

NeutralLandscapes.jl: a library for efficient generation of neutral landscapes with temporal change

[Michael D. Catchen](#)^{1,2}

¹ McGill University ² Québec Centre for Biodiversity Sciences

Correspondance to:

Michael D. Catchen — michael.catchen@mail.mcgill.ca

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Last revision: *January 7, 2022*



Soon to be a paper, maybe. TK authors, MKB,VB,RS,TP

1 Introduction

2 Neutral landscapes are increasingly used in ecological and evolutionary studies to provide a null
3 expectation spatial variation of a given measurement. Originally developed to simulate the spatially
4 autocorrelated data (**Gardner1987NeuMod?**; **Milne1992SpaAgg?**), they have seen use in a wide range of
5 disciplines: from landscape genetics (**Storfer2007PutLan?**), to landscape and spatial ecology
6 (**Tinker2004HisRan?**; **Remmel2013CatCla?**), and biogeography (**Albert2017BarDis?**).
7 The two primary packages used to simulate neutral landscapes are NLMR in (the R language)
8 (**Sciaini2018NlmLan?**) and NLMpy (in Python; **Etherington2015NlmPyt?**). We present
9 `NeutralLandscapes.jl`, a package in Julia for neutral landscapes which is faster than both above
10 package. Here we demonstrate that `NeutralLandscapes.jl`, depending on the method, is orders of
11 magnitude faster than previous neutral landscape packages. As biodiversity science becomes increasingly
12 concerned with temporal change and its consequences, it's clear there is a gap in methodology in
13 generating neutral landscapes that change over time. In addition we present a novel method for
14 generating landscape change with prescribed levels of spatial and temporal autocorrelation, which is
15 implemented in `NeutralLandscapes.jl`.

16 Software Overview

17 This software can generate neutral landscapes using several methods, enables masking and works with
18 other Julia packages.
19 [fig. 1](#) shows a replica of Figure 1 from (**Etherington2015NlmPyt?**), which shows the capacity of the
20 library to generate different types of neutral landscapes, and then apply masks and categorical
21 classification to them.

22 [Figure 1 about here.]

23 Interoperability

24 Ease of use with other Julia packages

25 Mask of neutral variable masked across Quebec in 3 lines.

```

26 using NeutralLandscapes
27 using SimpleSDMLayers
28
29 quebec = SimpleSDMPredictor(WorldClim, BioClim; left=-90., right=-50., top=75., bottom=40.)
30 qcmask = fill(true, size(quebec))
31 qcmask[findall(isnothing, quebec.grid)] .= false
32
33 pltsettings = (cbar=:none, frame=:box)
34
35 plot(
36     heatmap(rand(MidpointDisplacement(0.8), size(layer), mask=qcmask); pltsettings),
37     heatmap(rand(PlanarGradient(), size(layer), mask=qcmask); pltsettings),
38     heatmap(rand(PerlinNoise((4,4)), size(layer), mask=qcmask); pltsettings),
39     heatmap(rand(NearestNeighborCluster(0.5), size(layer), mask=qcmask); pltsettings),
40     dpi=400
41 )
42
43 savefig("interoperable.png")

```

[Figure 2 about here.]

45 **Benchmark comparison to nlmpy and NLMR**

46 It's fast. As the scale and resolution of raster data increases, neutral models must be able to scale to match
47 those data dimensions. Here we provide two benchmark tests. First a comparison of the speed variety of
48 methods from each NeutralLandscapes.jl, NLMR, and nlmpy. Second we compare these performance of
49 each of these software packages as rasters become larger. We show that Julia even outperforms the NLMR
50 via C++ implementation of a particularly slow neutral landscape method (midpoint displacement).

[Figure 3 about here.]

52 **Generating dynamic neutral landscapes**

53 We implement methods for generating change that are temporally autocorrelated, spatially autocorrelated,
54 or both.

$$55 \quad M_t = M_{t-1} + f(M(t-1))$$

56 **Models of change**

57 **Directional**

58 **Temporally autocorrelation**

59 r : rate, v : variability, U matrix of draws from standard Normal(0, 1)

$$60 \quad f_T(M_{ij}) = r + vU_{ij}$$

61 **Spatial autocorrelation**

62 r : rate, v : variability, $[Z(\delta)]_{ij}$: the (i, j) entry of the zscore of the δ matrix

