43 **Benchmark comparison to nlmpy and NLMR**

44 It's fast. As the scale and resolution of raster data increases, neutral models must be able to scale to match  
45 those data dimensions. Here we provide two benchmark tests. First a comparison of the speed variety of  
46 methods from each NeutralLandscapes.jl, NLMR, and nlmpy. Second we compare these performance of  
47 each of these software packages as rasters become larger. We show that Julia even outperforms the NLMR  
48 via C++ implementation of a particularly slow neutral landscape method (midpoint displacement).

49 [Figure 3 about here.]

## 50 **Generating dynamic neutral landscapes**

51 We implement methods for generating change that are temporally autocorrelated, spatially autocorrelated,  
52 or both.

$$53 \quad M_t = M_{t-1} + f(M(t-1))$$

## 54 **Models of change**

### 55 **Directional**

### 56 **Temporally autocorrelation**

57  $r$ : rate,  $v$ : variability,  $U$  matrix of draws from standard Normal(0, 1)

$$58 \quad f_T(M_{ij}) = r + vU_{ij}$$

### 59 **Spatial autocorrelation**

60  $r$ : rate,  $v$ : variability,  $[Z(\delta)]_{ij}$ : the  $(i, j)$  entry of the zscore of the  $\delta$  matrix

$$61 \quad f_S(M_{ij}) = r + v \cdot [Z(\delta)]_{ij}$$

### 62 **Spatiotemporal autocorrelation**

$$63 \quad f_{ST}(M_{ij}) = r + v \cdot [Z(\delta)]_{ij}$$

## 64 **Rescaling to mimic real data**

## 65 **Discussion**

## 66 **References**

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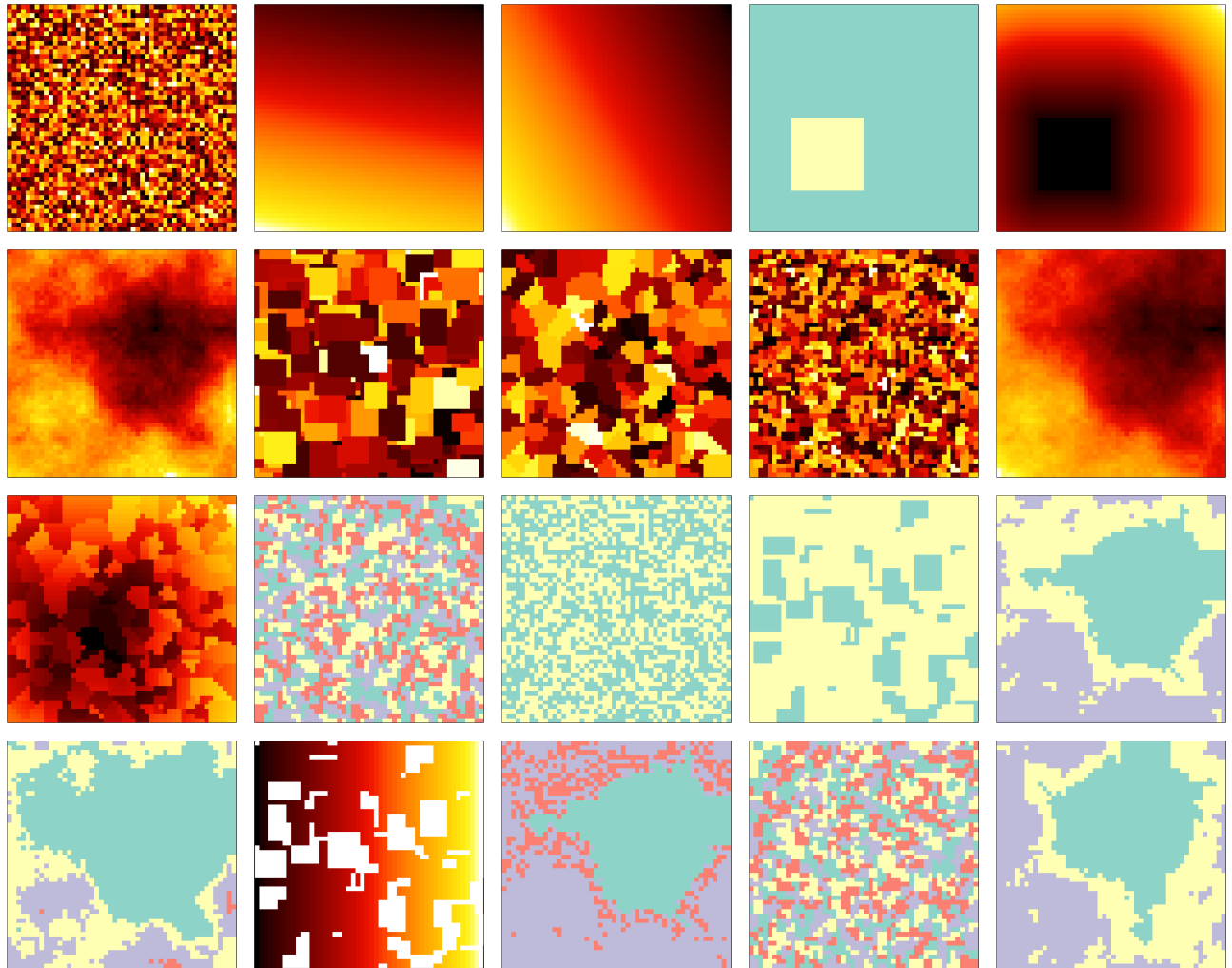