$$63 \quad f_S(M_{ij}) = r + v \cdot [Z(\delta)]_{ij}$$

64 **Spatiotemporal autocorrelation**

$$65 \quad f_{ST}(M_{ij}) = r + v \cdot [Z(\delta)]_{ij}$$

66 **Rescaling to mimic real data**

67 **Discussion**

68 **References**

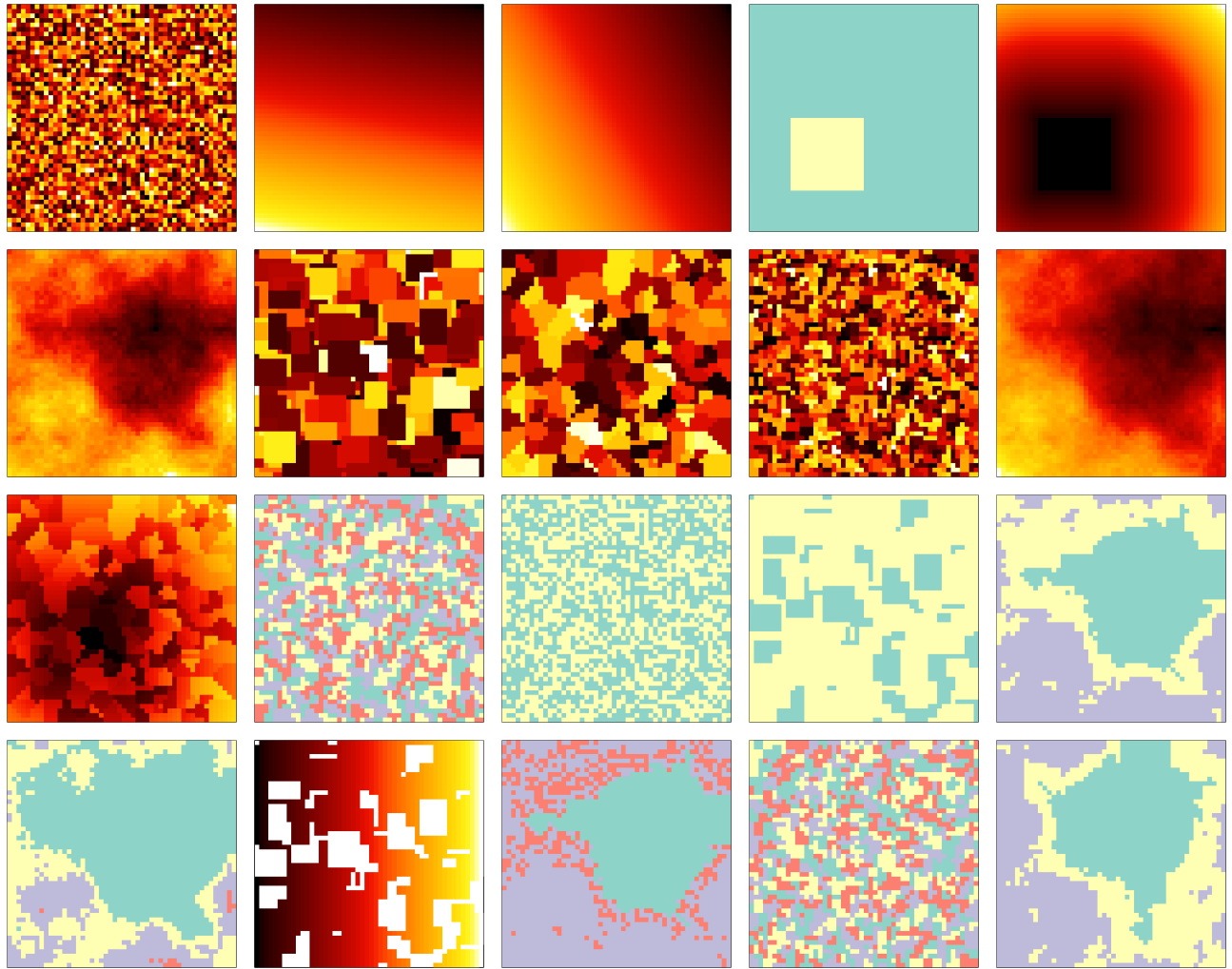


Figure 1: Recreation of the figure in n1mpy paper and the source, supplied in less than 40 lines of code.

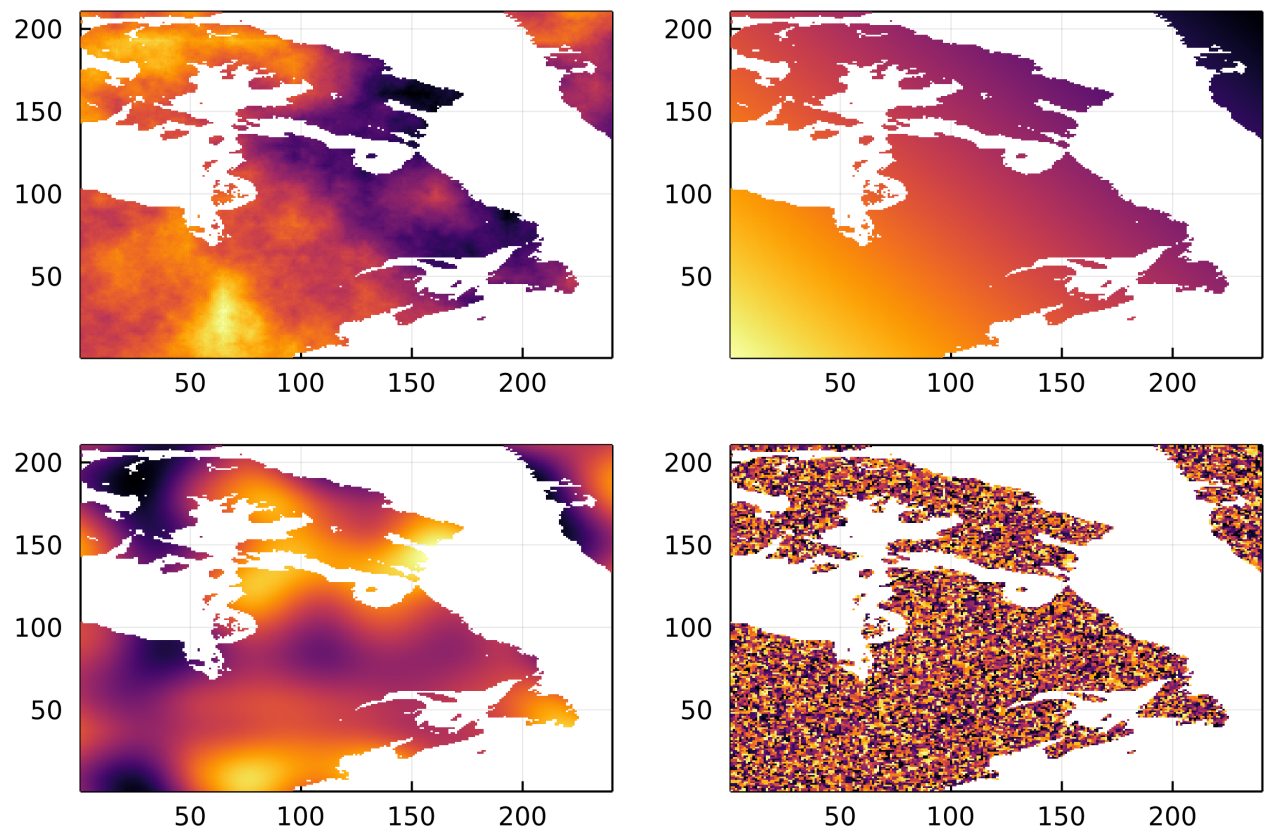


Figure 2: todo

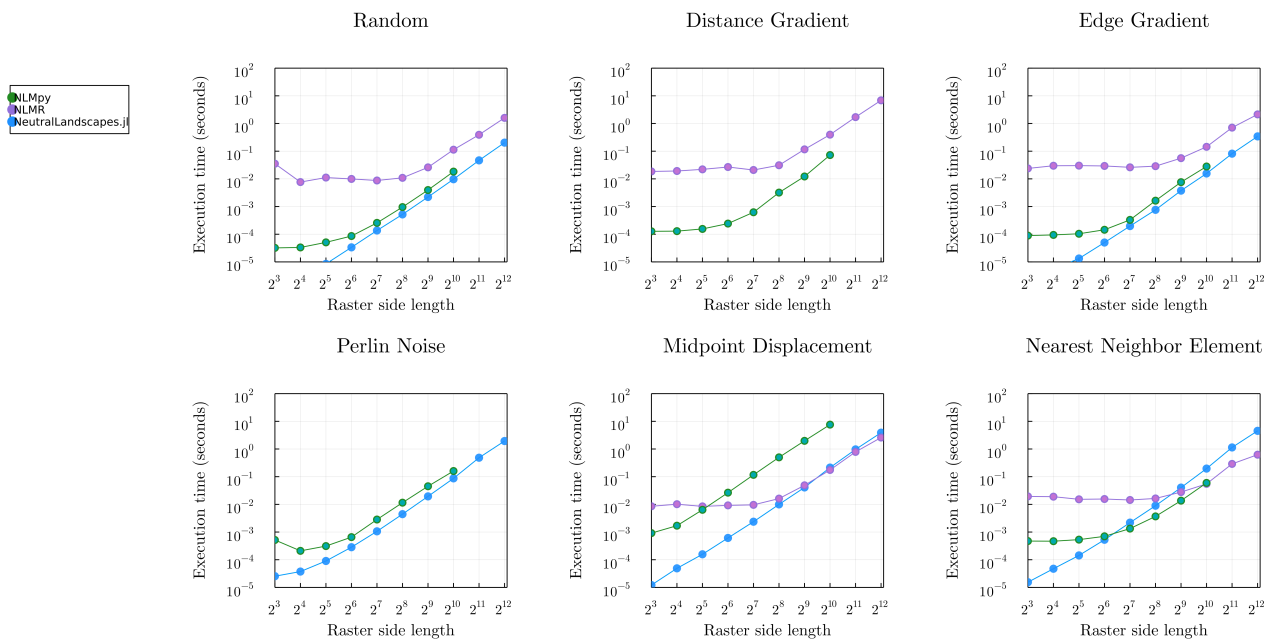


Figure 3: todo