Figure 1: Recreation of the figure in n1mpy paper and the source, supplied in less than 40 lines of code.

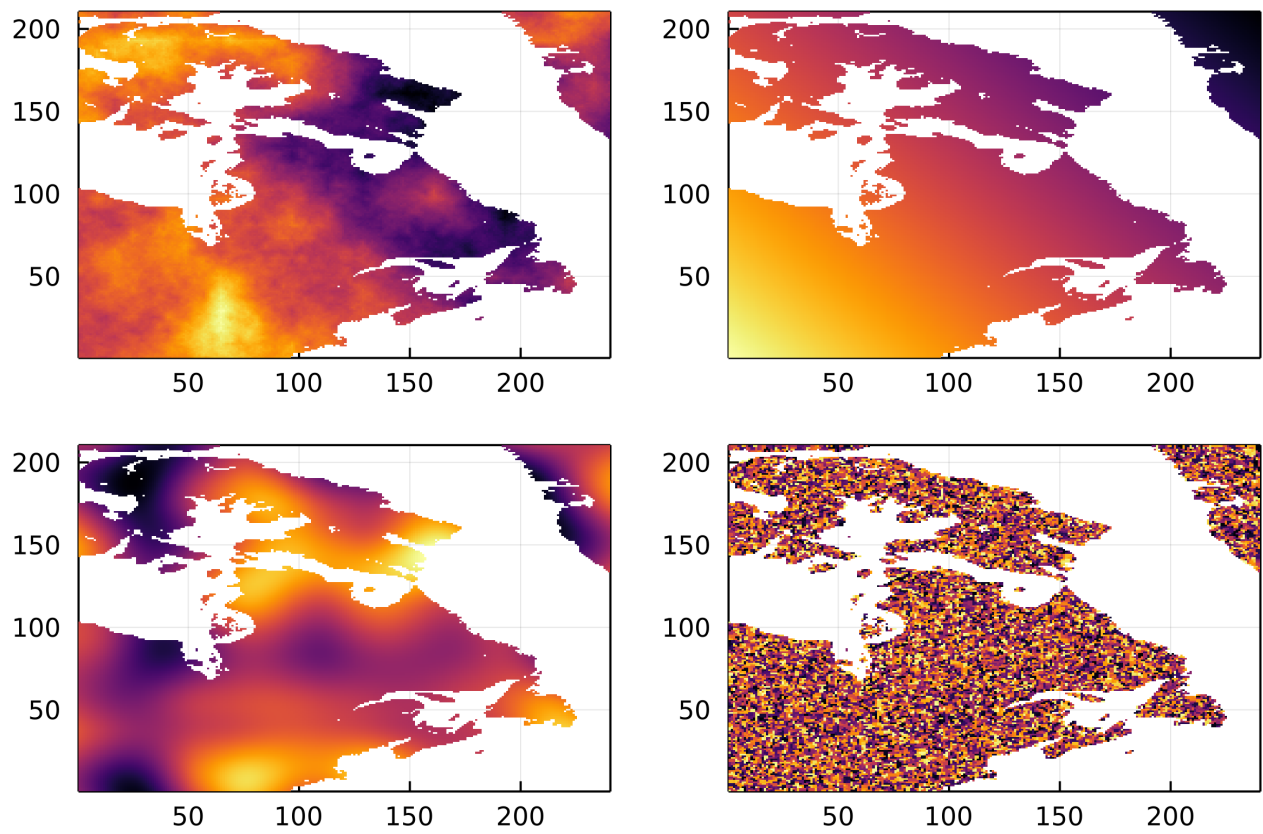


Figure 2: todo



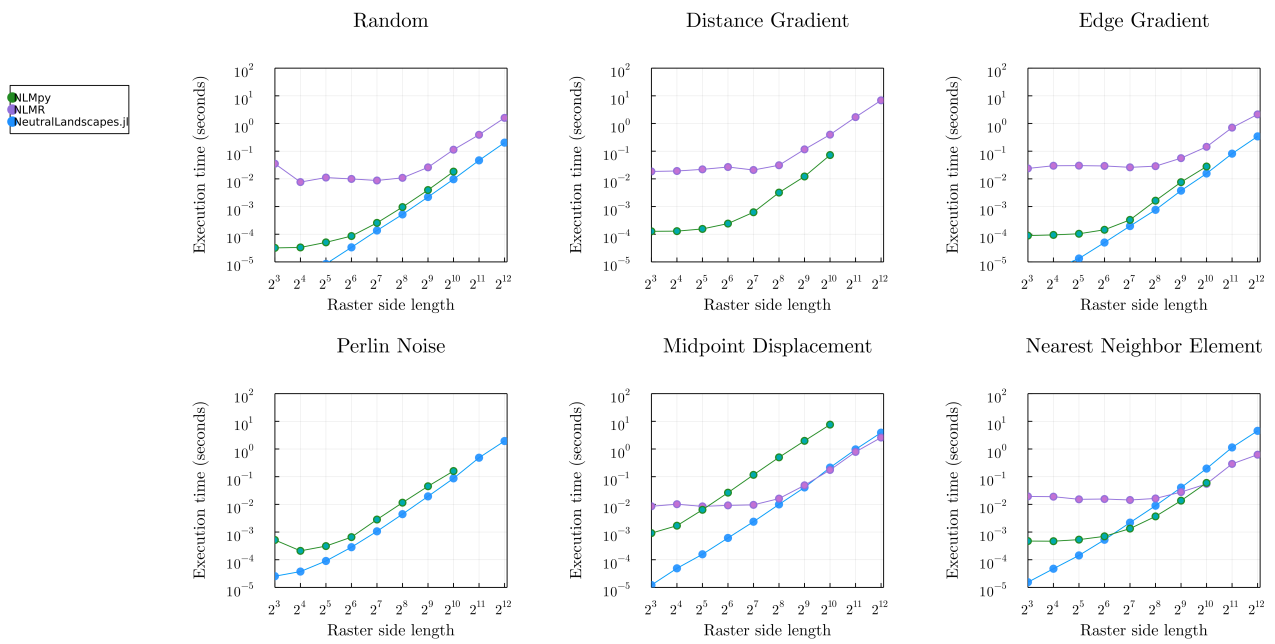


Figure 3: todo